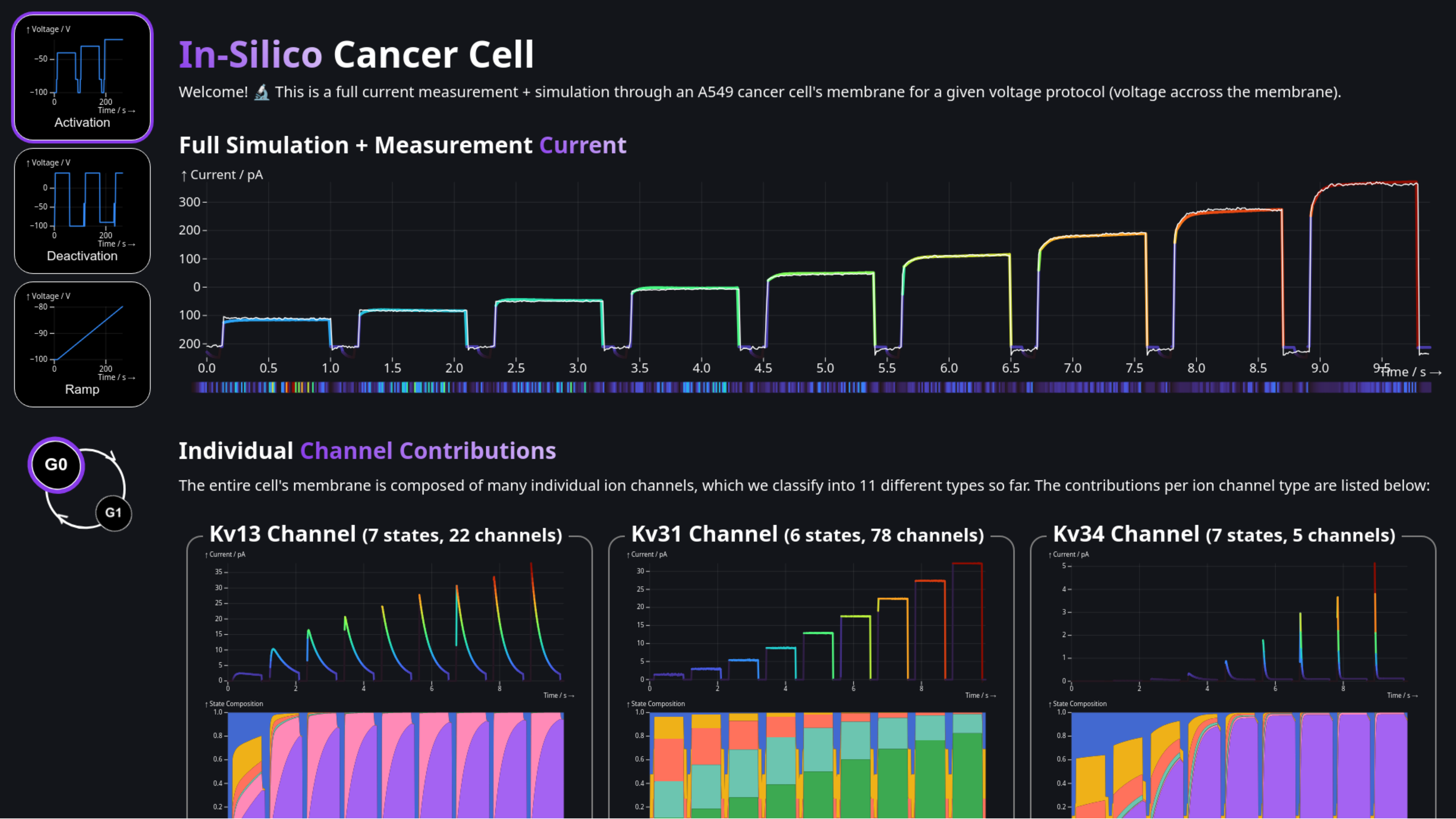


Live, In-Browser Cell Simulation Interface

Good stuff



Available live on in-silico.hce.tugraz.at.

Model

$$I(t) := \sum_{k=1}^M N_k I_k(t) = \sum_{k=1}^M N_k g_k p_{o,k} (V(t) - E_k) , \tag{1}$$

At each time step,

$$\boldsymbol{s}_{k,n+1} = H_k(V(t_n), \boldsymbol{C}(t_n), t_n) \boldsymbol{s}_{k,n} \tag{2}$$

