

21. Sei $v := (x, y, z)^T$.

$$\frac{\partial f}{\partial x}(v) = y, \quad \frac{\partial f}{\partial y}(v) = x + z \cdot \cos(yz), \quad \frac{\partial f}{\partial z}(v) = y \cdot \cos(yz);$$

$$\frac{\partial^2 f}{\partial^2 x}(v) = 0, \quad \frac{\partial^2 f}{\partial y \partial x}(v) = 1, \quad \frac{\partial^2 f}{\partial z \partial x}(v) = 0,$$

$$\frac{\partial^2 f}{\partial^2 y} = -z^2 \cdot \sin(yz), \quad \frac{\partial^2 f}{\partial x \partial y}(v) = 1, \quad \frac{\partial^2 f}{\partial z \partial y}(v) = -z^2 \cdot \sin(yz) + \cos(yz),$$

$$\frac{\partial^2 f}{\partial^2 z}(v) = -y \cdot \sin(yz), \quad \frac{\partial^2 f}{\partial x \partial z}(v) = 0, \quad \frac{\partial^2 f}{\partial y \partial z}(v) = -y^2 \cdot \sin(yz) + \cos(yz);$$

$$df(v) = \begin{pmatrix} y \\ x + z \cdot \cos(yz) \\ y \cdot \cos(yz) \end{pmatrix}^T.$$

$$[df(1, 1, 0)^T] \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = (1 \ 1 \ 1) \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = 2.$$

$$23. \frac{\partial f}{\partial x_1}(x) = 2x_1, \frac{\partial f}{\partial x_2}(x) = x_3, \frac{\partial f}{\partial x_3}(x) = x_2$$

$$\Rightarrow df(x) = (2x_1, x_3, x_2)$$

$$\Rightarrow df(1,1,1) = (2, 1, 1).$$

$$\text{Seien } (2, 1, 1) \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = 1/2 \text{ und } \sqrt{v_1^2 + v_2^2 + v_3^2} = 1.$$

$$\text{Also } 2v_1 + v_2 + v_3 = 1/2$$

$$v_1^2 + v_2^2 + v_3^2 = 1.$$

$$\text{Für } v_1 := 1/4 \Rightarrow v_2 = -v_3 \text{ und somit}$$

$$(1/4)^2 + (-v_3)^2 + v_3^2 = 1 \Leftrightarrow 2v_3^2 = 15/16$$

$$\Leftrightarrow v_3 = \sqrt{15/32}.$$

$$\text{Daher sei } v = (1/4, -\sqrt{15/32}, \sqrt{15/32})^T.$$

$$2h. \quad f(x,y) = \begin{cases} xy \frac{x^2 - y^2}{x^2 + y^2}, & (x,y) \neq (0,0) \\ 0, & (x,y) = (0,0) \end{cases}$$

$$\frac{\partial f}{\partial x}(x,y) = \frac{y(x^4 + 4x^2y^2 - y^4)}{(x^2 + y^2)^2} \quad \begin{array}{cc} y \rightarrow 0 & x \rightarrow 0 \\ \hline & \hline \end{array} \begin{array}{cc} 0 & 0 \\ -y & 0 \end{array}$$

$$\frac{\partial^2 f}{\partial y \partial x}(x,y) = \frac{x^6 + 9x^4y^2 - 9x^2y^4 - y^6}{(x^2 + y^2)^3}$$

$$\frac{\partial f}{\partial y}(x,y) = \frac{x(x^4 - 4x^2y^2 - y^4)}{(x^2 + y^2)^2} \quad \dots \quad 0$$

$$\frac{\partial^2 f}{\partial x \partial y}(x,y) = \frac{x^6 + 9x^4y^2 - 9x^2y^4 - y^6}{(x^2 + y^2)^3}$$

$$\frac{x^6 + 9x^4y^2 - 9x^2y^4 - y^6}{(x^2 + y^2)^3} \xrightarrow{x \rightarrow 0} \frac{-y^6}{(y^2)^3} = -1$$

$$\xrightarrow{y \rightarrow 0} \frac{x^6}{(x^2)^3} = 1$$

⇒ Zweite Ableitungen im Punkt (0,0) unstetig.

Satz von Schwarz gilt nicht.

