

CS 4240: Compilers

Lecture 12: Register Allocation

Guest Lecturer: Chris Porter

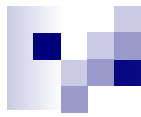
(cporter35@gatech.edu)

February 20, 2019

Happy International Pipe Day



https://www.youtube.com/watch?v=80oLTiVW_Ic



Register allocation

- Assume a 3-address code intermediate representation with an unbounded number of virtual/symbolic registers
- For each virtual register **r**, want to choose a physical machine register to store **r**'s values
- Intermediate step: determine the *live ranges* of each virtual register **r**

Register Allocation: Motivation

Option #1:

Keep in Memory

```
load r1, 4(sp)
load r2, 8(sp)
add r3, r1, r2
store r3, 12(sp)
```

Option #2:

Keep in Registers

```
add r3, r1, r2
```

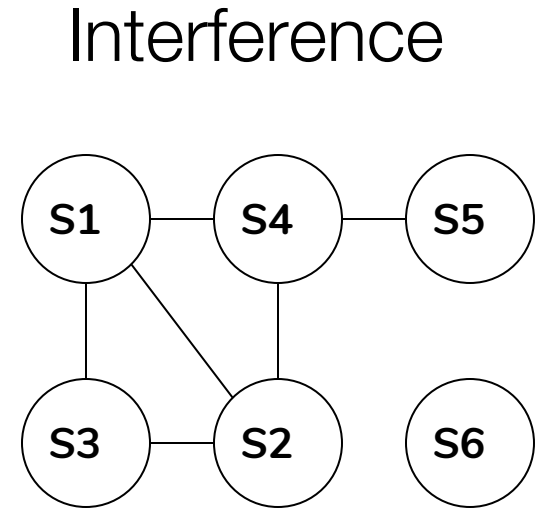
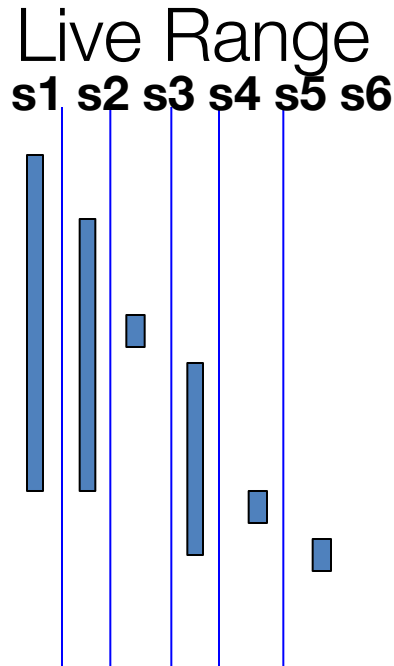
- Advantages to Option 2:
 - Uses fewer instructions: most instrs are reg
↔ reg
 - Each instruction is cheaper:
accessing memory is expensive

Register Allocation

- Determine which of the values (variables, temporaries, large constants) should be in registers at each program point
 - Processors have very few registers, but they can be accessed very quickly
- Goal: **minimize** the traffic between the CPU registers and the memory hierarchy
 - In practice, often the optimization with the **greatest** impact on performance

A Simple Example

```
s1 ← 2
s2 ← 4
s3 ← s1 + s2
s4 ← s3 + 1
s5 ← s1 * s2
s6 ← s4 * 2
```



- **Live:** variable will be used before it is overwritten
- **Dead:** variable will be overwritten before it is used

A Simple Example (contd)

Intermediate
Code w/ Symbolic
Registers

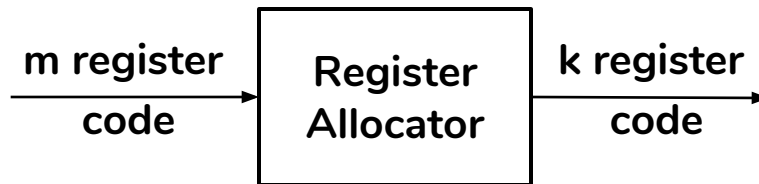
```
s1 ← 2
s2 ← 4
s3 ← s1 + s2
s4 ← s3 + 1
s5 ← s1 * s2
s6 ← s4 * 2
```

