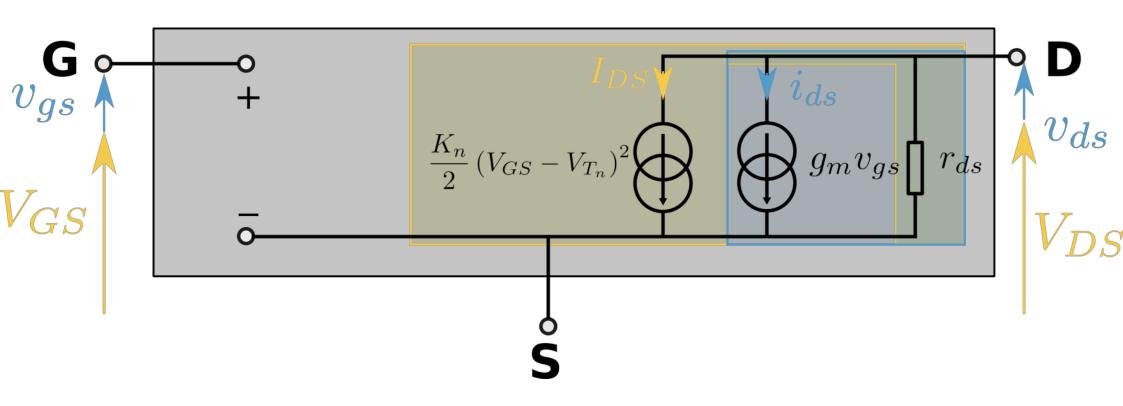
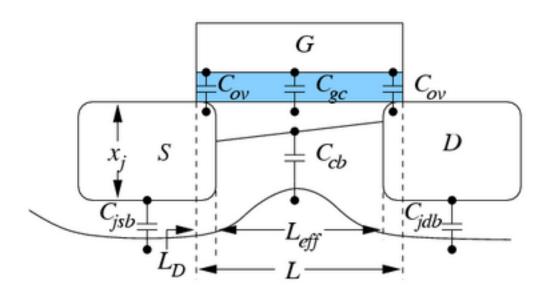


MOS: modélisation BF

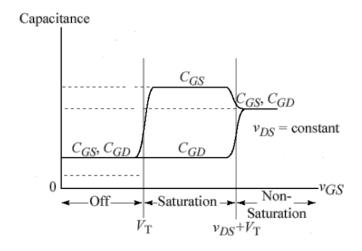




IRL

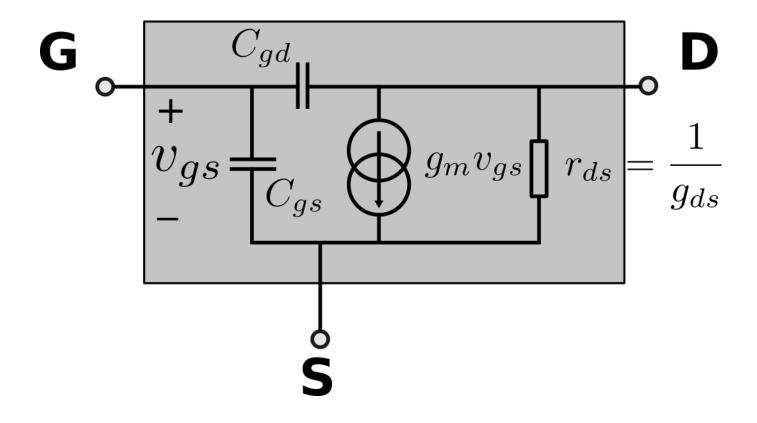


Et pour faire simple...