„Widerspruch“:

$$\left. \begin{array}{l} \frac{\partial f}{\partial x}(x,y) \xrightarrow{y \rightarrow 0} 0 \\ \xrightarrow{x \rightarrow 0} -y \xrightarrow{y \rightarrow 0} 0 \end{array} \right\} \begin{array}{l} \text{l\"ast sich stetig auf } 0 \\ \text{fortsetzen} \end{array}$$

$$\frac{\partial f}{\partial y}(x,y) \text{ analog}$$

Abl. von $\frac{\partial f}{\partial x}(x,y)$ nach y an der Stelle $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$:

$$\frac{\partial^2 f}{\partial y \partial x}(0,0) = \lim_{s \rightarrow 0} \frac{1}{s} \cdot \left(\frac{\partial f}{\partial x} \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) - \frac{\partial f}{\partial x} \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix} \right) \right) = \frac{1}{s} \cdot \frac{-s^5}{s^4} = -1.$$

Analoges Argument f\"ur $\frac{\partial f}{\partial y} \mapsto \frac{\partial^2 f}{\partial x \partial y}$.

$$25. F'(t) = (h(t, \beta(t)) \beta'(t) - h(t, \alpha(t)) \alpha'(t) + \int_{\alpha(t)}^{\beta(t)} \frac{\partial h}{\partial t}(t, s) ds, \text{ wobei}$$

$$\alpha(t) = t, \alpha'(t) = 1, \beta(t) = 1+t^2, \beta'(t) = 2t, \\ h(s, t) = \sin(st).$$

$$F'(t) = \sin(t(1+t^2)) 2t - \sin(t^2)t + \int_t^{1+t^2} s \cdot \cos(ts) ds.$$

Und jetzt, jeweils die Stammfunktionen:

$$\int \sin(tx) dx \Big|_{dx = 1/t du}^{u=tx} = \frac{1}{t} \int \sin u du = -\frac{1}{t} \cos(tx).$$

$$" \int (1+t^2) - " \int (t) = \frac{1}{t} (\cos(t^2) - \cos(t+t^3))$$

$$F'(t) = \frac{1}{t^2} (\sin(t+t^3) (t+3t^3) + \cos(t+t^3) - \sin(t^2) \cdot 2t^2 - \cos(t^2)).$$

Es kommt bei beiden Methoden dasselbe heraus.

26. Zz: $\forall f \in C^1(\mathbb{R}^2, \mathbb{R}) \exists A: \mathbb{R}^2 \rightarrow \mathbb{R}: T \text{ Tangentialebene.}$

Prop. 10.1.11. $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ stetig partiell differenzierbar:

(ii) $v \in \mathbb{R}^2, v+u \in \mathbb{R}^2 \setminus \{v\}$

$$\Rightarrow f(v+u) = f(v) + df(v)u + \|u\|_\infty \varepsilon(u)$$

mit $\lim_{u \rightarrow 0} \varepsilon(u) = 0$.

Weil $f \in C^1(\mathbb{R}^2, \mathbb{R})$ differenzierbar ist, auch partiell.

Wähle $v := (x_0, y_0)$,

$$u := (x, y) - (x_0, y_0) = (x - x_0, y - y_0),$$

$$\Rightarrow v+u = (x, y),$$

$$\Rightarrow (x_0, y_0, f(x_0, y_0)) = (x_0, y_0, z_0),$$

$$A := df(v).$$

$$\lim_{u \rightarrow 0} \varepsilon(u) = \lim_{u \rightarrow 0} \frac{|f(v+u) - f(v) - df(v)u|}{\|u\|_\infty} = 0.$$

$$27. \frac{\partial f}{\partial x}(x, y, z) = e^{x+yz}, \quad \frac{\partial f}{\partial y}(x, y, z) = ze^{x+yz},$$

$$\frac{\partial f}{\partial z}(x, y, z) = ye^{x+yz}.$$

$$df(x, y, z) = (e^{x+yz}, ze^{x+yz}, ye^{x+yz}),$$

$$df(1, 0, 1) = (e, e, 0).$$

$$d^2f(x, y, z) = \begin{bmatrix} \frac{\partial^2 f}{\partial x \partial x}(x, y, z) & \frac{\partial^2 f}{\partial x \partial y}(x, y, z) & \frac{\partial^2 f}{\partial x \partial z}(x, y, z) \\ \frac{\partial^2 f}{\partial y \partial x}(x, y, z) & \frac{\partial^2 f}{\partial y \partial y}(x, y, z) & \frac{\partial^2 f}{\partial y \partial z}(x, y, z) \\ \frac{\partial^2 f}{\partial z \partial x}(x, y, z) & \frac{\partial^2 f}{\partial z \partial y}(x, y, z) & \frac{\partial^2 f}{\partial z \partial z}(x, y, z) \end{bmatrix}$$

