

## 2.13 Toerentalvariatie

### 2.13.0 Algemeen

$$n_r = n_s \cdot (1 - s)$$

$$n_r = \frac{60 \cdot f_s}{p} \cdot (1 - s)$$

① var  $n_s$  



②  $n_s$  const. 



→  $R_1$   $R_2$

$$\rightarrow M_i \sim U_i^2$$

$$\rightarrow S.M.$$

## 2.13 Toerentalvariatie

### 2.13.1 Poolomschakelbare motoren

→  $\#p_2$  variabel

Meervoudige statorwikkelingen

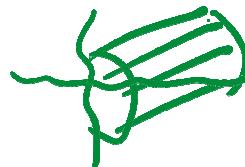
2, 3, ...

Dahlandermotor

A

$$\#p_s \equiv \#p_r$$

VAR



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Rotor → Kooi ROTOR

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### 2.13.1 Poolomschakelbare motoren

#### 2.13.1.1 Meervoudige statorwikkelingen

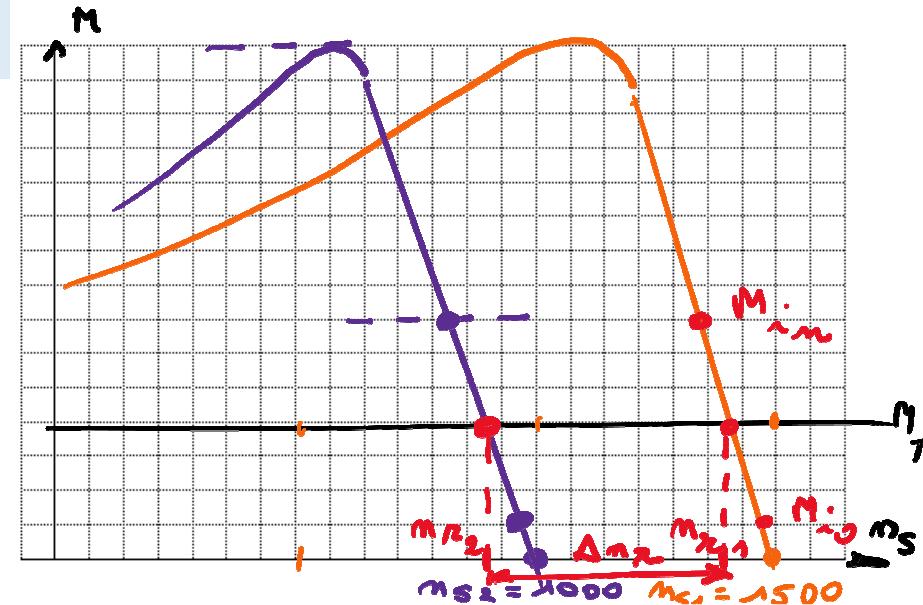
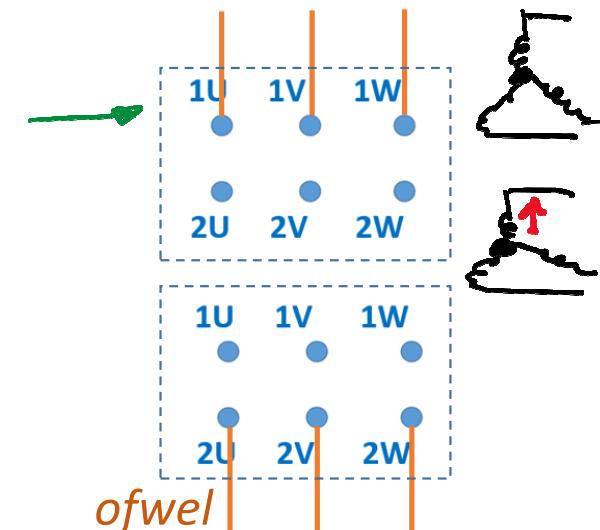
→  $\Delta n_r$

2p	2	4	6	8	10	12 ...
p	1	2	3	4	5	6 ...
t/min	$n_s$					
	3000 1500 1000 750 600 500					