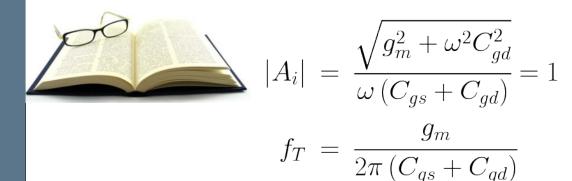
Modèle petit signal HF





Fréquence de transition

$$i_{in} = v_{gs} \cdot j\omega \left(C_{gs} + C_{gd}\right)$$
 $i_{cc} = v_{gs} \left(g_m - j\omega C_{gd}\right)$
 $A_i = \frac{i_{cc}}{i_{in}} = \frac{g_m - j\omega \cdot C_{gd}}{j\omega \left(C_{gs} + C_{gd}\right)}$

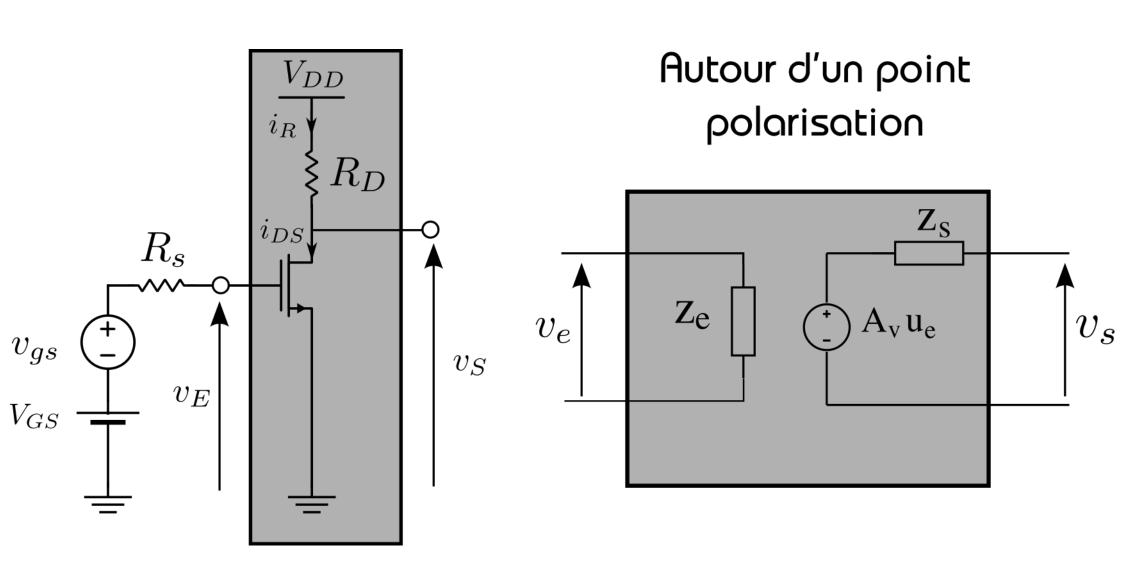


$$\frac{1}{2\pi f_T} \approx \frac{C_{gs}}{gm} = \frac{(2/3)WLC_{ox}}{K_n \underbrace{(V_{IQ} - V_T)}_{=V_{DSAT}}} = \underbrace{\frac{(2/3)L}{\mu_n \underbrace{V_{DSAT}/L}}}_{Vitesse\ \acute{e}lectron} \approx \tau_{transit}$$

