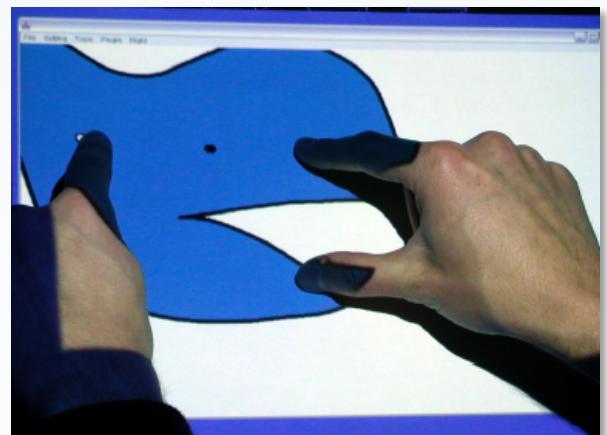


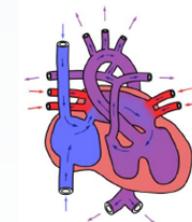
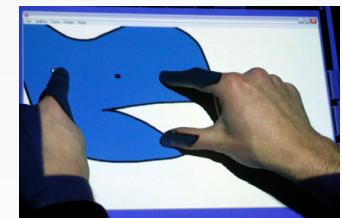
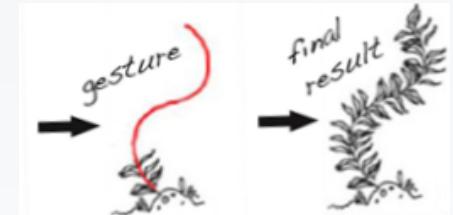
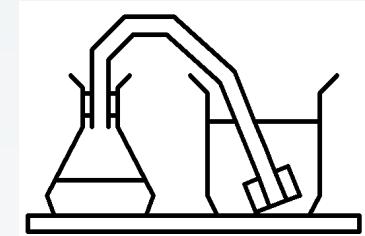
Week 2

2D Drawings and Animations



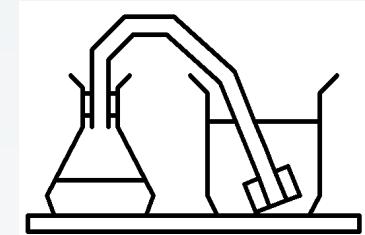
2D Drawings and Animations

- Diagram Beautification
- Pen-and-ink Textures
- Shape Manipulation
- Dynamic Illustrations



2D Drawings and Animations

- Diagram Beautification
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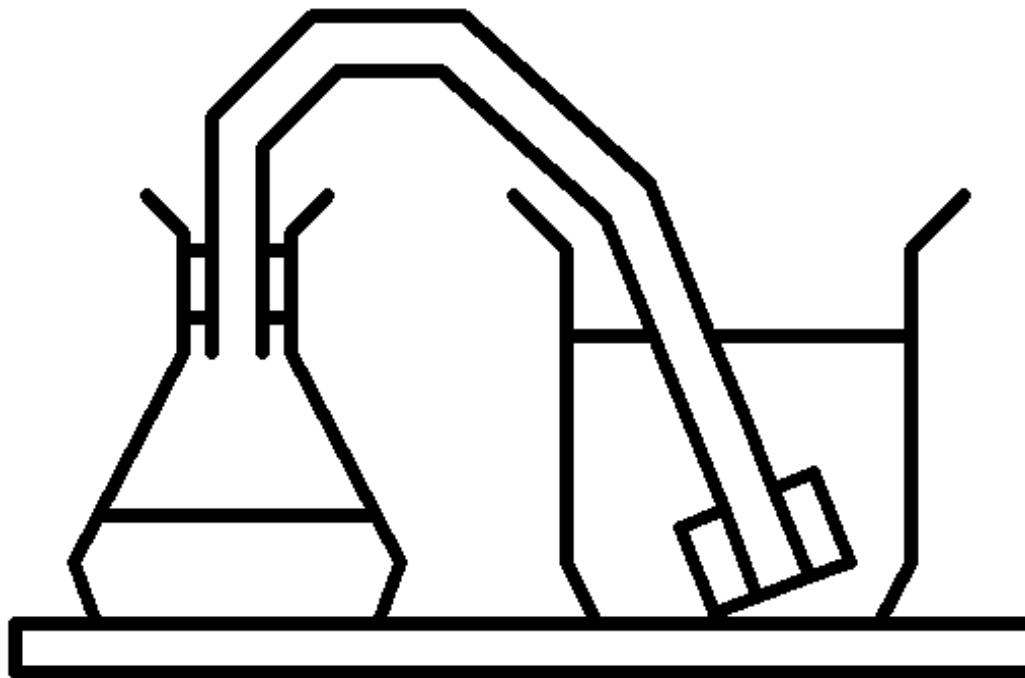


