

## RTA Application Note

### How to import an LDF file

*RTA-CAR*

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## 1 Introduction

### 1.1 Scope

This application note shows how to create a Lin node importing the relative LDF file. In this example, the Lin node will be imported in an existing ECU with CAN node already configured.

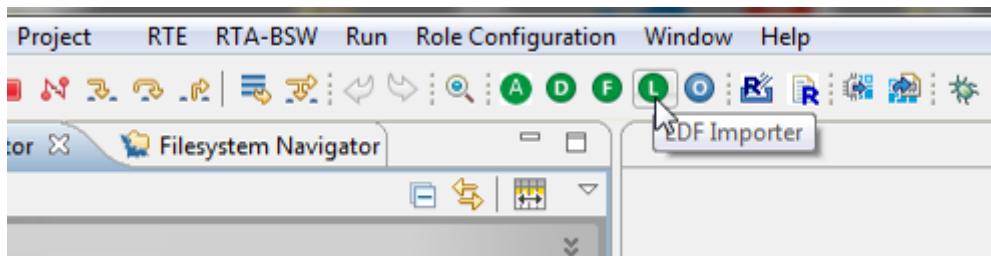
### 1.2 Preconditions

- ECU name in LDF is matching with the existing ECU in the System
- BSW makes use of the RTA-BSW configurator generator
- RTE, BSW and OS are generating with no issue

### 1.3 Import LDF in ISOLAR-AN-000

#### 1.3.1 LDF Importer

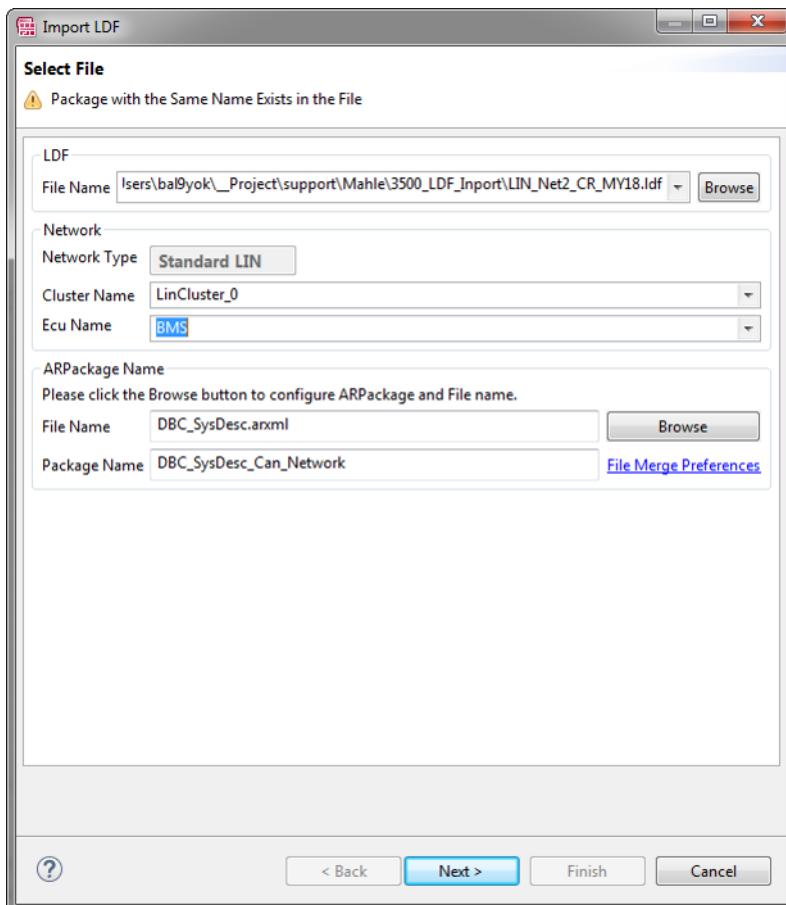
Select LDF import feature from ISOLAR-A



Select the LDF file from your file system. Select the ECU name (even if it's already selected, open the Ecu name menu and select the ECU to activate the merge option):

