

Physics 2130: Assignment III

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Problem 1. Consider the driven, damped harmonic oscillator. Its equation of motion is:

$$\ddot{x} + 2\beta\dot{x} + \omega_0^2 = A \cos(\omega t)$$

In the case of an underdamped oscillator, i.e., $\beta < \omega_0^2$ we found that the solution for the equation of motion is:

$$x(t) = x_c(t) + x_p(t)$$

Where:

$$x_c(t)e^{-\beta t} [c_1 e^{i\omega_1 t} + c_2 e^{-i\omega_1 t}] = B e^{-\beta t} \cos(\omega_1 t - \phi) = \Gamma(t)s(t)$$

And where:

$$\omega_1 = \sqrt{\omega_0^2 - \beta^2}$$

$$\Gamma(t) = B e^{-\beta t}$$

$$s(t) = (\omega_1 t - \phi)$$

The particular solution is instead:

$$x_p(t) = D \cos(\omega t - \delta)$$

Where:

$$D = \frac{A}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2\beta^2}}$$

$$\delta = \arctan\left(\frac{2\omega\beta}{\omega_0^2 - \omega^2}\right)$$

Solution 1.

$$x(t=0) = B \cos(-\phi) + D \cos(-\delta) = x_0$$

$$\Rightarrow x_0 - D \cos(\delta) = B \cos(\phi)$$

$$\Rightarrow \frac{x_0 - D \cos(\delta)}{\cos(\phi)} = B$$

$$\dot{x}(t=0) = -B\omega_1 \sin(-\phi) - B\beta \cos(-\phi) - D\omega \sin(-\delta) = 0$$

$$= B\omega_1 \sin(\phi) - B\beta \cos(\phi) + D\omega \sin(\delta)$$

$$= \frac{x_0 - D \cos(\delta)}{\cos(\phi)} \omega_1 \sin(\phi) - \frac{x_0 - D \cos(\delta)}{\cos(\phi)} \beta \cos(\phi) + D\omega \sin(\delta)$$

$$= (x_0 - D \cos(\delta)) \omega_1 \tan(\phi) - (x_0 - D \cos(\delta)) \beta + D\omega \sin(\delta)$$

$$\Rightarrow -\frac{D\omega \sin(\delta)}{(x_0 - D \cos(\delta))} = \omega_1 \tan(\phi) - \beta$$

$$\Rightarrow \arctan\left(\frac{\beta - \frac{D\omega \sin(\delta)}{(x_0 - D \cos(\delta))}}{\omega_1}\right) = \phi$$