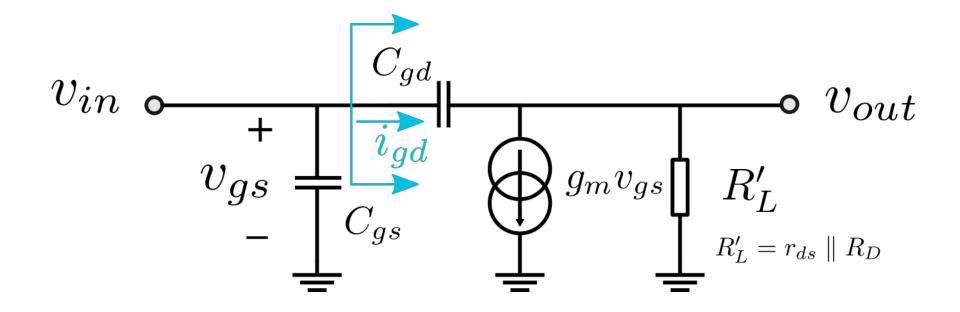


Montage SC: le remake





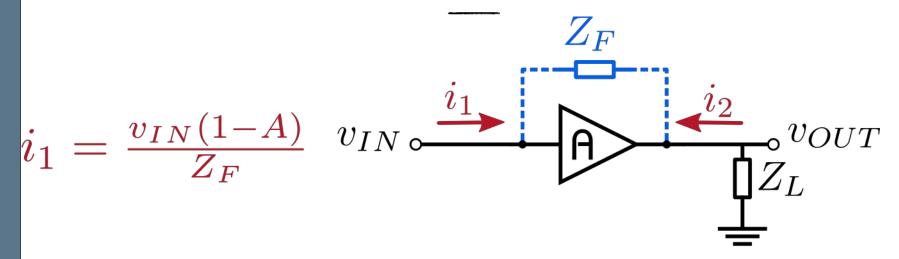
Montage SC: modèle petit signal



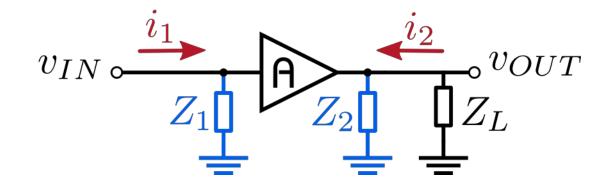


DEPENDENCE OF THE INPUT IMPEDANCE OF A THREE-ELECTRODE VACUUM TUBE UPON THE LOAD IN THE PLATE CIRCUIT

By John M. Miller



$$i_1 = \frac{v_{IN}}{Z_1}$$

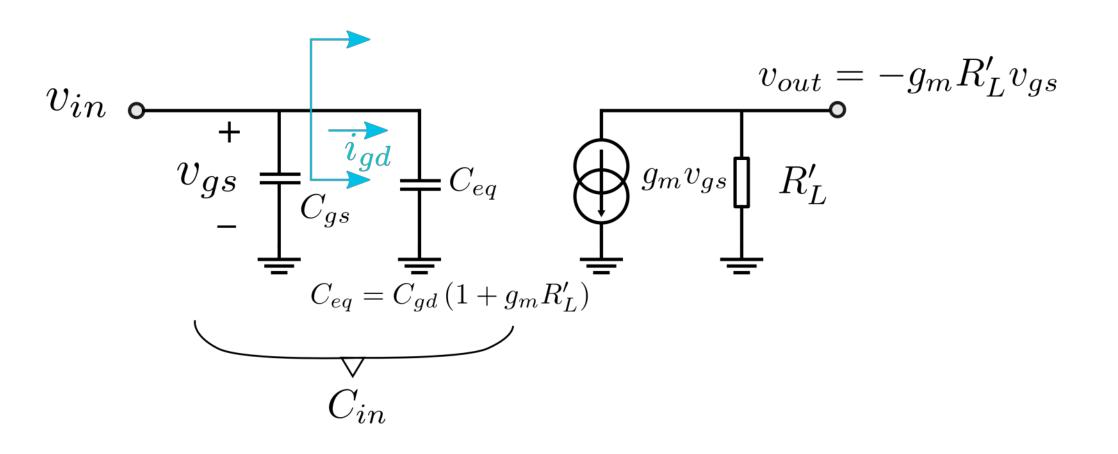




$$Z_1 = \frac{1}{1 - A} \cdot Z_F \approx -\frac{Z_F}{A}$$

$$Z_2 = \frac{A}{A-1} \cdot Z_F \approx Z_F$$

Montage SC: modèle petit signal HF





Montage SC: fréquence de coupure

Tout se passe comme si on avait ajouté, à l'entrée du montage idéal, un filtre RC.

