

# Signal Processing Primer: *Fourier Analysis, Sampling & Interpolation*



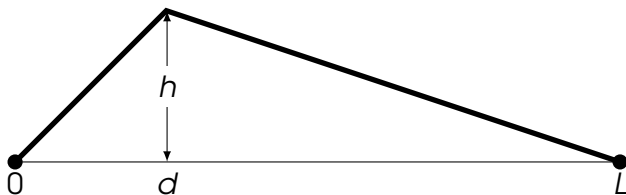
Sibi Raj B Pillai  
srbpteach@gmail  
Subject:EE103 23B3933

# Vibration of a String



Tied String of length  $L$  plucked to height  $h$ .

# Vibration of a String

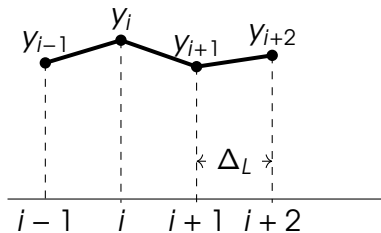


Tied String of length  $L$  plucked to height  $h$ .

What happens if you let it go?

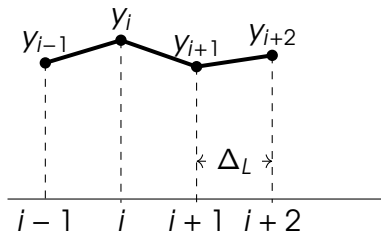
- ☐ String goes straight back to its original shape
- ☐ String snaps to two or more pieces
- ☒ String vibrates randomly, producing audible noise
- ☒ String continues to vibrate, producing sound waves

# Particle Model



Particle neighbours in the string

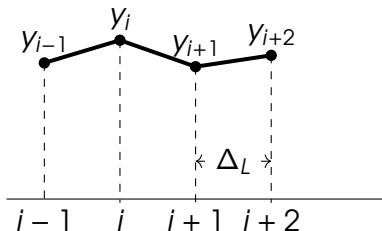
# Particle Model



Particle neighbours in the string

Force on the point  $i$  is  $F_i = \frac{\kappa}{\Delta_L}(y_{i+1} - y_i) + \frac{\kappa}{\Delta_L}(y_{i-1} - y_i)$ .

# Particle Model

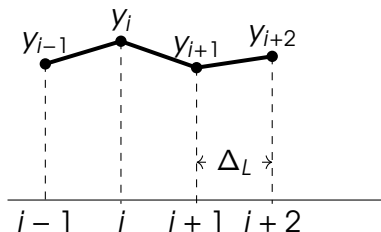


Particle neighbours in the string

Force on the point  $i$  is  $F_i = \frac{\kappa}{\Delta_L}(y_{i+1} - y_i) + \frac{\kappa}{\Delta_L}(y_{i-1} - y_i)$ .

$$\frac{\kappa}{\Delta_L}(y_{i+1} - y_i) + \frac{\kappa}{\Delta_L}(y_{i-1} - y_i) = \underbrace{m(\Delta_L) \frac{\partial^2 y}{\partial t^2}}_{\text{Newton's Law}}$$

# Particle Model

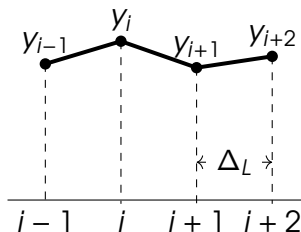


Particle neighbours in the string

Force on the point  $i$  is  $F_i = \frac{\kappa}{\Delta_L}(y_{i+1} - y_i) + \frac{\kappa}{\Delta_L}(y_{i-1} - y_i)$ .

$$\begin{aligned} \frac{\kappa}{\Delta_L}(y_{i+1} - y_i) + \frac{\kappa}{\Delta_L}(y_{i-1} - y_i) &= m(\Delta_L) \frac{\partial^2 y}{\partial t^2} \quad \text{: - Newton's Law} \\ &= \rho \Delta_L \frac{\partial^2 y}{\partial t^2}. \end{aligned}$$

# Particle Model



$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial^2 y}{\partial t^2}$$



Particle neighbours in the string

Force on the point  $i$  is  $F_i = \frac{\kappa}{\Delta_L}(y_{i+1} - y_i) + \frac{\kappa}{\Delta_L}(y_{i-1} - y_i)$ .

$$\begin{aligned} \frac{\kappa}{\Delta_L}(y_{i+1} - y_i) + \frac{\kappa}{\Delta_L}(y_{i-1} - y_i) &= m(\Delta_L) \frac{\partial^2 y}{\partial t^2} \quad \text{: - Newton's Law} \\ &= \rho \Delta_L \frac{\partial^2 y}{\partial t^2}. \end{aligned}$$



# Fourier's Solutions

$$y(x, t) = \sum_{m \in \mathbb{Z}} 2j c_m e^{-j \frac{\pi}{L} m t} \sin\left(\frac{\pi}{L} m x\right)$$

$$y(x, t) = \sum 2j c_m e^{-j \frac{\pi}{L} m t} \sin\left(\frac{\pi}{L} m x\right)$$