$n_s$  ≠ factor 2

b.v.  $\tau = 2 \rightarrow n_{s_1}$   
 $\tau = 3 \rightarrow n_{s_2}$

$M_{ik_1} \approx M_{ik_2}$   
 $M_{im_1} \approx M_{im_2}$



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### 2.13.1 Poolomschakelbare motoren

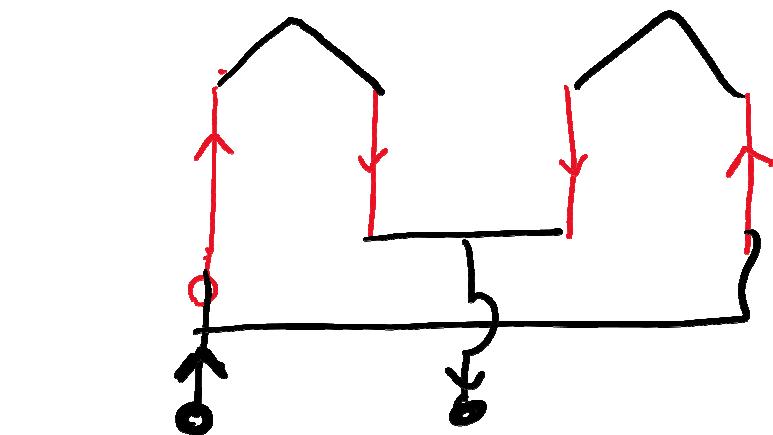
#### 2.13.1.2 Dahlandermotor

↳ exact factor 2 in  $n_s$

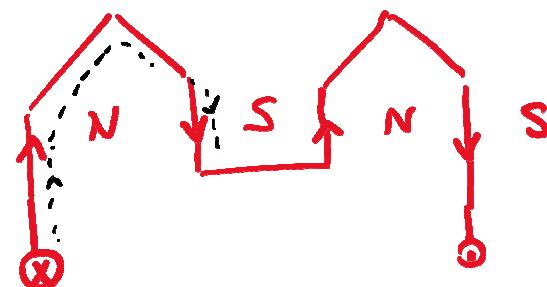
$$\text{d.w. } p = 1$$

$$p = 2$$

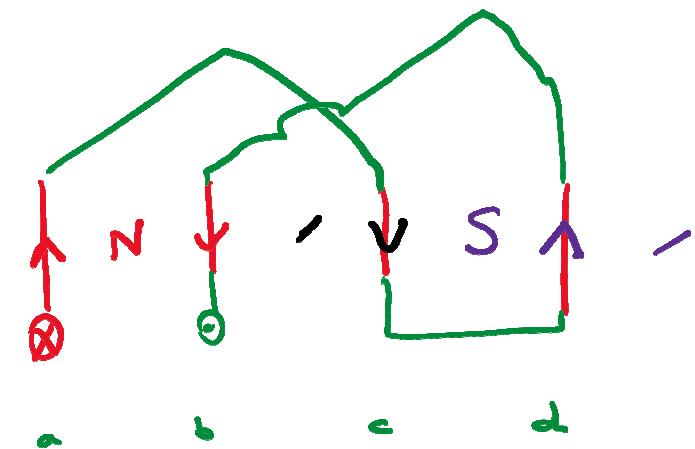
$p = 2$  4 polig draaiveld ( $p \cdot 2^1$ )



$\rightarrow p=1$  2 polig draaiveld



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### 2.13.1 Poolomschakelbare motoren

#### 2.13.1.2 Dahlandermotor

De constructie DM : dezelfde als de driefasige ASM met kooianker.

