## **Config sample lines from hal file:**

loadrt hostmot2

loadrt hm2 eth board ip="192.168.1.121" config="num encoders=1 num pwmgens=0 num stepgens=3 sserial port 0=21xxxxxx"

## Notes:

board ip="192.168.1.121" The default IP address of the 7i76e

Its suggested to use the 10.10.10.10 IP address for LinuxCNC so you don't end up with the real time Ethernet IP address range, overlapping a DHCP pool of local network addresses.

(set W3 up instead of down to use 10.10.10.10)

num encoders=1 see man hostmot2 for additional details

num\_pwmgens=0 see man hostmot2 for additional details

num\_stepgens=3 see man hostmot2 for additional details

sserial port 0=21xxxxxx The first digit (2) selects the software mode from the 7i76e itself,

The second digit (1) selects the software mode of the connected SSerial device i.e. the 7i73

## 7i76e supports 3 Software modes:

MODE 0 I/O only mode (32 bits of input data, 16 bit of output data)

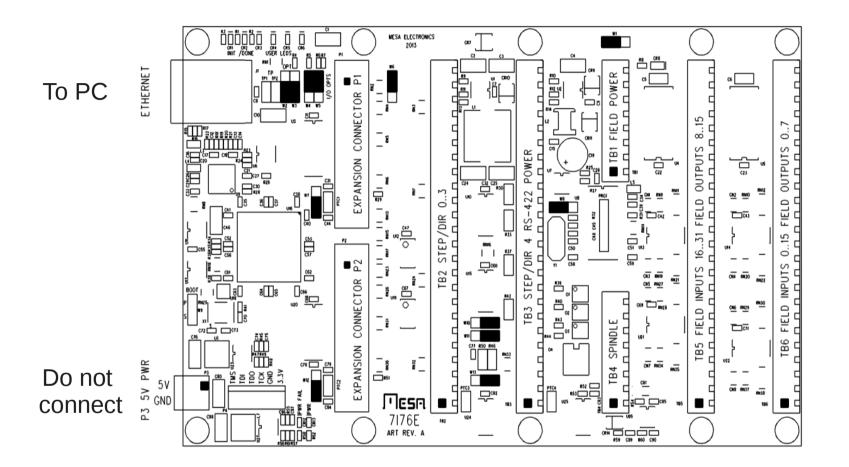
MODE 1 I/O plus analog input mode (32 bits of input data, 16 bits of output data, 4analog input channels)

MODE 2 I/O plus analog input and field voltage and MPG mode

32 bits of input data, 16 bits of output data, 4 analog input channels, field voltage analog in,

and 2 MPG encoders on inputs 16..19.

Default encoder count mode is 1X to match normal 100 ppr MPG's.



W1 : left (default)
W2 : down (default)
W3 : down (default) \*
W4 : up (default)

**Jumpers:** 

W5 : up (default)
W6 : up (default)

W7 : down (default)

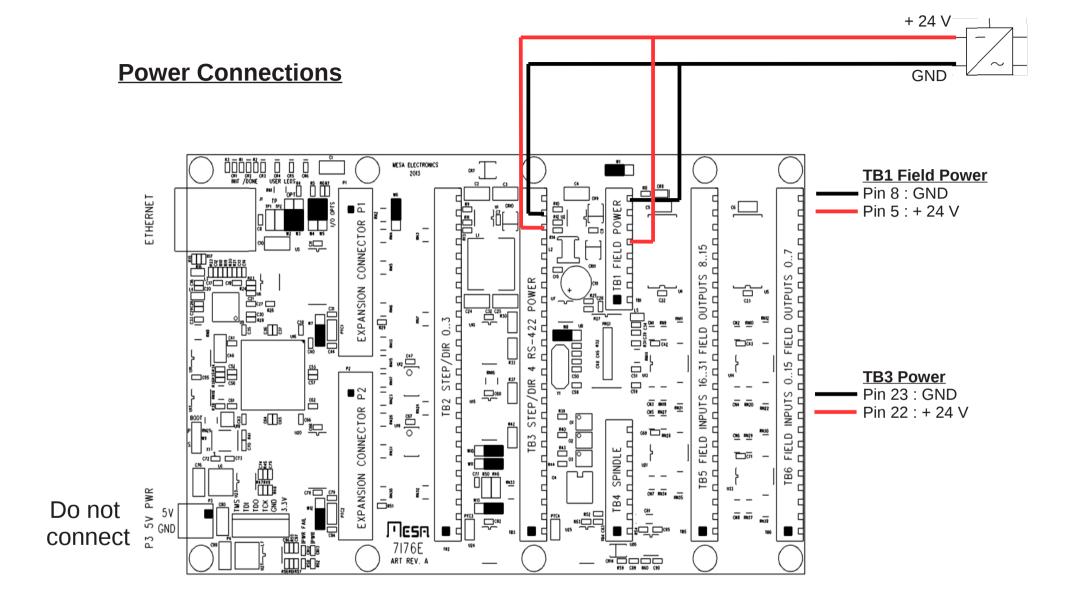
W8 : left (default) W9 : up (default)