# Fourier's Solutions

$$\begin{aligned}y(x, t) &= \sum_{m \in \mathbb{Z}} 2j c_m e^{-j \frac{\pi}{L} m t} \sin\left(\frac{\pi}{L} m x\right) \\&= \sum_{m \geq 1} \left( \tilde{a}_m \cos\left(\frac{\pi}{L} m t\right) + \tilde{b}_m \sin\left(\frac{\pi}{L} m t\right) \right) \sin\left(\frac{\pi}{L} m x\right).\end{aligned}$$

$$\frac{dy}{dt} = \sum_{m \geq 1} \left( -\tilde{a}_m \sin\left(\frac{\pi}{L} m t\right) \frac{\pi m}{L} + \tilde{b}_m \cos\left(\frac{\pi}{L} m t\right) \frac{\pi m}{L} \right) \sin\left(\frac{\pi}{L} m x\right)$$

$t = 0$

$$\Rightarrow \sum_{m \geq 1} 0 + \tilde{b}_m (\ ) = 0 \Rightarrow \tilde{b}_m = 0$$

# Fourier's Solutions

$$\begin{aligned}y(x, t) &= \sum_{m \in \mathbb{Z}} 2j c_m e^{-j \frac{\pi}{L} m t} \sin\left(\frac{\pi}{L} m x\right) \\&= \sum_{m \geq 1} \left( \tilde{a}_m \cos\left(\frac{\pi}{L} m t\right) + \tilde{b}_m \sin\left(\frac{\pi}{L} m t\right) \right) \sin\left(\frac{\pi}{L} m x\right).\end{aligned}$$

## Opposite Camp

$$y(x, 0) = \sum_{m \geq 1} \tilde{a}_m \sin\left(\frac{\pi}{L} m x\right), \quad 0 \leq x \leq L \quad \text{“Initial Position”}$$

# Fourier's Solutions

$$\begin{aligned}y(x, t) &= \sum_{m \in \mathbb{Z}} 2j c_m e^{-j \frac{\pi}{L} m t} \sin\left(\frac{\pi}{L} m x\right) \\&= \sum_{m \geq 1} \left( \tilde{a}_m \cos\left(\frac{\pi}{L} m t\right) + \tilde{b}_m \sin\left(\frac{\pi}{L} m t\right) \right) \sin\left(\frac{\pi}{L} m x\right).\end{aligned}$$

## Opposite Camp

$$y(x, 0) = \sum_{m \geq 1} \tilde{a}_m \sin\left(\frac{\pi}{L} m x\right), \quad 0 \leq x \leq L \quad \text{"Initial Position"}$$

$\Rightarrow$  Any initial position can be expressed as sum of sinusoids??

# Fourier's Solutions

$$\begin{aligned} y(x, t) &= \sum_{m \in \mathbb{Z}} 2j c_m e^{-j \frac{\pi}{L} m t} \sin\left(\frac{\pi}{L} m x\right) \\ &= \sum_{m \geq 1} \left( \tilde{a}_m \cos\left(\frac{\pi}{L} m t\right) + \tilde{b}_m \sin\left(\frac{\pi}{L} m t\right) \right) \sin\left(\frac{\pi}{L} m x\right). \end{aligned}$$

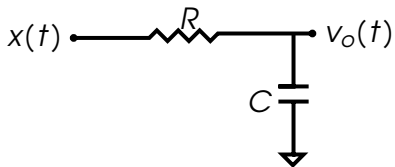
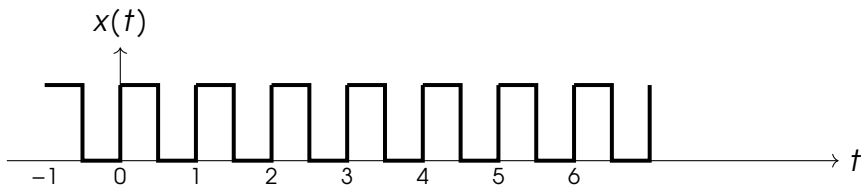
## Opposite Camp

$$y(x, 0) = \sum_{m \geq 1} \tilde{a}_m \sin\left(\frac{\pi}{L} m x\right), \quad 0 \leq x \leq L \quad \text{"Initial Position"}$$

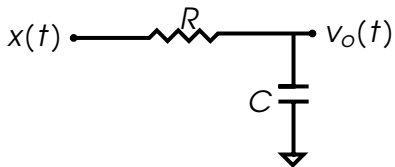
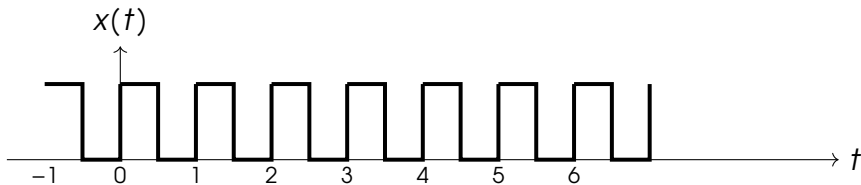
$\Rightarrow$  Any initial position can be expressed as sum of sinusoids??

NOTE: RHS is an odd function, periodic with period  $T = 2L$ .