Het verschil

- elk van de drie statorwikkelingen is verdeeld in twee gelijke helften.
- poolparen met verhoudingen 4:2, 8:4 of 12:6.
- De poolomschakeling resp. snelheidswijziging met een factor twee
- Bij het grootste aantal polen - de **laagste snelheid** - wordt de motor in **driehoekschakeling** aangesloten. De wikkellingshelften zijn in serie geschakeld.
- Bij het laagst aantal polen - de **hoogste snelheid** - wordt de motor in **dubbelsterschakeling** aangesloten. De wikkellingshelften zijn in parallel geschakeld.

$$\begin{array}{l} n = 2 \longrightarrow 1500 \\ n = 1 \longrightarrow 3000 \end{array}$$

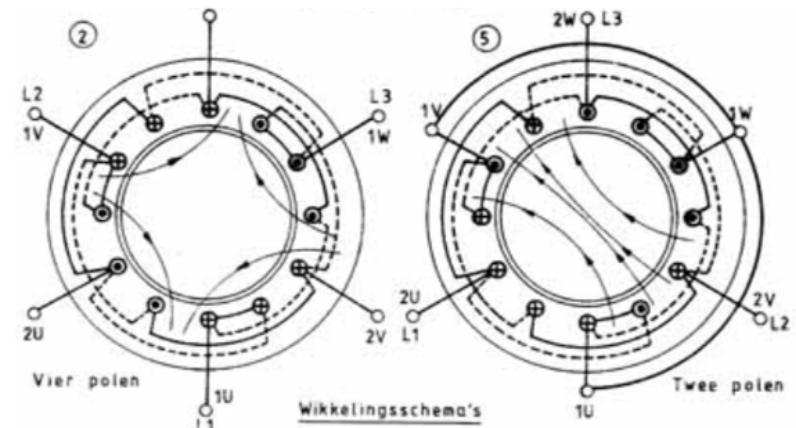
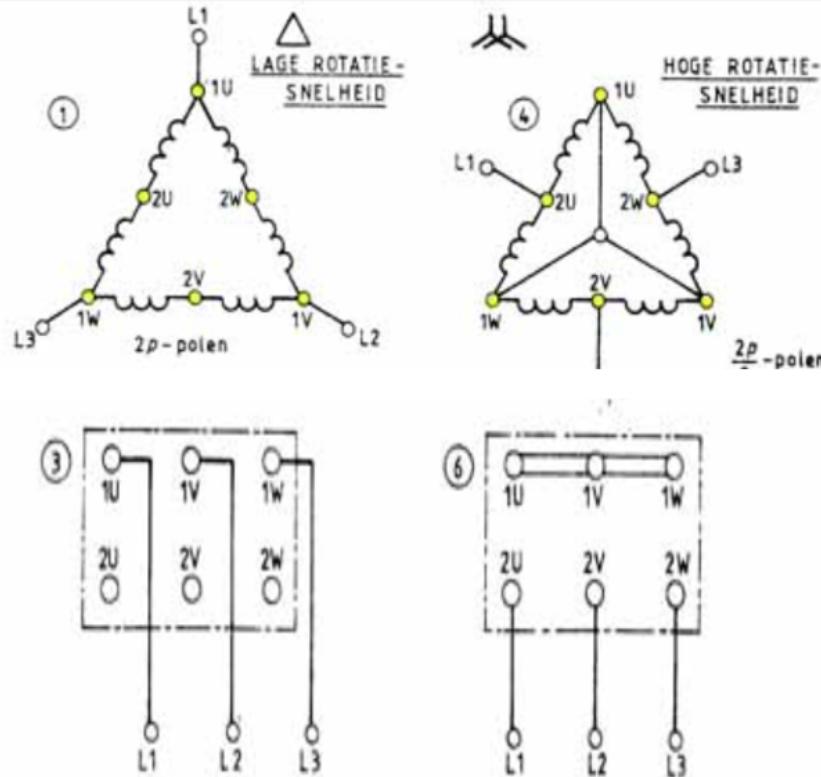
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### 2.13.1 Poolomschakelbare motoren

#### 2.13.1.2 Dahlandermotor



Rob. Dahlander,  
Fotograaf.