$$\frac{v_{out}}{v_{in}} = -g_m R_L' \cdot \frac{Z_e}{R_s + Z_e} = -\frac{g_m R_L'}{1 + j\omega R_s (C_{GS} + C_{eq})}$$

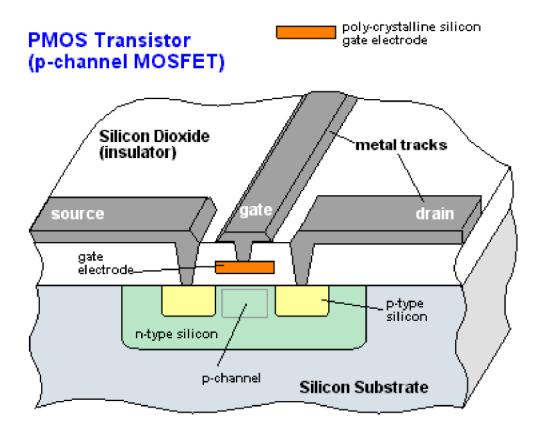
Fréquence de coupure :

$$f_c = \frac{1}{2\pi R_s (C_{gs} + C_{eq})} = \frac{1}{2\pi (C_{gs} + C_{gd} (1 + g_m R_L'))}$$









Pour le PMOS : un courant de trous.

Le comportement du PMOS est l'opposé de celui du NMOS.

On utilise donc les formules du NMOS:

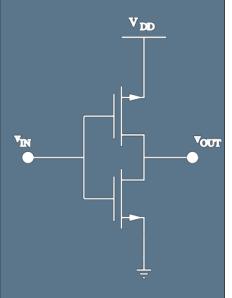
1) sachant que les tensions sont toutes négatives et que les inégalités sont inversées

