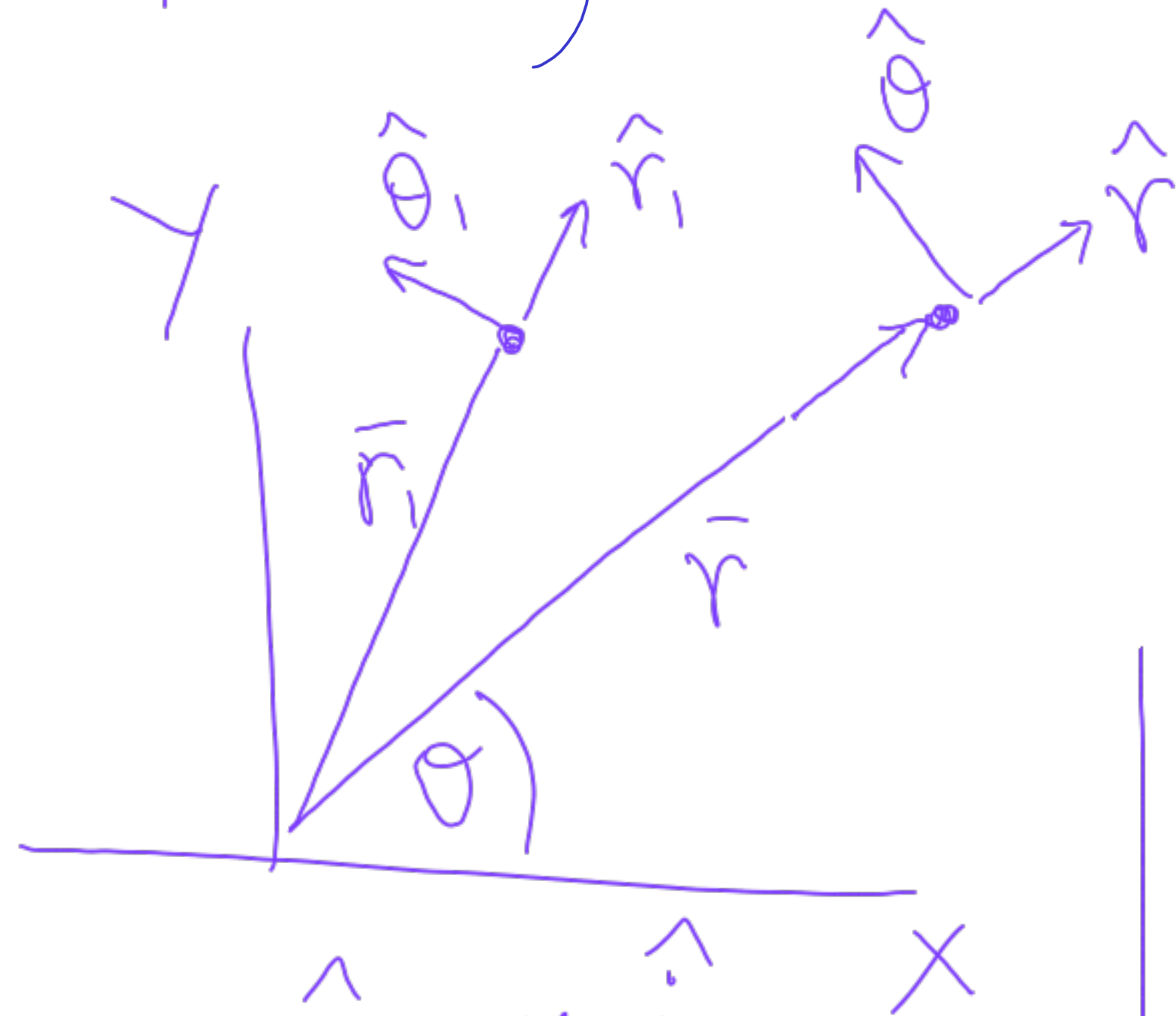


one orthogonal set to another orthogonal set of co-ordinates

$$(\hat{x}, \hat{y}, \hat{z})$$

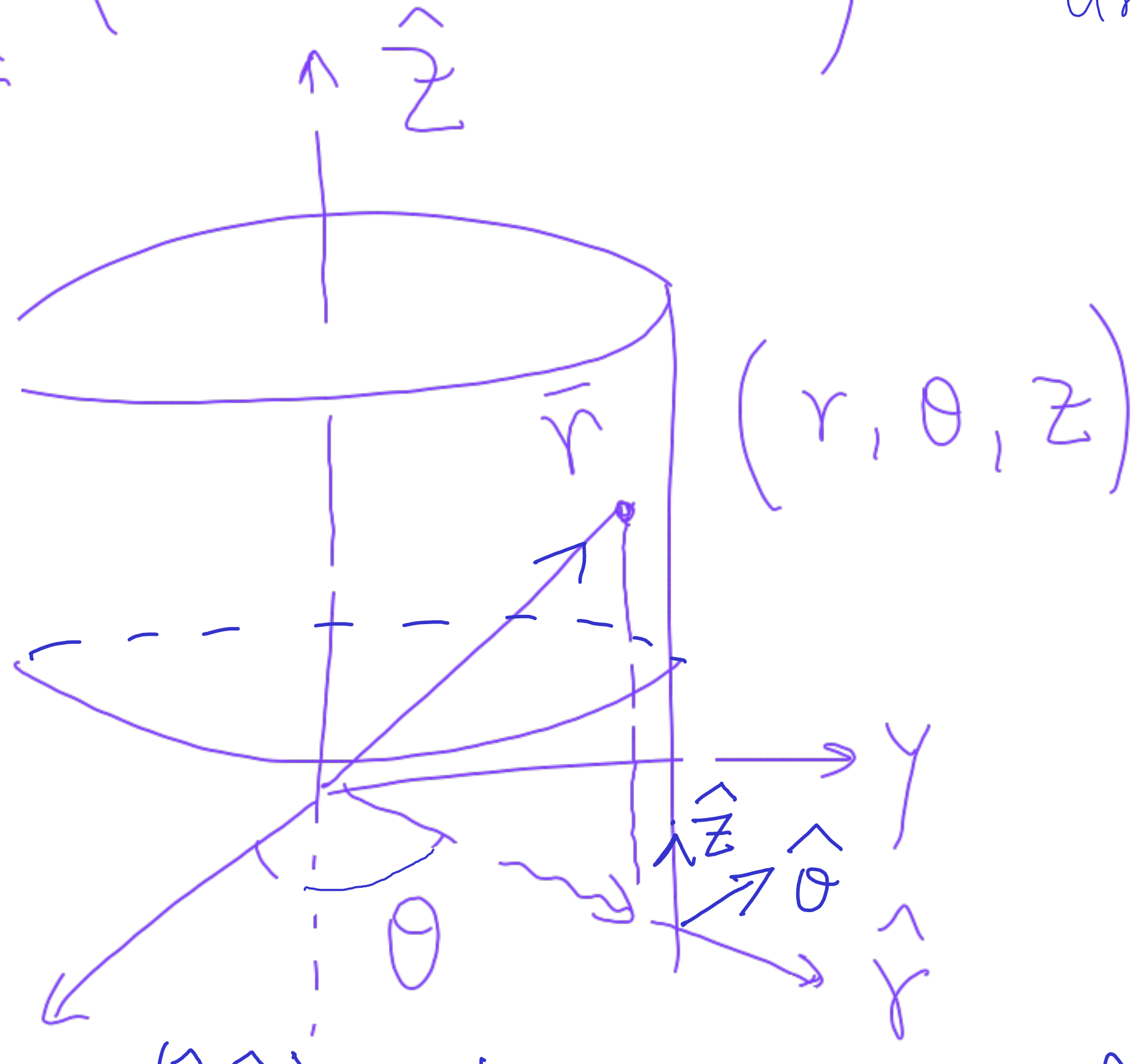
$$(\hat{r}, \hat{\theta}, \hat{z})$$

Hat ^ implies unit vector

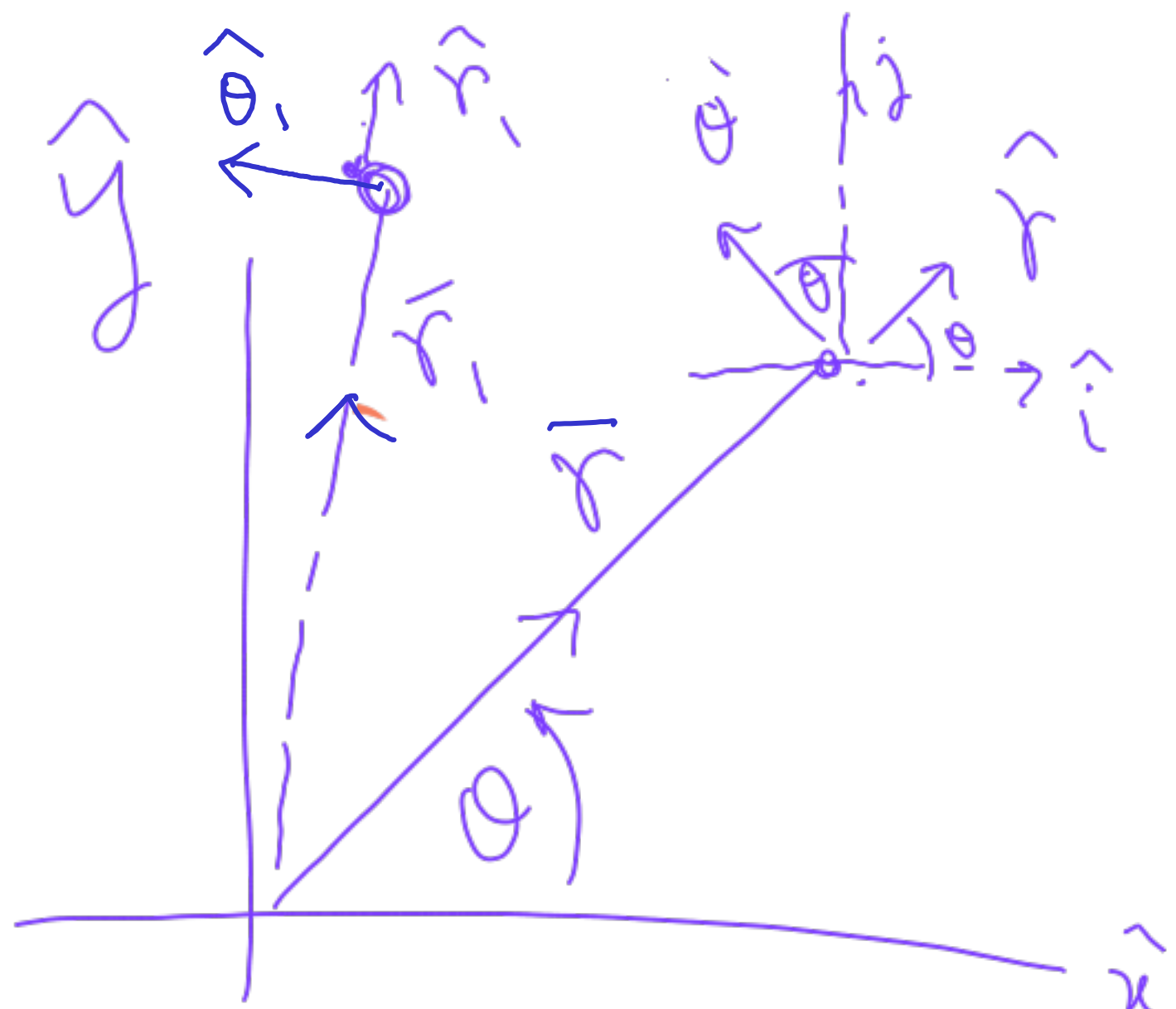


$$\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$$

$$= r \hat{r}$$



While  $(\hat{x}, \hat{y}, \hat{z})$  are fixed in space,  $(\hat{r}, \hat{\theta})$  keeps changing depending on  $\vec{r}$



$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1} \left( \frac{y}{x} \right)$$

$$\vec{r} = r \hat{r}$$

$$\vec{r} = x \hat{i} + y \hat{j}$$

$$d\vec{r} = dx \hat{i} + dy \hat{j} = dr \hat{r} + r d\theta \hat{\theta}$$

(prove this)

$$\begin{aligned} \hat{i} &= \cos \theta \hat{r} - \sin \theta \hat{\theta} \\ \hat{j} &= \sin \theta \hat{r} + \cos \theta \hat{\theta} \\ \hat{r} &= \cos \theta \hat{i} + \sin \theta \hat{j} \\ \hat{\theta} &= -\sin \theta \hat{i} + \cos \theta \hat{j} \end{aligned}$$

$$\begin{aligned} \hat{i} &= \hat{x} \\ \hat{j} &= \hat{y} \\ \hat{k} &= \hat{z} \end{aligned}$$

Relation among  
(r, theta, z) & (i-hat, j-hat, k-hat)

Compute velocity  $\frac{d\vec{r}}{dt}$ :

