

## Goal driven error estimates

Classical error estimators estimate the error  $u - u_h$  in the energy norm  $V$  for the problem: Find  $u \in V$  such that

$$A(u, v) = f(v) \quad \forall v \in V \quad (1)$$

and  $u_h \in V_h \subset V$  is the corresponding Galerkin solution.

Some applications require to compute certain values (such as point values, average values, line integrals, fluxes through surfaces, ...). These values are described by linear functionals  $b : V \rightarrow \mathbb{R}$ . We want to design a method such that the error in this goal, i.e.,

$$b(u) - b(u_h) \quad (2)$$

is small. The technique is to solve additionally the dual problem, where the right hand side is the goal functional: Find  $w \in V$  such that

$$A(v, w) = b(v) \quad \forall v \in V. \quad (3)$$

Usually, one cannot solve the dual problem either, and one applies a Galerkin method also for the dual problem: Find  $w_h \in V_h$  such that

$$A(v_h, w_h) = b(v_h) \quad \forall v_h \in V_h. \quad (4)$$

In the case of point values, the solution of the dual problem is the Green function (which is not in  $H^1$ ). The error in the goal is

$$b(u - u_h) = A(u - u_h, w) = A(u - u_h, w - w_h). \quad (5)$$

A rigorous upper bound for the error in the goal is obtained by using continuity of the bilinear-form, and energy error estimates  $\eta^1$  and  $\eta^2$  for the primal and dual problem, respectively:

$$|b(u - u_h)| \leq c \|u - u_h\|_V \|w - w_h\|_V \leq C \eta^1(u_h, f) \eta^2(w_h, b). \quad (6)$$

A good heuristic is the following (unfortunately, not correct) estimate

$$b(u - u_h) = A(u - u_h, w - w_h) \leq c \sum_{T \in \mathcal{T}} \|u - u_h\|_{H^1(T)} \|w - w_h\|_{H^1(T)} \leq C \sum_{T \in \mathcal{T}} \eta_T^1(u_h, f) \eta_T^2(w_h, b) \quad (7)$$

The last step would require a local reliability estimate. But, this is not true. We can interpret (7) that way: The local estimators  $\eta_T^2(w_h)$  provide a way for weighting the primal local estimators according to the desired goal.