Pegasus: a Drawing System for Rapid Geometric Design



Takeo Igarashi, Sachiko Kawachiya,
Satoshi Matusoka, Hidehiko Tanaka

Problem



How do you draw this?

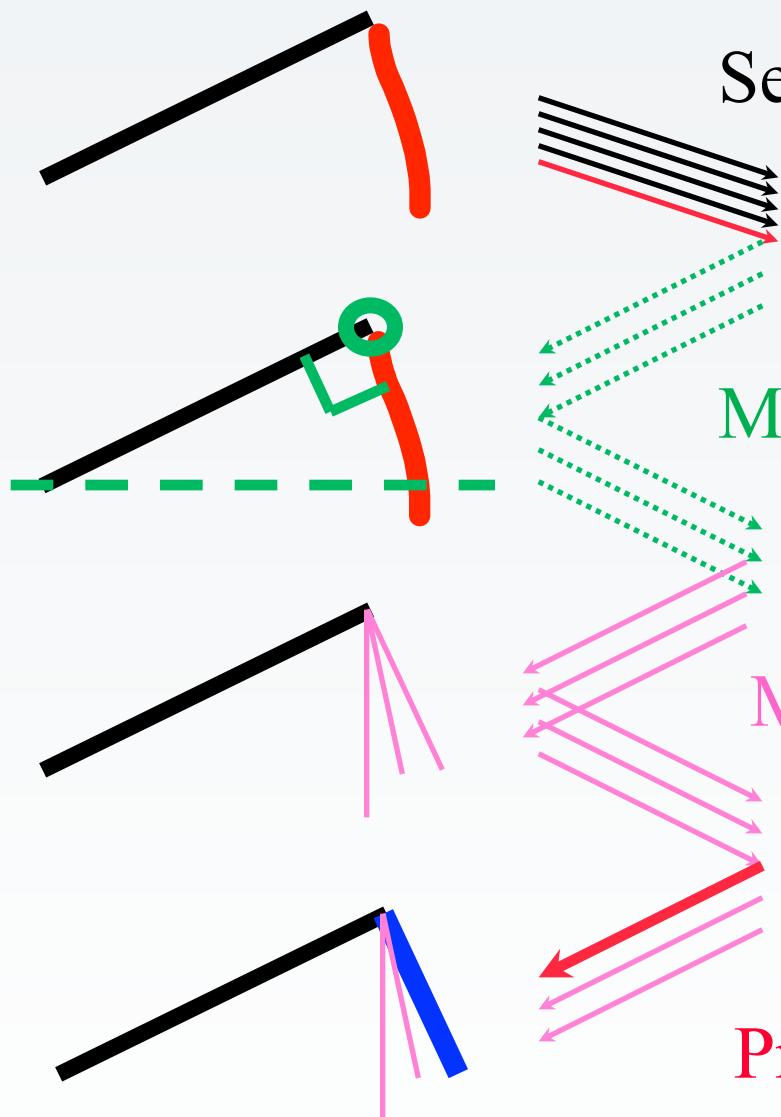
Demo

[pegasus](#)

