

Discrete Event Simulation and Modelling with Event Graphs

Modelling Approach/
Representation Form

Model Type

Event Graphs

leads
to →

Discrete Event
Simulation Model

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Compare:

System Dynamics or
Lagrange Formalism

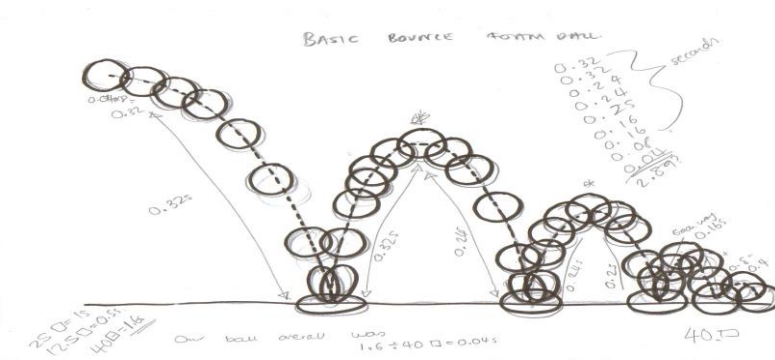
leads
to →

Differential Equation
Model

-
- A photograph of a busy supermarket aisle. Several customers are pushing shopping carts, filled with various items. A large red sign with the price '1.19' is visible in the background. The aisle is well-lit and stocked with products.



- (Simulation of systems that can be approximated as such)



Two fundamental components of a discrete event simulation (DES) model

State Variables

„Observables“ of the model. Used to generate the simulation output

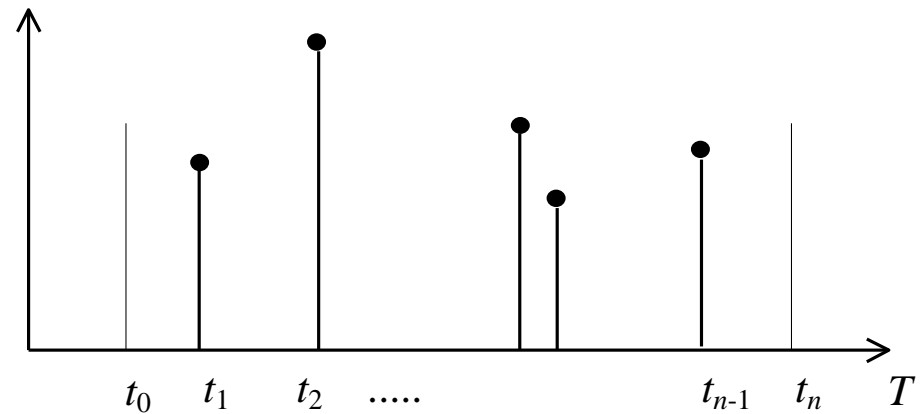
Events:

Cause state variables to change and schedule/cancel future events

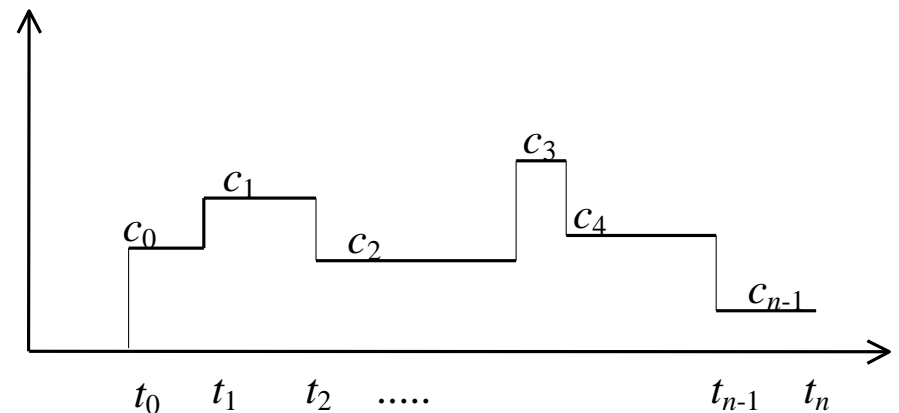
Discrete Event Simulation

Fundamental Concept

- Events



- States piecewise constant



Discrete Event Simulation

Fundamental Concept

Events are scheduled using

Event Notices.

Every event notice contains two pieces of information:

- What (type of) event is being scheduled, and
- the (simulated) time at which the event is planned to occur

The

Event List

keeps the event notices in order by ranking them based on the lowest scheduled time.

