Static Single Assignment Form

CMPT 379: Compilers

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anoopsarkar.github.io/compilers-class

SSA Form

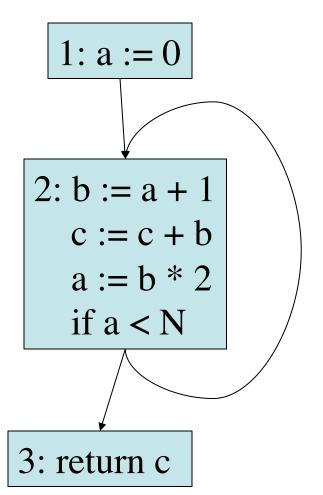
- Conversion from a Control Flow Graph (created from TAC) into SSA Form is not trivial
- SSA creation algorithms:
 - Original algorithm by Cytron et al. 1986
 - Lengauer-Tarjan algorithm (see the Tiger book by Andrew W. Appel for more details)
 - Harel algorithm

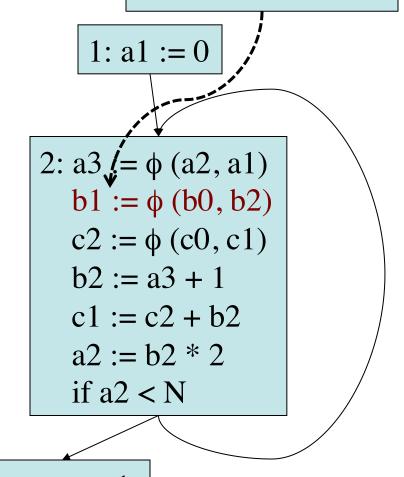
Conversion to SSA Form

- Simple idea: add a ϕ function for every variable at a join point
- A join point is any node in the control-flow graph with more than one predecessor
- But: this is wasteful and unnecessary.

Conversion to SSA

b1 is never used, stmt can be deleted

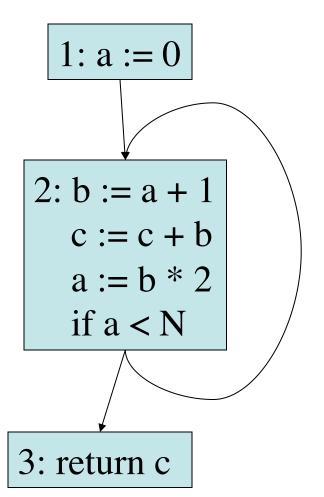


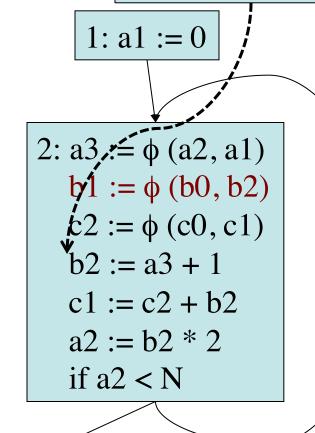


3: return c1

Conversion to SSA

b2 changes in each loop. SSA is **not** functional programming!