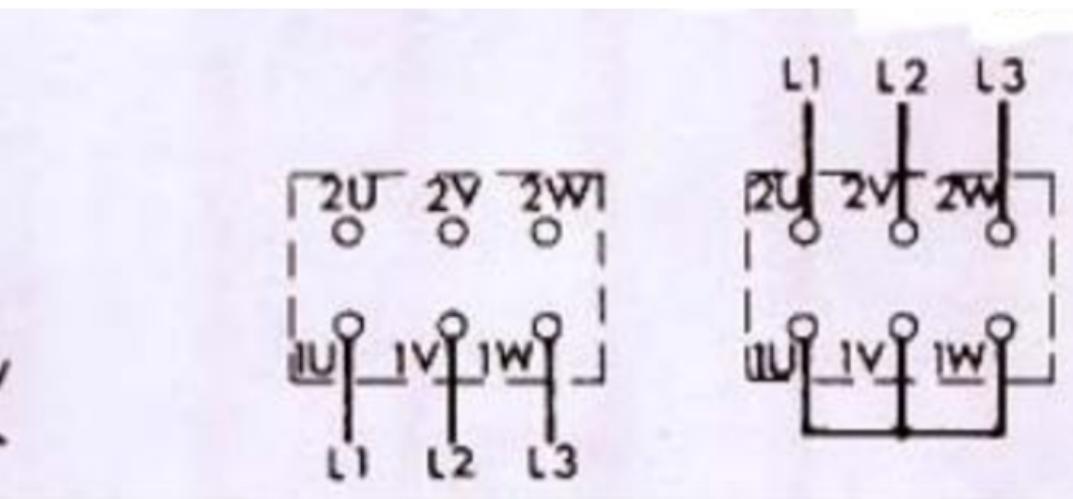
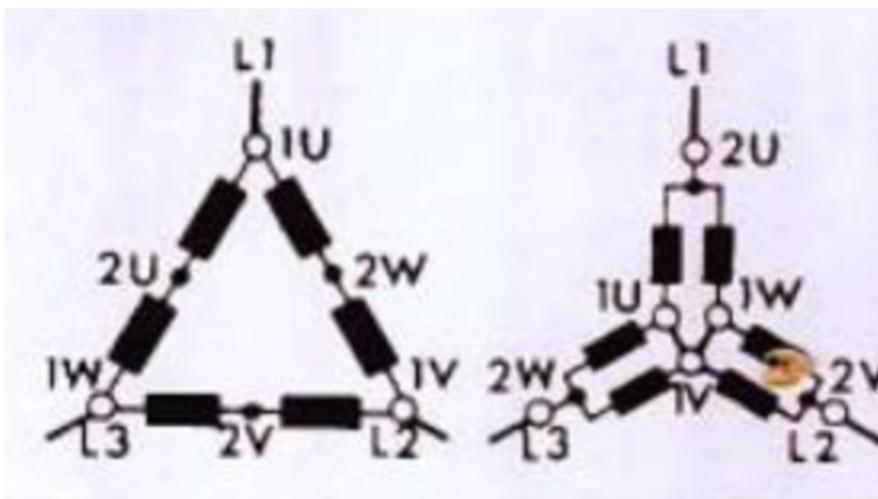


# THREE-PHASE ASYNCHRONOUS MOTOR, DAHLANDER, 0.3KW

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### 2.13.1 Poolomschakelbare motoren

