

ODE Cheat Sheet

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Revision 3

Fundamentals

Classification

$\frac{d^n y}{dx^n} = f(x, y)$ denotes an ODE of order n . Note that $(\frac{dy}{dx})^n \neq \frac{d^n y}{dx^n}$. ODEs of order n will have n constants in their general form solutions.

A linear ODE is one which can be written in the form $a_n(x) \frac{d^n y}{dx^n} + a_{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots + a_1(x) \frac{dy}{dx} + a_0(x)y = g(x)$.

Solutions

Given some IVP $\frac{dy}{dx} = f(x, y)$, $y(x_0) = y_0$ if f and $\frac{\partial f}{\partial y}$ are continuous in the rectangle $(x_0, y_0) \in \{(x, y) : a < x < b, c < y < d\}$ then the IVP has a unique solution $\phi(x)$ in some interval $(x_0 - h, x_0 + h)$, $h \geq 0$

Solution Techniques $n = 1$

Direct Integration

Directly integrate ...

Seperable

For some ODE $\frac{dy}{dx} = f(x, y) = g(x)p(y)$ the differential can be split $s.t.$ $\frac{1}{p(y)} dy = g(x) dx$ which can be solved by direct integration. Note that when dividing by some function we assume that the function is nonzero. If there is a case (e.g. in an IVP) where the function is zero, the solution is lost.

Linear

For some linear ODE of the form $\frac{dy}{dx} + P(x)y = Q(x)$ we can multiply both sides of the ODE by $\mu(x) = \exp(\int P(x) dx)$ to obtain $\mu \frac{dy}{dx} + \mu P(x)y = \mu Q(x)$ which is equivalent to $\mu y = \mu Q(x)$ which can be solved by direct integration.

Exact

Exact equations are ODEs of the form $Mdx + Ndy = 0$ where $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$. Then, $f(x, y) = \int M dx + h(y) = C$ or $f(x, y) = \int N dy + g(x) = C$ and $\frac{d}{dy}(\int M dx + h(y)) = N$ or $\frac{d}{dx}(\int N dy + g(x)) = M$

Non-Exact

In cases where something looks exact but $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$ you can find an integrating factor

$$\mu(x) = \exp\left(\int \frac{\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x}}{N} dx\right)$$
$$\mu(y) = \exp\left(\int \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{M} dy\right)$$

Homogeneous

If each term of the ODE is of equal order (e.g. the right hand side can be expressed as a function of only $\frac{y}{x}$) we can substitute $y = ux \implies dy = udx + xdu$. This should result in a seperable equation.

Bernoulli

If we have an equation of the form $\frac{dy}{dx} + P(x)y = Q(x)y^n$ we divide by y^n and substitute $u = y^{1-n} \implies \frac{dy}{dx} = \frac{du}{du} \frac{du}{dx}$ (you should know what $\frac{dy}{du}$ is here). This should result in a linear equation.

Linear Substituion

An ODE of the form $\frac{dy}{dx} = f(Ax + By + C)$, $B \neq 0$ can be solved by

$$u = Ax + By + C$$
$$\implies \frac{du}{dx} = A + B \frac{dy}{dx}$$
$$\implies \frac{dy}{dx} = \left(\frac{du}{dx} - A\right) \frac{1}{B}$$

Solution Techniques $n = 2$

Reduction of Order

If you solve a second order ODE and obtain a single solution y_1 , $y_2 = y_1 \int \frac{e^{-\int P(x) dx}}{y_1^2} dx$ where $P(x)$ is found in $y'' + P(x)y' + Q(x)y = g(x)$

Constant Coefficients

An equation of the form $ay'' + by' + cy = g(x)$ can be solved through the characteristic equation obtained by substituting $y = e^{mt}$ and solving for m . This gives a solution of the form $y_h = C_1 e^{m_1 t} + C_2 e^{m_2 t}$.

Undetermined Coefficients

To obtain the particular solution of $ay'' + by' + cy = g(x)$ we try

| |
|--|
| $g(x)$ |
| $Ce^{\alpha x}$ |
| $C_n x^n + \dots + C_1 x + C_0$ |
| $C \cos(\beta x), C \sin(\beta x)$ |
| $(C_n x^n + \dots + C_1 x + C_0) e^{\alpha x}$ |
| $y_p(x)$ |
| $x^s (Ae^{\alpha x})$ |
| $x^s (A_n x^n + \dots + A_1 x + A_0)$ |
| $x^s (A \cos(\beta x) + A_1 \sin(\beta x))$ |
| $x^s (A_n x^n + \dots + A_1 x + A_0) e^{\alpha x}$ |

Variation of Parameters

For $y'' + P(x)y' + Q(x)y = g(x)$ if you have the homogeneous solutions $y_1(x)$ and $y_2(x)$, the particular solution $y_p(x) = u_1(x)y_1(x) + u_2(x)y_2(x)$ where

$$u_1(x) = - \int \frac{g(x)y_2(x)}{W[y_1, y_2]} dx$$

$$u_2(x) = \int \frac{g(x)y_1(x)}{W[y_1, y_2]} dx$$

where $W[y_1, y_2]$ is the Wronskian,

$$\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$$

Cauchy-Euler

An equation of the form $ax^2 y'' + bxy' + cy = g(x)$ can be solved through the characteristic equation $am^2 + (b-a)m + c = 0$ obtained by substituting $y = x^{mt}$ and solving for m . In the case where m is complex here you end up with trig functions of logarithms.