W10 : left (default) W11 : left (default)

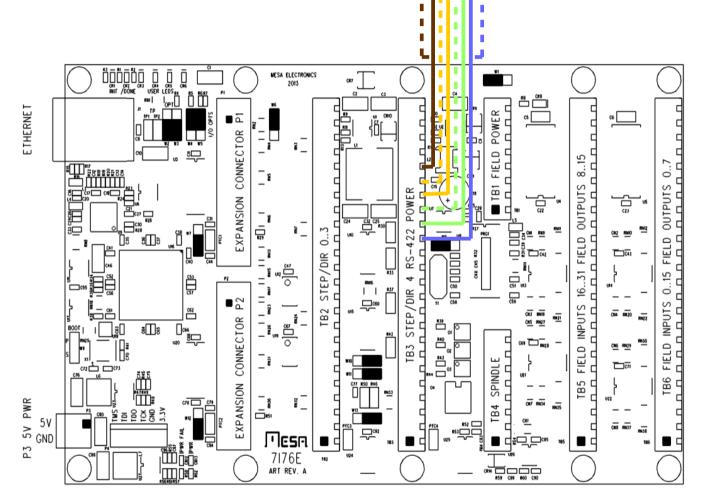
W12 : down (default)

W13 : left (default)

\* Its suggested to use the 10.10.10.10 IP address for LinuxCNC so you don't end up with the real time Ethernet IP address range, overlapping a DHCP pool of local network addresses. (set W3 up instead of down to use 10.10.10.10)



# Connection to SSerial device, i.e. 7i73



## **TB3 SSerial**

Pin 20 : Brown and

Brown/White

Pin 19: Orange/White

Pin 18: Orange

Pin 17 : Green/White

Pin 16 : Green

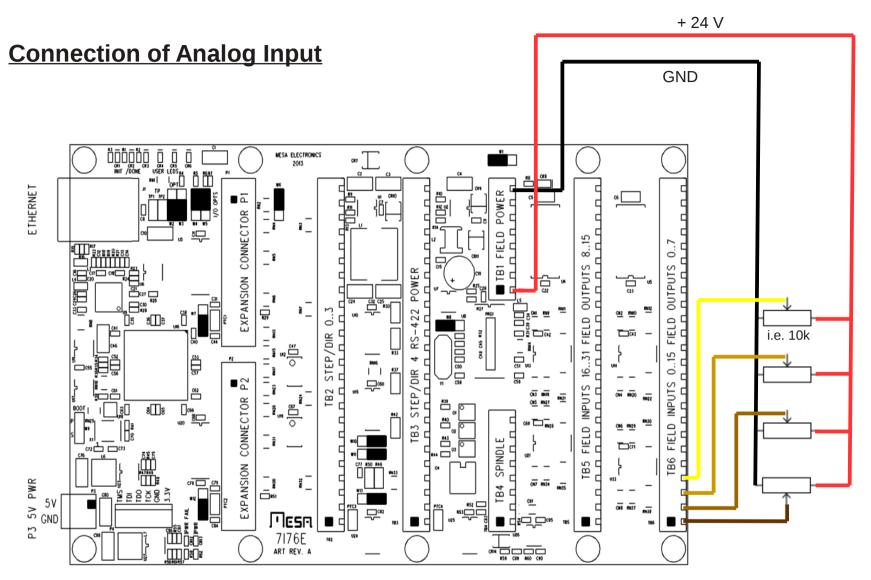
Pin 15 : Blue and

Blue/White

Colors correspond to Standard CAT 5 or CAT 6 network cable If wired according T568B Just cut one end

For details see:

https://en.wikipedia.org/wiki/TIA/EIA-568



**TB1 Field Power** 

Pin 8 : GND Pin 1 : + 24 V You may use also:

Pin 5: + 24 V Pin 4: + 24 V Pin 3: + 24 V Pin 2: + 24 V

as power source or get GND and +24 V directly from the powersupply.

