

# **RUSTY RAILWAYS**

Project: embedded software for IoT



## MASTER

| 8        | Rust based                |   |
|----------|---------------------------|---|
| $\wedge$ | Map                       | Keeps the state of the system   |
|          | High Level Controller     | Communicates the system status with the UI (using HTTP) Receive move requests |
| •••      | Path Finder and Scheduler | Find the most optimal path Avoid train crashes Manage conflicts               |
|          | Low Level Controller      | Controls train and switches (using HTTP)                                      |

## TRAIN

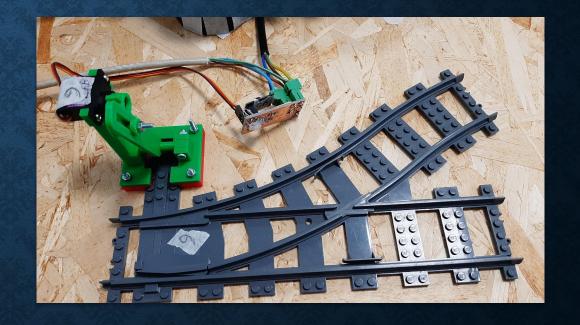
- Rust based
- Structured on 2 separate tasks using a FreeRTOS based library
- One task Manage Wifi communications
- One task manage hardware I/O interfacing
- Non blocking Queue to communicate
- RFID reader with SPI
- H bridge with PWM control motors



## RAILWAY SWITCHES



- PWM servo controller
- WiFi communication



## CLIENT (GUI)



Godot Based (with GDScript)



Main UI

Create and Edit the Train Track, set IDs and Master IP



HTTPIO

Send move requests to Master (using HTTP)



**Updaters** 

Pools Train Positions, States, Speeds and Switch States data from Master (using HTTP)



#### STRUCTURE AND TESTING

- All Rust components are split into hardware dependent and hardware independent parts using rust's Trait System <u>Example</u>
- The entire system has been recreated in a <u>simulation</u> to test all the master's feature without the needs of a physical system
- The master has also 30+ automated unit test
- All the code is fully covered by <u>documentation</u> tanks to doxygen and rustdoc



### FUTURE IMPLEMENTATIONS



Adding an encoder to the motors to allow a better speed control using PID



Adding battery level reader using ADC



Add charging station inside the map



OTA: Possibility to update the firmware via internet



Integrate with a loading/unloading system to deliver goods (possibly a coffee delivery machine for our professor Yildirim)

#### CONTRIBUTIONS



#### Master:

Low Level Controller: Federico Peruzzo
 Path Finder And scheduler: Luca Sartore
 High Level Controller: Lorenzo Cattai

Trains: Luca Sartore and Michele Callegari

Switches: Michele Callegari

Graphical user interface: Lorenzo Cattai

Electronic Design, testing and manufacturing: Federico Peruzzo

3D Design: Luca Sartore

Git Repository: <a href="https://github.com/MrLakige/rusty-railways">https://github.com/MrLakige/rusty-railways</a>

A Special tanks to the UniTh Fablab Team!