Algorithm

1. Beautification
2. Prediction

1. Beautification Algorithm



Segment coordinates

Constraint Inference

Multiple equations

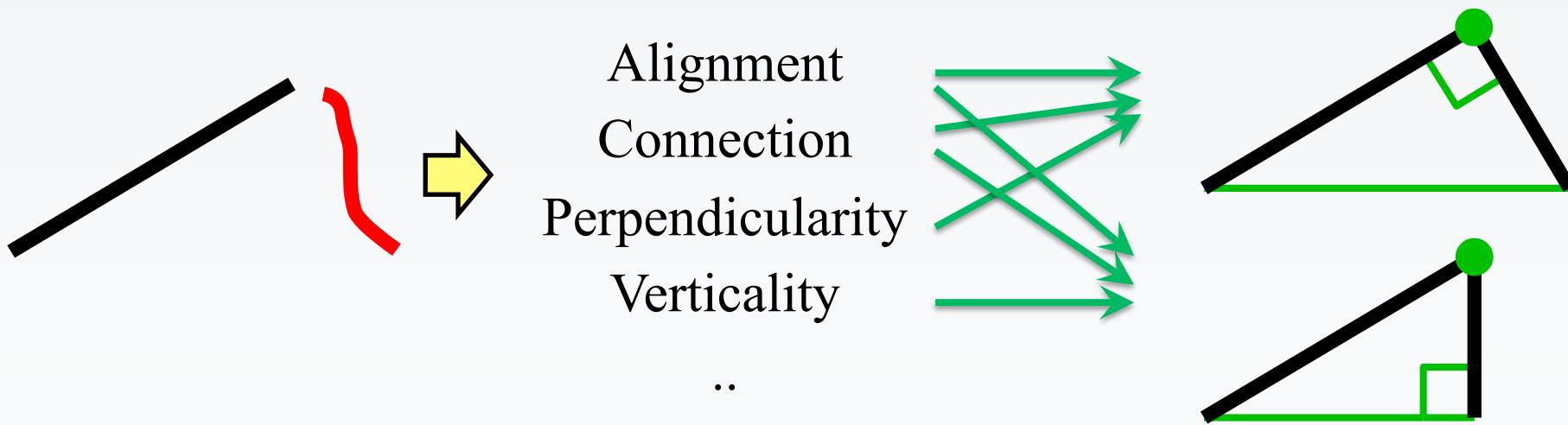
Constraint Solver

Multiple candidates