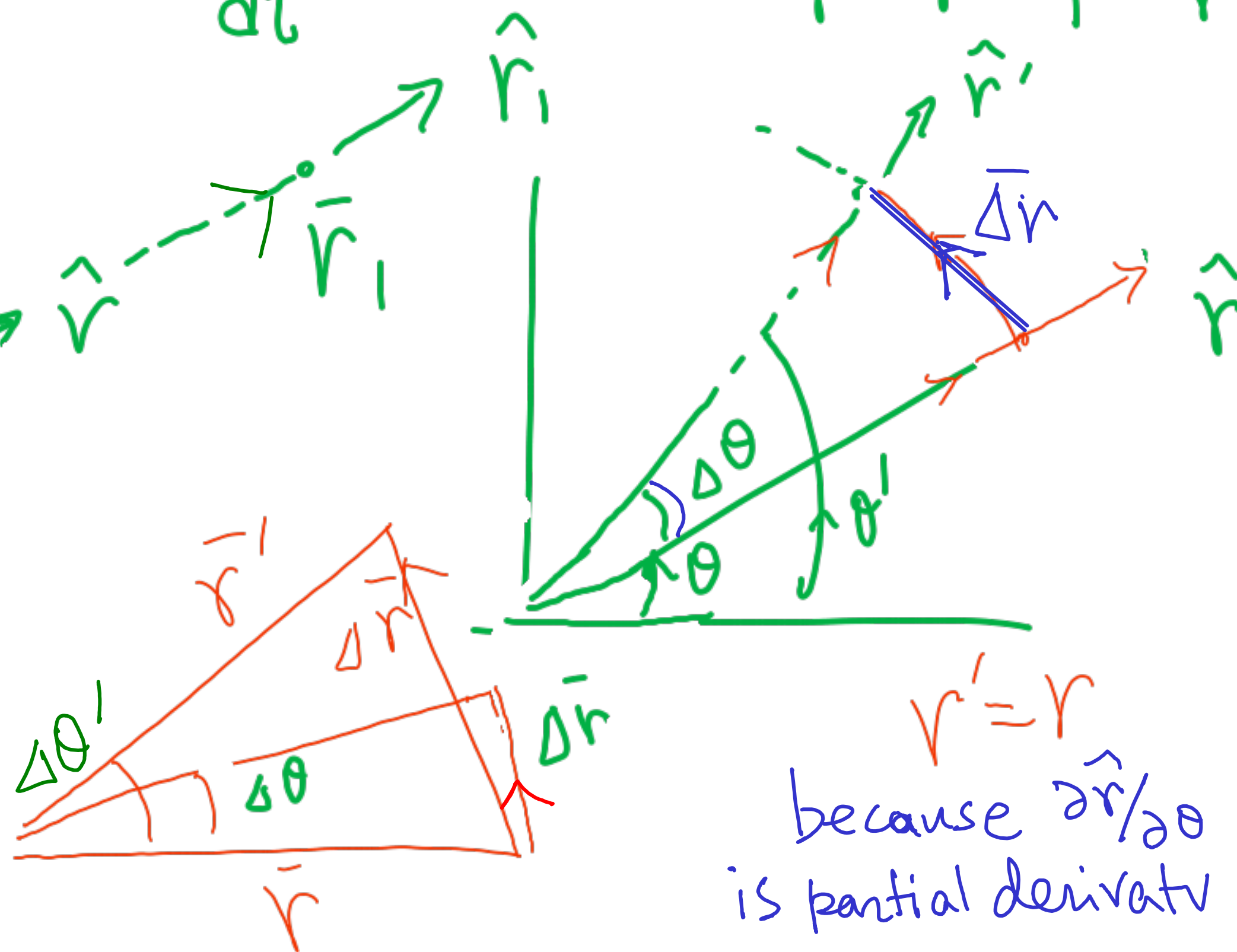
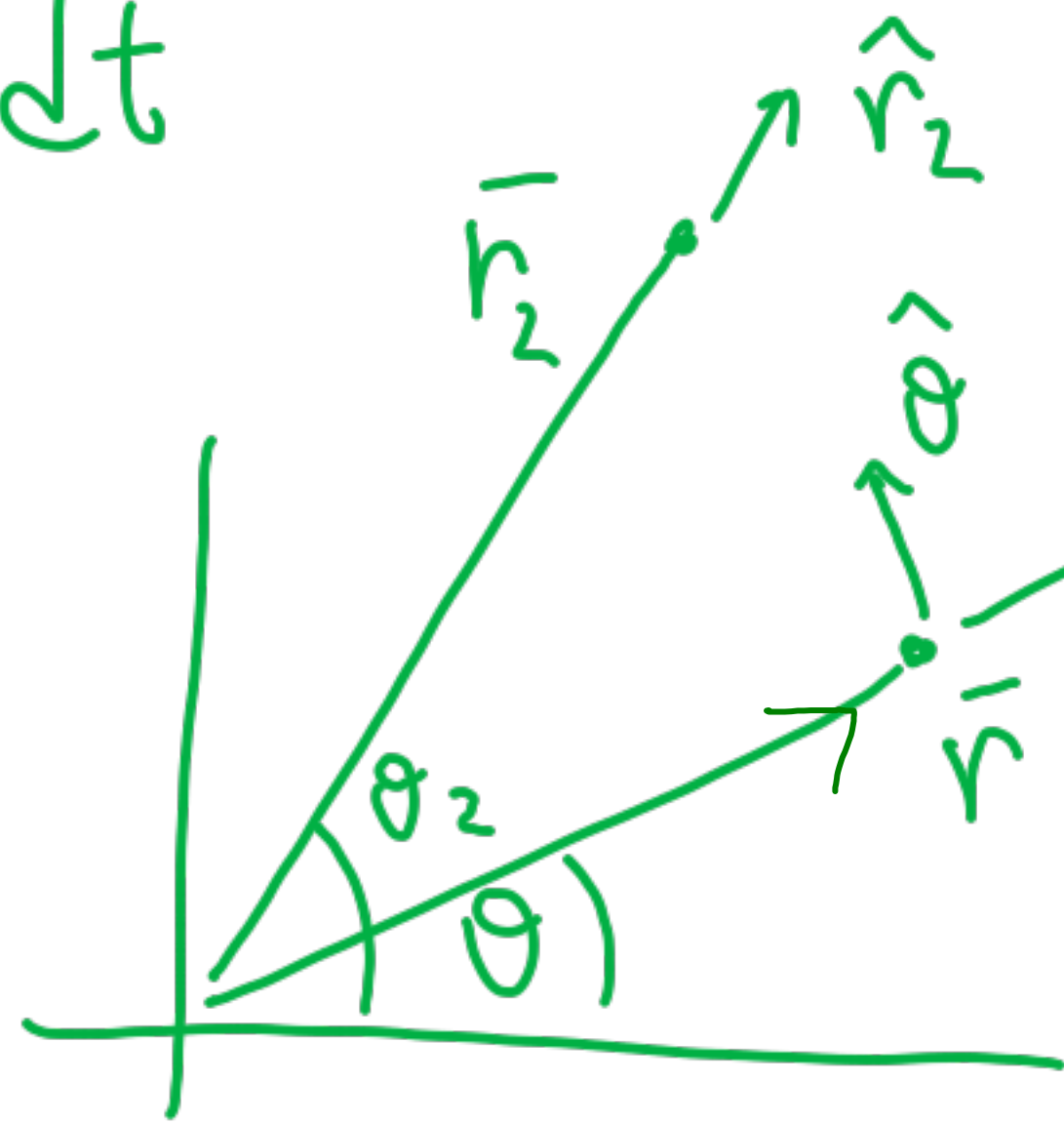
$$\vec{r} = r \hat{r}$$

$$\frac{d\hat{r}}{dt}(r, \theta) = \frac{\partial \hat{r}}{\partial r} \dot{r} + \frac{\partial \hat{r}}{\partial \theta} \dot{\theta}$$

