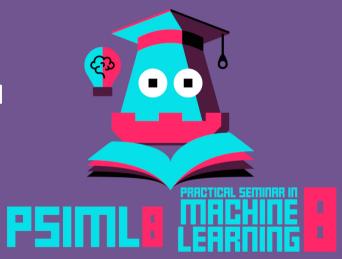
Convolutional NN

Introduction

Uros Stegic *uros.stegic@everseen.com*



Description



- ► Process & analyze visual signal
- Extract information from visual signal
- ► Perform on raw signal (pixel intensities values)

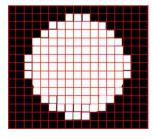
Enhance Intuition



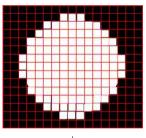
Computer Graphics

$$(x_0, y_0) = (9, 8)$$

 $r = 7$



Computer Vision



$$(x_0, y_0) = (9, 8)$$

 $r = 7$

Tasks in Computer Vision



- ► Object Recognition
- ► Image Retrieval
- ▶ Object Detection
- OCR
- Pose Estimation
- ...

- ▶ Tracking
- Scene Reconstruction
- Optical Flow
- Semantic Segmentation
- ► Image Reconstuction
- ...

Tasks in Computer Vision



- ► Object Recognition
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- **.**..

Convolution Operator - Definition



Let $A, B \in \mathcal{D} \subseteq \mathbb{R}^{n \times n}$. Convolution operator, denoted as * maps the space $\mathcal{D} \times \mathcal{D}$ to a field of real numbers and is defined as follows:

$$A*B = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij}B_{ij}$$



$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} * \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} * \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = 2 * 1 + 4 * 1 + 6 * 1 + 8 * 1 = 20$$



$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} * \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = 2 * 1 + 4 * 1 + 6 * 1 + 8 * 1 = 20$$



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$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} * \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = 2 * 1 + 4 * 1 + 6 * 1 + 8 * 1 = 20$$

Filters



[211 138 151 129 140 221	39 44 73 101 122 115	200 184 190 123 153 77	102 110 114 181 231 244	174 193 189 201 209 198	25 30 41 169 157 149	90 92 105 117 124 156	144 136 128 191 113 247	*	$\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$	1 0 1	0 1 0	
[221	115	77	244	198	149	156	247]					

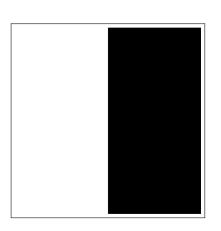
Filters - Examples



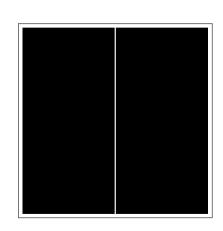
- ► Vertical Edge Extractor
- ► Horizontal Edge Extractor
- ► Sobel filter
- Sharpen
- ► Gaussian Blur

Filters - Edge Extractor





$$*\begin{bmatrix}1 & 0 & -1\\1 & 0 & -1\\1 & 0 & -1\end{bmatrix} =$$



Filters - Edge Extractor





$$*\begin{bmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} =$$

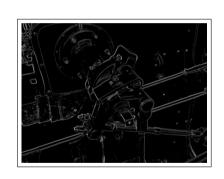


Filters - Sobel





$$*\begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix} =$$



Filters - Gaussian Blur





$$*\frac{1}{256}\begin{bmatrix}1&4&6&4&1\\4&16&24&16&4\\6&24&36&24&6\\4&16&24&16&4\\1&4&6&4&1\end{bmatrix}=$$



Multiple Input Channels



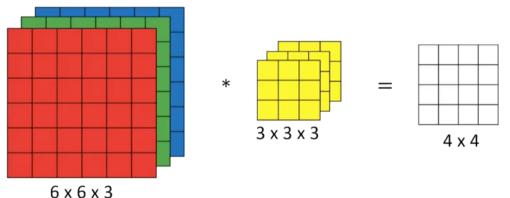
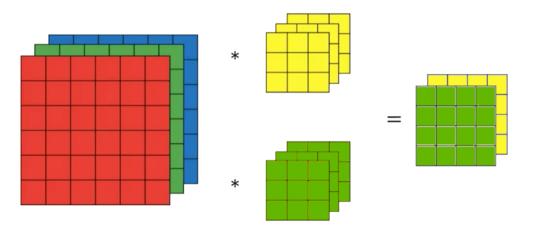


Figure: Convolution of multichannel image

Multiple Filters





Basic Concepts



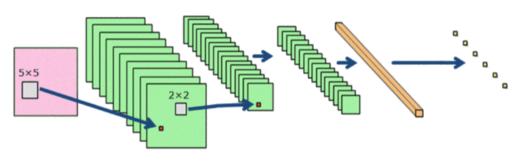


Figure: Convolutional layers stacked

Basic Concepts - Takeaway



- ► Image Classification
- ► Parameters (filters) Learning [LBD+89]
- ▶ Weight Sharing
- ► Feature Extraction
- ► Translation invariant