# A Circuit Question



# A Circuit Question

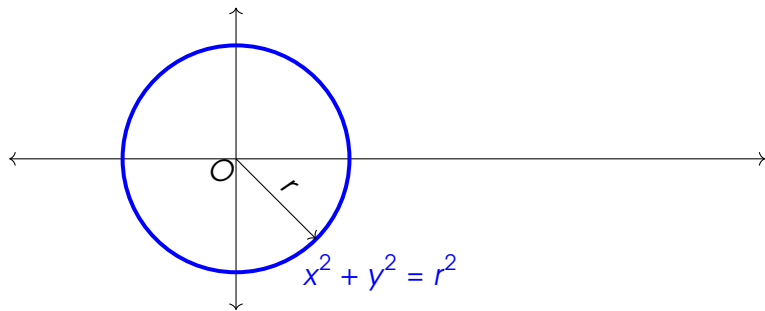


$$x(t) = \sum_m \alpha_m \Phi_m(t)$$

“Superposition”

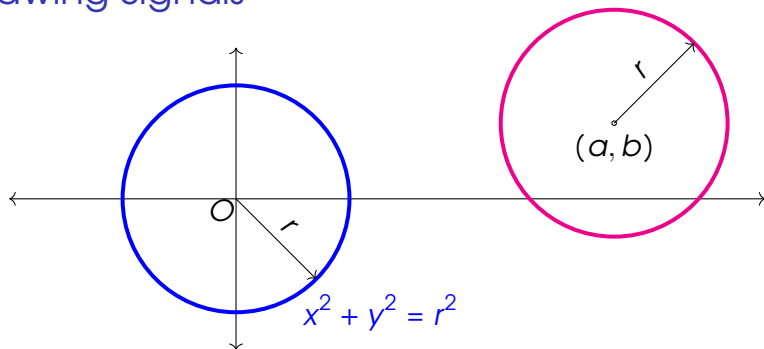
$$v_o(t) = \sum_m \frac{1}{1 + j2\pi f_m RC} \alpha_m \Phi_m(t)$$

# Drawing Signals

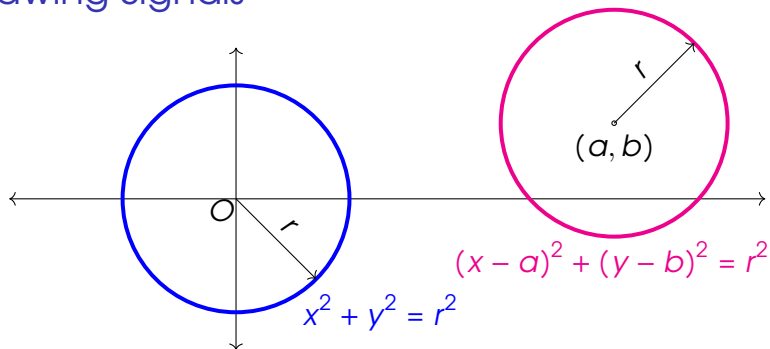




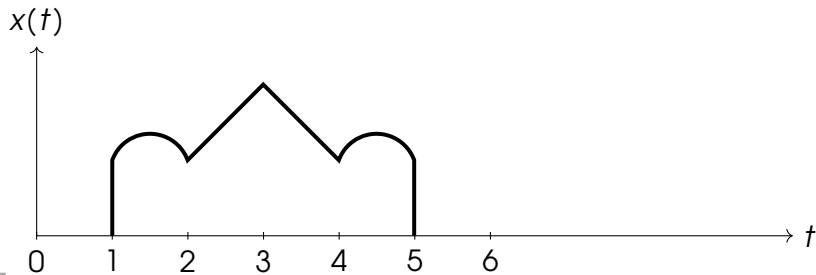
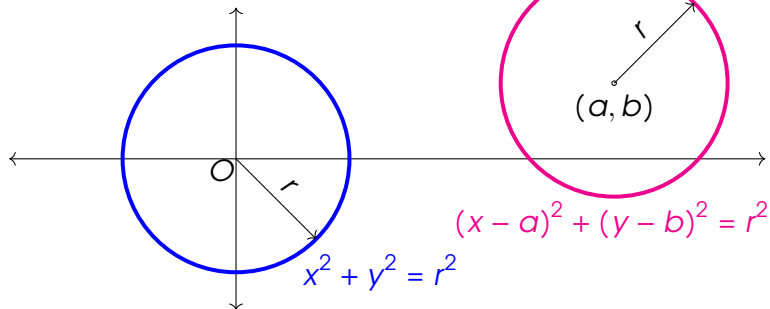
# Drawing Signals