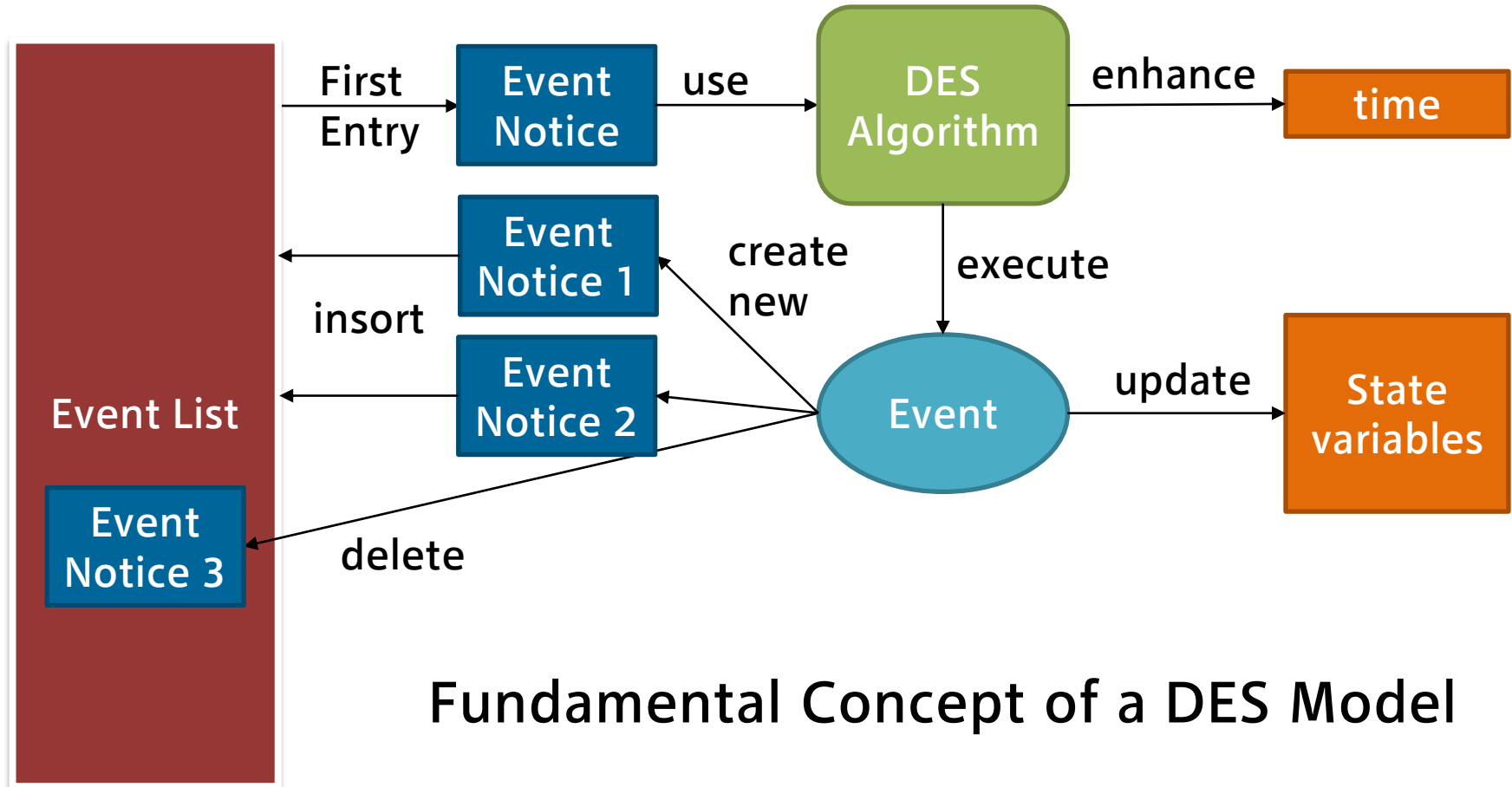
The events list is managed by basic

Discrete Event Algorithm

that controls the flow of time in the simulated world of the model

Discrete Event Simulation

Fundamental Concept



Fundamental Concept of a DES Model

How to formalise DES Models

EVENT GRAPHS

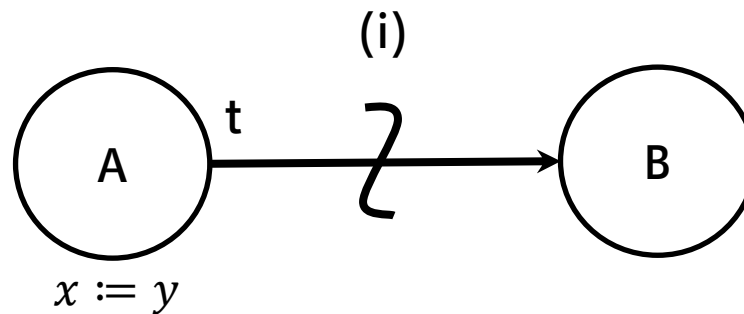
- Concept introduced by Lee Schruben in 1983
 - Sometimes called „Simulation Graphs“
 - Graphical representation of a DES model which can directly be fed to Event Graphs simulators, e.g. SIGMA (Compare with System Dynamics and AnyLogic)
 - Very general – for most applications, more specialised concepts / simulators are used
-

The occurrence of an event with type A

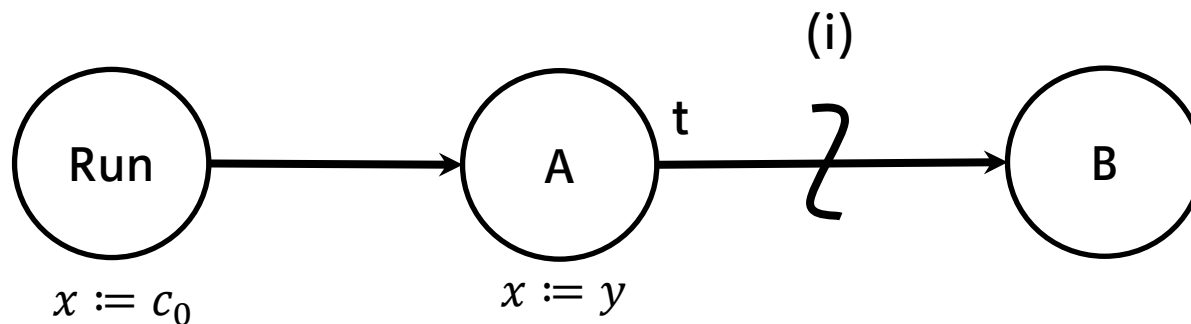
- causes state variable x to change its state to y

causes an event with type B

- to be scheduled after a time delay of t ,
- providing condition (i) is true, after the state transitions for Event A have been performed



- As the event-list is empty at the beginning of the simulation, a designated initial event needs to be given.
- Usually this event is labelled with „Run“



- Goal: model the sequence

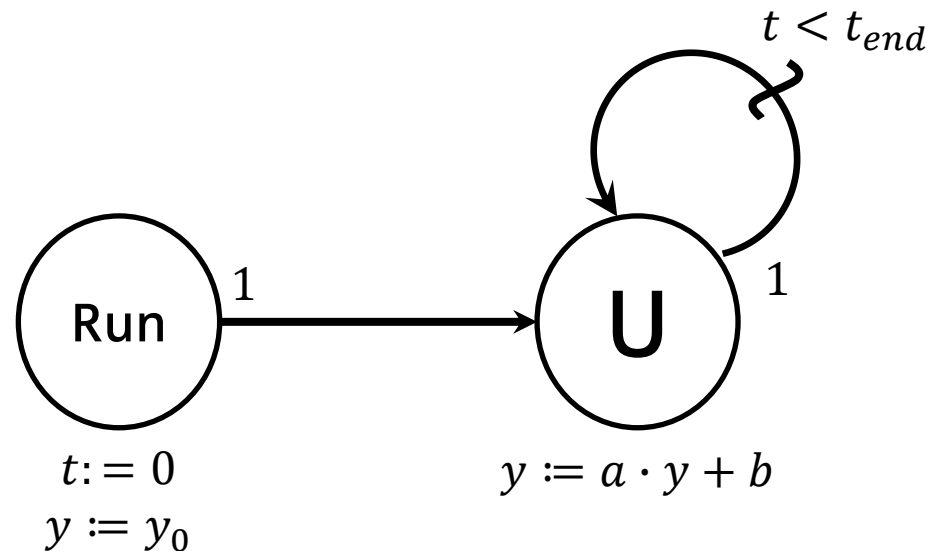
$$y(k+1) = ay(k) + b,$$
$$k = 0, \dots, t_{end}, \quad y(0) = y_0$$

using the Event Graph formalism

- Goal: model the sequence

$$y(k+1) = ay(k) + b,$$
$$k = 0, \dots, t_{end}, \quad y(0) = y_0$$

using the Event Graph formalism

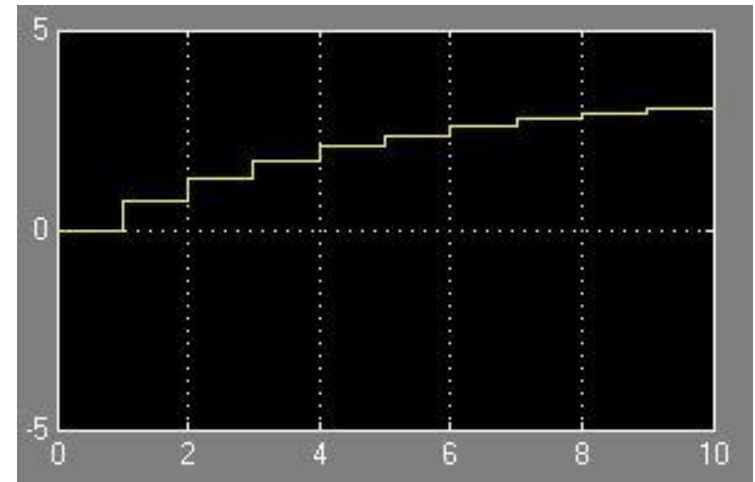
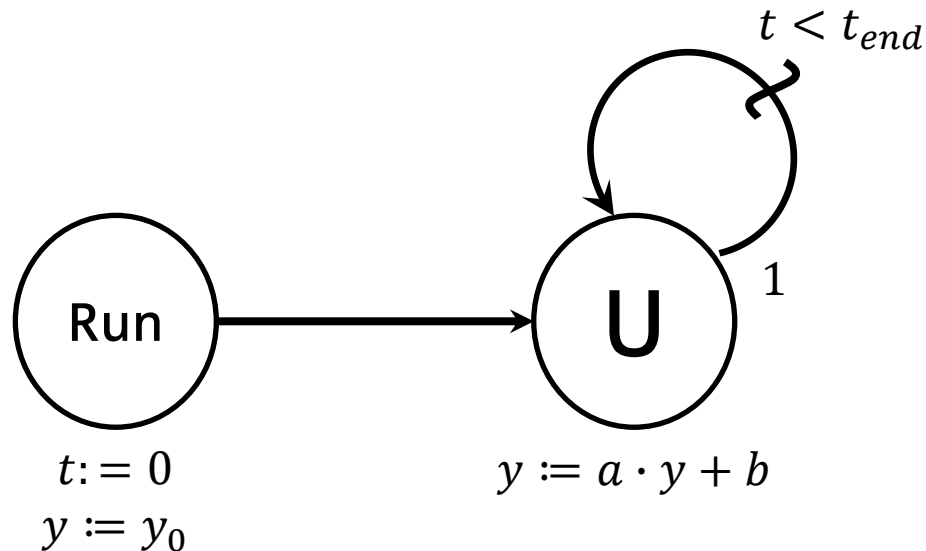