Machine
Code w/ Physical
Registers

```
r1 ← 2
r2 ← 4
r3 ← r1 + r2
r3 ← r3 + 1
r1 ← r1 * r2
r2 ← r3 * 2
```

Global Register Allocation

The big picture



Optimal global allocation is NP-Complete, under almost any assumptions.

At each point in the code

- 1 Determine which values will reside in registers
- 2 Select a register for each such value

The goal is an allocation that “minimizes” running time

Most modern, global allocators use a graph-coloring paradigm

- » Build a “**conflict graph**” or “**interference graph**”
- » Find a k -coloring for the graph, or change the code to a nearby problem that it can k -color

Building the Interference Graph

What is an “interference” ? (or conflict)

- » Two values **interfere** if there exists an operation where both are simultaneously live
- » If x and y interfere, they cannot occupy the same register

To compute interferences, we must know where values are “live”

The interference graph, $G_I = (N_I, E_I)$

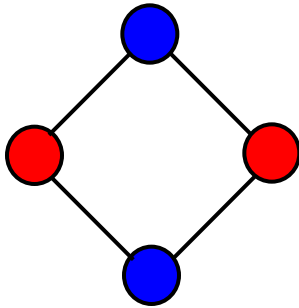
- » Nodes in G_I represent values, or live ranges
- » Edges in G_I represent individual interferences
 - For $x, y \in N_I$, $\langle x, y \rangle \in E_I$ iff x and y interfere
- » A k -coloring of G_I can be mapped into an allocation to k registers

Graph Coloring

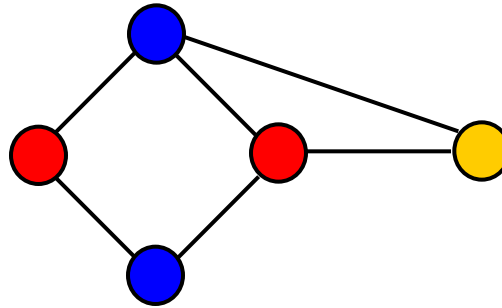
The problem

A graph G is said to be k -colorable iff the nodes can be labeled with integers $1 \dots k$ so that no edge in G connects two nodes with the same label