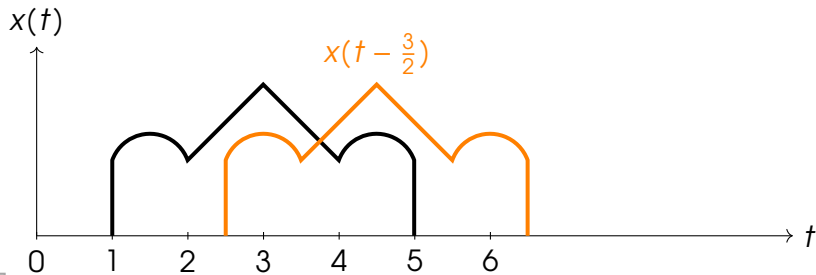
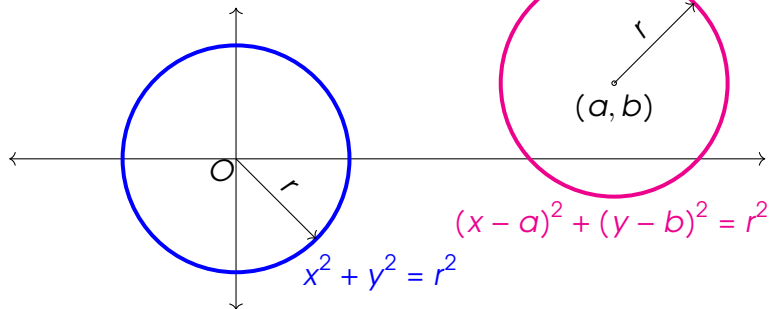
# Drawing Signals



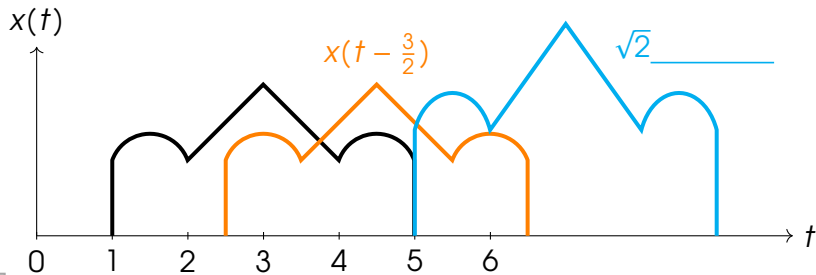
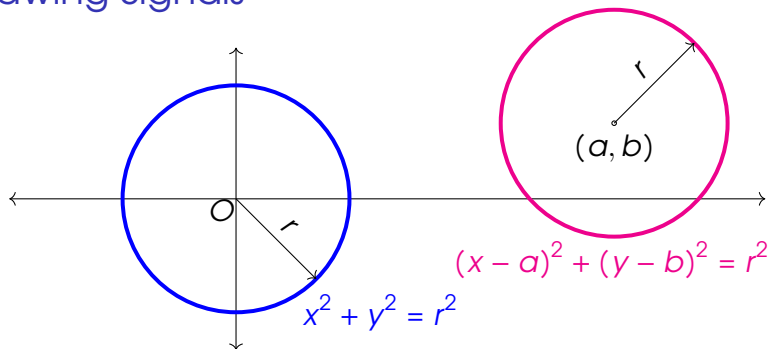
# Drawing Signals



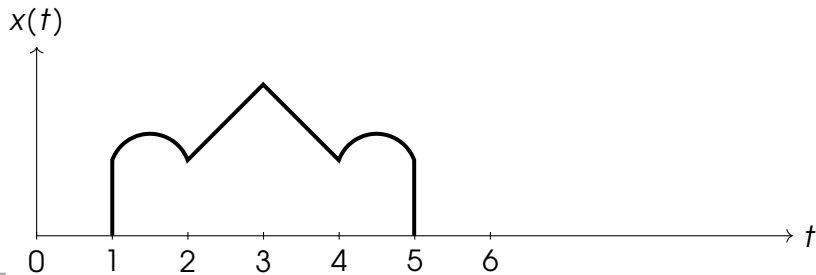
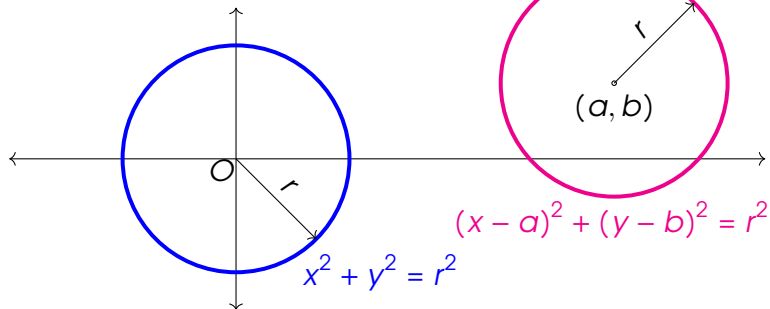
# Drawing Signals



# Drawing Signals



# Drawing Signals



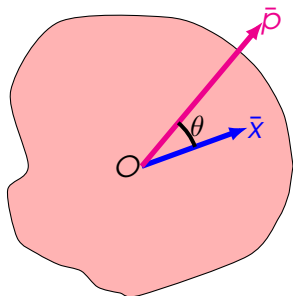
# Dot-Product and Projections

$$x(t) = \sum_{i \in \mathbb{Z}} \alpha_i \Phi_i(t) \quad (1)$$

# Dot-Product and Projections

$$x(t) = \sum_{i \in \mathbb{Z}} \alpha_i \Phi_i(t) \quad (1)$$

The dot product  $\langle \bar{x}, \bar{p} \rangle$  of vectors  $\bar{x}, \bar{p}$  measures their **overlap**.