Laplace Transform

If $f(t)$ has period T and is piecewise continuous on $[0, T]$ then

$$\mathcal{L}\{f(t)\} = \frac{\int_0^T e^{-st} f(t) dt}{1 - e^{-sT}}$$

Properties of the Laplace Transform

$$\mathcal{L}\{f_1 + f_2\} = \mathcal{L}\{f_1\} + \mathcal{L}\{f_2\}$$
$$\mathcal{L}\{cf_1\} = c\mathcal{L}\{f_1\}$$
$$\mathcal{L}\{e^{at} f(t)\} = F(s - a)$$
$$\mathcal{L}\{f'(t)\} = s\mathcal{L}\{f(t)\} - f(0)$$
$$\mathcal{L}\{f''(t)\} = s^2 \mathcal{L}\{f(t)\} - sf(0) - f'(0)$$
$$\mathcal{L}\{t^n f(t)\} = (-1)^n \frac{d^n F(s)}{ds^n} \implies f(t) = \frac{(-1)^n}{t^n} \mathcal{L}^{-1}\left\{\frac{d^n F(s)}{ds^n}\right\}$$
$$\mathcal{L}\{f(t-a)\mu(t-a)\} = e^{-as} F(s)$$
$$\mathcal{L}^{-1}\{e^{-as} F(s)\} = f(t-a)\mu(t-a)$$

Solving Discontinuous IVPs with Laplace Transforms

For some ODE $ay'' + by' + cy = g(t)$ $\mathcal{L}\{g(t)\mu(t-a)\} = e^{-as} \mathcal{L}\{g(t+a)\}$

$$\mu(t-a) = \begin{cases} 0 & t < a \\ 1 & t > a \end{cases}$$

Applications

Newton's Cooling

$$\frac{dT}{dt} = k(T - T_m) \implies T(t) = T_m + Ce^{kt}$$

where T is the temperature of an object, T_m the temperature of the medium in which the object sits, and k some cooling constant determined by initial/boundary conditions. C comes about as a result of solving the ODE and can also be determined using initial conditions.

Circuit Theory

$$V_{Resistor} = RI = R \frac{dQ}{dt}$$

$$V_{Inductor} = L \frac{dI}{dt} = L \frac{d^2Q}{dt^2}$$

$$V_{Capacitor} = \frac{Q}{C}$$

Miscellaneous

Partial Fractions

$$\frac{px+q}{(x-a)(x-b)} \rightarrow \frac{A}{x-a} + \frac{B}{x-b}$$

$$\frac{px+q}{(x-a)^2} \rightarrow \frac{A}{x-a} + \frac{B}{(x-a)^2}$$

$$\frac{px^2+qx+r}{(x-a)(x-b)(x-c)} \rightarrow \frac{A}{x-a} + \frac{B}{x-b} + \frac{C}{x-c}$$

$$\frac{px^2+qx+r}{(x-a)^2(x-b)} \rightarrow \frac{A}{x-a} + \frac{B}{(x-a)^2} + \frac{C}{x-b}$$

$$\frac{px^2+qx+r}{(x-a)(x^2-bx+c)} \rightarrow \frac{A}{x-a} + \frac{B}{(x^2-bx+c)}$$

Systems

$$x' = \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = Ax \text{ Then}$$

guess that $x = e^{\lambda t} \implies A\vec{v} = \lambda\vec{v}$. To

solve for eigenvalues find

$\det(A - \lambda I) = 0$. Then solve for

eigenvectors \vec{v}_n for each λ_n with $(A - \lambda_n I) \vec{v}_n = 0$. For real, distinct

eigenvector-value pairs write

$y(t) = C_1 e^{\lambda_1 t} \vec{v}_1 + C_2 e^{\lambda_2 t} \vec{v}_2$. For a

repeated eigenvalue write

$y(t) = C_1 e^{\lambda_1 t} \vec{v}_1 + C_2 e^{\lambda_1 t} (\vec{v}_2 + t\vec{v}_1)$ where

$A\vec{v}_2 - \lambda_1 \vec{v}_2 = \vec{v}_1$