

Schuljahr: 2012 / 2013

Name: Andreas Gruber
5BHDK
grubi@edumail.at

Projekttitel: High Level Movement Control for Autonomous Vehicle

Betreuer: Peter Bauer

Auftraggeber: Roland Richter
Johannes Kepler Universität
Department of Knowledge-Based Mathematical Systems

Ziel: The main goal of this thesis is to build a system which calculates the most accurate current position of a model car based on a set of different (cheap) sensors.

Bedarf: Software: Visual Studio, Visual Micro, Arduino Libraries
Hardware: Arduino Board, Sensors, Car

Bearbeiter

Betreuungslehrer

Abteilungsvorstand

Landesschulinspektor

Datum