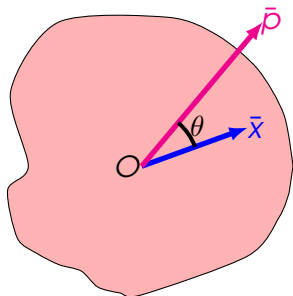




# Dot-Product and Projections

$$x(t) = \sum_{i \in \mathbb{Z}} \alpha_i \Phi_i(t) \quad (1)$$

The dot product  $\langle \bar{x}, \bar{p} \rangle$  of vectors  $\bar{x}, \bar{p}$  measures their **overlap**.



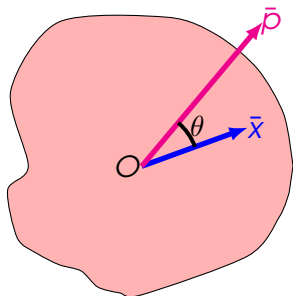
$$\langle x(t), p(t) \rangle := \int_{\mathbb{R}} x(t) p^*(t) dt.$$

$$\langle x(t), p(t) \rangle = 0 \Rightarrow \text{orthogonal}$$

# Dot-Product and Projections

$$x(t) = \sum_{i \in \mathbb{Z}} \alpha_i \Phi_i(t) \quad (1)$$

The dot product  $\langle \bar{x}, \bar{p} \rangle$  of vectors  $\bar{x}, \bar{p}$  measures their overlap.



$$\langle x(t), p(t) \rangle := \int_{\mathbb{R}} x(t) p^*(t) dt.$$

$$\langle x(t), p(t) \rangle = 0 \Rightarrow \text{orthogonal}$$

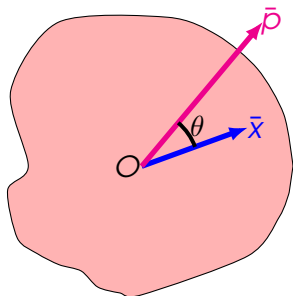
If  $\{\Phi_1, \Phi_2, \dots\}$  orthogonal in (1),

$$\langle x(t), \Phi_i(t) \rangle = \alpha_i, \forall i$$

# Dot-Product and Projections

$$x(t) = \sum_{i \in \mathbb{Z}} \alpha_i \Phi_i(t) \quad (1)$$

The dot product  $\langle \bar{x}, \bar{p} \rangle$  of vectors  $\bar{x}, \bar{p}$  measures their **overlap**.



$$\langle x(t), p(t) \rangle := \int_{\mathbb{R}} x(t) p^*(t) dt.$$

$$\langle x(t), p(t) \rangle = 0 \Rightarrow \text{orthogonal}$$

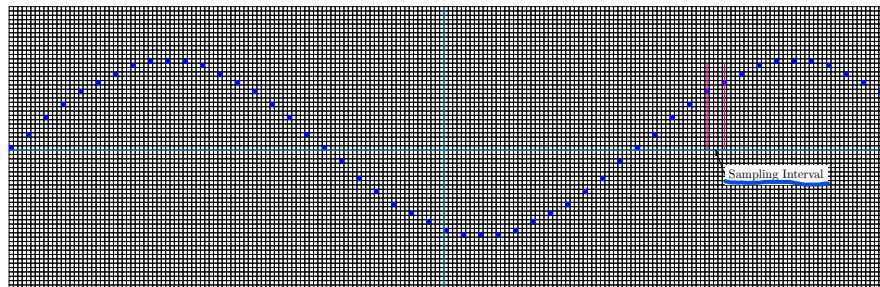
If  $\{\Phi_1, \Phi_2, \dots\}$  **orthogonal** in (1),

$$\langle x(t), \Phi_i(t) \rangle = \alpha_i, \forall i$$

## Bandlimited Signal

$$\langle x(t), \cos(2\pi ft) \rangle = \langle x(t), \sin(2\pi ft) \rangle = 0, \forall f \geq f_0$$

# Digital Oscilloscope

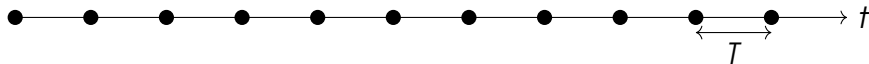


Digital-to-Analog :- “Sufficiently many samples **interpolated**”

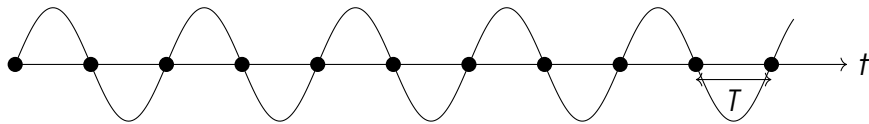
Analog-to-Digital :- “**Sample** enough to preserve signal identity”

Modern Systems strive to stay digital till the last *whisker*.