Formulation as a Quadratic Program

Relaxing the integer condition on the solution, and letting $\boldsymbol{d} := \boldsymbol{I}_{\text{meas}}$ for brevity, we can reformulate ??,

$$\boldsymbol{N}_{\text{opt}} \approx \arg \min_{\boldsymbol{x} \in \mathbb{R}_+^M} f(\boldsymbol{x}) = \arg \min_{\boldsymbol{x} \in \mathbb{R}_+^M} \frac{1}{2} \|R\boldsymbol{x} - \boldsymbol{d}\|_2^2 ,$$

with cost function $f : \mathbb{R}^M \rightarrow \mathbb{R}^+$, which we manipulate to

$$\begin{aligned} f(\boldsymbol{x}) &= \frac{1}{2} (R\boldsymbol{x} - \boldsymbol{d})^T (R\boldsymbol{x} - \boldsymbol{d}) \\ &= \frac{1}{2} (\boldsymbol{x}^T R^T R \boldsymbol{x} - \boldsymbol{x}^T R^T \boldsymbol{d} - \boldsymbol{d}^T R \boldsymbol{x} + \boldsymbol{d}^T \boldsymbol{d}) \\ &= \frac{1}{2} (\boldsymbol{x}^T P \boldsymbol{x} + \boldsymbol{x}^T \boldsymbol{q} + \boldsymbol{q}^T \boldsymbol{x}) + \mathcal{O}(1) \\ &= \frac{1}{2} \boldsymbol{x}^T P \boldsymbol{x} + \boldsymbol{q}^T \boldsymbol{x} + \mathcal{O}(1) \end{aligned}$$

where we let $P := R^T R \in \mathbb{R}^{M \times M}$ and $\boldsymbol{q} := -R^T \boldsymbol{d} \in \mathbb{R}^M$ and leave out the constant $\boldsymbol{d}^T \boldsymbol{d}$ as $\mathcal{O}(1)$. We can express the nonnegativity constraint $\boldsymbol{x} \geq \mathbf{0}$ as an equality constraint using a slack variable $\boldsymbol{s} \in \mathbb{R}_+^M$,

$$-\boldsymbol{x} + \boldsymbol{s} = \mathbf{0} \quad \Leftrightarrow \quad A\boldsymbol{x} + \boldsymbol{s} = \boldsymbol{b} ,$$

where we set $A := -\mathbf{1} \in \mathbb{R}^{M \times M}$ and $\boldsymbol{b} := \mathbf{0} \in \mathbb{R}^M$. This leaves us with a constrained quadratic program,

$$\min_{\boldsymbol{x} \in \mathbb{R}_+^M} \frac{1}{2} \boldsymbol{x}^T P \boldsymbol{x} + \boldsymbol{q}^T \boldsymbol{x} , \tag{3}$$

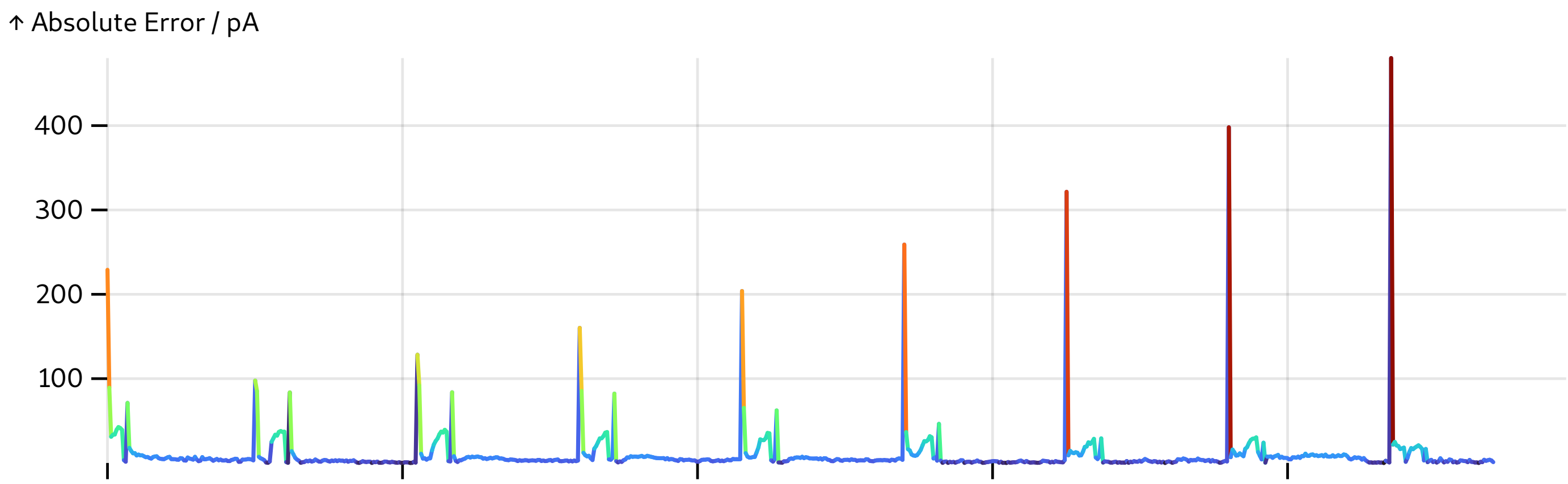
$$\text{s.t. } A\boldsymbol{x} + \boldsymbol{s} = \boldsymbol{b} , \boldsymbol{s} \in \mathbb{R}_+^M . \tag{4}$$

We solve the quadratic problem in this exact form using Clarabel [1]. Note that in Clarabel notation, the slack variable is to be taken as an element of the nonnegativity cone.