$$\frac{d\vec{r}}{dt} = \dot{r} \hat{r} + r \frac{d\hat{r}}{dt}$$

$$= \dot{r} \hat{r} + r \frac{\partial \hat{r}}{\partial \theta} \dot{\theta}$$

$$= \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$



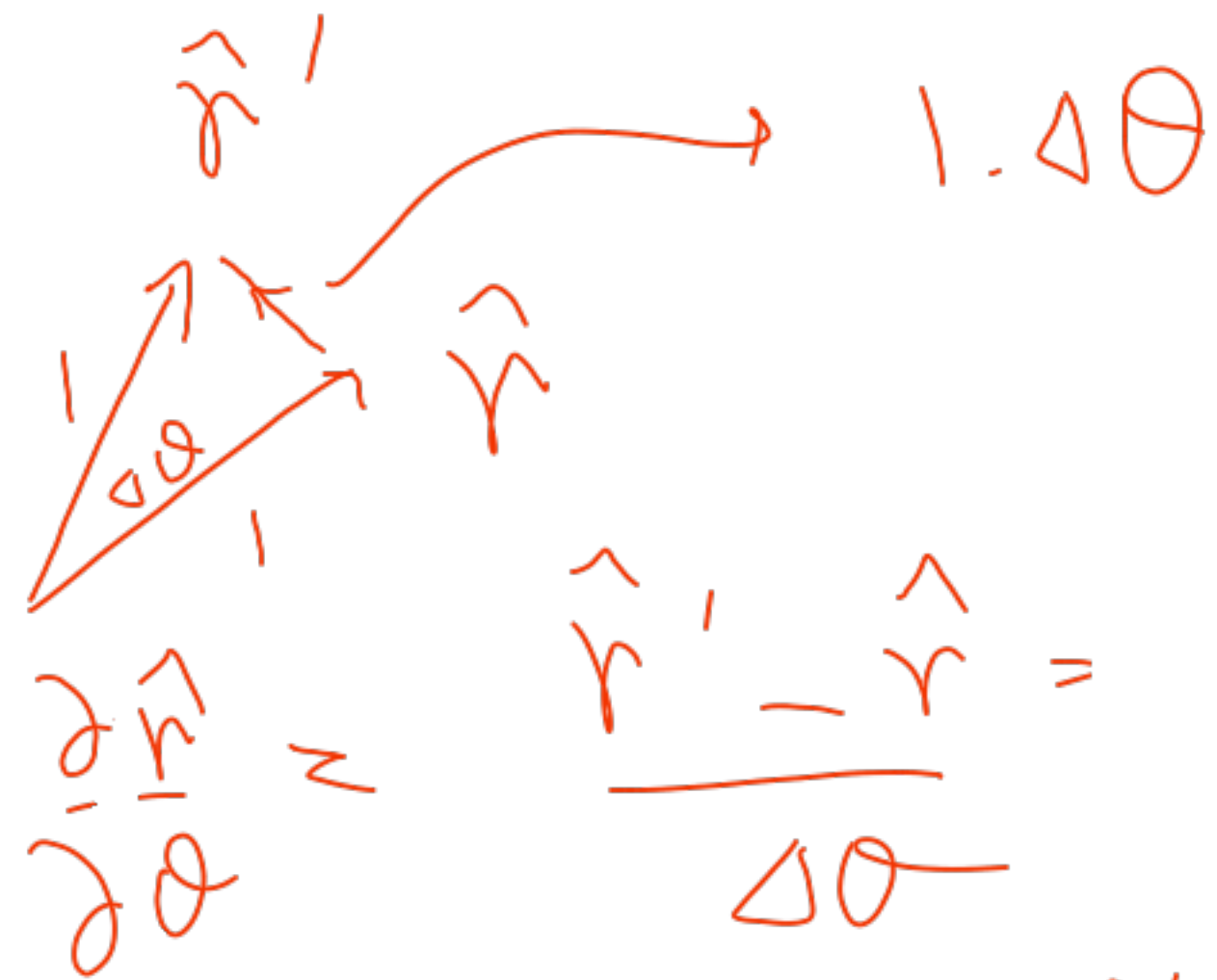
As  $\Delta\theta \rightarrow 0$ ,  $\Delta\vec{r}$  becomes  $\perp$  to  $\vec{r}$

because  $\partial \hat{r} / \partial \theta$  is partial derivative

$$\begin{aligned} \frac{\partial \hat{r}}{\partial \theta} &= \lim_{\Delta\theta \rightarrow 0} \frac{\hat{r}' - \hat{r}}{\Delta\theta} \\ &= \lim_{\Delta\theta \rightarrow 0} \left( \frac{\vec{r}' - \vec{r}}{r' - r} \right) \frac{1}{\Delta\theta} \\ &= \left( \frac{\vec{r}' - \vec{r}}{r' - r} \right) \frac{1}{\Delta\theta} \\ &= \frac{r \Delta\theta}{r \Delta\theta} \hat{\theta} \end{aligned}$$