Example: Difference Equation

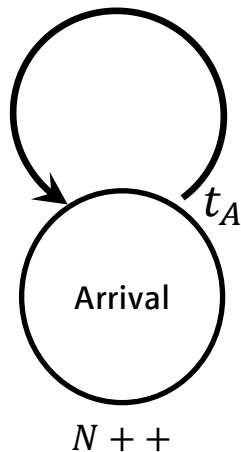
- Goal: model the sequence

$$y(k+1) = ay(k) + b,$$
$$k = 0, \dots, t_{end}, \quad y(0) = y_0$$

using the Event Graph formalism



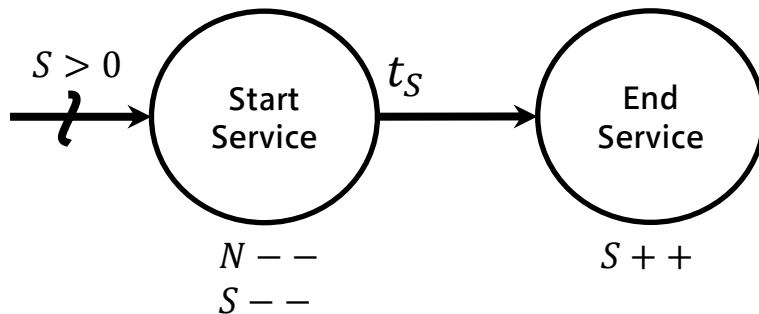
Arrival Process:



- Used to generate „entities“ coming from outside the system boundaries
- Usually changes increases a cumulative state variable by one. This variable is usually called a **queue**
- Sequence of interarrival times t_A that can be
 - constant, a
 - deterministic sequence, or a
 - sequence of random variables

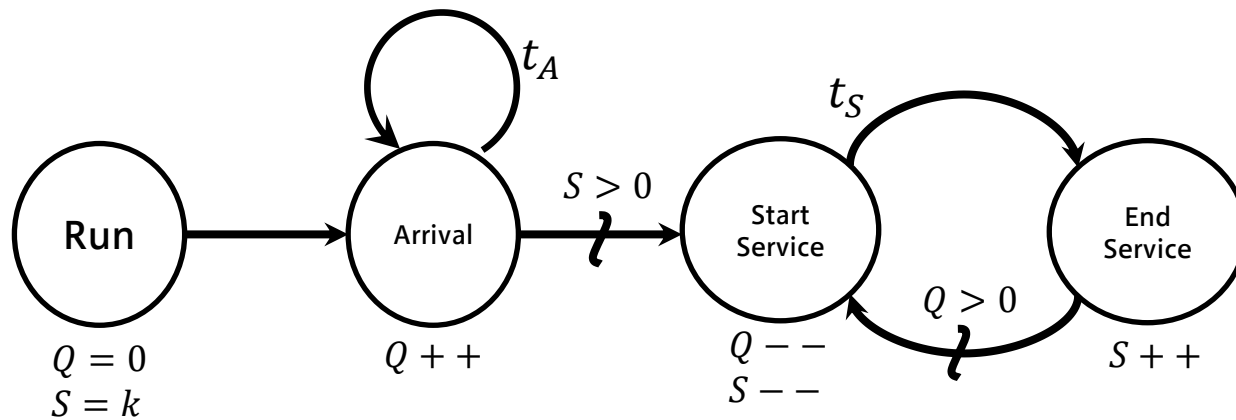
Service Process:

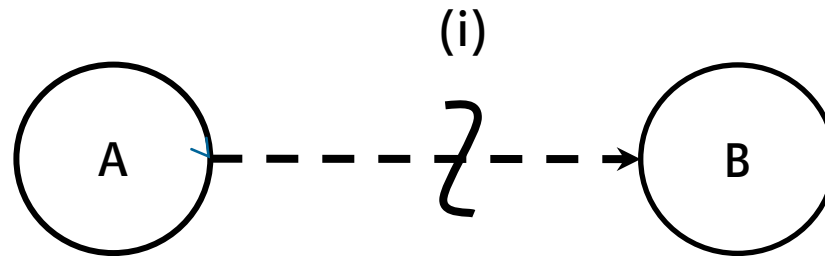
- Used to treat „entities“ coming from, e.g. an arrival process
- If available ($S > 0$), takes an element from the queue
- Sequence of service times t_S that can be
 - constant, a
 - deterministic sequence, or a
 - sequence of random variables



- Customers arrive to a service facility according to an arrival process and are served by one of k servers.
 - Customers arriving to find all servers busy wait in a single queue and are served in order of their arrival.
 - Parameters:
 - t_A = interarrival times
 - t_s = service times
 - k = total number of servers
 - State Variables:
 - Q := # of customers in queue
 - S = # of available servers
-

- Customers arrive to a service facility according to an arrival process and are served by one of k servers order of their arrival.
- Parameters:
 - t_A = interarrival times
 - t_S = service times
 - k = total number of servers
- State Variables:
 - Q := # of customers in queue
 - S = # of available servers





- the inverse operation of the scheduling edge
 - whenever event with type A occurs, then if condition (i) is true, the first occurrence of an event with type B is removed from the event list
 - if event B is not scheduled to occur, then nothing happens.
 - if there are multiple occurrences, only the first is removed.
-

Multiple Server Queue with Failure

- Customers arrive to a service facility according to an arrival process and are served by one of k servers order of their arrival.
- With certain failure probability the server breaks while serving

- Parameters:

t_A = interarrival times

t_S = service times

k = total number of servers

p_f = failure probability

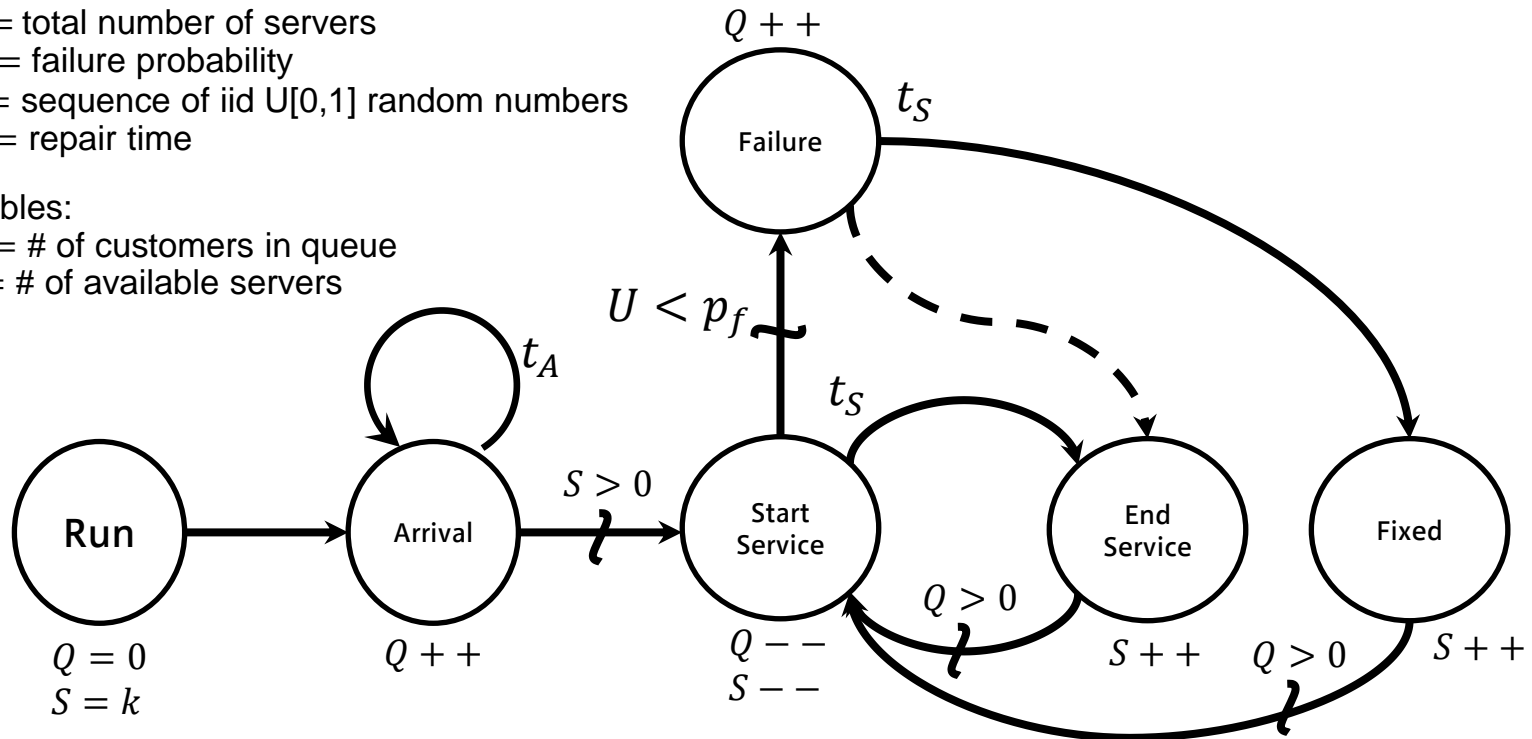
U = sequence of iid $U[0,1]$ random numbers