OU

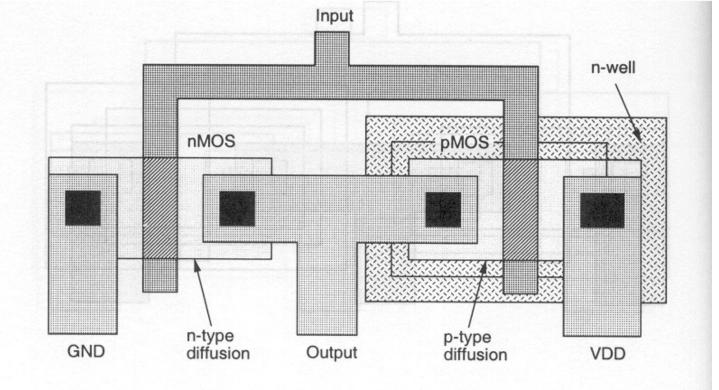
2) en inversant S et D ET S et G



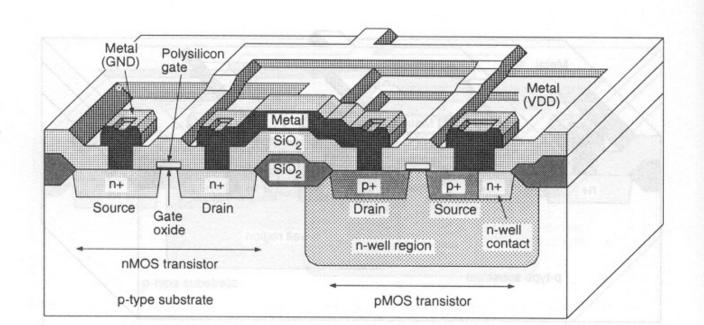


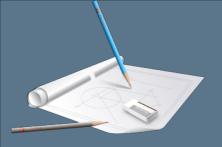




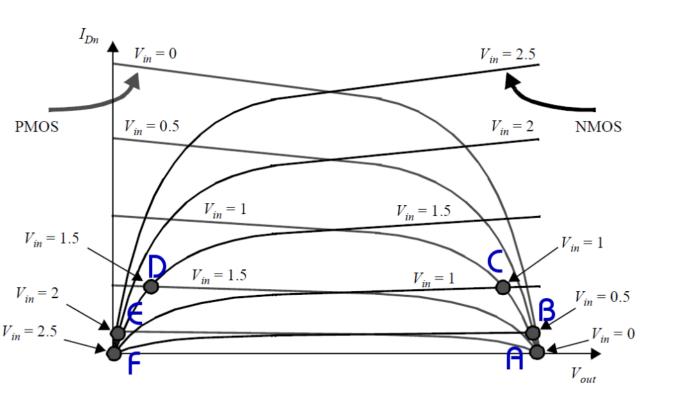


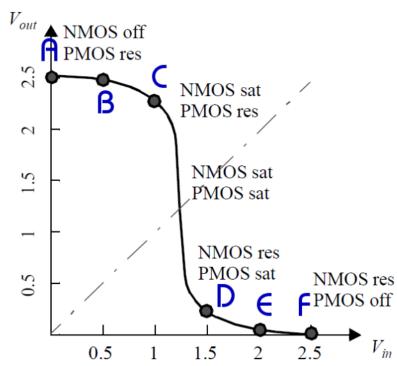