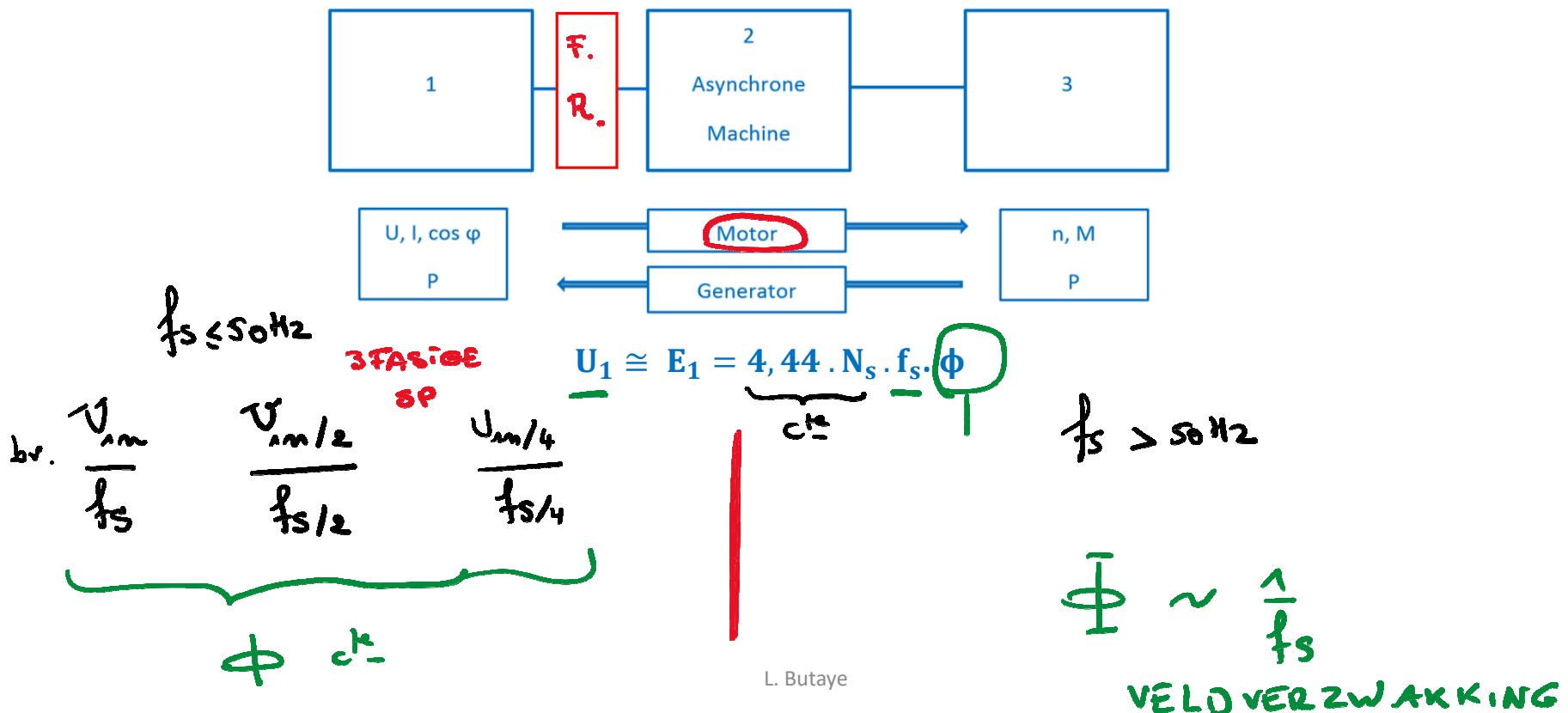
#### 2.13.1.2 Dahlandermotor



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## 2.13 Toerentalvariatie

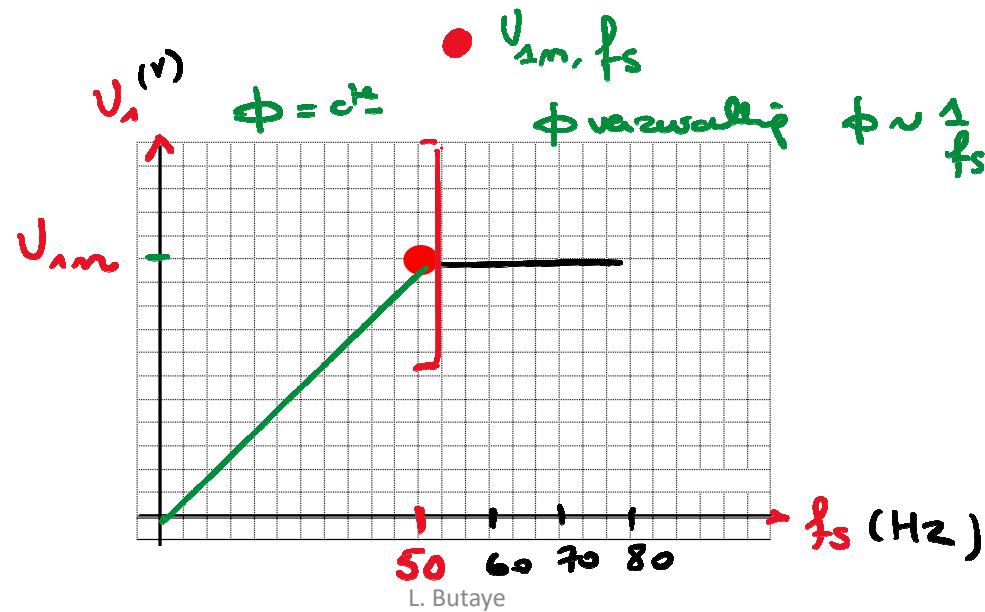
### 2.13.2 Frequentieregeling



## 2.13 Toerentalvariatie

### 2.13.2 Frequentieregeling

$$U_1 \cong E_1 = 4,44 \cdot N_s \cdot f_s \cdot \Phi$$



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### 2.13.2 Frequentieregeling

Nominaal inwendig koppel  $M_{in}$

$$M_{in} = k \cdot \Phi \cdot I_{2n}$$

nominaal belast

$$f_s \leq 50 \text{ Hz} \longrightarrow \Phi = c \frac{k}{f_s} \longrightarrow M_{in} = k \Phi \cdot I_{2n} = c \frac{k^2}{f_s}$$

$$f_s > 50 \text{ Hz} \longrightarrow \Phi \sim \frac{1}{f_s} \longrightarrow n_{in} \sim \frac{1}{f_s}$$

## 2.13 Toerentalvariatie

$$M_k = \pm \frac{(3)}{\omega_s} \cdot \frac{U_1^2}{(k^2)} \cdot \frac{1}{(2)X_{2,ST}}$$

### 2.13.2 Frequentieregeling

Kipkoppel  $M_{ik}$

$$\textcircled{1} \quad f_s \leq 50\text{Hz} \quad \rightarrow \quad \frac{U_1}{f_s} = c^k \quad \rightarrow \quad M_k \sim \frac{U_1^2}{\omega_s \cdot \omega_s(L_2)} \sim \frac{U_1^2}{f_s^2} \quad \omega_s = \frac{2\pi f_s}{r}$$