Examples



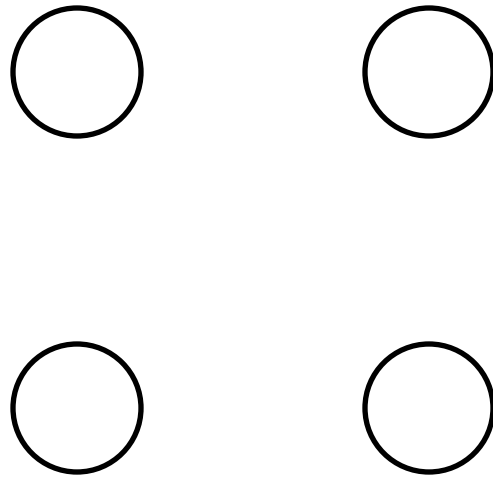
2-colorable



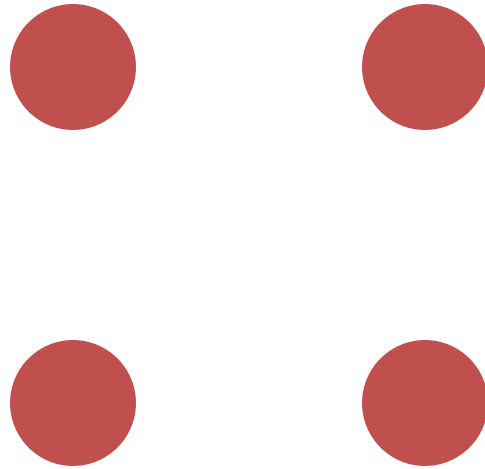
3-colorable

Each color can be mapped to a distinct physical register

Graph Coloring Example #1

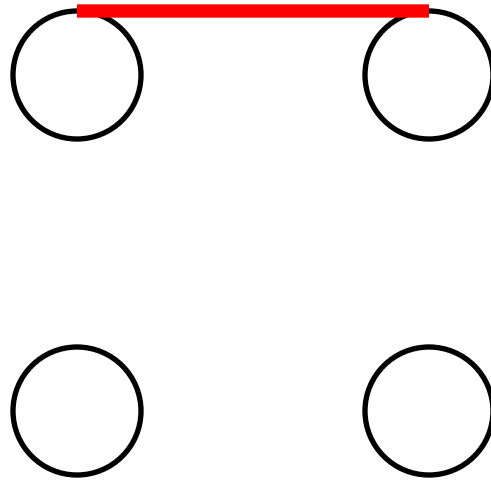


Graph Coloring Example #1

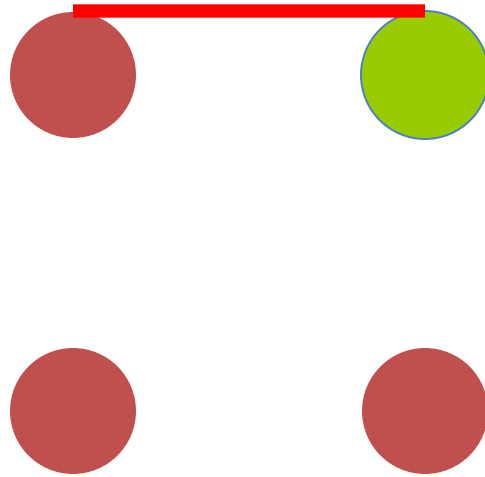


Colors: **1**

Graph Coloring Example #2

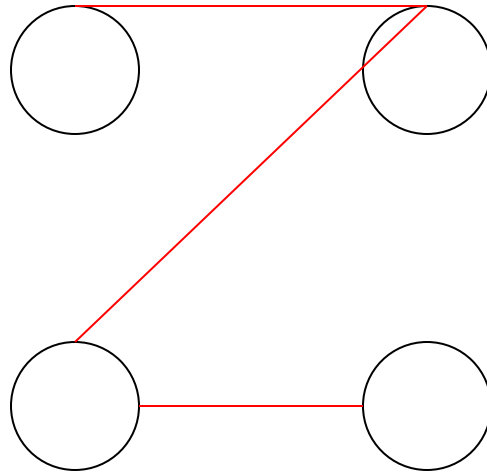


Graph Coloring Example #2

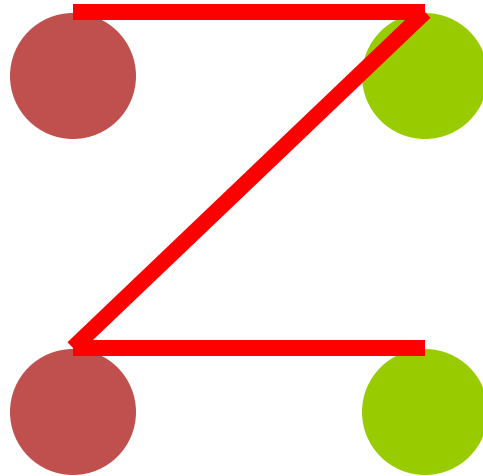


Colors: **2**

Graph Coloring Example #3

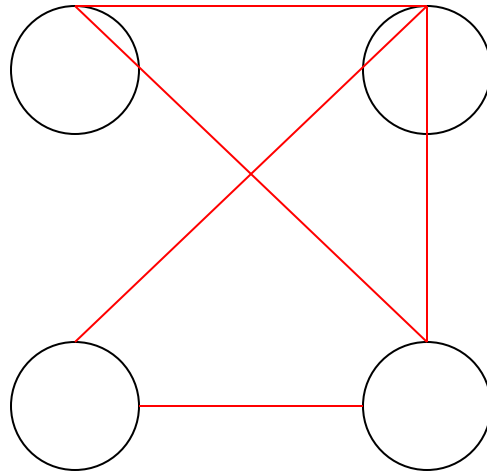


Graph Coloring Example #3

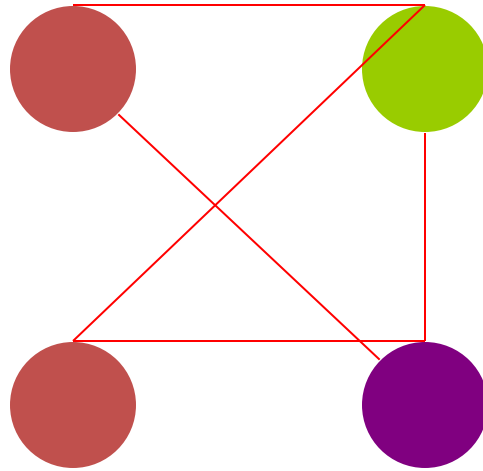


Colors: **still 2**

Graph Coloring Example #4



Graph Coloring Example #4



Colors: **3**

Computing LIVE Sets (live ranges)

A value v is live at program point p if \exists a path from p to some use of v along which v is not re-defined

Data-flow problems are expressed as simultaneous equations

$$\text{LIVEOUT}(b) = \bigcup_{s \in \text{succ}(b)} \text{LIVEIN}(s)$$

