base\_link Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1576294533.816 (0.037 sec old) Buffer length: 4.800 sec link1 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1576294533.816 ( 0.037 sec old) Buffer length: 4.800 sec link2 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1576294533.816 (0.037 sec old) Buffer length: 4.800 sec link3 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1576294533.816 ( 0.037 sec old) Buffer length: 4.800 sec link4 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1576294533.816 ( 0.037 sec old) Buffer length: 4.800 sec link5 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1576294533.816 (0.037 sec old) Buffer length: 4.800 sec link6 Broadcaster: /robot\_state\_publisher Average rate: 10.209 Hz Most recent transform: 1576294533.816 ( 0.037 sec old) Buffer length: 4.800 sec link7 Broadcaster: /dummy\_handeye Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1576294533.853 sec old) Buffer length: 0.000 sec camera\_color\_optical\_frame Broadcaster: /camera\_color\_optical2camera\_link\_broadcaster Broadcaster: /aruco\_tracker Average rate: 2.173 Hz Average rate: 98.853 Hz Most recent transform: 1576294533.848 ( 0.005 sec old) Most recent transform: 1576294533.861 ( -0.008 sec old) Buffer length: 4.601 sec Buffer length: 4.937 sec camera\_link camera\_marker Broadcaster: /camera/realsense2\_camera\_manager Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1576294533.853 sec old) Buffer length: 0.000 sec camera\_color\_frame

view\_frames Result

Recorded at time: 1576294533.853