t_R = repair time

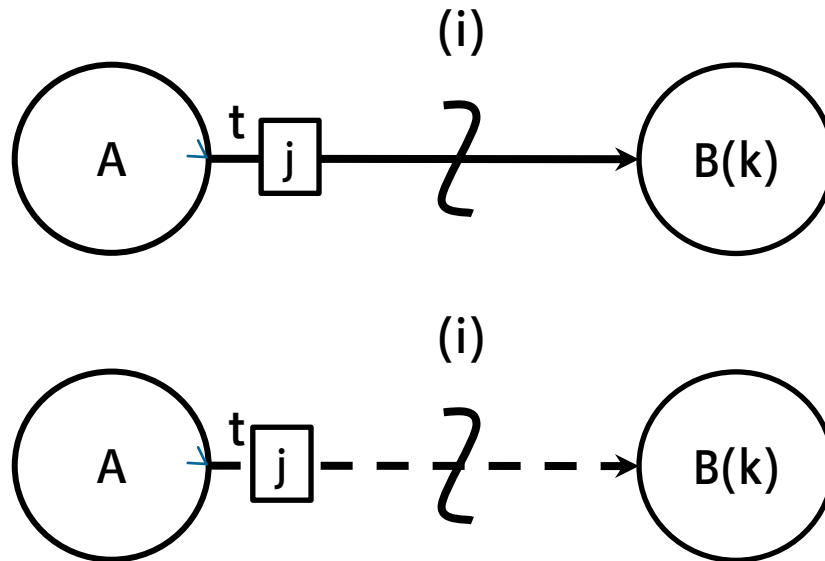
- State Variables:

Q := # of customers in queue

S := # of available servers

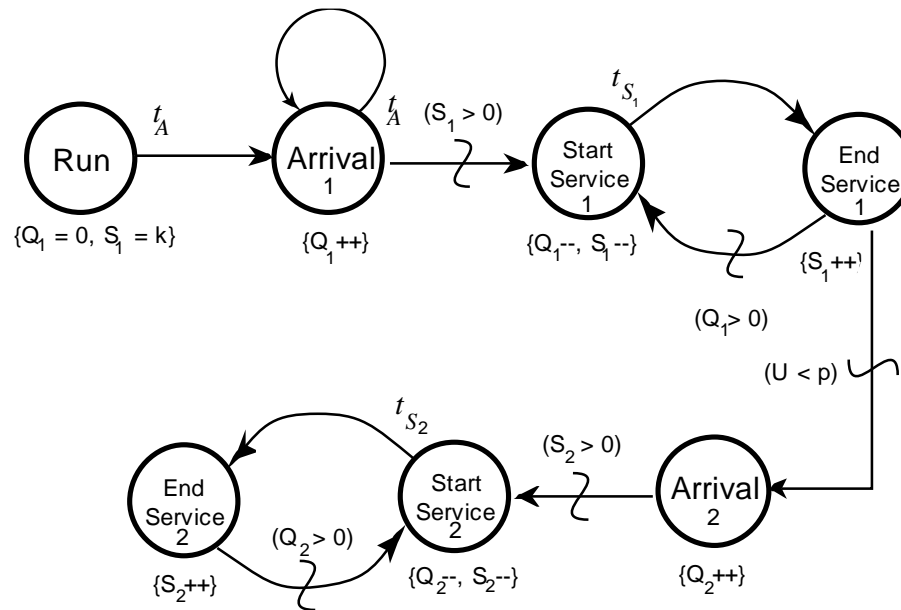


Scheduling edge with parameter: When A occurs then, if (i) is true, B is scheduled after t time units. When B occurs, its parameter k will be set to the value given by the expression j (j is calculated when A occurs).

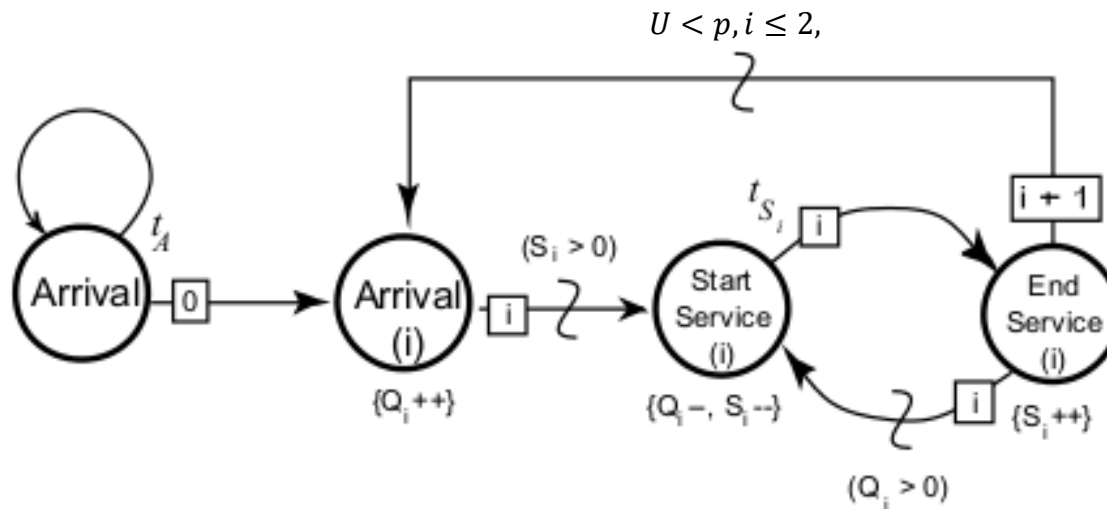


- Customers processed by one workstation consisting of a multiple-server queue.
 - Upon completion of service at the first workstation, a customer proceeds with probability p to a second workstation or departs the system with probability $(1 - p)$.
 - Parameters:
 - t_{A_i} = interarrival times at WS i
 - t_{s_i} = service times at WS i
 - k_i = total number of servers at WS i
 - p = probability to proceed from 1 to 2
 - U = sequence of iid $U(0,1)$ random numbers
 - State Variables:
 - Q_i := # of customers in queue at WS i
 - S_i = # of available servers at WS i
-

- Customers processed by one workstation consisting of a multiple-server queue.
- Upon completion of service at the first workstation, a customer proceeds with probability p to a second workstation or departs the system with probability $(1-p)$.

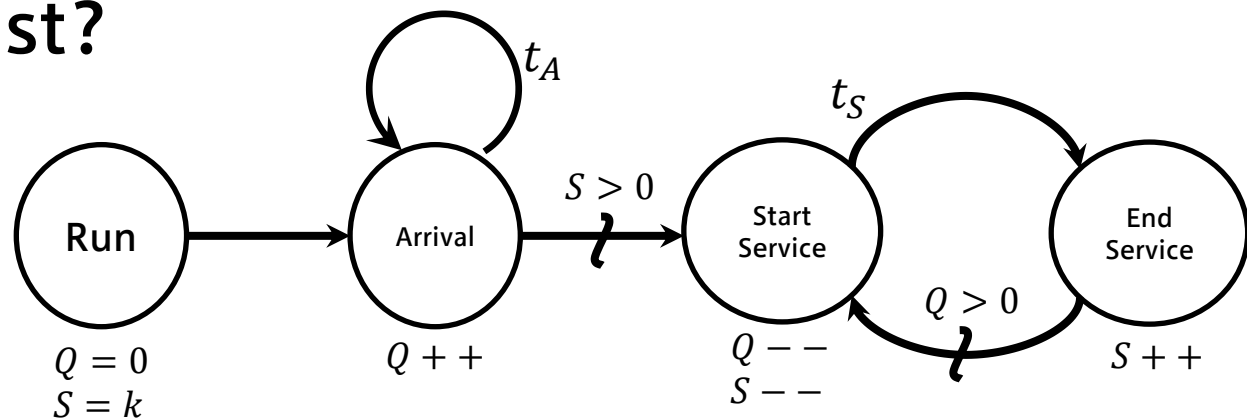


- Customers processed by one workstation consisting of a multiple-server queue.
- Upon completion of service at the first workstation, a customer proceeds with probability p to a second workstation or departs the system with probability $(1-p)$.



