CNN Architectures

CNN Architectures

- AlexNet
- VGG
- GoogleNet
- ResNet

- ImageNet Classification with Deep Convolutional Neural Networks - Alex Krizhevsky, Ilya Sutskever, Geoffrey E. Hinton; 2012
- Facilitated by GPUs, highly optimized convolution implementation and large datasets (ImageNet)
- One of the largest CNNs to date
- Has 60 Million parameter compared to 60k parameter of LeNet-5

Architecture

CONV1

MAX POOL1

NORM1

CONV2

MAX POOL2

NORM2

CONV3

CONV4

CONV5

Max POOL3

FC6

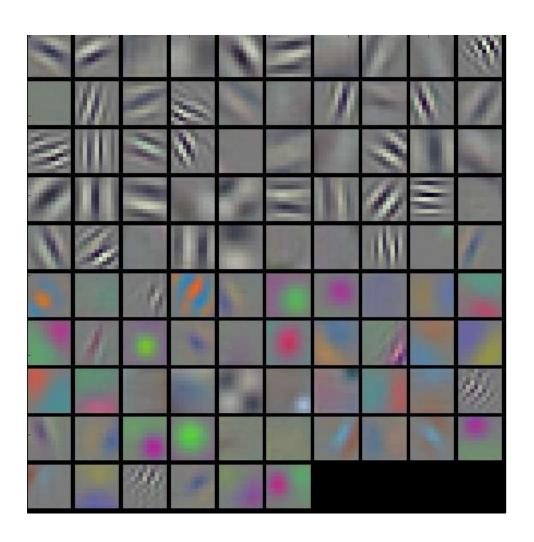
FC7

FC8

AlexNet

- Input: 227x227x3 images (224x224 before padding)
- First layer: 96 11x11 filters applied at stride 4
- Output volume size?

Number of parameters in this layer?



Details/Retrospectives:

- first use of ReLU
- used Norm layers (not common anymore)
- heavy data augmentation
- dropout 0.5
- batch size 128
- 7 CNN ensemble

- Trained on GTX 580 GPU with only 3 GB of memory.
- Network spread across 2 GPUs, half the neurons (feature maps) on each GPU.

- CONV1, CONV2, CONV4, CONV5: Connections only with feature maps on same GPU.
- CONV3, FC6, FC7, FC8:
 Connections with all feature maps in preceding layer,
 communication across GPUs.

VGGNet

- Very Deep Convolutional Networks For Large Scale Image Recognition - Karen Simonyan and Andrew Zisserman; 2015
- The runner-up at the ILSVRC 2014 competition
- Significantly deeper than AlexNet
- 140 million parameters

Input 3x3 conv, 64 3x3 conv, 64 Pool 1/2 3x3 conv, 128 3x3 conv, 128 Pool 1/2 3x3 conv, 256 3x3 conv, 256 Pool 1/2 3x3 conv, 512 3x3 conv, 512 3x3 conv, 512 Pool 1/2 3x3 conv, 512 3x3 conv, 512 3x3 conv, 512 Pool 1/2 FC 4096 FC 4096 FC 1000 Softmax

VGGNet

Smaller filters

Only 3x3 CONV filters, stride 1, pad 1 and 2x2 MAX POOL, stride 2

Deeper network

AlexNet: 8 layers

VGGNet: 16 - 19 layers

ZFNet: 11.7% top 5 error in ILSVRC'13

• VGGNet: 7.3% top 5 error in ILSVRC'14

VGGNet

Why use smaller filters? (3x3 conv)

Stack of three 3x3 conv (stride 1) layers has the same effective receptive field as one 7x7 conv layer.

What is the effective receptive field of three 3x3 conv (stride
 1) layers?

7x7

But deeper, more non-linearities

And fewer parameters: 3 * (3²C²) vs. 7²C² for C channels per layer

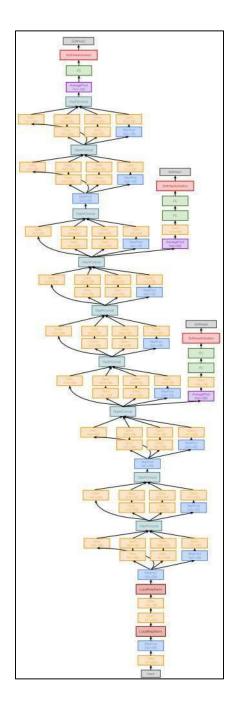
VGGNet

Details/Retrospectives:

- ILSVRC'14 2nd in classification, 1st in localization
- Similar training procedure as AlexNet
- No Local Response Normalisation (LRN)
- Use VGG16 or VGG19 (VGG19 only slightly better, more memory)
- Use ensembles for best results
- FC7 features generalize well to other tasks
- Trained on 4 Nvidia Titan Black GPUs for two to three weeks.