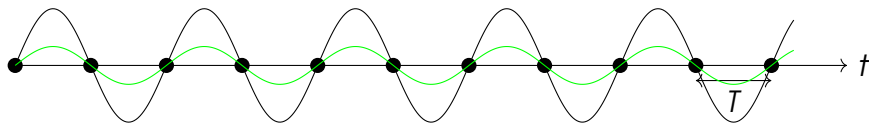
# Sampling Idea: All Zero Signal



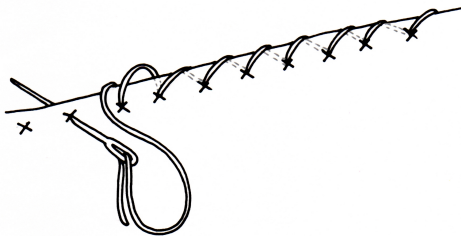
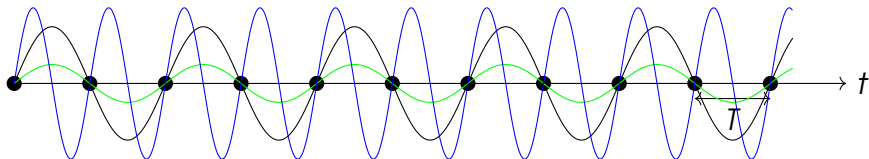
## Sampling Idea: All Zero Signal



## Sampling Idea: All Zero Signal

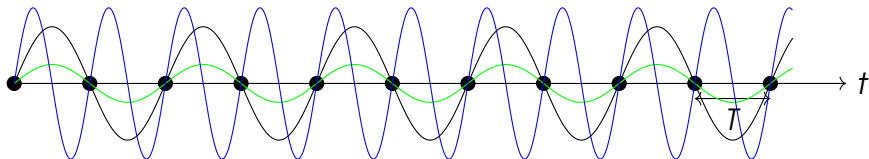


# Sampling Idea: All Zero Signal

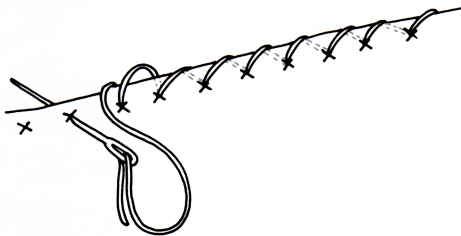




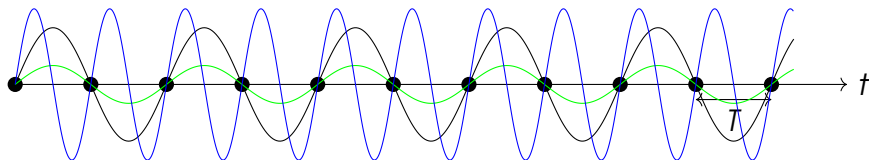
# Sampling Idea: All Zero Signal



No non-zero continuous interpolator having only frequencies  $< \frac{1}{2T}$ .

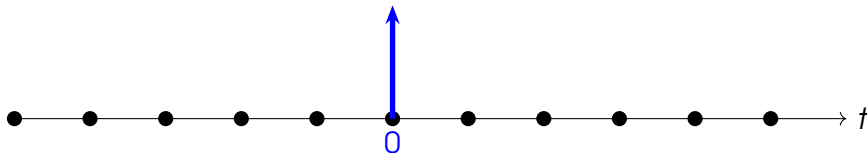


# Sampling Idea: All Zero Signal

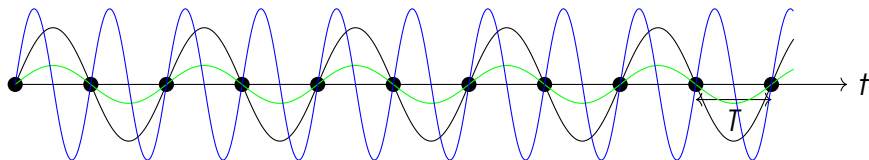


No non-zero continuous interpolator having only frequencies  $< \frac{1}{2T}$ .

Shannon Interpolator:  $\text{sinc}(\frac{t}{T})$

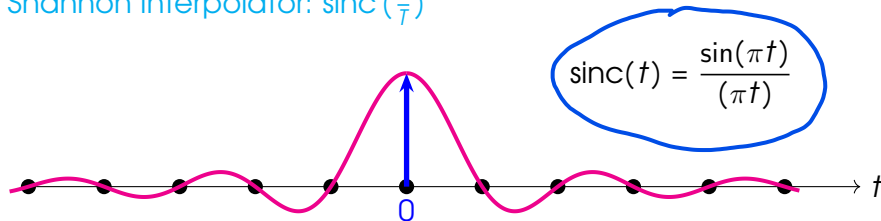


# Sampling Idea: All Zero Signal



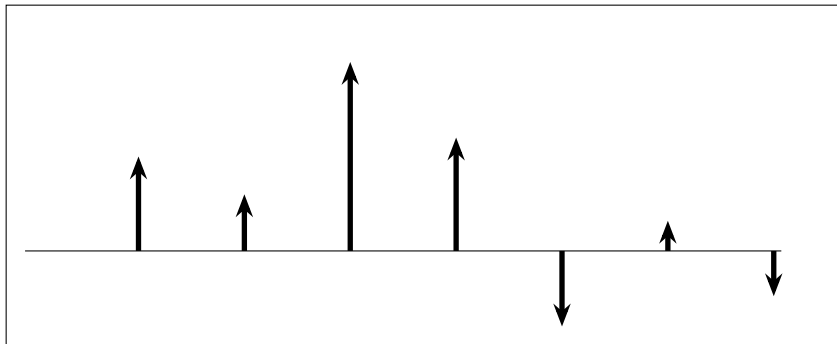
No non-zero continuous interpolator having only frequencies  $< \frac{1}{2T}$ .