Case Study:

- What happens, when executing a Multiple Server Queue model with deterministic service and arrival times?
- Event Notices?
- Event List?



DISCRETE start

server = 2; queue = 0

SCHEDULE arrival .AT. t+0.

END ! of start

DISCRETE arrival

queue = queue + 1; **t_arrival = 1**

SCHEDULE arrival .AT. t+tarr

IF server .GE. 0 SCHEDULE start_service at t+0.

END ! of arrival

DISCRETE start_service

queue = queue - 1; server = server - 1

t_service = 2.5

SCHEDULE end_service .AT. t+t_service

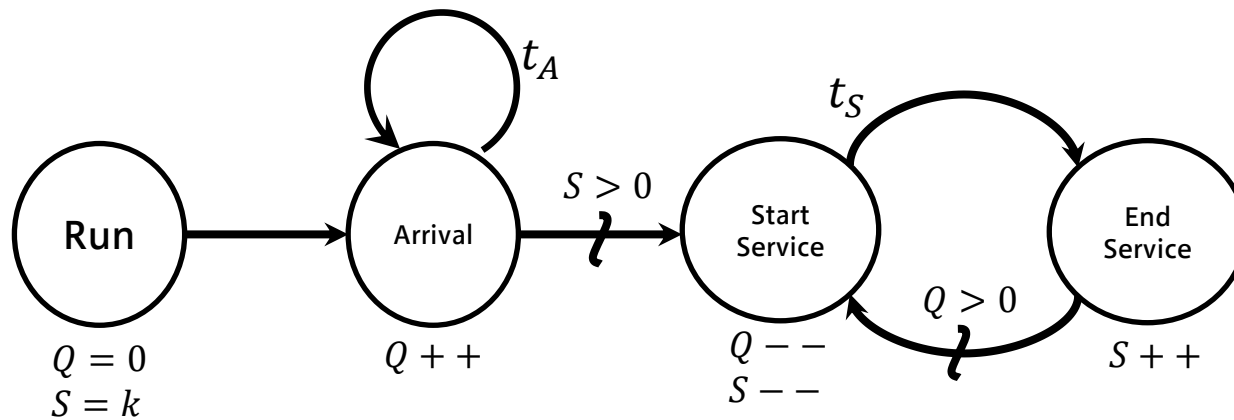
END ! of start_service

DISCRETE end_service

server = server + 1

IF queue .GE. 0 SCHEDULE start_service at t+0.

END ! of end_service



Event List Multiple Server Queue

time	event	action	schedule
0	ST	$Q=0; S=2;$	A at $t+0=0$
0	A	$Q=Q+1=1$	A at $t+1=1$; SS at $t+0=0$
0	SS	$Q=Q-1=0; S=S-1=1$	ES at $t+2.5=2.5$
1	A		
2.5	ES		
<pre> graph LR ST((ST)) -- "λ" --> A((A)) A -- "1" --> A A -- "S > 0 λ" --> SS((SS)) SS -- "2.5" --> SS SS -- "Q > 0 λ" --> ES((ES)) ES -- "S++" --> SS </pre> <p> $Q = 0$ $S = 3$ </p> <p> $Q++$ </p> <p> $Q--$ $S--$ </p> <p> $S++$ </p>			

Event List Multiple Server Queue

time	event	action	schedule
0	ST	$Q=0; S=2;$	A at $t+0$
0	A	$Q=Q+1=1$	A at $t+1=1$; SS at $t+0=0$
0	SS	$Q=Q-1=0; S=S-1=1$	ES at $t+2.5=2.5$
1	A	$Q=Q+1=1$	A at $t+1=2$; SS at $t+0=1$
1	SS	$Q=Q-1=0; S=S-1=0$	ES at $t+2.5=3.5$
2.5	ES		
2	A		
3.5	ES		


```

graph LR
    ST((ST)) --> A((A))
    A -- 1 --> A
    A -- "S > 0" --> SS((SS))
    SS -- "2.5" --> SS
    SS -- "Q > 0" --> ES((ES))
    ES --> SS
    style ST fill:#fff,stroke:#000
    style A fill:#fff,stroke:#000
    style SS fill:#fff,stroke:#000
    style ES fill:#fff,stroke:#000

```

Initial state: $Q = 0, S = 3$

State A: $Q++$

State SS: $Q--, S--$

State ES: $S++$

Event List Multiple Server Queue

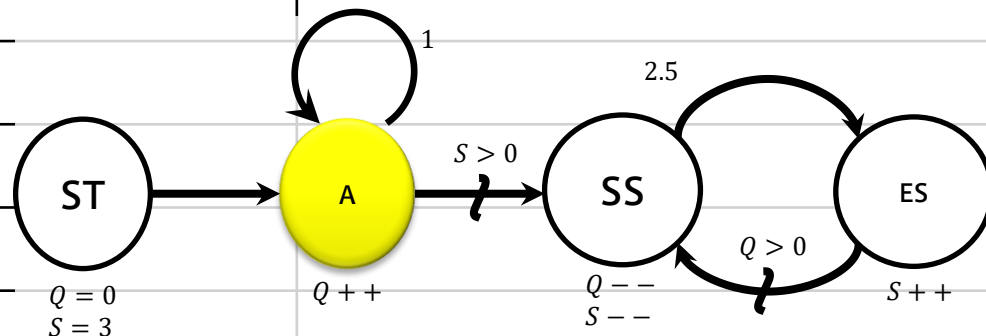
time	event	action	schedule
0	ST	$Q=0; S=2;$	A at $t+0$
0	A	$Q=Q+1=1$	A at $t+1=1$; SS at $t+0=0$
0	SS	$Q=Q-1=0; S=S-1=1$	ES at $t+2.5=2.5$
1	A	$Q=Q+1=1$	A at $t+1=2$; SS at $t+0=1$
1	SS	$Q=Q-1=0; S=S-1=0$	ES at $t+2.5=3.5$
2	A	$Q=Q+1=1$	A at $t+1=3$; (SS condition not true)
2.5	ES		
3.5	ES		
3	A		

Event List Multiple Server Queue

time	event	action	schedule
0	ST	$Q=0; S=2;$	
0	A	$Q=Q+1=1$	
0	SS	$Q=Q-1=0$	
1	A	$Q=Q+1=1$	
1	SS	$Q=Q-1=0; S=S-1=0$	
2	A	$Q=Q+1=1$	A at $t+1=3$; (SS condition not true)
2.5	ES	$S=S+1=1;$	SS at $t+0=2.5$
2.5	SS	$Q=Q-1=0; S=S-1=0$	ES at $t+2.5=5$
3	A		
3.5	ES		
5	ES		

Event List Multiple Server Queue

time	event	action	schedule
2.5	ES	$S=S+1=1$;	SS at $t+0=2.5$
2.5	SS	$Q=Q-1=0$; $S=S-1=0$	ES at $t+2.5=5$
3	A	$Q=Q+1=1$	A at $t+1=4$; (SS condition not true)
3.5	ES		
5	ES		
4	A		