$$\text{LIVEIN}(b) = \text{UEVAR}(b) \cup (\text{LIVEOUT}(b) - \text{VARKILL}(b))$$

where

$\text{UEVAR}(b)$ is the set of names used in block b before being defined in b (Upwards Exposed Variables)

$\text{VARKILL}(b)$ is the set of variables assigned in b

Solve the equations using a fixed-point iterative scheme

Computing LIVE Sets

The compiler can solve these equations with an iterative algorithm

```
WorkList  $\leftarrow$  { all blocks }  
while ( WorkList  $\neq \emptyset$  )  
    remove a block b from WorkList  
    Compute LIVEOUT(b)  
    Compute LIVEIN(b)  
    if LIVEIN(b) changed  
        then add pred (b) to WorkList
```

The Worklist Iterative
Algorithm

The world's quickest introduction to data-flow analysis !

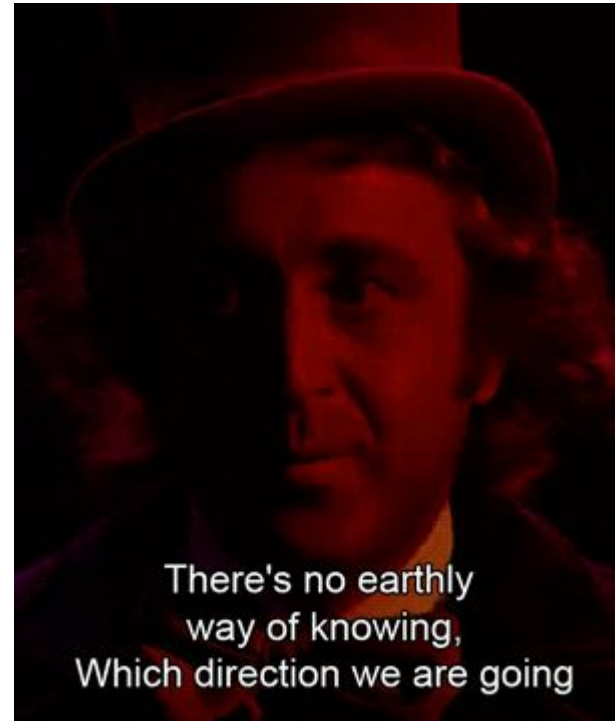
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```

The Worklist Iterative
Algorithm

The world's quickest introduction to data-flow

Why does this work?