$$M_k = c^k$$

$$\textcircled{2} \quad f_s > 50\text{Hz} \quad \frac{U_{1m}}{f_s} \quad \rightarrow \quad M_k \sim \frac{U_1^2}{f_s^2} = \frac{U_{1m}^2}{f_s^2} \quad \text{VAST} \quad \rightarrow \quad M_k \sim \frac{1}{f_s^2}$$

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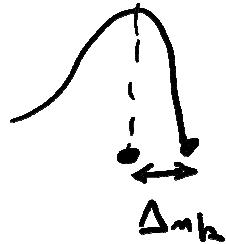
### 2.13.2 Frequentieregeling

Synchroon toerental  $n_s$

$$n_s = \frac{60 f_s}{\pi}$$

$$n_s = f(f_s) \\ \text{Lin}$$

$$\Delta n_k = n_s - n_k = n_s - \left( n_s \left( 1 - \frac{s}{k} \right) \right)$$



$$= n_s \cdot s_k$$

$\frac{\partial n}{\partial k}$   
onafh. freq.

$$= \frac{60 f_s}{\pi} \cdot \frac{R_2}{X_{2ST}} = \frac{60 f_s}{\pi} \cdot \frac{R_2}{\frac{2\pi f_s}{\pi} L_2} = \frac{60 R_2}{2\pi^2 f_s L_2}$$

$P = 1$

$$n_{S_1} = 3000 \text{ tpm} \quad 50 \text{ Hz}$$

$$n_{S_2} = 2400 \text{ tpm} \quad 60 \text{ Hz}$$

$$n_{S_3} = 1800 \text{ tpm} \quad 30 \text{ Hz}$$

$$n_{S_4} = 1200 \text{ tpm} \quad 20 \text{ Hz}$$

$$n_{S_4} = 600 \text{ tpm} \quad \sim 12 \text{ Hz}$$

ONAFK  
FREQ