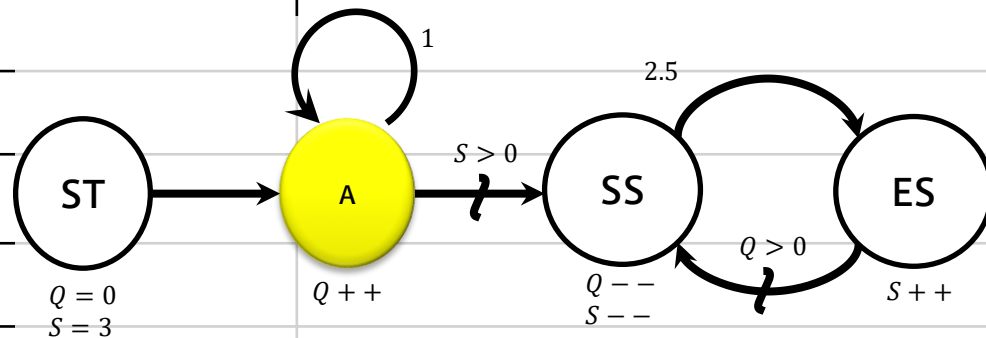


Event List Multiple Server Queue

time	event	action	schedule
2.5	ES	$S=S+1=1$;	SS at $t+0=2.5$
2.5	SS	$Q=Q-1=0$; $S=S-1=0$	ES at $t+2.5=5$
3	A	$Q=Q+1=1$	A at $t+1=4$; (SS condition not true)
3.5	ES	$S=S+1=1$	SS at $t+0=3.5$
3.5	SS	$Q=Q-1=0$; $S=S-1=0$	ES at $t+2.5=6$
4	A		
5	ES		
6	ES		
<pre> graph LR ST((ST)) -- "Q=0, S=3" --> A((A)) A -- "1" --> A A -- "S > 0, Q++" --> SS((SS)) SS -- "2.5" --> SS SS -- "Q > 0, S++" --> ES((ES)) ES -- "Q--, S--" --> SS </pre>			

Event List Multiple Server Queue

time	event	action	schedule
3.5	ES	$S=S+1=1$	SS at $t+0=3.5$
3.5	SS	$Q=Q-1=0$; $S=S-1=0$	ES at $t+2.5=6$
4	A	$Q=Q+1=1$;	A at $t+1=5$; (SS condition not true)
5	ES		
5	A		
6	ES		



Event List Multiple Server Queue

time	event	action	schedule
3.5	ES	$S=S+1=1$	SS at $t+0=3.5$
3.5	SS	$Q=Q-1=0$; $S=S-1=0$	ES at $t+2.5=6$
4	A	$Q=Q+1=1$;	A at $t+1=5$; (SS condition not true)
5	ES	$S=S+1=1$;	SS at $t+0=5$
5	SS	simultaneous events – ordering problems	
5	A		
6	ES		

Event List Multiple Server Queue

time	event	action	schedule
3.5	ES	$S=S+1=1$	SS at $t+0=3.5$
3.5	SS	$Q=Q-1=0; S=S-1=0$	ES at $t+2.5=6$
4	A	$Q=Q+1=1;$	A at $t+1=5;$ (SS condition not true)
5	ES	$S=S+1=1;$	SS at $t+0=5$
5	SS	$Q=Q-1=0; S=S-1=0$	ES at $t+2.5=7.5$
5	A	$Q=Q+1=1;$	A at $t+1=6;$ (SS condition not true)
		Which one should occur first? Does it matter?	
6	ES		
7.5	ES		
6	A		

Event List Multiple Server Queue

time	event	action	schedule
3.5	ES	$S=S+1=1$	SS at $t+0=3.5$
3.5	SS	$Q=Q-1=0; S=S-1=0$	ES at $t+2.5=6$
4	A	$Q=Q+1=1;$	A at $t+1=5;$ (SS condition not true)
5	ES	$S=S+1=1;$	SS at $t+0=5$
5	A	$Q=Q+1=2;$	A at $t+1=6;$ SS at $t+0=5$
5	SS	$Q=Q-1=1; S=S-1=0$	ES at $t+2.5=7.5$
		Which one should occur first? Does it matter?	
6	ES		
7.5	ES		
6	A		
5	SS		

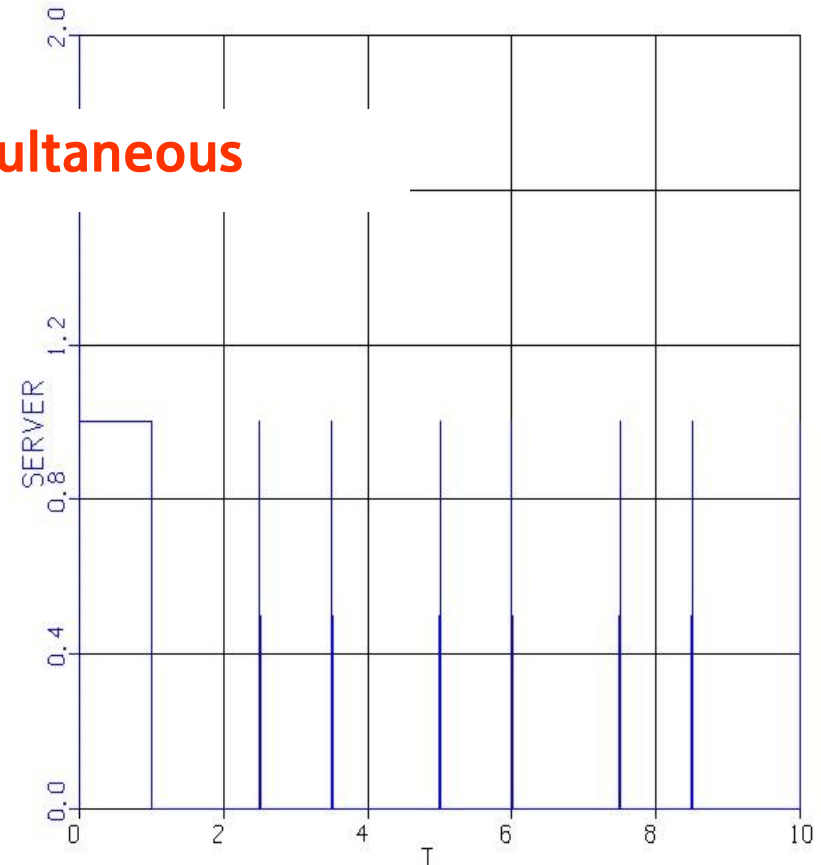
Event List Multiple Server Queue

time	event	action	schedule
3.5	ES	$S=S+1=1$	SS at $t+0=3.5$
3.5	SS	$Q=Q-1=0; S=S-1=0$	ES at $t+2.5=6$
4	A	$Q=Q+1=1;$	A at $t+1=5;$ (SS condition not true)
5	ES	$S=S+1=1;$	SS at $t+0=5$
5	A	$Q=Q+1=2;$	A at $t+1=6;$ SS at $t+0=5$
5	SS	$Q=Q-1=1; S=S-1=0$	ES at $t+2.5=7.5$
5	SS	$Q=Q-1=0; S=S-1=-1$	ES at $t+2.5=7.5$
6	ES		
6	A		
7.5	ES		