- LIVEOUT, LIVEIN $\subseteq 2^{\text{Names}}$
 - UEVAR, VARKILL are constants for b
 - Equations are monotone
 - Finite # of additions to sets
- \Rightarrow will reach a fixed point !

Speed of convergence depends on the order in which blocks are "removed" & their sets recomputed

Observation on Coloring for Register Allocation

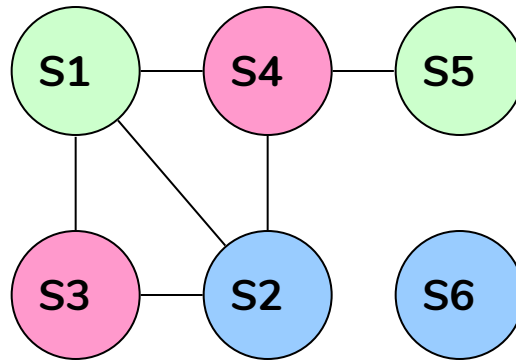
- » Suppose you have k registers—look for a k coloring
- » Any vertex n that has fewer than k neighbors in the interference graph ($n^\circ < k$) can **always** be colored!
 - Pick any color not used by its neighbors — there must be one
- » Ideas behind a classical algorithm due to Chaitin:
 - Pick any vertex n such that $n^\circ < k$ and put it on the stack
 - Remove that vertex and all edges incident from the interference graph
 - This may make additional nodes have fewer than k neighbors
 - At the end, if some vertex n still has k or more neighbors, then spill the live range associated with n
 - Otherwise successively pop vertices off the stack and color them in the lowest color not used by some neighbor

Allocation via Graph Coloring

Intermediate Code

```
s1 ← 2
s2 ← 4
s3 ← s1 + s2
s4 ← s3 + 1
s5 ← s1 * s2
s6 ← s4 * 2
```

Graph Coloring



```
r1 ← green
r2 ← blue
r3 ← pink
```

Machine Code

```
r1 ← 2
r2 ← 4
r3 ← r1 + r2
r3 ← r3 + 1
r1 ← r1 * r2
r2 ← r3 * 2
```


Register Allocation

1. Determine live ranges for each symbolic register
2. Determine overlapping ranges (**interference**)
3. Compute the benefit of keeping each live range in a register (**spill cost**)
4. Try to assign each live range to a machine register (**allocation**).
If needed, **spill** or **split** live range
5. Generate code, including spills

Chaitin's Algorithm

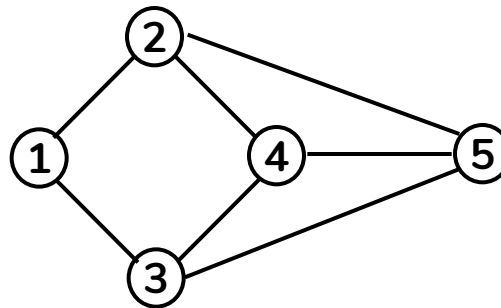
1. While \exists vertices with $< k$ neighbors in G_I
 - > Pick any vertex n such that $n^\circ < k$ and put it on the stack
 - > Remove that vertex and all edges incident to it from G_I
 1. This will lower the degree of n 's neighbors
2. If G_I is non-empty (all vertices have k or more neighbors) then:
 - > Pick a vertex n (using some heuristic) and spill the live range associated with n
 1. Remove vertex n from G_I , along with all edges incident to it and put it on the stack
 - > If this causes some vertex in G_I to have fewer than k neighbors, then go to step 1; otherwise, repeat step 2
- > Successively pop vertices off the stack and color them in the lowest color not used by some neighbor

