

# Computer Graphics

From mathematics ...



$$S = \{\mathbf{p} \in \mathbf{R}^3, f(\mathbf{p}) = 0\}$$

$$\mathbf{n} = -\nabla f(\mathbf{p}) / |\nabla f(\mathbf{p})|$$

... to the screen

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# Computer Graphics

Core  
Modeling  
**Ray Tracing**  
Meshing

# Computer Graphics

## Introduction

# Introduction

Introduction

Ray marching

Sphere tracing

## Visualization

$$S = \{\mathbf{p} \in \mathbf{R}^3 | f(\mathbf{p}) = 0\}$$

**Polygonization** [Araujo2015] converts model to **large** meshes

Direct **ray tracing** remains computationally **intensive**

**Parallel** implementation partially alleviate the problem



Ladybug  
© Inigo Quilez

# Computer Graphics

## Ray marching

# Ray marching

Introduction

Ray marching

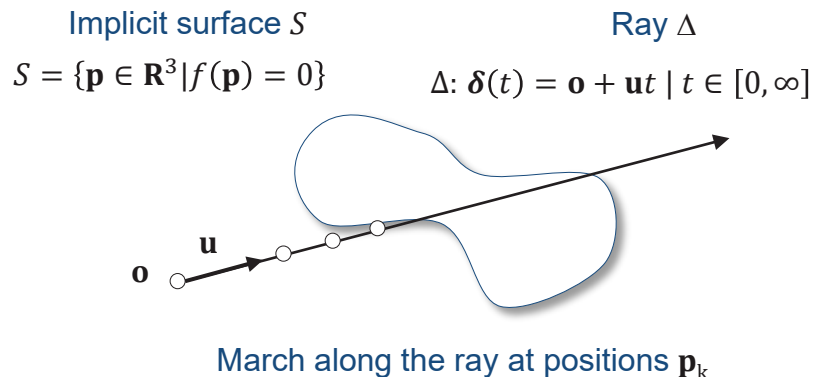
Sphere tracing

## Algorithm

General but **slow** technique [Perlin1989]

**No assumptions** about the mathematical properties of  $f$

Adapted for computing the intersection with fractal objects



## Ray marching

**General** algorithm that steps and evaluates  $f$  at points  $\mathbf{p}$  along the ray

Computationally **intensive** with **fixed step** [Perlin1989]

**Robust** Lipschitz techniques with **global** constants [Kalra1989]

K. Perlin, E. Hoffert. Hypertexture. *ACM SIGGRAPH Computer Graphics*, 23(3), 1989.

D. Kalra, H. Barr. Guaranteed Ray Intersections with Implicit Surfaces. *ACM SIGGRAPH Computer Graphics*, 23(3), 1989.



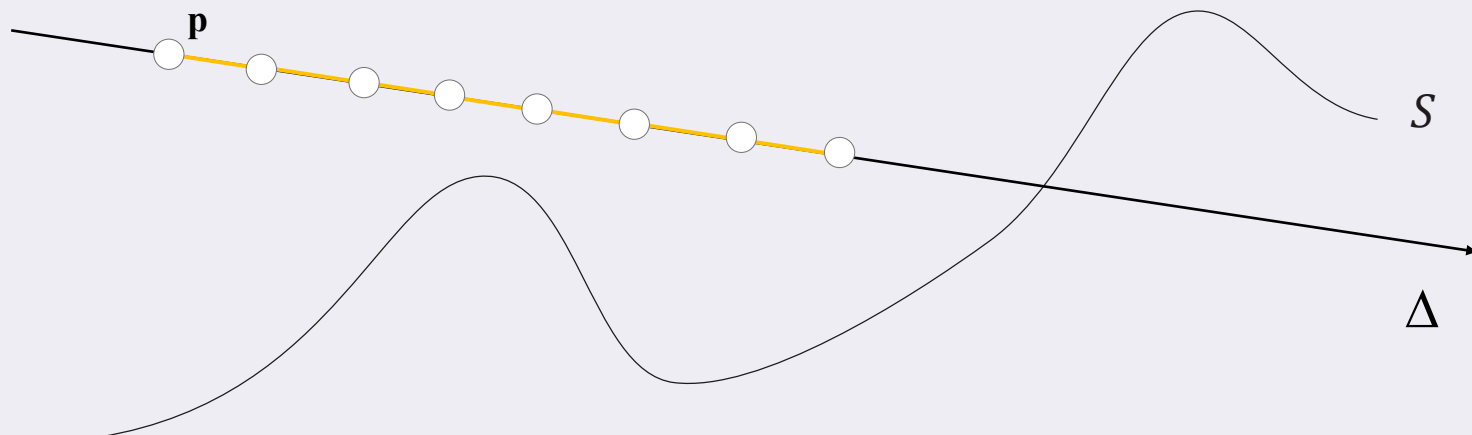
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# Ray marching: visual interpretation

Introduction

Ray marching

Sphere tracing



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# Computer Graphics

## Sphere tracing



# Sphere Tracing

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## Lipschitz functions

$$\exists \lambda > 0 \quad \forall (\mathbf{p}, \mathbf{q}) \in \mathbf{R}^3 \times \mathbf{R}^3 \quad |f(\mathbf{p}) - f(\mathbf{q})| \leq \lambda |\mathbf{p} - \mathbf{q}|$$

**Exclusion criterion:**  $|f(\mathbf{p})| / \lambda$  is a signed distance bound to  $S$

$$\forall \mathbf{p} \in \mathbf{R}^3 \quad B(\mathbf{p}, |f(\mathbf{p}) / \lambda|) \cap S = \emptyset$$

Global bound  $\lambda$  over  $\mathbf{R}^3$

## Sphere Tracing [Hart1996]

Start from ray origin  $\mathbf{p} = \mathbf{o}$

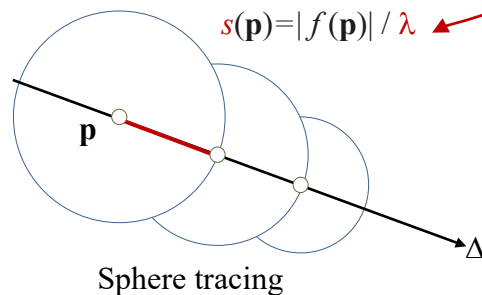
At every step  $i$

If  $f(\mathbf{p}_i) < 0$  then

Intersection found

Otherwise step forward

$$s(\mathbf{p}_i) = |f(\mathbf{p}_i)| / \lambda$$



Sphere Tracing [Hart1989, Hart1996, Keinert2014] **adapts** step with **global** constants

J. Hart. Sphere Tracing: A Geometric Method for the Antialiased Ray Tracing of Implicit Surfaces. *The Visual Computer* 12(10), 527-545, 1996,

# Sphere Tracing: visual interpretation

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