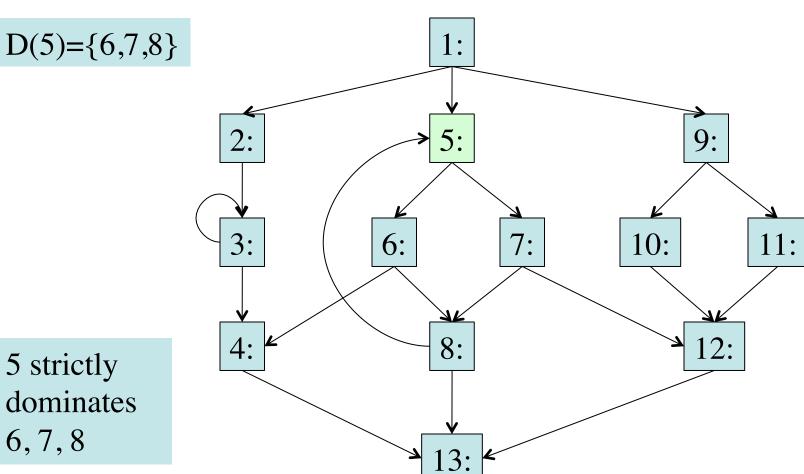
3: return c1

Dominance Relation

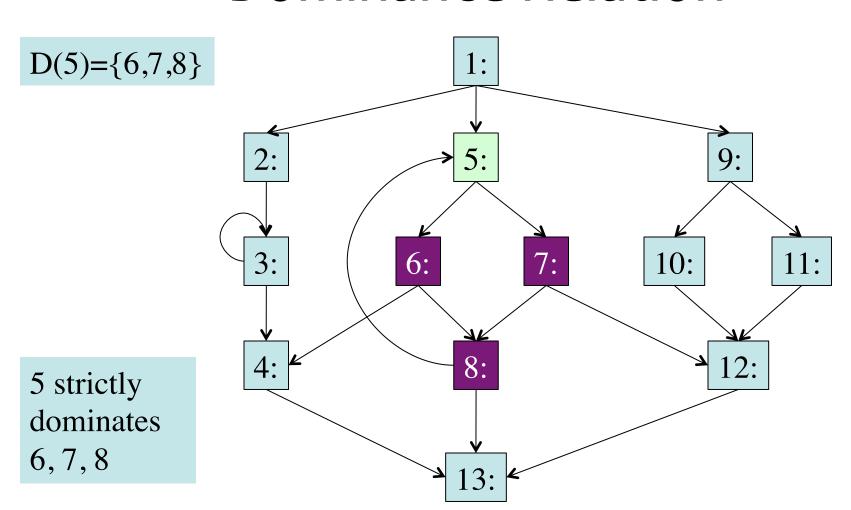
- X dominates Y if every path from the start node to Y goes through X
- D(X) is the set of nodes that X dominates
- X strictly dominates Y if X dominates Y and X ≠ Y

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Dominance Relation



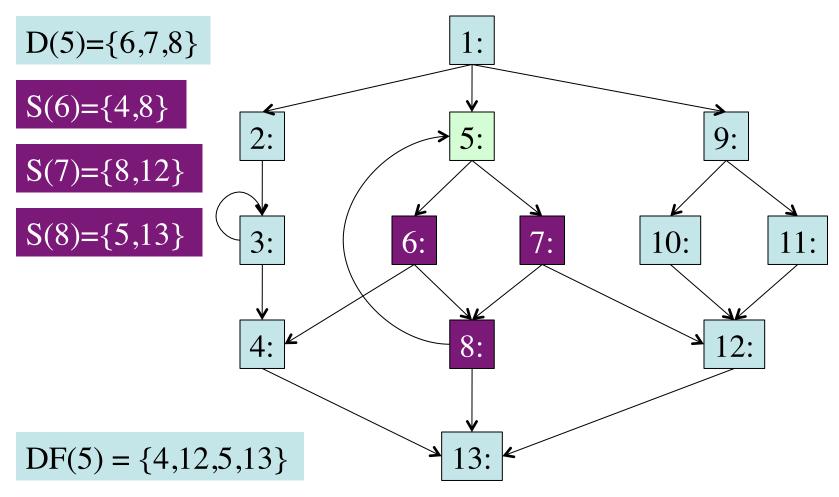
Dominance Relation



Dominance Property of SSA

- Essential property of SSA form is the definition of a variable must dominate use of the variable:
 - If X is used in a φ function in block n, then definition of X dominates every predecessor of n
 - If X is used in a non-φ statement in block n, then the definition of X dominates n.

- X strictly dominates Y if X dominates Y and X ≠ Y
- Dominance Frontier (DF) of node X is the set of all nodes Y such that:
 - X dominates a predecessor of Y, AND
 - X does not strictly dominate Y



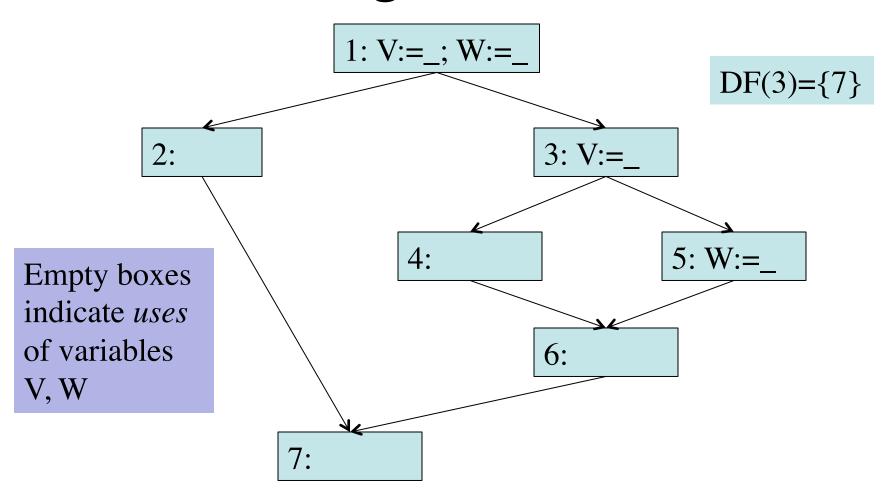
- Algorithm to compute DF(X):
 - Local(X) := set of successors of X who do not immediately dominate X
 - Up(X) := set of nodes in DF(X) that are not dominated by X's immediate dominator.
 - DF(X) := Union of Local(X) & (Union of Up(K) for all K that are children of X)