Chaitin's Algorithm in Practice

3 Registers



Stack

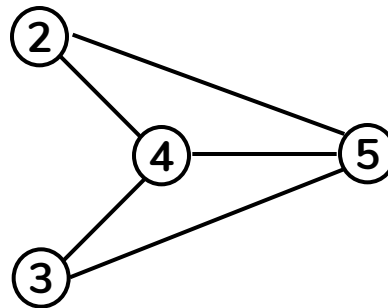


Chaitin's Algorithm in Practice

3 Registers



Stack

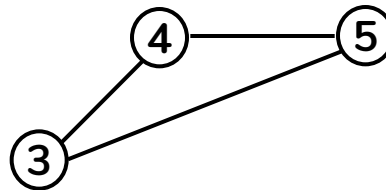


Chaitin's Algorithm in Practice

3 Registers

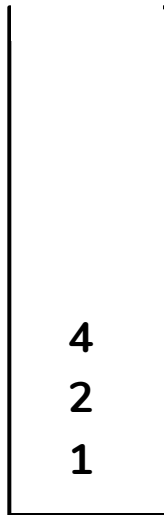


Stack

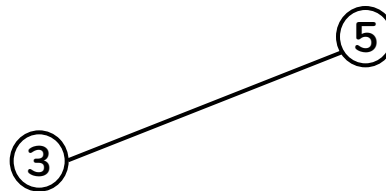


Chaitin's Algorithm in Practice

3 Registers

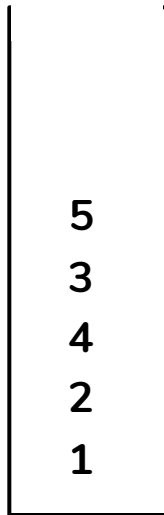


Stack



Chaitin's Algorithm in Practice


3 Registers



Stack

Colors:

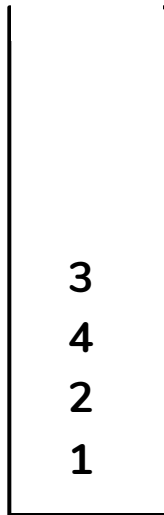
1: 

2: 

3: 

Chaitin's Algorithm in Practice

3 Registers




Stack

5

Colors:

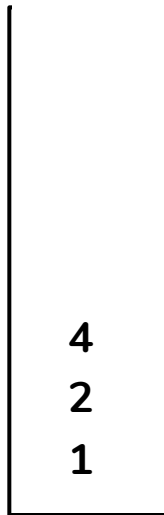
1: 

2: 

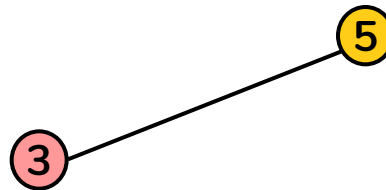
3: 

Chaitin's Algorithm in Practice

3 Registers




Stack



Colors:

1: 

2: 

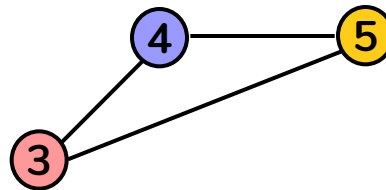
3: 

Chaitin's Algorithm in Practice

3 Registers



Stack



Colors:

1: 

2: 

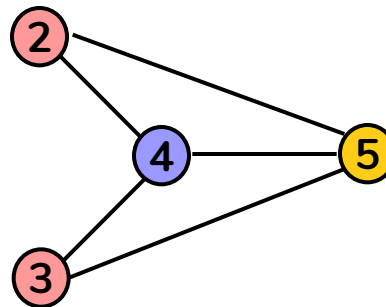
3: 

Chaitin's Algorithm in Practice

3 Registers



Stack



Colors:

1: 

2: 