## TB6: Analog in

PIN 4 = hm2\_7i76e.0.7i76.0.0.analogin3
PIN 3 = hm2\_7i76e.0.7i76.0.0.analogin2
PIN 2 = hm2\_7i76e.0.7i76.0.0.analogin1
PIN 1 = hm2\_7i76e.0.7i76.0.0.analogin0

### PIN 16 = hm2 7i76e.0.7i76.0.0.input-15 **TB1 Field Power Connection of Digital Input** PIN 15 = hm2 7i76e.0.7i76.0.0.input-14 Pin 2 · + 24 V PIN 14 = hm2 7i76e.0.7i76.0.0.input-13 PIN 13 = hm2 7i76e.0.7i76.0.0.input-12 You may use: PIN 12 = hm2 7i76e.0.7i76.0.0.input-11 Pin 5: + 24 V PIN 11 = hm2 7i76e.0.7i76.0.0.input-10 + 24 V Pin 4: +24 V PIN 10 = hm2 7i76e.0.7i76.0.0.input-09 Pin 3: +24 V PIN 9 = hm2 7i76e.0.7i76.0.0.input-08 Pin 1: + 24 V PIN 8 = hm2 7i76e.0.7i76.0.0.input-07 PIN 7 = hm2 7i76e.0.7i76.0.0.input-06 as power source or PIN 6 = hm2 7i76e.0.7i76.0.0.input-05 get it directly from PIN 5 = hm2 7i76e.0.7i76.0.0.input-04 the power supply. Do not use MESA ELECTRONICS hm2 7i76e.0.7i76.0.0.input-03 hm2 7i76e.0.7i76.0.0.input-02 ETHERNET hm2 7i76e.0.7i76.0.0.input-01 CONNECTOR hm2 7i76e.0.7i76.0.0.input-00 --FIELD As they are used as analog input 8..15 0..7 \_ £ TB5: Digital in OUTPUTS OUTPUTS EXPANSION PIN 16 = hm2 7i76e.0.7i76.0.0.input-31 - gi PIN 15 = hm2 7i76e.0.7i76.0.0.input-30 FIELD PIN 14 = hm2 7i76e.0.7i76.0.0.input-29 **□**ξ PIN 13 = hm2 7i76e.0.7i76.0.0.input-28 0..15 CSI PIN 12 = hm2 7i76e.0.7i76.0.0.input-27 \_\_\_ PIN 11 = hm2 7i76e.0.7i76.0.0.input-26 INPUTS PIN 10 = hm2 7i76e.0.7i76.0.0.input-25 CONNECTOR ≨∭% PIN 9 = hm2 7i76e.0.7i76.0.0.input-24 PIN 8 = hm2 7i76e.0.7i76.0.0.input-23 SPINDLE PIN 7 = hm2 7i76e.0.7i76.0.0.input-22 = hm2 7i76e.0.7i76.0.0.input-21 EXPANSION Switches PIN 5 - KW3 = hm2 7i76e.0.7i76.0.0.input-20 5V PWR TB4 i.e. limit Do not use Mesal X,Y,Zhm2 7i76e.0.7i76.0.0.input-19 7176E hm2 7i76e.0.7i76.0.0.input-18 ART REV. A hm2 7i76e.0.7i76.0.0.input-17 hm2 7i76e.0.7i76.0.0.input-16 As they are used as MPG input