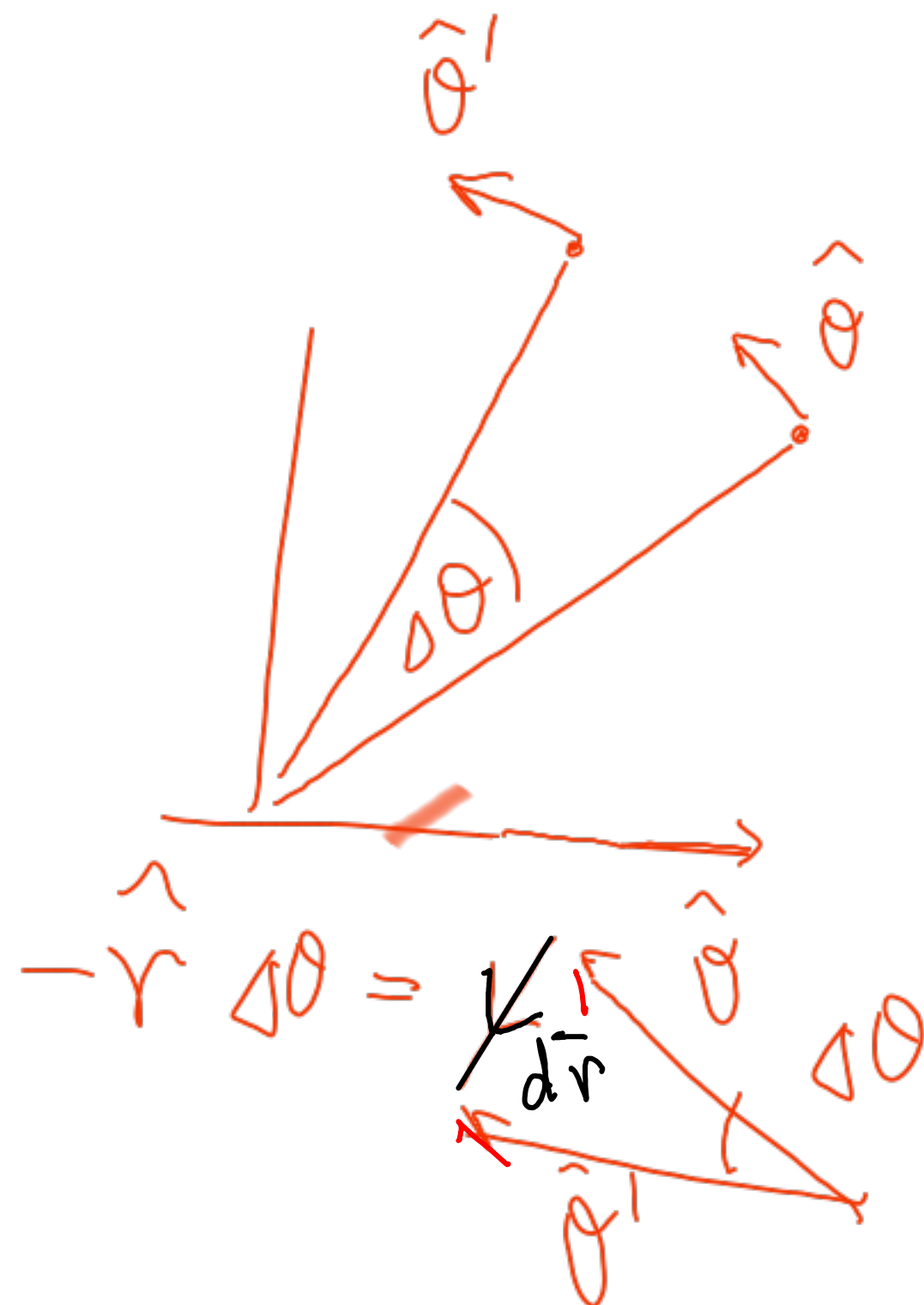
All the partial derivatives  
of the unit vectors.



$$\frac{\partial \hat{r}}{\partial r} = 0$$

$$\frac{\partial \hat{\theta}}{\partial \theta} = 0$$

$$\frac{\partial \hat{r}}{\partial \theta} = -\hat{\theta}$$



Note: as  $\Delta\theta \rightarrow 0$ ,  $d\hat{r}$  becomes  
+ to  $\hat{\theta}$

# Calculate Accel<sup>n</sup>.

$$\frac{\partial \hat{r}}{\partial \theta} = \hat{\theta}$$

$$\bar{v} = \frac{d\bar{r}}{dt} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

$$\frac{d\hat{\theta}}{dt} = \frac{\partial \hat{\theta}}{\partial \theta} \dot{\theta} = -\hat{r} \dot{\theta}$$

$$\frac{\partial \hat{\theta}}{\partial \theta} = -\hat{r}$$

$$\bar{a} = \frac{d^2 \bar{r}}{dt^2} = \ddot{r} \hat{r} + \dot{r} \frac{d\hat{r}}{dt} + \dot{r} \dot{\theta} \hat{\theta} + r \ddot{\theta} \hat{\theta} + r \dot{\theta} \frac{d\hat{\theta}}{dt}$$