**WRONG ORDER,
WRONG RESULTS**

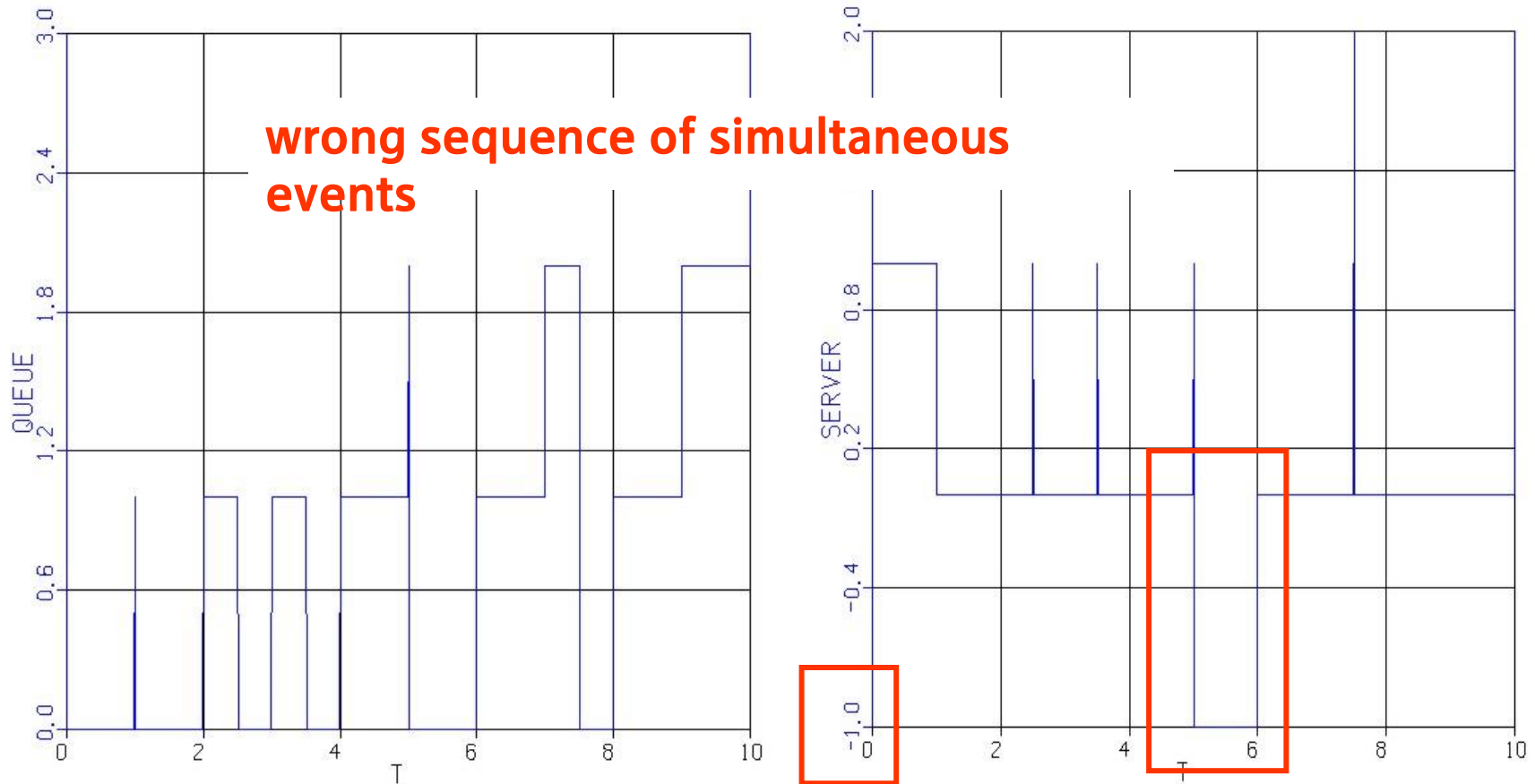
- Simultaneous events occur when more than one event is scheduled to occur at exactly the same time.
 - In some cases the order of execution of the events is irrelevant, but in other cases certain permutations of the order of occurrence impact the outcome dramatically, often leading to invalid state trajectories and inadmissible values of state variables.
 - Event Graph methodology provides the capability of **prioritizing** scheduling edges, so that simultaneous occurrences of the scheduled event always occur before other scheduled events.
 - Although these edge priorities are typically not indicated on the graph itself, all software implementations of Event Graph methodology support edge prioritization.
-

Simulation Multiple Server Queue



$t_{\text{arrival}} = 1$, $t_{\text{service}} = 2.5$, $\text{max_server} = 2$

Simulation Multiple Server Queue



$t_{\text{arrival}} = 1, \quad t_{\text{service}} = 2.5, \quad \text{max_server} = 2$

ANALYSIS OF QUEUING MODELS

- Abbreviation of Queues:

Arrival Time	Service Time	Servers
Deterministic D	Deterministic D	One 1
Markovian M	Markovian M	Multiple m
General G	General G	

⇒ Possible combinations:

D/D/1, M/D/m, G/D/m, M/M/m, ...

- „Deterministic“: t is Constant
 - „Markovian“: Distribution of t is memoryless.
I.e. Exponentially distributed $t \sim E(\lambda)$
 \Rightarrow times become a Markov-process
 - „General“ : Distribution of t is arbitrary
(positive)
-

- Deterministic Queues (D/D/1, D/D/m):

$$\frac{\textit{servicetime}}{\textit{servers}} > \textit{arrivaltime} \\ \Rightarrow \textit{unstable}$$

$$\frac{\textit{servicetime}}{\textit{servers}} \leq \textit{arrivaltime} \\ \Rightarrow \textit{stable}$$

- Stochastic Queues (M/M/1, G/M/m,...):

$$\frac{E(\text{servicetime})}{\text{servers}} \geq E(\text{arrivaltime})$$

\Rightarrow *unstable*

$$\frac{E(\text{servicetime})}{\text{servers}} < E(\text{arrivaltime})$$

\Rightarrow *stable*

- Notation

- Y_k – time elapsed between (k-1)th and k-th arrival

$$E(Y_k) = \frac{1}{\lambda} \dots \text{average interarrival time}$$

(λ is the average arrival rate)

- Z_k – k-th customer service time

$$E(Z_k) = \frac{1}{\mu} \dots \text{average service time}$$

(μ is the average service rate)

- W_k – k-th customer waiting time

- $X(t)$ – average queue length
-

- Customer system time

$S_k = W_k + Z_k$, the time k-th customer spends in the system

$E(W_k) = W$... average waiting time

$E(S_k) = T$... average system time, $T = W + \frac{1}{\mu}$

- Little's law

- \bar{N} ... average number of customers in the system

$$\bar{N} = \lambda T$$

- special cases

$\overline{X(t)} = \bar{N}_q = \lambda W$... average number of customers in the queue

$\bar{N}_s = \frac{\lambda}{\mu}$... average no. of customers in service

Results M/M/1 queues:

- Average waiting time in the queue

$$W = \frac{1}{\mu - \lambda} - \frac{1}{\mu} = \frac{\rho}{(1 - \rho)\mu}, \quad \rho = \frac{\lambda}{\mu}$$

- Average length of the queue

$$\overline{X(t)} = \bar{N}_q = \lambda W = \frac{\rho^2}{1 - \rho}$$

- Average system time of customers

$$T = W + \frac{1}{\mu} = \frac{1}{\mu - \lambda} = \frac{1}{(1 - \rho)\mu}$$

- Average number of customers in the system

$$\bar{N} = \lambda T = \frac{\rho}{1 - \rho}$$

Results M/G/1 queues:

- Exponential distribution of interarrival times
- Service times are mutually independent and distributed arbitrarily with parameters

$$E(Z_k) = \frac{1}{\mu} \text{ in } \text{var}(Z_k) = \sigma^2, \text{ we define also } \rho = \frac{\lambda}{\mu}$$

- Average queue length

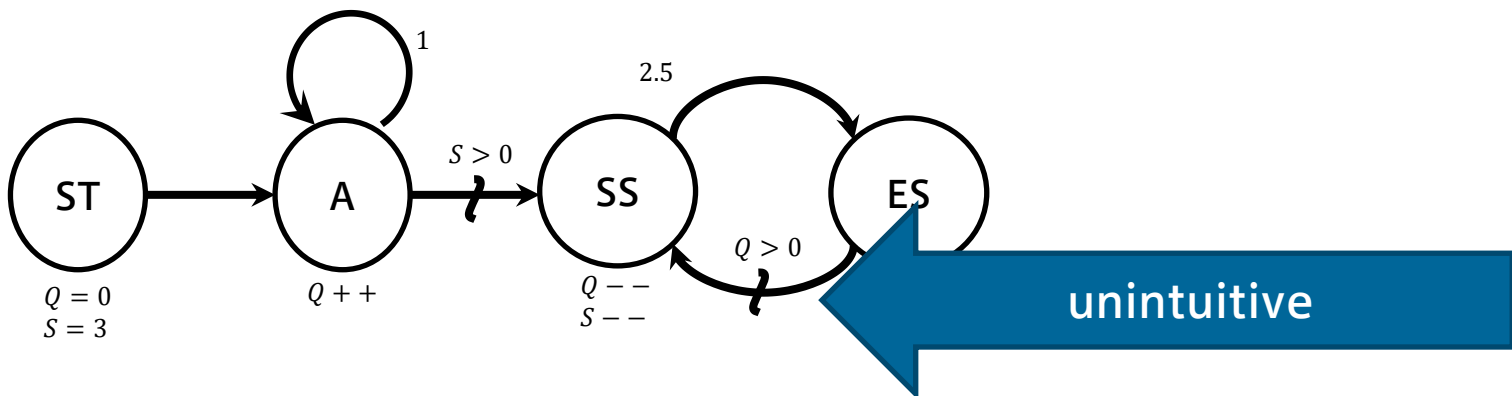
$$\overline{X(t)} = \bar{N}_q = \frac{\rho^2}{2(1-\rho)} (1 + \mu^2 \sigma^2)$$

