

# ODE Cheat Sheet

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## Fundamentals

### Classification

$\frac{d^n y}{dx^n} = f(x, y)$  denotes an ODE of order  $n$ . Note that  $(\frac{dy}{dx})^n \neq \frac{d^n y}{dx^n}$ . ODEs of order  $n$  will have  $n$  constants in their general form solutions.

A linear ODE is one which can be written in the form  $a_n(x)\frac{d^n y}{dx^n} + a_{n-1}\frac{d^{n-1} y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$ .

### Solutions

Given some IVP  $\frac{dy}{dx} = f(x, y)$ ,  $y(x_0) = y_0$  if  $f$  and  $\frac{\partial f}{\partial y}$  are continuous in the rectangle  $(x_0, y_0) \in \{(x, y) : a < x < b, c < y < d\}$  then the IVP has a unique solution  $\phi(x)$  in some interval  $(x_0 - h, x_0 + h)$ ,  $h \geq 0$

## Solution Techniques $n = 1$

### Direct Integration

Directly integrate ...

### Seperable

For some ODE  $\frac{dy}{dx} = f(x, y) = g(x)p(y)$  the differential can be split  $s.t.$

$\frac{1}{p(y)} dy = g(x) dx$  which can be solved by direct integration. Note that when dividing by some function we assume that the function is nonzero. If there is a case (e.g. in an IVP) where the function is zero, the solution is lost.

### Linear

For some linear ODE of the form  $\frac{dy}{dx} + P(x)y = Q(x)$  we can multiply both sides of the ODE by

$\mu(x) = \exp(\int P(x) dx)$  to obtain

$\mu \frac{dy}{dx} + \mu P(x)y = \mu Q(x)$  which is equivalent to  $\mu y = \mu Q(x)$  which can be solved by direct integration.

### Exact

Exact equations are ODEs of the form  $M dx + N dy = 0$  where  $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$ . Then,  $f(x, y) = \int M dx + h(y) = C$  or  $f(x, y) = \int N dy + g(x) = C$  and  $\frac{d}{dy}(\int M dx + h(y)) = N$  or  $\frac{d}{dx}(\int N dy + g(x)) = M$

### Non-Exact

In cases where something looks exact but  $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$  you can find an integrating factor

$$\mu(x) = \exp\left(\int \frac{\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x}}{N} dx\right)$$
$$\mu(y) = \exp\left(\int \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{M} dy\right)$$

### Homogeneous

If each term of the ODE is of equal order (e.g. the right hand side can be expressed as a function of only  $\frac{y}{x}$ ) we can substitute  $y = ux \implies dy = u dx + x du$ . This should result in a seperable equation.

### Bernoulli

If we have an equation of the form  $\frac{dy}{dx} + P(x)y = Q(x)y^n$  we divide by  $y^n$  and substitute  $u = y^{1-n} \implies \frac{dy}{dx} = \frac{du}{du} \frac{du}{dx}$  (you should know what  $\frac{dy}{du}$  is here). This should result in a linear equation.

### Linear Substituion

An ODE of the form  $\frac{dy}{dx} = f(Ax + By + C)$ ,  $B \neq 0$  can be solved by

$$u = Ax + By + C$$
$$\implies \frac{du}{dx} = A + B \frac{dy}{dx}$$
$$\implies \frac{dy}{dx} = \left(\frac{du}{dx} - A\right) \frac{1}{B}$$

## Solution Techniques $n = 2$

### Reduction of Order

If you solve a second order ODE and obtain a single solution  $y_1$ ,  $y_2 = y_1 \int \frac{e^{-\int P(x) dx}}{y_1^2} dx$

where  $P(x)$  is found in  $y'' + P(x)y' + Q(x)y = g(x)$

### Constant Coefficients

An equation of the form  $ay'' + by' + cy = g(x)$  can be solved through the characteristic equation obtained by substituting  $y = e^{mt}$  and solving for  $m$ . This gives a solution of the form  $y_h = C_1 e^{m_1 t} + C_2 e^{m_2 t}$ .