Shannon Interpolator:  $\text{sinc}(\frac{t}{T})$

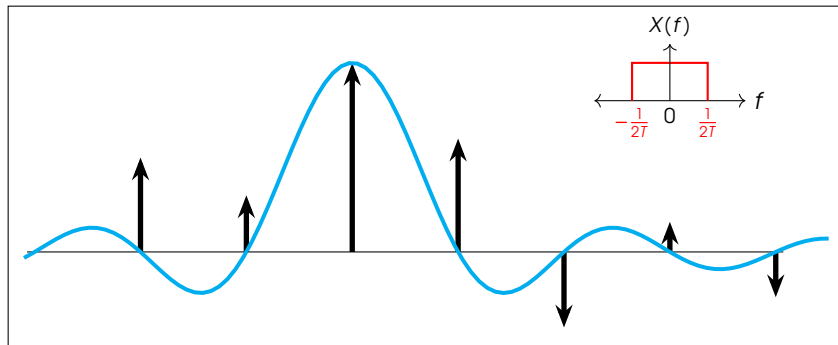


$$\text{sinc}(t) = \frac{\sin(\pi t)}{(\pi t)}$$

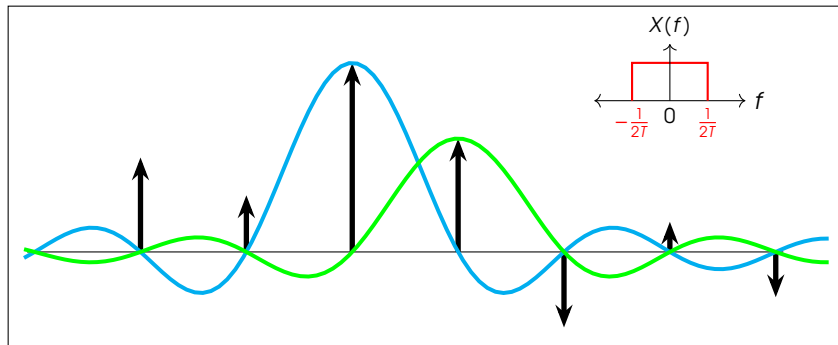
# Digital-to-Analog



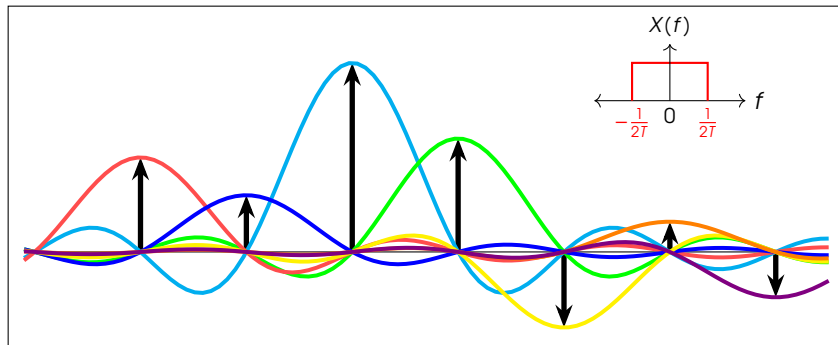
# Digital-to-Analog



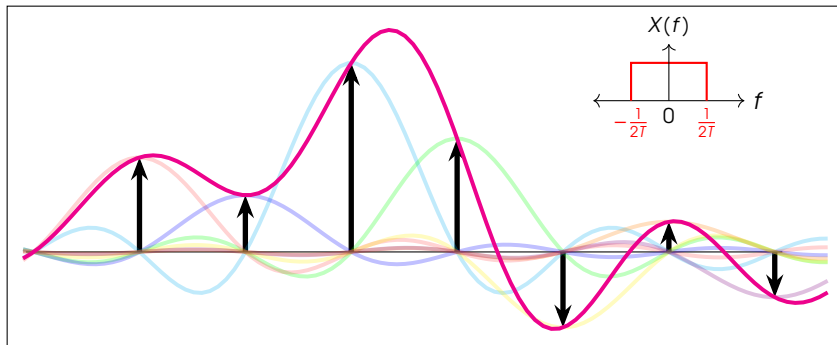
# Digital-to-Analog



# Digital-to-Analog

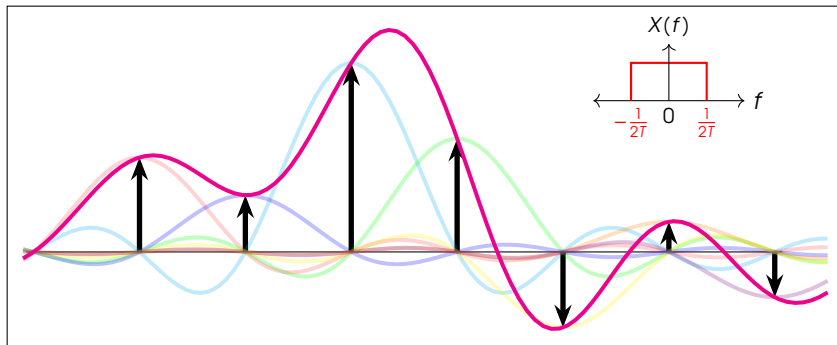


# Digital-to-Analog





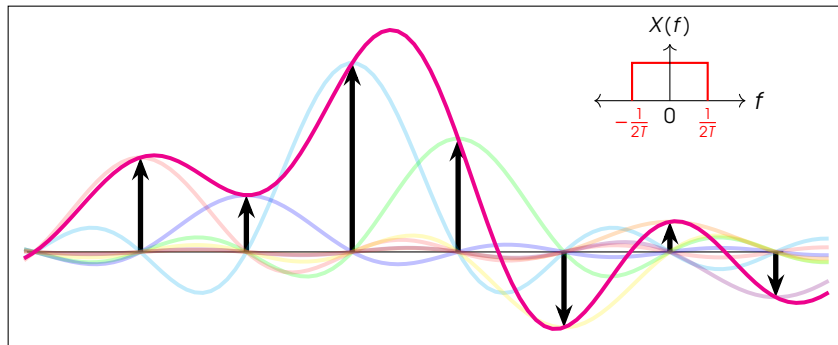
# Digital-to-Analog



Using superposition: (Shannon Interpolation Formula)

$$x(t) = \sum_{n \in \mathbb{Z}} x[n] \operatorname{sinc}\left(\frac{t}{T} - n\right)$$