GoogleNet

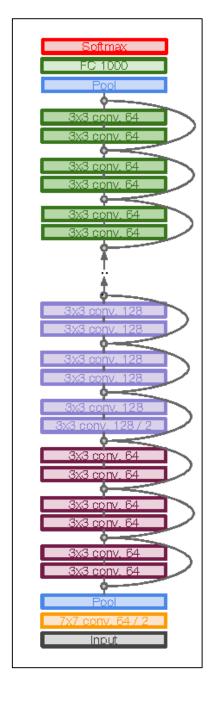
- Going Deeper with Convolutions Christian Szegedy et al.; 2015
- ILSVRC 2014 competition winner
- Also significantly deeper than AlexNet
- x12 less parameters than AlexNet
- Focused on computational efficiency



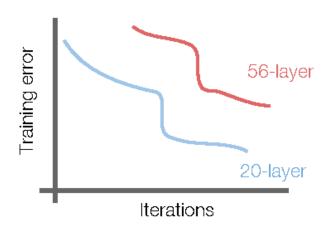
GoogleNet

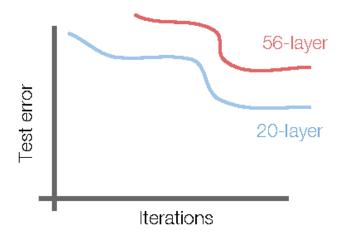
- 22 layers
- Efficient "Inception" module strayed from the general approach of simply stacking conv and pooling layers on top of each other in a sequential structure
- No FC layers
- Only 5 million parameters!
- ILSVRC'14 classification winner (6.7% top 5 error)

- Deep Residual Learning for Image Recognition -Kaiming He, Xiangyu Zhang, Shaoqing Ren, Jian Sun; 2015
- Extremely deep network 152 layers
- Deeper neural networks are more difficult to train.
- Deep networks suffer from vanishing and exploding gradients.
- Present a residual learning framework to ease the training of networks that are substantially deeper than those used previously.



ILSVRC'15 classification winner (3.57% top 5 error, humans generally hover around a 5-10% error rate)
 Swept all classification and detection competitions in ILSVRC'15 and COCO'15!





- What happens when we continue stacking deeper layers on a convolutional neural network?
- 6-layer model performs worse on both training and test error
- -> The deeper model performs worse (not caused by overfitting)!

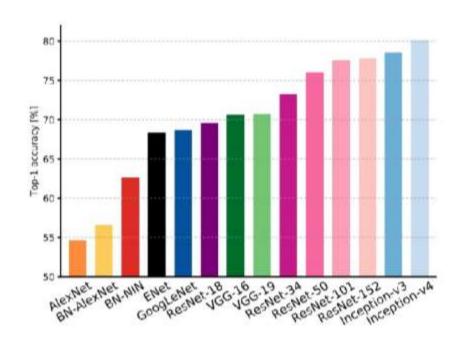
- **Hypothesis**: The problem is an optimization problem. Very deep networks are harder to optimize.
- **Solution**: Use network layers to fit residual mapping instead of directly trying to fit a desired underlying mapping.
- We will use skip connections allowing us to take the activation from one layer and feed it into another layer, much deeper into the network.
- Use layers to fit residual F(x) = H(x) x instead of H(x) directly

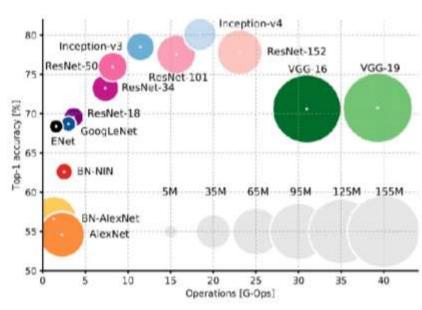
Experimental Results:

- Able to train very deep networks without degrading
- Deeper networks now achieve lower training errors as expected

Accuracy comparison







References

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- CNNs Architectures: LeNet, AlexNet, VGG, GoogLeNet, ResNet and more ... By Siddharth Das https://medium.com/@siddharthdas 32104/cnns-architectures-lenet-alexnet-vgg-googlenet-resnet-and-more-666091488df5
- Slide taken from Forward And Backpropagation in Convolutional Neural Network. –
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