Eqn. of orbits from
$$E = \frac{M\dot{y}^2}{2} + \frac{1L}{2\mu \dot{y}^2} + \frac{1L}{c} = \frac{1}{c} \frac{du}{d\theta} \frac{d\theta}{d\theta} \frac{d\theta}{$$

$$\begin{aligned}
& | A| = \frac{AC}{t^{1}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_{0}} + \overline{U_{1}} (cs (0-0.)) \\
& | T| = \frac{1}{T_$$

QCQC/67-777