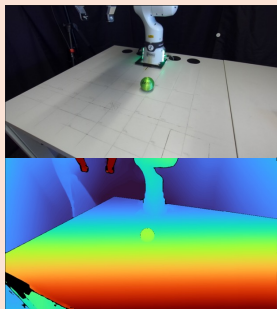
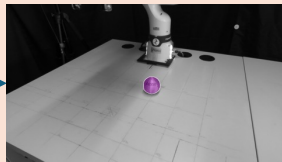


Reference Cloud

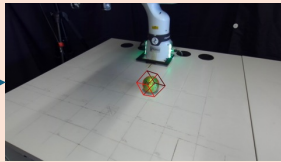
Camera Frame



RGB/Depth 1



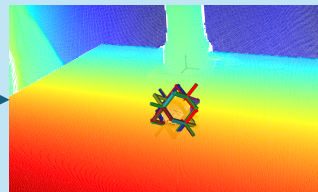
SAM Instance Segmentation



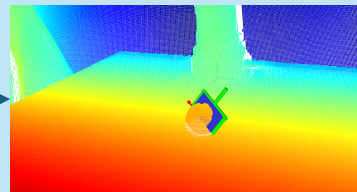
Pose Estimation Model

Grasp File

Robot Frame



Grasp Generation



Final Grasp Pose