

MOHAMMAD REZA KARIMI DASTJERDI

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Overview

I am a specialist in computer vision and machine learning. My expertise is to develop learning-based solutions for problems at the intersection of computer vision and computer graphics. My skills span over:

- **Lighting Estimation**
- **Image-based Lighting**
- **High Dynamic Range Imaging**
- **Generative Models**
- **Novel View Synthesis**

Education

- PhD Candidate of Electrical Engineering**, Université Laval, Canada Sep. 2019–Present
Dissertation: Lighting Estimation and Capturing for Photo-realistic Virtual Object Insertion
- MSc in Culture Technology**, KAIST, South Korea Sep. 2017–Jul. 2019
Thesis: Cinemagraph Generation from a Static Image with Generative Adversarial Networks
- BSc in Computer Engineering**, K.N.Toosi University of Technology, Iran Sep. 2011–Sep. 2016

Publications

- J. Giroux, **M. Karimi Dastjerdi**, Y. Hold-Geoffroy, J. Vazquez-Corral, J. Lalonde, Towards a Perceptual Evaluation Framework for Lighting Estimation, IEEE / CVF Computer Vision and Pattern Recognition Conference (CVPR) 2024. [\[Project page\]](#)
- **M. Karimi Dastjerdi**, Y. Hold-Geoffroy, J. Eisenmann, J. Lalonde, EverLight: Indoor-Outdoor Editable HDR Lighting Estimation, International Conference on Computer Vision (ICCV) 2023. [\[Project page\]](#)
- **M. Karimi Dastjerdi**, Y. Hold-Geoffroy, J. Eisenmann, S. Khodadadeh, J. Lalonde, Guided Co-Modulated GAN for 360° Field of View Extrapolation, IEEE International Conference on 3D Vision (3DV) 2022, **Oral presentation**, [\[Project page\]](#)
- P. Gera, **M. Karimi Dastjerdi**, C. Renaud, P. J. Narayanan, J. Lalonde, Casual Indoor HDR Radiance Capture from Omnidirectional Images, The British Machine Vision Conference (BMVC) 2022, **Spotlight presentation**, [\[Project page\]](#)

Research Experience

- Research Assistant, Computer Vision and Systems Laboratory, Université Laval** Sep. 2019–Present
- Proposing different methods based on Neural Radiance Fields (NeRF) and 360° cameras to capture HDR radiance of indoor scenes.
 - Advised two graduate students and mentored multiple interns in their projects.
- Research Intern, Adobe** May. 2022–Mar. 2023
- Proposed a lighting estimation method that works for both indoor and outdoor domains seamlessly and produces high dynamic range, high-resolution panoramas ready to use as HDRI in rendering engines.
 - Introduced lighting comodulation in GANs, combining the flexibility and intuitiveness of parametric lighting models with the generative power of GANs, resulting in easily editable outputs.
 - Adobe is currently integrating the proposed method for the Match Image feature of Adobe Substance 3D Stager.
- Research Scientist Intern, Adobe** May. 2021–Nov. 2021
- Presented an end-to-end trainable pipeline based on GANs specifically tailored to the 360° FOV extrapolation.
 - Introduced guided co-modulation mechanism in GANs to edit the content of the generated pixels without any GAN inversion.
 - At the time, demonstrated state-of-the-art results both quantitatively and qualitatively.
 - It is currently being integrated for face anonymization in Adobe Photoshop and Match Image in Adobe Substance 3D Stager.
 - This work is featured at **Adobe Max Sneaks 2022** as **#ProjectBeyondTheSeen**.

Patents

- **M. Karimi Dastjerdi**, Y. Hold-Geoffroy, S. Bi, J. Eisenmann, J. Lalonde, Artificial Intelligence Techniques For Extrapolating HDR Panoramas From LDR Low FOV Images, **Joint Patent between Adobe and Université Laval** - In preparation.
- **M. Karimi Dastjerdi**, Y. Hold-Geoffroy, J. Eisenmann, V. Kim, J. Lalonde, Extrapolating Panoramas from Images using a Generative Model - Worldwide applications, Application no. 18055716 - Pending.
- J. Noh, H. Lee, B. Kim, G. Kim, J. Lelong, **M. Karimi Dastjerdi**, A. Kim, J. Lee, Image Processing Method and Device Therefor, US patent - Patent no. 11893704. February 2024.

Honors and Awards

ICCV Doctoral Consortium (Oct. 2023)

Winner of Otis-Lalonde Scholarship (Mar. 2023)

Bourse en vision artificielle 2e et 3e cycle, Québec, Canada

Presentation Competition: First Place (Apr. 2022), **Second Place** (Apr. 2021)

Journées de la relève en intelligence et données, Québec, Canada

Machine Vision: Explorer League: First Place (Sep. 2015) **Second Place** (Nov. 2014)

SharifCup Open Robotics Competition, Sharif University of Technology, Tehran, Iran

Professional Experiences

Chair, IEEE Young Professionals Affinity Group, IEEE Quebec Section (2021 - 2023)

Reviewer, CVPR 2024, IEEE TVCG 2024, 2023, 3DV 2021, ICCV workshop 2021

Student Committee Member, ICRoM 2014, 2016.

Technical Committee Member, The 2nd International Students Competition in Robotic, Amirkabir University of Technology, Tehran, Iran. Mar. 2016.

Technical Committee Member, The 1st KNTU Workshop on Robotics and Embedded Systems, Khazar University, Baku, Azerbaijan. Dec. 2015.

Computer skills

Programming languages Python, C++, and C

Machine Learning PyTorch, Keras, Tensorflow

Computer Graphics Blender, Maya, Unity3D

Language

English (Proficient) Persian (Native) Korean (Basic) French (Basic)

REFERENCES

Prof. Jean-François Lalonde

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Dr. Yannick Hold-Geoffroy

Senior Research Scientist,

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