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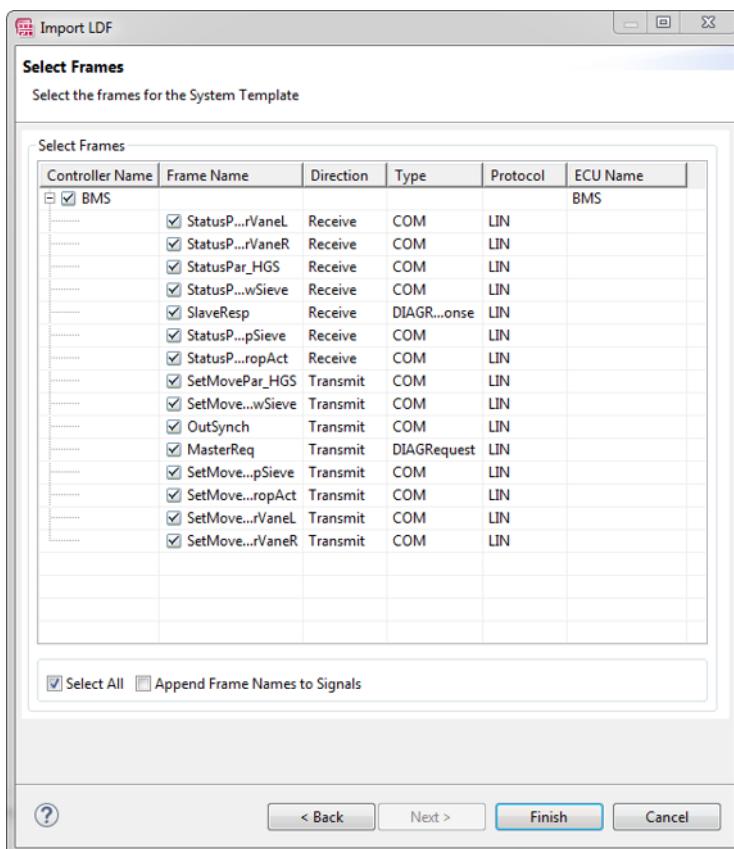
In File Merge Preferences selected the wanted merge option.

### 1.3.2 Select ECU and Frames

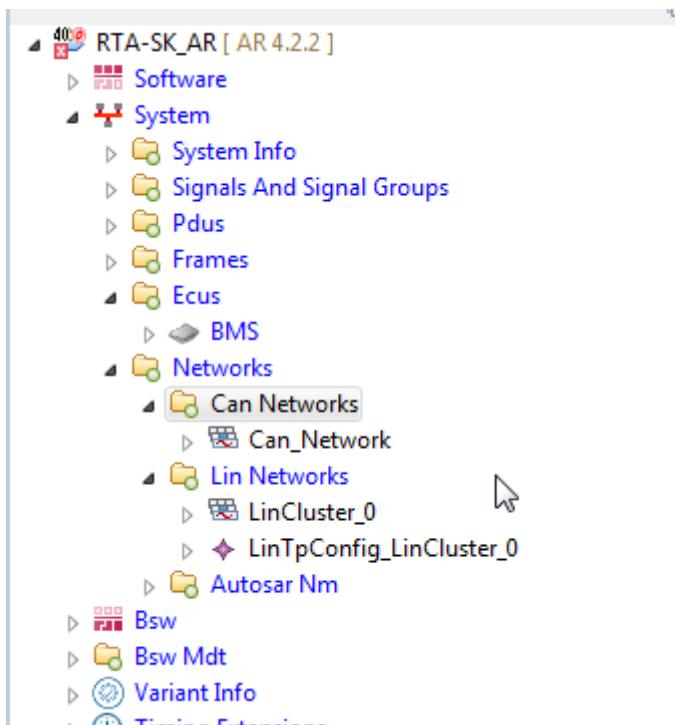
In the next window select the required Master ECU, and then the Lin frames:

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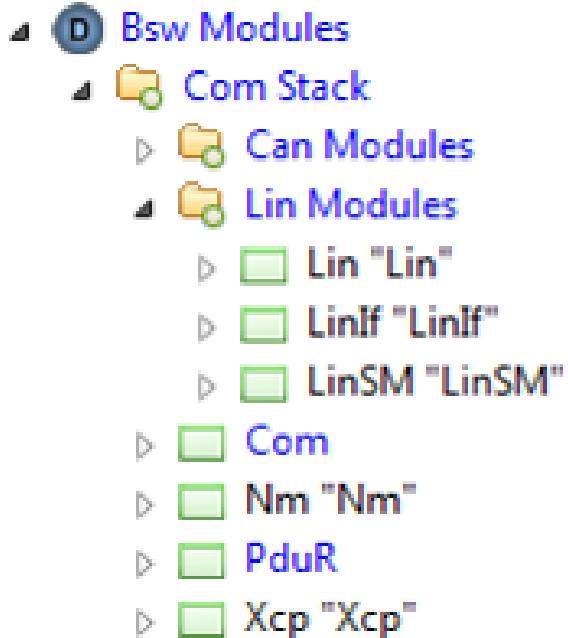