© Atlas of IC Technlogy, W. Maly





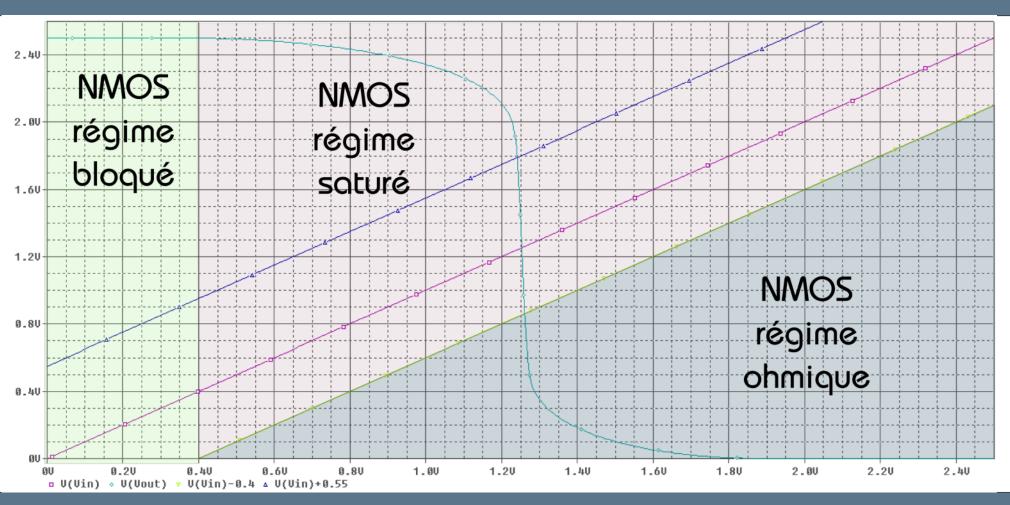
Caractéristique de transfert





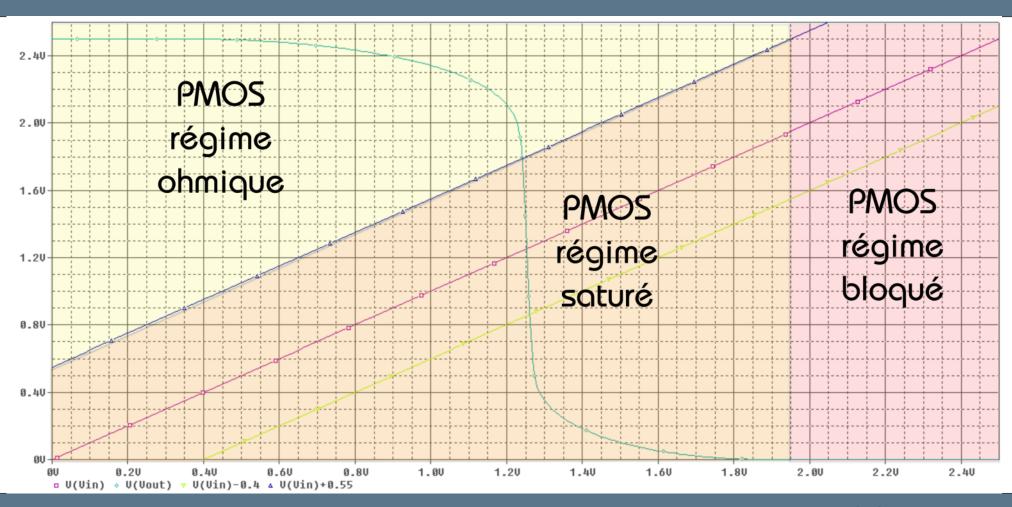


Le NMOS?



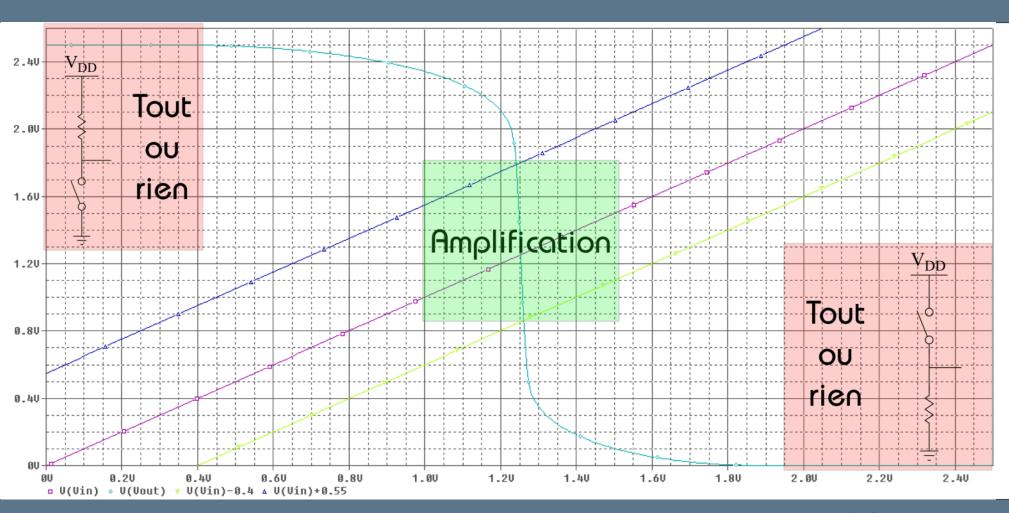


Le PMOS?