• ComputeDF(X):

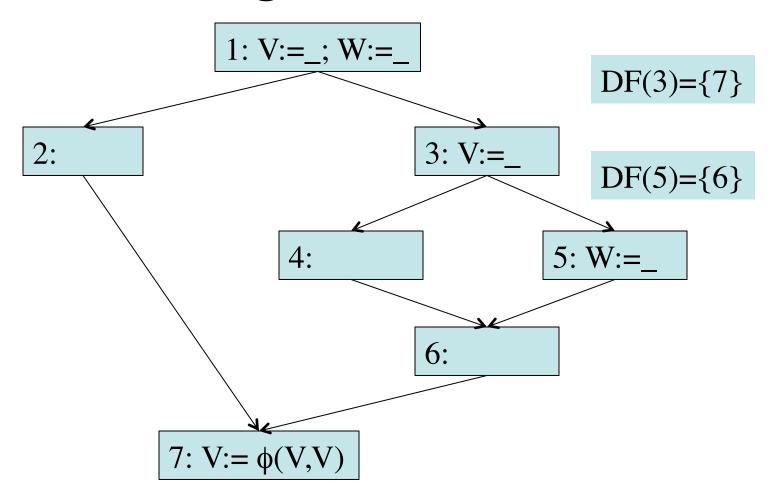
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S := {} // empty set
For each node Y in Successor(X):
  If Y is not immediately dominating X:
    S := S + \{Y\} // \text{ this is Local}(X), + \text{ means union}
For each child K of X in D(X): // X dominates K
  For each element Y in ComputeDF(K):
    If X does not dominate Y,
            S := S + \{Y\} // \text{ this is } Up(X)
DF(X) = S
```

- Dominance Frontier Criterion
 - If node X contains definition of some variable a, then any node Y in the DF(X) needs a ϕ function for a.
- Iterated Dominance Frontier
 - Since a ϕ function is itself a definition of a new variable, we must iterate the DF criterion until no nodes in the CFG need a ϕ function.

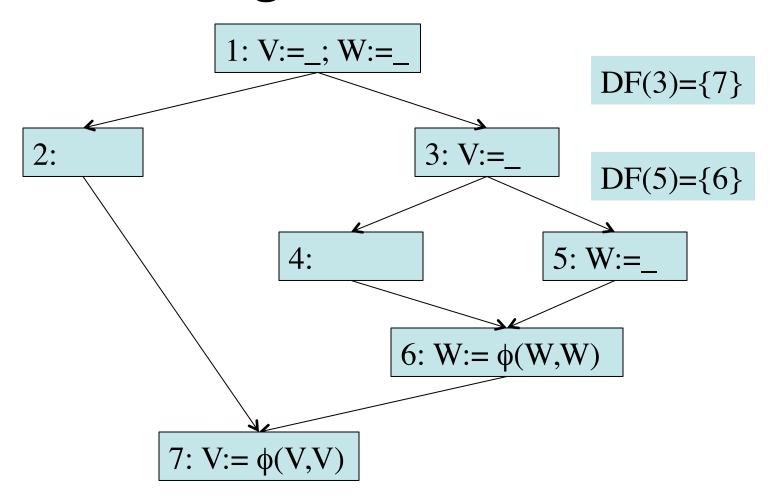
Placing φ Functions



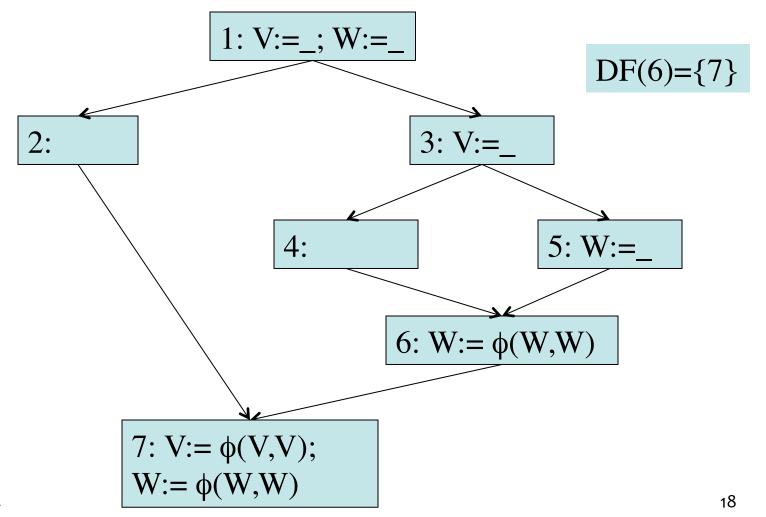
Placing φ Functions



Placing φ Functions



Placing \phi Functions



Rename Variables

