# Yuhang Zheng

School of Mechanical Engineering and Automation, Beihang University, Beijing

■ +86 188-1313-7601 | Zhengyh021@gmail.com | MrSecant.github.io | Digithub.com/MrSecant

# **Education**

Beihang University

Beijing, China

Academic Master in Mechanical Engineering | Advisor: **Prof. Meiqing Wang** 

Sept 2022 - Jun 2025

• GPA: 3.80 / 4

· Thesis Title: An Automatic Parsing Method of Multi-modal Welding Process Files Based on Deep Learning.

Beihang University

Beijing, China

Bachelor in Mechanical Engineering (National First-class Discipline Program)

Sept 2018 - Jun 2022

• GPA: 3.64 / 4

• Thesis Title: An Automatic Extraction Method of Welding Process Elements Based on Chinese Named Entity Recognition.

#### **Awards**

Awards during Undergraduate and Graduate Studies

- National Scholarship (top 2%), 2024.
- Outstanding Postgraduate Student Award, Beihang University, 2024.
- "Alumnus of Beihang University" Scholarship, Beihang University, 2023.
- Outstanding Graduate Award, Beihang University, 2022.
- First Prize of the Chinese Mathematics Competitions for Undergraduates, Chinese Mathematical Society, 2021.

# Research Interest

My **long-term research goal** is to build agents that efficiently understand the physical world. These agents will then apply their knowledge to interact with the physical world, fostering adaptability and enabling continuous skill acquisition.

**Computer Vision** 3D scene understanding; Monocular geometry estimation; 3D Reconstruction.

**Robotics** Language-guided manipulation, 3D Representation for Robotics.

# Research Experience

# **ECE, Hong Kong University of Science and Technology**

Beijing, China

Research Intern @ <u>UST.ECE</u> | Advisor: **Dr. Xiaoxiao Long** and **Prof. Ping Tan** 

Apr 2024 - Current

• **Topic:** Monocular geometry estimation; Robotic manipulation.

EncoSmart Company Beijing, China

Research Intern @ EncoSmart | Advisor: Dr. Xiaoxiao Long and Dr. Chao Yang

Jan 2024 - Current

• **Topic:** Language-guided grasping; 3D Reconstruction.

AIR, Tsinghua University

Beijing, China

Research Intern @ DISCOVER Lab | Collaborator: Dr. Xiaoxiao Long and Dr. Chao Yang

Aug 2021 - Jan 2024

• **Topic:** 3D scene understanding; Robotic manipulation; Autonomous driving; Mechanical structure design.

# SMEA, Beihang University

Beijing, China

Research Intern @ Robotics Institute | Advisor: Prof. Huichao Deng and Prof. Wei Wang

• Topic: Micro flapping-wing aircraft; Dental implant robot; Mechanical structure design.

Sept 2020 - Dec 2021

# **Publications**.

(\* denotes equal contribution; † denotes corresponding author.)

JOURNAL ARTICLES

# GaussianGrasper: 3D Language Gaussian Splatting for Open-vocabulary Robotic Grasping

**Yuhang Zheng**, Xiangyu Chen, Yupeng Zheng, Songen Gu, Runyi Yang, Bu Jin, Pengfei Li, Chengliang Zhong, Zengmao Wang, Lina Liu, Chao Yang, Dawei Wang, Zhen Chen, Xiaoxiao Long†, Meiqing Wang† **RA-L**. 2024

#### Adaptive Surface Normal Constraint for Geometric Estimation from Monocular Images

Xiaoxiao Long\*, **Yuhang Zheng\***, Yupeng Zheng, Beiwen Tian, Cheng Lin, Lingjie Liu, Hao Zhao†, Guyue Zhou, Wenping Wang†

IEEE TPAMI, 2024

# **ECT: Fine-grained Edge Detection with Learned Cause Tokens**

Shaocong Xu, Xiaoxue Chen, **Yuhang Zheng**, Guyue Zhou, Yurong Chen, Hongbin Zha, Hao Zhao† *Image and Vision Computing*, 2024

YUHANG ZHENG'S CV DECEMBER 2, 2024

#### Lift System Optimization for Hover-capable Flapping Wing Micro Air Vehicle

Shengjie Xiao, Yongqi Shi, Zemin Wang, Zhe Ni, **Yuhang Zheng**, Huichao Deng†, Xilun Ding *Frontiers of Mechanical Engineering*, 2024