$$= \begin{bmatrix} e^{x+yz} & ze^{x+yz} & ze^{x+yz} \\ ze^{x+yz} & z^2 e^{x+yz} & (yz+1)e^{x+yz} \\ ye^{x+yz} & (zy+1)e^{x+yz} & y^2 e^{x+yz} \end{bmatrix}.$$

$$\Rightarrow d^2f(1, 0, 1) = \begin{bmatrix} e & e & 0 \\ e & e & e \\ 0 & e & 0 \end{bmatrix}.$$

$$(1, 1, 0) \begin{bmatrix} e & e & 0 \\ e & e & e \\ 0 & e & 0 \end{bmatrix} \begin{pmatrix} e \\ ze \\ e \end{pmatrix} = 3e.$$

$$28. \quad f(x) = f(y) + \sum_{l=1}^q \frac{1}{l!} d^l f(y) \underbrace{(x-y, \dots, x-y)}_{l\text{-mal}} + R_q(x).$$

$$df(x, y, z) = \left(1, -\frac{1}{y^2 z (1 + 1/yz)}, -\frac{1}{yz^2 (1 + 1/yz)} \right)$$

$$df(1, 1, 1) = (1, -1/2, -1/2)$$

$$d^2 f(x, y, z) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \frac{2yz+1}{y^2(yz+1)^2} & \frac{1}{(yz^2+1)^2} \\ 0 & \frac{1}{(yz+1)^2} & \frac{2yz+1}{z^2(yz+1)^2} \end{bmatrix}$$

$$d^2 f(1, 1, 1) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3/4 & 1/4 \\ 0 & 1/4 & 3/4 \end{bmatrix}$$

$$T_2(x, y, z) = (1 + \log 2) + (1, -1/2, -1/2) \begin{pmatrix} x-1 \\ y-1 \\ z-1 \end{pmatrix} +$$

$$(x-1, y-1, z-1) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3/4 & 1/4 \\ 0 & 1/4 & 3/4 \end{bmatrix} \begin{pmatrix} x-1 \\ y-1 \\ z-1 \end{pmatrix} \cdot 1/2 =$$

$$1 + \log 2 + x - \frac{y+z}{2} + \frac{(y-1)^2 + (z-1)^2}{2}.$$

$$29. d\mathbf{f}(x,y) = (\cos x + 2x - y \cdot \sin(xy), -x \cdot \sin(xy))$$

$$d\mathbf{f}(0,1) = (1,0)$$

$$d^2\mathbf{f}(x,y) = \begin{bmatrix} -\sin x + 2 - y^2 \cos(xy) & -\sin(xy) - xy \cdot \cos(xy) \\ -\sin(xy) - xy \cdot \cos(xy) & -x^2 \cos(xy) \end{bmatrix}$$

$$d^2\mathbf{f}(0,1) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$T_2(x,y) = \mathbf{f}(0,1) + \frac{1}{1!} (1,0) \left(\begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) +$$

$$\frac{1}{2!} \left(\begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \left(\begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right) =$$

$$1 + x + \frac{x^2}{2}.$$

30.

$$\frac{dh}{dx}(x) = \left(\cos x \cdot 2 \sin x \cdot \cos x + \sin^2 x \cdot (-\sin x) \right) \frac{1}{\sin^2 x \cdot \cos x}$$

$$= \frac{2 \cos^2 x - \sin^2 x}{\sin x \cdot \cos x}$$

Kettenregel: $d(f \circ g)(t) = df(g(t)) dg(t) =$

$$df(\underbrace{\sin^2 t}_{=: a}, \underbrace{\cos t}_{=: b}) dg(t) = d \ln(a \cdot b) dg(t) =$$

$$\left(\frac{1}{\cos t}, \frac{1}{\sin^2 t} \right) \begin{pmatrix} \cos t \cdot 2 \sin t \\ -\sin t \end{pmatrix} = \dots \quad \checkmark$$