base_link Broadcaster: /robot_state_publisher Average rate: 33.666 Hz Most recent transform: 1564315303.236 (0.016 sec old) Buffer length: 4.960 sec link1 Broadcaster: /robot_state_publisher Average rate: 33.666 Hz Most recent transform: 1564315303.236 (0.016 sec old) Buffer length: 4.960 sec link2 Broadcaster: /robot_state_publisher Average rate: 33.666 Hz Most recent transform: 1564315303.236 (0.016 sec old) Buffer length: 4.960 sec link3 Broadcaster: /robot_state_publisher Average rate: 33.666 Hz Most recent transform: 1564315303.236 (0.016 sec old) Buffer length: 4.960 sec link4 Broadcaster: /robot_state_publisher Average rate: 33.666 Hz Most recent transform: 1564315303.236 (0.016 sec old) Buffer length: 4.960 sec link5 Broadcaster: /robot_state_publisher Average rate: 33.666 Hz Most recent transform: 1564315303.236 (0.016 sec old) Buffer length: 4.960 sec link6 Broadcaster: /robot_state_publisher Average rate: 33.666 Hz Most recent transform: 1564315303.236 (0.016 sec old) Buffer length: 4.960 sec link7 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1564315303.252 sec old) Buffer length: 0.000 sec gripper Broadcaster: /camera2effector_broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (1564315303.252 sec old) Buffer length: 0.000 sec camera_color_optical_frame Broadcaster: /camera_color_optical2camera_link_broadcaster Average rate: 10.192 Hz Most recent transform: 1564315303.284 (-0.032 sec old) Buffer length: 4.906 sec camera_link Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1564315303.252 sec old) Most recent transform: 0.000 (1564315303.252 sec old) Most recent transform: 0.000 (1564315303.252 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera_color_frame camera_depth_frame camera_aligned_depth_to_color_frame Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Most recent transform: 0.000 (1564315303.252 sec old) Buffer length: 0.000 sec camera_depth_optical_frame

view_frames Result

Recorded at time: 1564315303.252