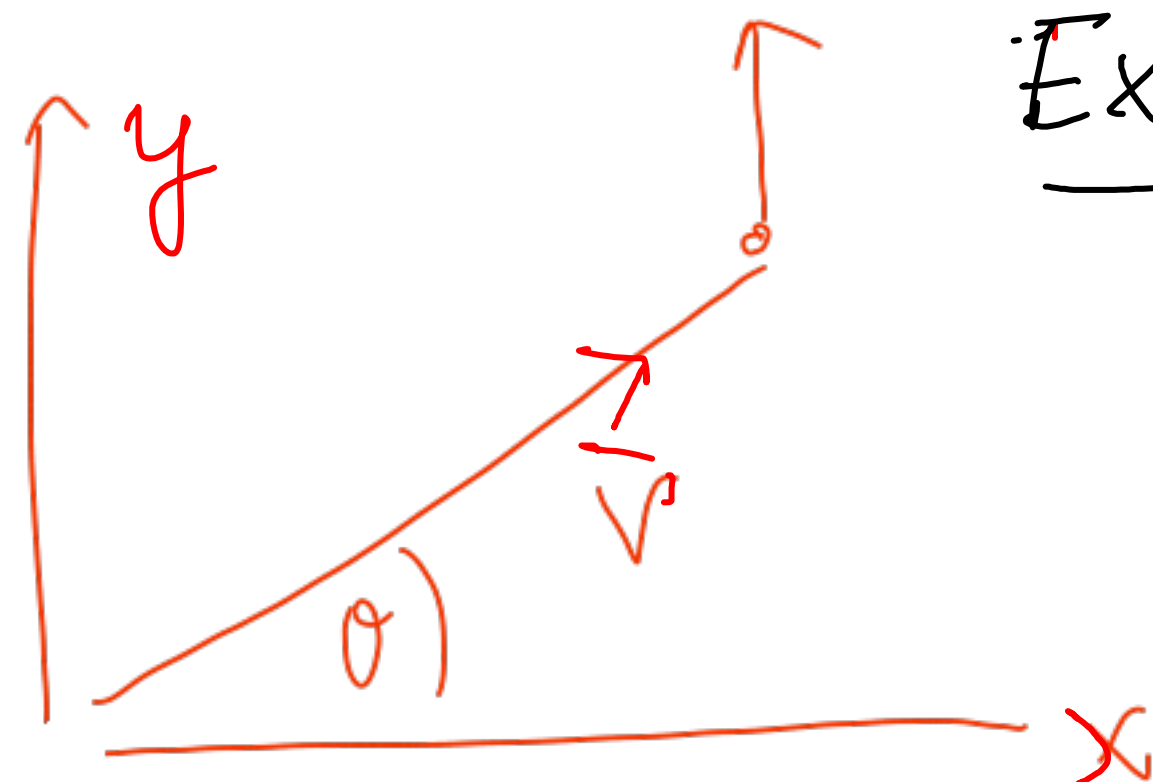
$$= \ddot{r} \hat{r} + \dot{r} \dot{\theta} \hat{\theta} + \dot{r} \dot{\theta} \hat{\theta} + r \ddot{\theta} \hat{\theta} - r \dot{\theta}^2 \hat{r}$$

$$= \hat{r} (\ddot{r} - r \dot{\theta}^2) + \hat{\theta} (2\dot{r} \dot{\theta} + r \ddot{\theta})$$

$$\frac{\partial \hat{r}}{\partial r} = \frac{\partial \hat{\theta}}{\partial r} = 0$$

$$r(t)$$

$$\theta(t)$$



Examples

1) Study circular motion  $\dot{r}=0$   
only  $-r \dot{\theta}^2 \neq 0$   
centripetal accel<sup>n</sup>