As result of the import, ISOLAR-A will create PDU, Frames and Signals. It will also create a new Lin network:



### 1.3.3 BSW Configuration

It is now possible to generate the BSW configuration RTA-BSW will create the configuration for the new modules LinIf and LinSM:



The following actions needs to be added to the initialization of the ECU to complete the BSW integration:

1. Initialize LinIf
2. Initialize LinSM
3. ComM allow communication on Lin channel
4. ComM set FULL\_COMM for Lin channel
5. Lin Schedule tables shall be activated

All these action can be implemented by BswM adding them in the BswMActions and BswMActionLists.

**NB:** Point 1 to 4 are same as any ComM channel (e.g. CAN nodes), while point 5 is dedicated for Lin channels.

The following pictures show a sample configuration:

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The screenshot shows the ETAS RTA application interface. At the top, there is a tree view of BswMActions [30]. Several actions are highlighted with green boxes, including BswM\_AI\_LinIfInit, BswM\_AI\_LinSMinit, BswM\_AI\_CanSMinit, BswM\_AI\_CanInit, BswM\_AI\_PduRInit, BswM\_AI\_RteStop, BswM\_AI\_RteTimerStart, BswM\_AI\_ComMDelInit, BswM\_AI\_LinRequestSchedule, and BswMAvailableActions "BswMAvailableActions". Below this, there are two detailed tables for BswActionListItems.

	BswActionListItem	BswAbortOn...	BswActionL...	BswActionListItemRef*
1	BswM_AI_RteTimerStart			BswM_AI_RteTimerStart
2	BswM_AI_BswMSwitchStartupTwo			BswM_AI_BswMSwitchStartupTwo
3	BswM_AI_LinInit			BswM_AI_LinInit
4	BswM_AI_CanInit			BswM_AI_CanInit
5	BswM_AI_LinRInit			BswM_AI_LinRInit
6	BswM_AI_CanRInit			BswM_AI_CanRInit
7	BswM_AI_LinSMinit			BswM_AI_LinSMinit
8	BswM_AI_CanSMinit			BswM_AI_CanSMinit
9	BswM_AI_PduRInit			BswM_AI_PduRInit
10	BswM_AI_RteStop			BswM_AI_RteStop
11	BswM_AI_ComMDelInit			BswM_AI_ComMDelInit
bulk				

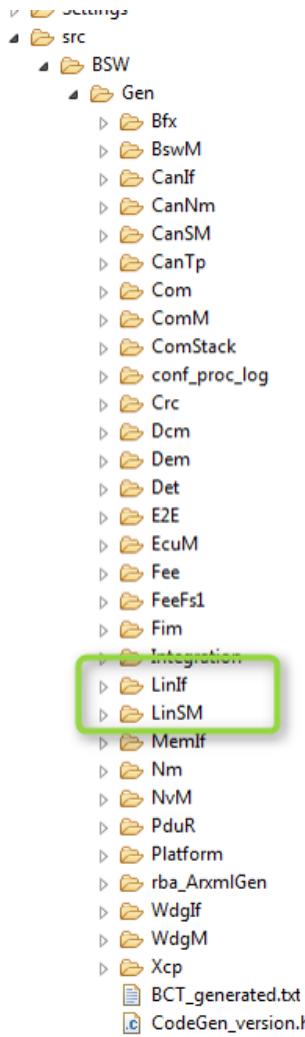
	BswActionListItem	BswAbortOn...	BswActionL...	BswActionListItemRef*
1	BswM_AL_StartPdu			BswM_AL_StartPdu
2	BswM_AL_AllowCom...			BswM_AL_AllowCom...
3	BswM_AL_AllowCom...			BswM_AL_AllowCom...
4	BswM_AL_RequestC...			BswM_AL_RequestC...
5	BswM_AL_RequestC...			BswM_AL_RequestC...
6	BswM_AL_BswMapp...			BswM_AL_BswMapp...
7				
bulk				