# **CONFERENCE PROCEEDINGS**

# **TOD3Cap: Towards 3D Dense Captioning in Outdoor Scenes**

Bu Jin, Yupeng Zheng†, Pengfei Li, Weize Li, **Yuhang Zheng**, Sujie Hu, Xinyu Liu, Jinwei Zhu, Zhijie Yan, Haiyang Sun, Kun Zhan, Peng Jia, Xiaoxiao Long, Yilun Chen, Hao Zhao *ECCV*. 2024

#### **Monoocc: Digging into Monocular Semantic Occupancy Prediction**

Yupeng Zheng, Xiang Li, Pengfei Li, **Yuhang Zheng**, Bu Jin, Chengliang Zhong, Xiaoxiao Long, Hao Zhao, Qichao Zhang† *ICRA*. 2024

# **Enhancing Daily Life through an Interactive Desktop Robotics System**

**Yuhang Zheng**, Qiyao Wang, Chengliang Zhong†, He Liang, Zhengxiao Han, Yupeng Zheng *CICAI*, *Best Demo Award*, 2023

#### **3D Implicit Transporter for Temporally Consistent Keypoint Discovery**

Chengliang Zhong, **Yuhang Zheng**, Yupeng Zheng, Hao Zhao†, Li Yi, Xiaodong Mu, Ling Wang, Pengfei Li, Guyue Zhou, Chao Yang, Xinliang Zhang, Jian Zhao *ICCV*, *Oral*, 2023

#### **DPF: Learning Dense Prediction Fields with Weak Supervision**

Xiaoxue Chen, Yuhang Zheng, Yupeng Zheng, Qiang Zhou, Hao Zhao†, Guyue Zhou, Ya-Qin Zhang CVPR, 2023

#### **Int2: Interactive Trajectory Prediction at Intersections**

Zhijie Yan, Pengfei Li, Zheng Fu, Shaocong Xu, Yongliang Shi, Xiaoxue Chen, **Yuhang Zheng**, Yang Li, Tianyu Liu, Chuxuan Li, Nairui Luo, Xu Gao, Yilun Chen, Zuoxu Wang, Yifeng Shi, Pengfei Huang, Zhengxiao Han, Jirui Yuan, Jiangtao Gong, Guyue Zhou, Hao† Zhao

*ICCV*, 2023

# Steps: Joint self-supervised Nighttime Image Enhancement and Depth Estimation

Yupeng Zheng, Chengliang Zhong, Pengfei Li, Huan-ang Gao, **Yuhang Zheng**, Bu Jin, Ling Wang, Hao Zhao, Guyue Zhou, Qichao Zhang†, Dongbin Zhao *ICRA*. 2023

### **Adapt: Action-aware Driving Caption Transformer**

Bu Jin, Xinyu Liu, Yupeng Zheng, Pengfei Li, Hao Zhao†, Tong Zhang, **Yuhang Zheng**, Guyue Zhou, Jingjing Liu *ICRA*. 2023

# **INVENTION PATENT**

# Automatic Recognition Method for Groove Form and Joint Type of Welding Groove Schematic Diagram

Meiqing Wang, **Yuhang Zheng**, Zijian Wu, Chenhao Ye, Hao Luo **Chinese Invention Patent, Substantive Examination.** CN117102738A, 2023

#### Automatic Groove Size Information Analysis Method for Welding Groove Schematic Diagram

Meiqing Wang, **Yuhang Zheng**, Zijian Wu, Hao Luo, Chenhao Ye **Chinese Invention Patent, Substantive Examination.** CN117133010A, 2023

#### Process Knowledge Element Extraction Method for Welding Process Text

Meiqing Wang, Yuhang Zheng, Jinjian Duan

Chinese Invention Patent, Substantive Examination. CN115577709A, 2023

#### Flapping Wing Elastic Energy Storage Mechanism of Miniature Bionic Flapping Wing Aircraft

Huichao Deng, Zhe Ni, Zemin Wang, **Yuhang Zheng**, Yongqi Shi, Shutong Zhang *Chinese Invention Patent*, *Patent Grant*. *CN113148145B*, 2022

# Bionic Flapping Mechanism Applied to Hovering Type Micro Flapping Wing Aircraft

Huichao Deng, Yongqi Shi, **Yuhang Zheng**, Zemin Wang, Zhe Ni, Shutong Zhang *Chinese Invention Patent*, *Patent Grant*. *CN113148146B*, 2022

# **Selected Projects**

### **3D Generation of OmniSim Platform**

OmniSim Organization | Advised by **Prof. Hao Dong** 

In Progress

• **Method:** Given a task name, we first prompt LLM to enrich the task description to depict a scene and propose the relevant objects (description) with the proper size and location. Then, we build a text-image-3D pipeline to generate diverse 3D assets according to the proposed objects' descriptions.