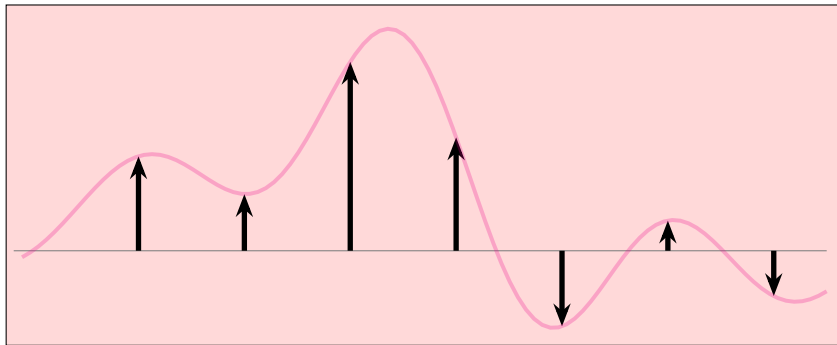
# Digital-to-Analog



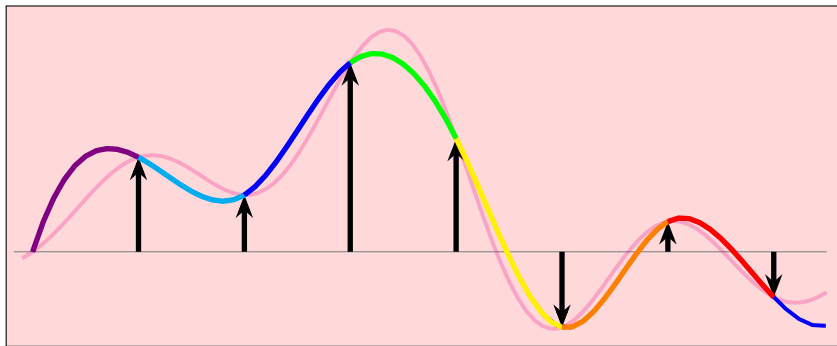
Using superposition: (Shannon Interpolation Formula)

$$x(t) = \sum_{n \in \mathbb{Z}} x[n] \operatorname{sinc}\left(\frac{t}{T} - n\right) \text{ "Convolution"}$$

# Piece-wise Polynomials

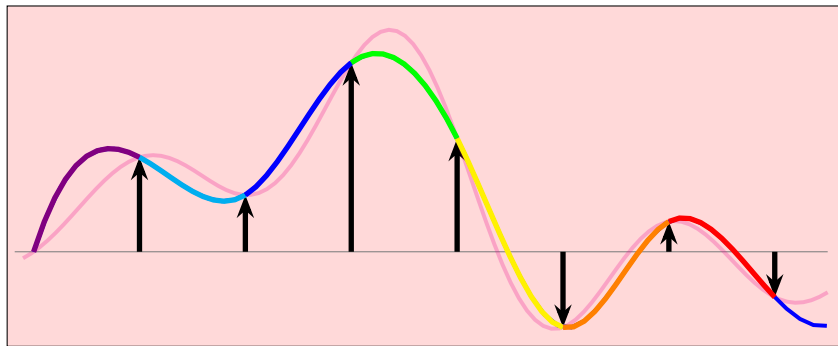


# Piece-wise Polynomials



2D Demo: Interpolating Images; 1D : Audio (MP3 or WAV)

# Piece-wise Polynomials



2D Demo: Interpolating Images; 1D : Audio (MP3 or WAV)

How to deal with Colors (multi-dimensional)