2)  $\dot{\theta}=0, \ddot{\theta}=0$

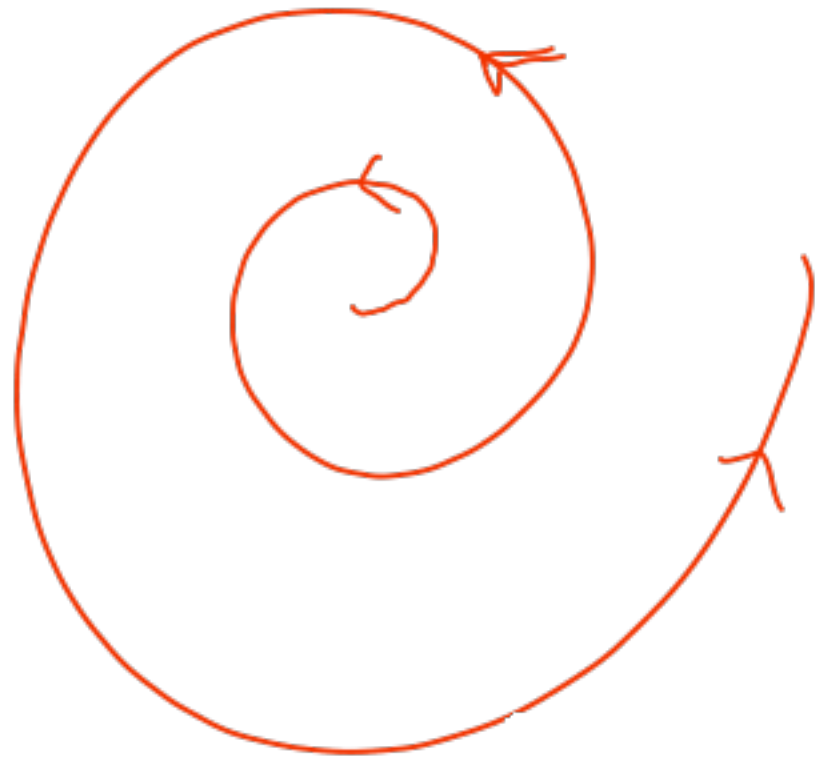
1-D motion along  $\hat{r}$

$$3) \quad \dot{\theta} = \omega_0, \quad \dot{r} = \alpha$$

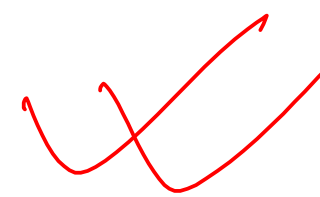
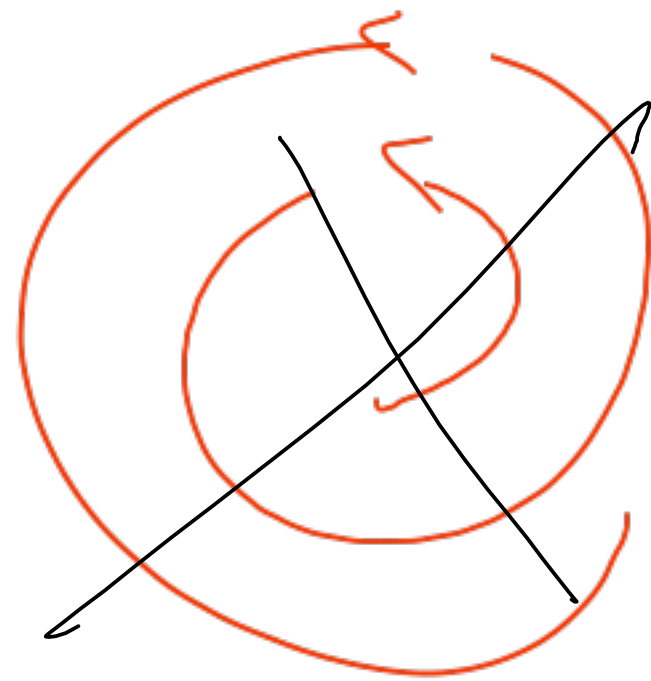
↓

$$r(t) = \alpha t + r_0$$

$$\alpha > 0$$



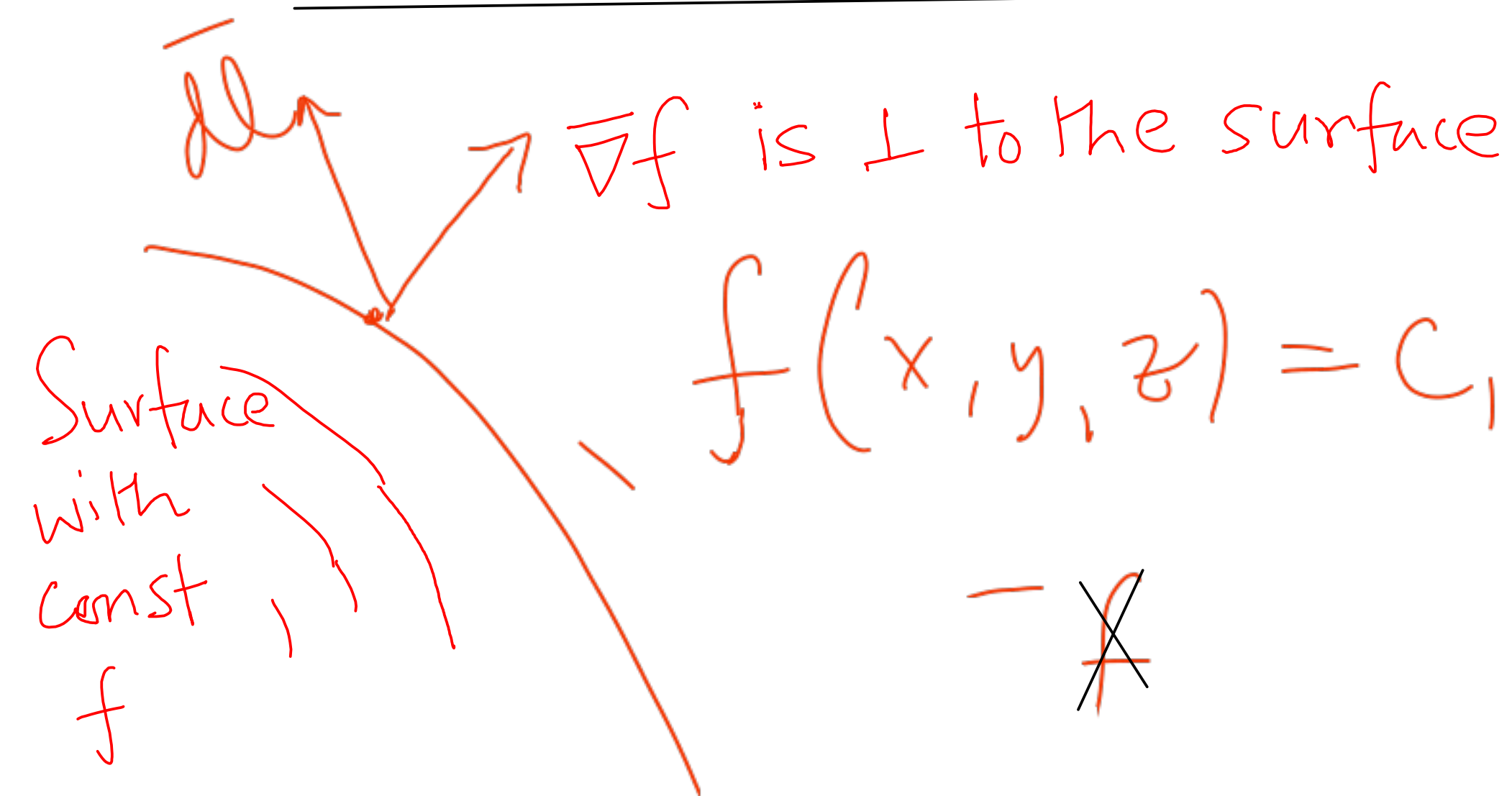
$$\alpha < 0$$



Since  $\dot{\theta} = \omega_0 > 0$   
 $\theta$  keeps increasing  
 while  $r(t)$  decreases

grad, div, curl

certain types of  
all are space derivatives,  
but what's the difference?



$$df = \vec{\nabla} f \cdot d\vec{l} \quad (\text{change in } f \text{ along } d\vec{l})$$