### 1.3.4 BSW Code generation

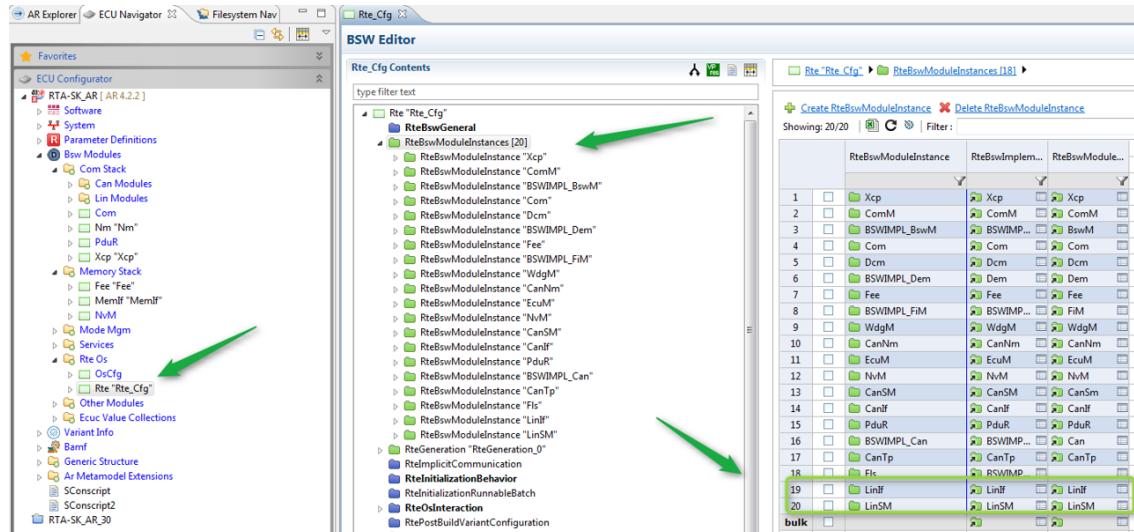
It's now possible to generate the BSW code. RTA-BSW will update the COM stack modules with the new configuration and will create the LinIf and LinSM source code:

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**1.3.5 RTE integration**

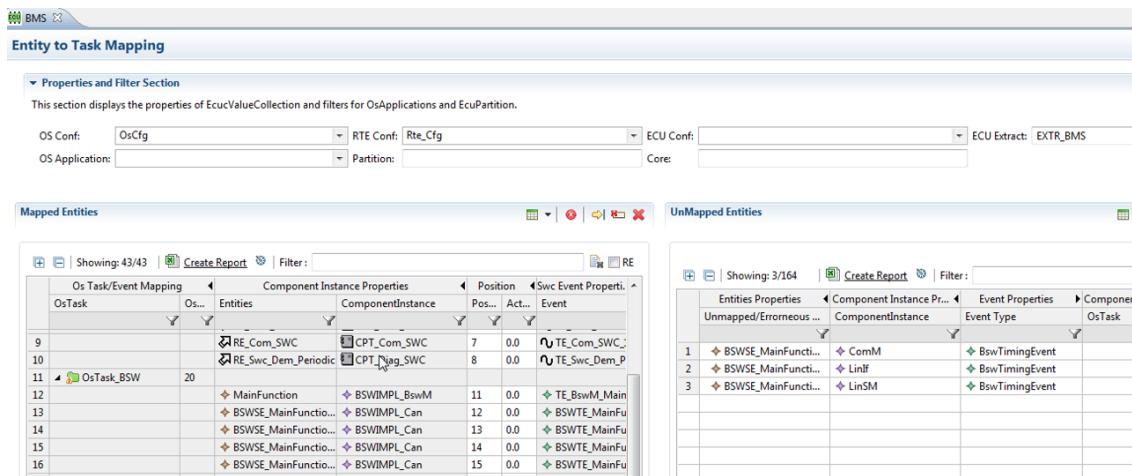
From ECU Configurator open the Rte modules and add the LinSM and LinIf module instance. This step is BSW module equivalent of adding a SWC to the Composition



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Now in the RTE Editor, Entity to Task Mapping window, map the LinIf, LinSM and the new ComM MainFunction to a task



Then generate the RTE.

### 1.3.6 MCAL Integration

Lin driver shall be configured in the MCAL generation tool. The driver configuration does not contains information about frames (which means that frames does not have to be aligned) but it contains Channel configuration that shall be aligned to the BSW configuration. RTA-BSW generates a Lin configuration, but is limited to the LinChannels, this configuration can be imported into MCAL, but the driver will require additional configuration which are not dependent by the BSW. After the Lin has been configured and generated, it may requires to be integrated in the system for:

- MainFunciton: scheduled by task
- Init: invoked by EcuM in the InitList

### 1.3.7 Update build environment

When all the new module have been generated, is time to update the build environment to add this module to the building list. During the phase some integration files may required adaption to integrate the BSW with the MCAL.

## 2 **Contact, Support and Problem Reporting**

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