### Undetermined Coefficients

To obtain the particular solution of  $ay'' + by' + cy = g(x)$  we try

$\frac{g(x)}{C e^{\alpha x}}$
$C_n x^n + \dots + C_1 x + C_0$ $C \cos(\beta x), C \sin(\beta x)$ $(C_n x^n + \dots + C_1 x + C_0) e^{\alpha x}$
$y_p(x)$ $x^s (A e^{\alpha x})$ $x^s (A_n x^n + \dots + A_1 x + A_0)$ $x^s (A \cos(\beta x) + A_1 \sin(\beta x))$ $x^s (A_n x^n + \dots + A_1 x + A_0) e^{\alpha x}$

### Variation of Parameters

For  $y'' + P(x)y' + Q(x)y = g(x)$  if you have the homogeneous solutions  $y_1(x)$  and  $y_2(x)$ , the particular solution  $y_p(x) = u_1(x)y_1(x) + u_2(x)y_2(x)$  where

$$u_1(x) = - \int \frac{g(x)y_2(x)}{W[y_1, y_2]} dx$$

$$u_2(x) = \int \frac{g(x)y_1(x)}{W[y_1, y_2]} dx$$

where  $W[y_1, y_2]$  is the Wronskian,

$$\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$$

### Cauchy-Euler

An equation of the form  $ax^2 y'' + bxy' + cy = g(x)$  can be solved through the characteristic equation  $am^2 + (b-a)m + c = 0$  obtained by substituting  $y = x^{mt}$  and solving for  $m$ . In the case where  $m$  is complex here you end up with trig functions of logarithms.

## Laplace Transform

If  $f(t)$  has period  $T$  and is piecewise continuous on  $[0, T]$  then

$$\mathcal{L}\{f(t)\} = \frac{\int_0^T e^{-st} f(t) dt}{1 - e^{-sT}}$$

### Properties of the Laplace Transform

$$\mathcal{L}\{f_1 + f_2\} = \mathcal{L}\{f_1\} + \mathcal{L}\{f_2\}$$
$$\mathcal{L}\{cf_1\} = c\mathcal{L}\{f_1\}$$
$$\mathcal{L}\{e^{at} f(t)\} = F(s - a)$$
$$\mathcal{L}\{f'(t)\} = s\mathcal{L}\{f(t)\} - f(0)$$
$$\mathcal{L}\{f''(t)\} = s^2 \mathcal{L}\{f(t)\} - sf(0) - f'(0)$$
$$\mathcal{L}\{t^n f(t)\} = (-1)^n \frac{d^n F(s)}{ds^n} \implies f(t) = \frac{(-1)^n}{t^n} \mathcal{L}^{-1}\left\{\frac{d^n F(s)}{ds^n}\right\}$$
$$\mathcal{L}\{f(t - a)\mu(t - a)\} = e^{-as} F(s)$$
$$\mathcal{L}^{-1}\{e^{-as} F(s)\} = f(t - a)\mu(t - a)$$

### Solving Discontinuous IVPs with Laplace Transforms

For some ODE  $ay'' + by' + cy = g(t)$   $\mathcal{L}\{g(t)\mu(t - a)\} = e^{-as} \mathcal{L}\{g(t + a)\}$

$$\mu(t - a) = \begin{cases} 0 & t < a \\ 1 & t > a \end{cases}$$

## Applications

### Newton's Cooling

$$\frac{dT}{dt} = k(T - T_m) \implies T(t) = T_m + C e^{kt}$$

where  $T$  is the temperature of an object,  $T_m$  the temperature of the medium in which the object sits, and  $k$  some cooling constant determined by initial/boundary conditions.  $C$  comes about as a result of solving the ODE and can also be determined using initial conditions.

### Circuit Theory

$$V_{Resistor} = RI = R \frac{dQ}{dt}$$

$$V_{Inductor} = L \frac{dI}{dt} = L \frac{d^2 Q}{dt^2}$$

$$V_{Capacitor} = \frac{Q}{C} = L \frac{d^2 Q}{dt^2}$$