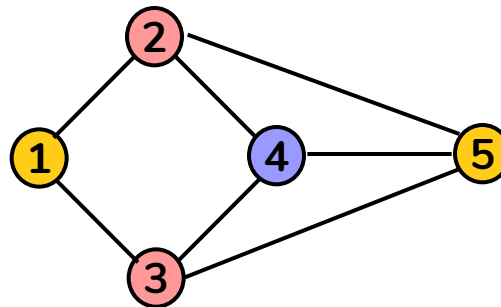
3: 

Chaitin's Algorithm in Practice

3 Registers



Stack



Colors:

1: 

2: 

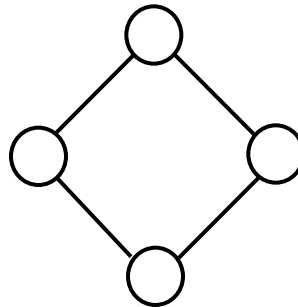
3: 

Improvement in Coloring Scheme

Optimistic Coloring (Briggs, Cooper, Kennedy, and Torczon)

- » If Chaitin's algorithm reaches a state where every node has k or more neighbors, it chooses a node to spill.
- » Briggs said, take that same node and push it on the stack
 - When you pop it off, a color might be available for it!

2 Registers:



Chaitin's algorithm immediately spills one of these nodes

- For example, a node n might have $k+2$ neighbors, but those neighbors might only use 3 ($<k$) colors
 - Degree is a loose upper bound on colorability

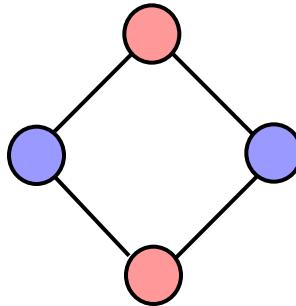
Improvement in Coloring Scheme

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 - When you pop it off, a color might be available for it!

2 Registers:

2-colorable



Briggs algorithm finds an available color

- For example, a node n might have $k+2$ neighbors, but those neighbors might only use just one color (or any number $< k$)
 - Degree is a loose upper bound on colorability

Chaitin-Briggs Algorithm

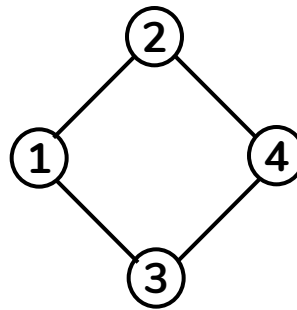
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 - > Remove that vertex and all edges incident to it from G_I
 1. This may create vertices with fewer than k neighbors
2. If G_I is non-empty (all vertices have k or more neighbors) then:
 - > Pick a vertex n (using some heuristic condition), push n on the stack and remove n from G_I , along with all edges incident to it
 - > If this causes some vertex in G_I to have fewer than k neighbors, then go to step 1; otherwise, repeat step 2
- > Successively pop vertices off the stack and color them in the lowest color not used by some neighbor
 - > If some vertex cannot be colored, then pick an uncolored vertex to spill, spill it, and restart at step 1

Chaitin-Briggs in Practice

2 Registers

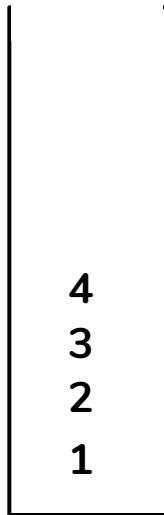


Stack

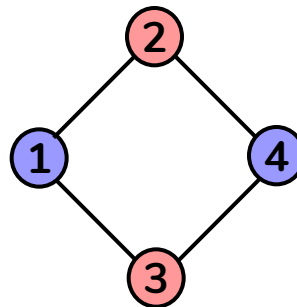


Chaitin-Briggs in Practice

2 Registers



Stack



Colors:

1: 

2: 

Worksheet 12

- » Color the interference graph below with the minimum number of colors. Indicate if this coloring can be obtained using the Chaitin or Chaitin-Briggs algorithms studied in class.