Basic Concepts - Feature Abstractions



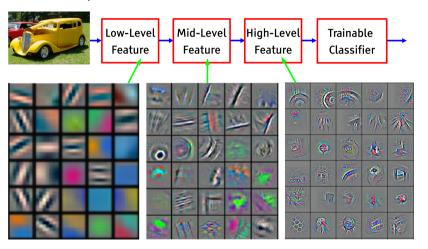


Figure: Feature Visualization [ZF13]

Basic Concepts - Pooling Layers



- Sampling important Features
- ► Reduce Computation Time
- Make Features Robust

Basic Concepts - Pooling Layers (Example)



Pooling Layer - Max Pooling

$$\begin{bmatrix} 9 & 2 & 4 & 1 \\ 3 & 1 & 8 & 2 \\ 4 & 5 & 9 & 2 \\ 5 & 6 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 9 & 8 \\ 6 & 9 \end{bmatrix}$$

Basic Concepts - Architecture



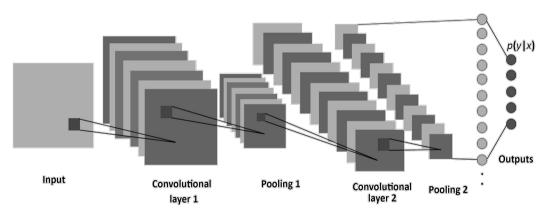


Figure: Convolutional Neural Network - Example

CNN Architecture - Lenet-5



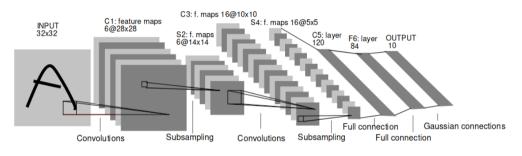


Figure: Lenet-5 Architecture [LBBH98]

CNN Architecture - AlexNet

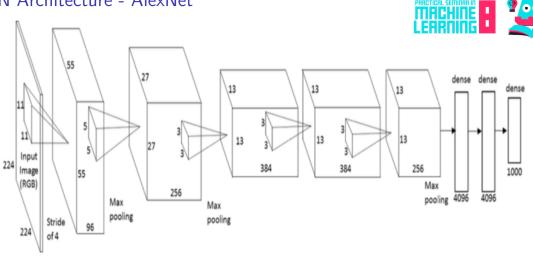


Figure: AlexNet Architecture [KSH12]

CNN Architecture - VGG



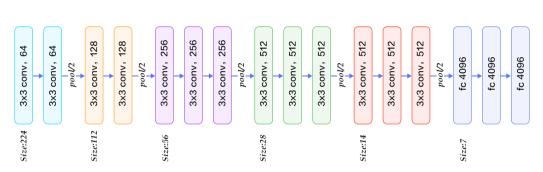


Figure: VGG Architecture

CNN - Problems



- ► Vanishing Gradient
- Exploding Gradient
- Computational Complexity

Residual Block



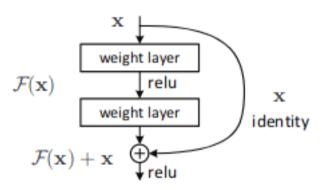


Figure: Residual Block (Skip Connection) [HZRS15]

Residual Network

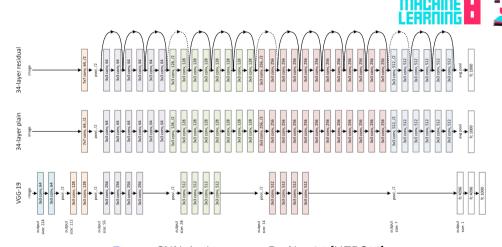


Figure: CNN Architecture - ResNet-34 [HZRS15]

1x1 Convolution



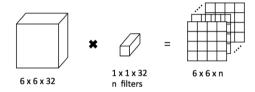


Figure: 1x1 Convolution [LCY13]

Inception Module - Idea Filter concatenation 1x1 convolutions 3x3 convolutions 5x5 convolutions 3x3 max pooling Previous layer

Figure: Inception Module Naive Version [SLJ+14]

Inception Module - Redone



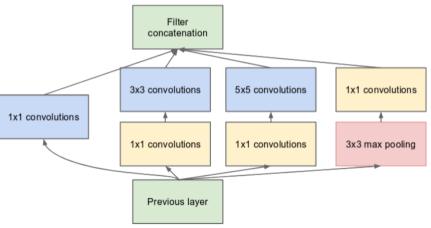


Figure: Inception Module With Dimension Reduction [SLJ⁺14]

Inception Network



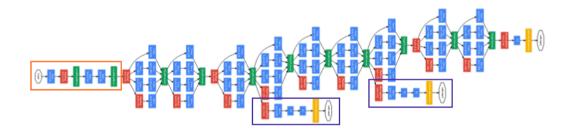


Figure: Inception Network (GoogLeNet) [SLJ⁺14]



CONVERGENCE

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