TB6: Digital in

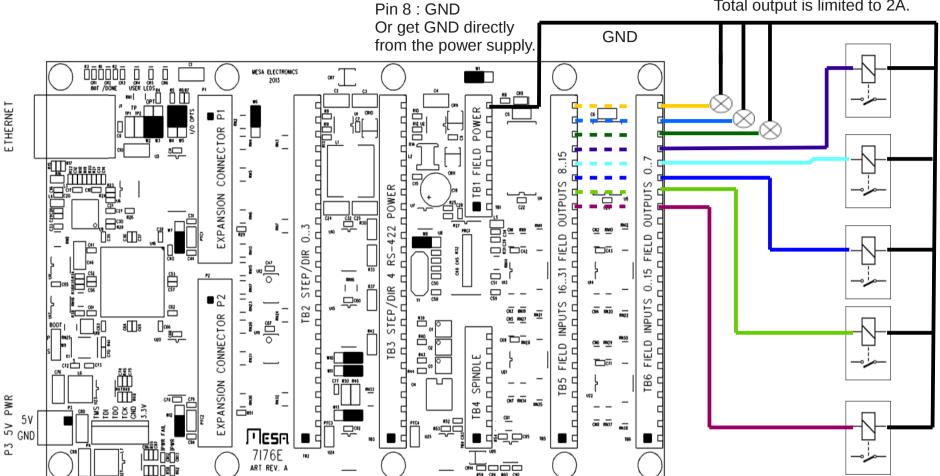
TB5: Digital in **Connection of TB1 Field Power** PIN Names see previous page Pin 2: + 24 V inductive proximity sensors TB6: Digital in You may use: PIN Names see previous page Pin 5: + 24 V Pin 4: + 24 V + 24 V Pin 3: + 24 V Pin 1: + 24 V NO as power source or NPN NC get it directly from the power supply. **GND** MESA ELECTRONICS ETHERNET CONNECTOR 8..15 0..7 OUTPUTS **OUTPUTS** EXPANSION NO **PNP** NC FIELD 0..15 CS1 V \_\_\_\_ css INPUTS CONNECTOR **∄**∭% FIELD SPINDLE **TB**6 **EXPANSION** - m 5V PWR Mesn P3 2 k / 1W 7176E ART REV. A Pull up needed only for NPN Better use PNP!

# **Connection of Digital Output**

## **TB1 Field Power**

Maximum output load per pin is 350 mA Total output is limited to 2A.

Important note:

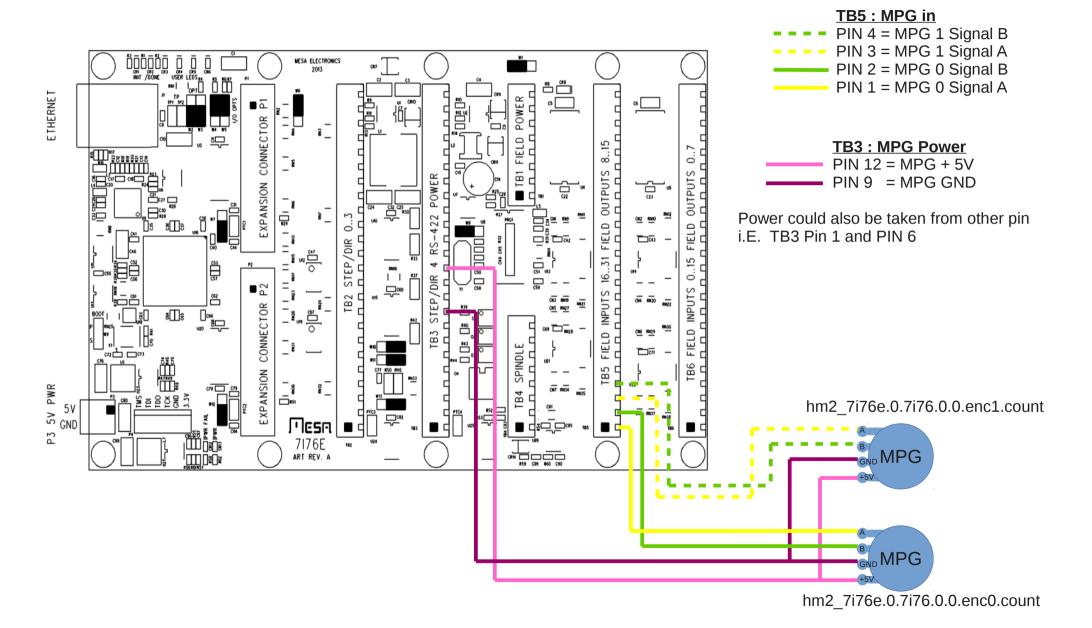


# TB5 : Digital out PIN 24 = hm2\_7i76e.0.7i76.0.0.output-15 PIN 23 = hm2\_7i76e.0.7i76.0.0.output-14 PIN 22 = hm2\_7i76e.0.7i76.0.0.output-13 PIN 21 = hm2\_7i76e.0.7i76.0.0.output-12 PIN 20 = hm2\_7i76e.0.7i76.0.0.output-11 PIN 19 = hm2\_7i76e.0.7i76.0.0.output-10 PIN 18 = hm2\_7i76e.0.7i76.0.0.output-09 PIN 17 = hm2\_7i76e.0.7i76.0.0.output-08