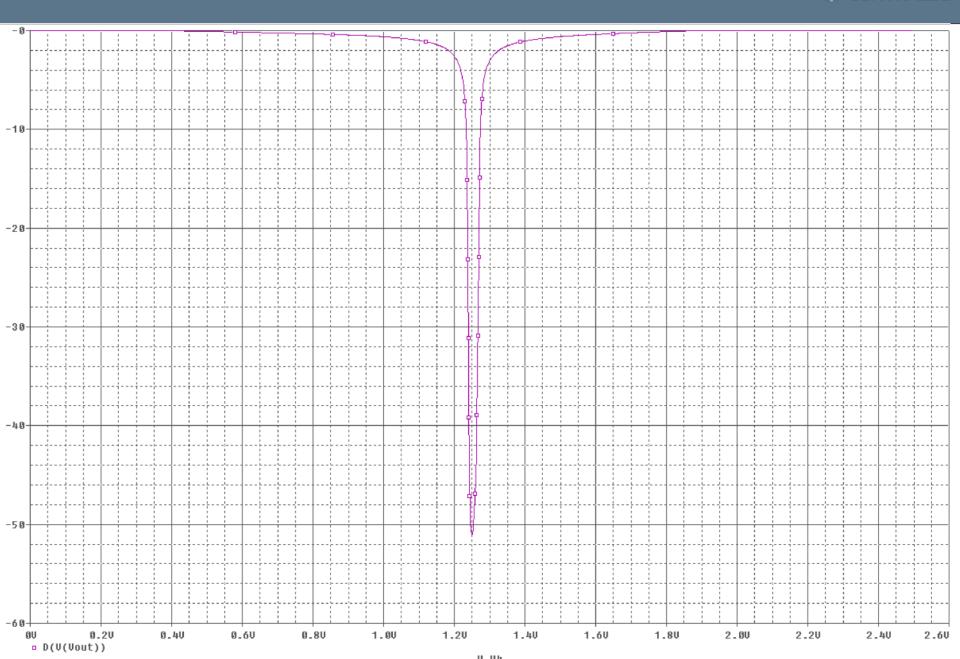
Deux régimes de fonctionnement





Dérivons I_{ds} par rapport à V_{DS}





Point de fonctionnement idéal

Égalité des courants

$$I_{DSn} = \frac{K_n}{2} (V_{GSn} - V_{Tn})^2 \cdot (1 + \lambda \cdot V_{DSn}) = I_{DSp} = \frac{K_p}{2} (V_{SGp} - |V_{Tp}|)^2 \cdot (1 + \lambda \cdot V_{SDp})$$

Équation Équation

Redéfinissons le problème : $V_{IN} = \frac{V_{DD}}{2}$

$$V_{IN} = \frac{V_{DD}}{2}$$

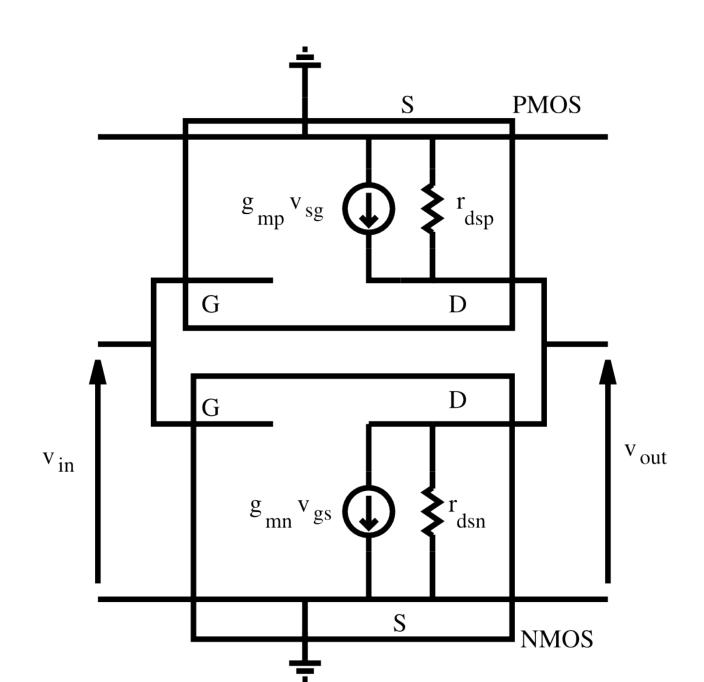
$$K_n \left(\frac{V_{DD}}{2} - V_{Tn} \right)^2 \cdot (1 + \lambda \cdot V_{OUT}) = K_p \left(V_{DD} - \frac{V_{DD}}{2} - |V_{Tp}| \right)^2 \cdot (1 + \lambda \cdot (V_{DD} - V_{OUT}))$$

Considérons un cas particulier :

$$V_{OUT} = V_{IN} = \frac{V_{DD}}{2}$$
 $\Rightarrow \frac{\frac{W_n}{L_n}}{\frac{W_p}{L_n}} = \frac{\mu_p}{\mu_n}$



Modèle petit signal de l'inverseur CMOS





Modèle quadripolaire