- Average number of customers in the system

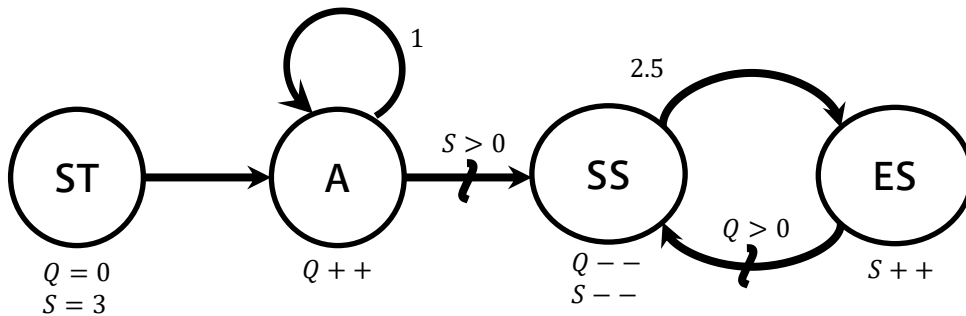
$$\bar{N} = \bar{N}_q + \rho = \frac{\rho}{1-\rho} - \frac{\rho^2}{2(1-\rho)} (1 - \mu^2 \sigma^2)$$

OTHER SIMULATION ENVIRONMENTS

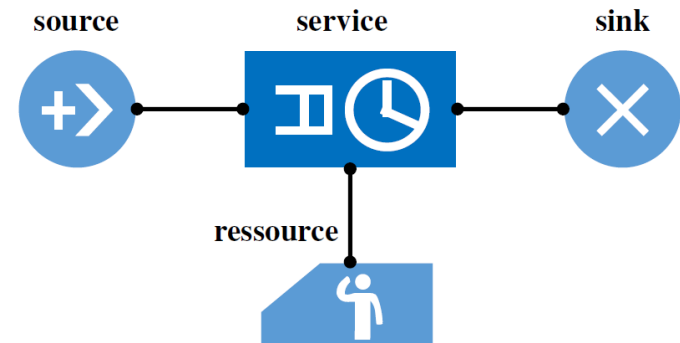
- Most DES models are based on entities being processed in a system
- Therefore they use very similar process structures
- Event Graph description sometimes unnecessary general and unintuitive



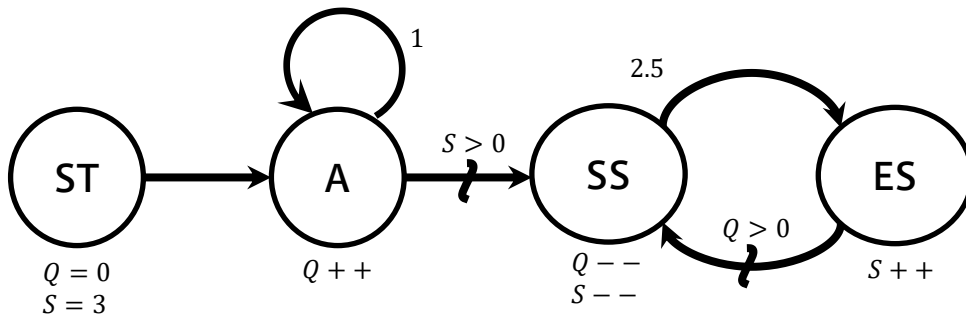
- DES Simulators for simulation of processes usually use a more intuitive description



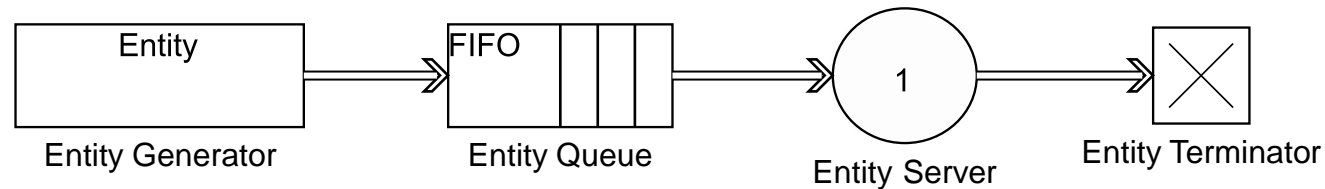
DES Modeling in
AnyLogic



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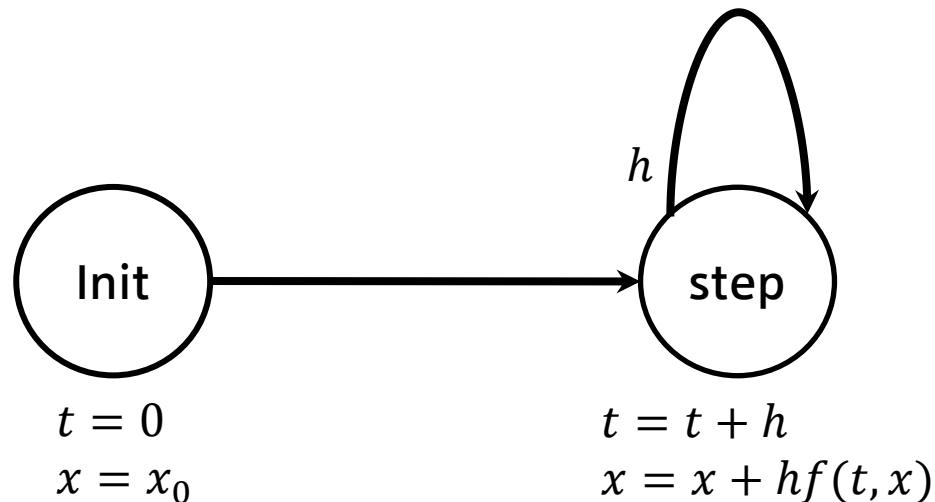


DES Modeling in
SimEvents



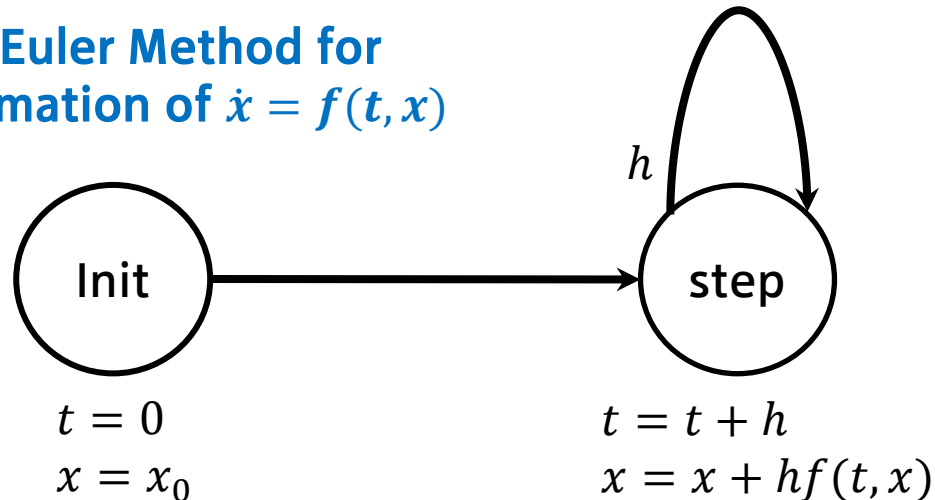
EVENT GRAPHS BEYOND ENTITIES

- DES / Event Graphs not only interesting for queuing systems.



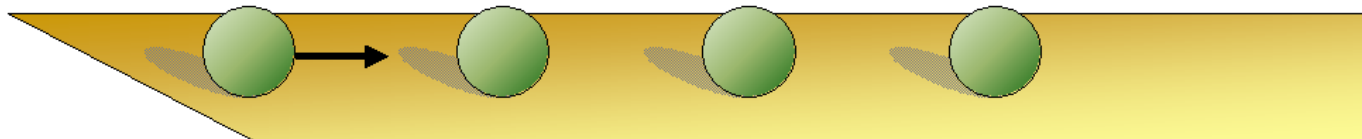
- DES / Event Graphs not only interesting for queuing systems.

Explicit Euler Method for
approximation of $\dot{x} = f(t, x)$



- DES / Event Graphs not only interesting for queuing systems.

Case Study 1: Collision of Spheres



- DES / Event Graphs not only interesting for queuing systems.