The integer solution can then be obtained from rounding,

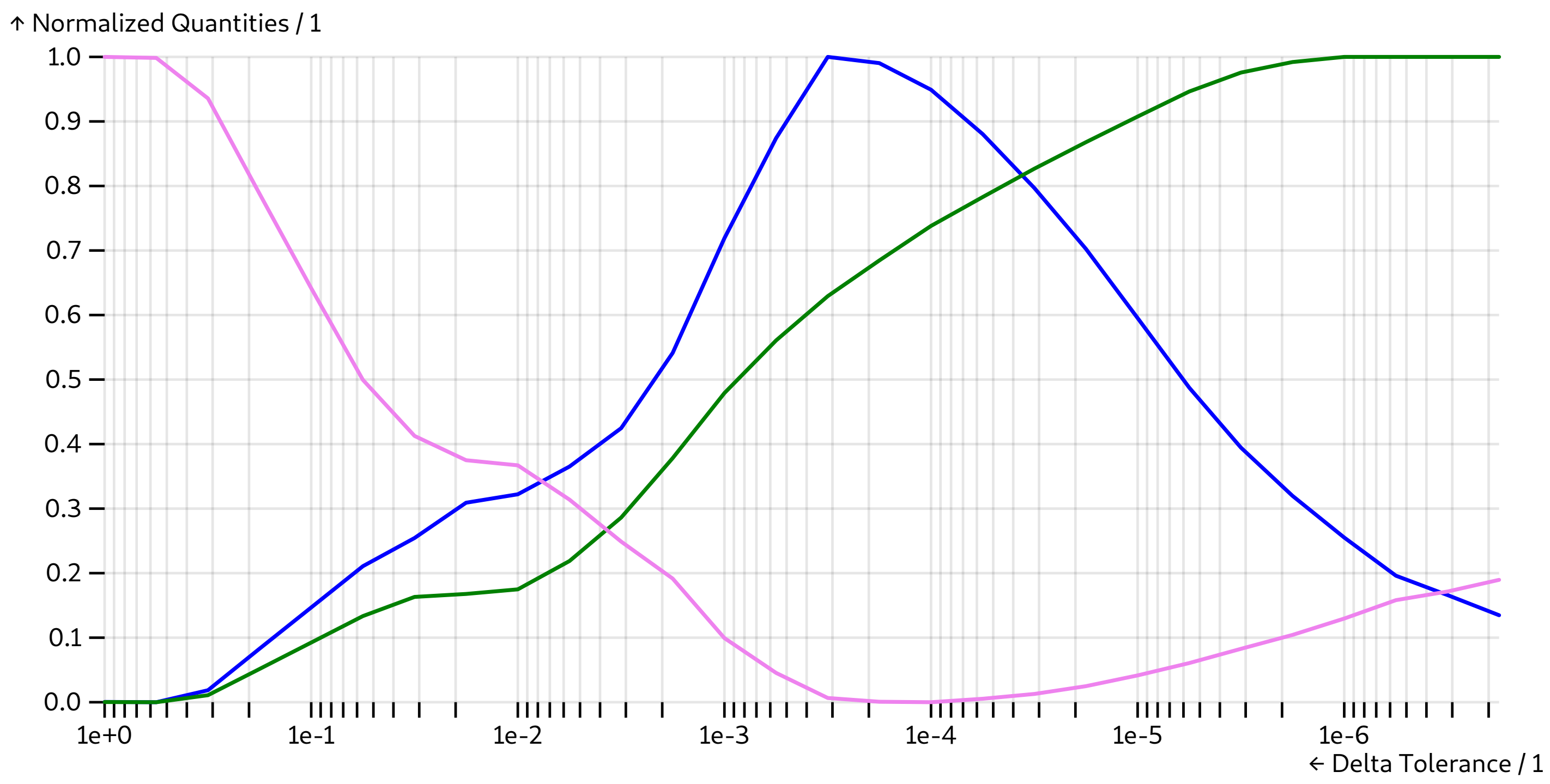
$$\boldsymbol{N}_{\text{opt}} = \lfloor \boldsymbol{x} \rfloor \in \mathbb{N}_0^M .$$

Pointwise Error between Simulation and Measurements



Adaptive Timestepping

$$(\Delta t)_{n+1} = (\Delta t)_n \left(\frac{\Delta^{\text{tol}}}{\sum_{k=1}^M N_k \|\boldsymbol{s}_{k,n+1} - \boldsymbol{s}_{k,n}\|_2} \right)^{1/2} , \tag{5}$$



Comparison of Optimization Methods

Algorithm	Abbreviation	Runtime / ms	RMSE / pA
Particle Swarm Optimization	PSO	22571	27.69
Gradient Descent + More Thuente	GD	18924	32.34
Limited-Memory BFGS + Hager Zhang	LBFGS	4845	32.20
Non-Negative Least Squares [2]	NNLS	318	28.00
Quadratic Program	QP	18	28.13