## TB6: Digital out

PIN 24 = hm2\_7i76e.0.7i76.0.0.output-07 PIN 23 = hm2\_7i76e.0.7i76.0.0.output-06 PIN 22 = hm2\_7i76e.0.7i76.0.0.output-05 PIN 21 = hm2\_7i76e.0.7i76.0.0.output-04 PIN 20 = hm2\_7i76e.0.7i76.0.0.output-03 PIN 19 = hm2\_7i76e.0.7i76.0.0.output-02 PIN 18 = hm2\_7i76e.0.7i76.0.0.output-01 PIN 17 = hm2\_7i76e.0.7i76.0.0.output-00

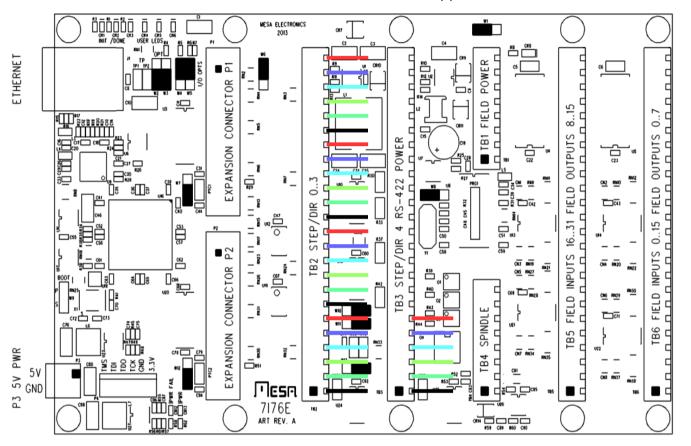
# **Connection of MPG's**



# **Connection of Steppers**

## Note:

Not used pins can not be used as IO Pin, even if not all stepper are used



## hm2 7i76e.0.stepgen.00.step type

Type 0	Type2	
+ 5 V	+ 5 V	Sets the type to be used:
DIR +	Α	Type 0 = step/dir
DIR -	A-	Type $1 = up/down$
STEP +	В	Type $2 = quadratur A/B$
STEP -	B-	Type 3 = Three phase full step
GND	GND	Etc.

See "man stepgen" for all details

# TB2: Stepper in PIN 24 = +5V

: Stepper 3 PIN 23 = DIR+ : Stepper 3 PIN 22 = DIR-: Stepper 3 PIN 21 = STEP+ : Stepper 3 PIN 20 = STEP -: Stepper 3 PIN 19 = GND : Stepper 3

PIN 18 = + 5V : Stepper 2 PIN 17 = DIR+ : Stepper 2 : Stepper 2 PIN 16 = DIR-PIN 15 = STEP+ : Stepper 2 PIN 14 = STEP -: Stepper 2 PIN 13 = GND : Stepper 2

PIN 12 = + 5V : Stepper 1 PIN 11 = DIR+ : Stepper 1 PIN 10 = DIR-: Stepper 1 PIN 9 = STEP+ : Stepper 1 : Stepper 1 PIN 8 = STEP -PIN 7 = GND : Stepper 1

PIN 6 = +5V: Stepper 0 PIN 5 = DIR +: Stepper 0 PIN 4 = DIR-: Stepper 0 PIN 3 = STEP+ : Stepper 0 PIN 2 = STEP -: Stepper 0 PIN 1 = GND : Stepper 0

## TB3: Stepper in

0

PIN 6 = +5V: Stepper 4 PIN 5 = DIR +: Stepper 4 : Stepper 4 PIN 4 = DIR-PIN 3 = STEP+ : Stepper 4 PIN 2 = STEP -: Stepper 4 PIN 1 = GND : Stepper 4