Candidate Evaluation

Primary candidate

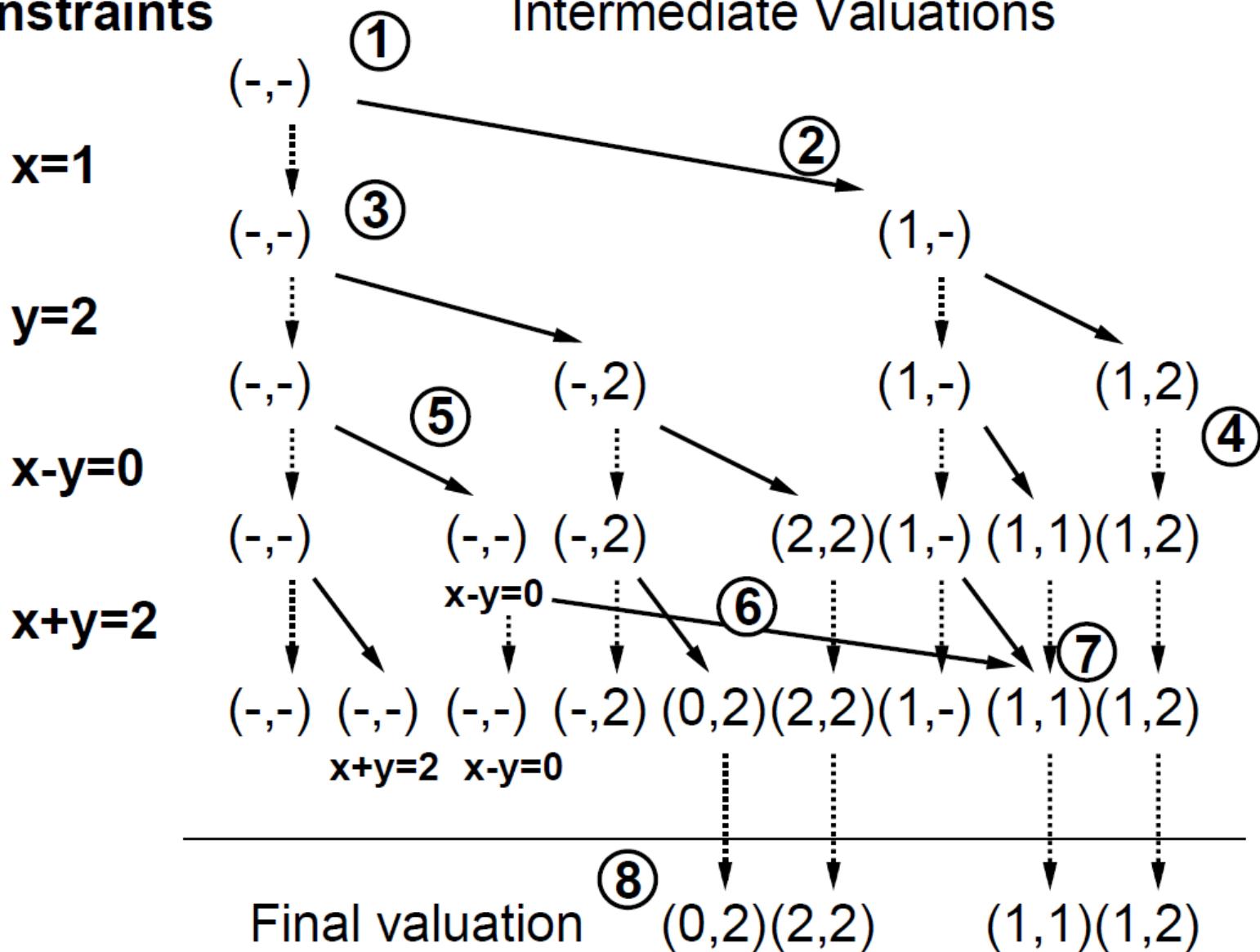
Constraint Solver



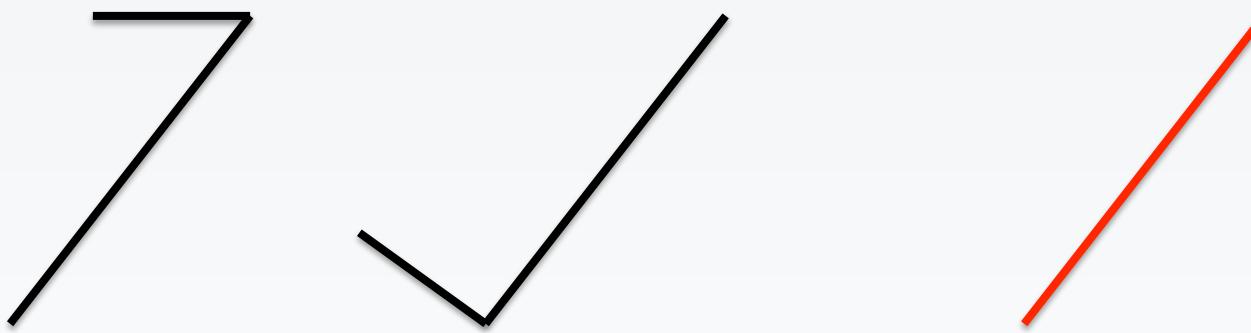
Find valid combination of constraints.

Constraints

Intermediate Valuations



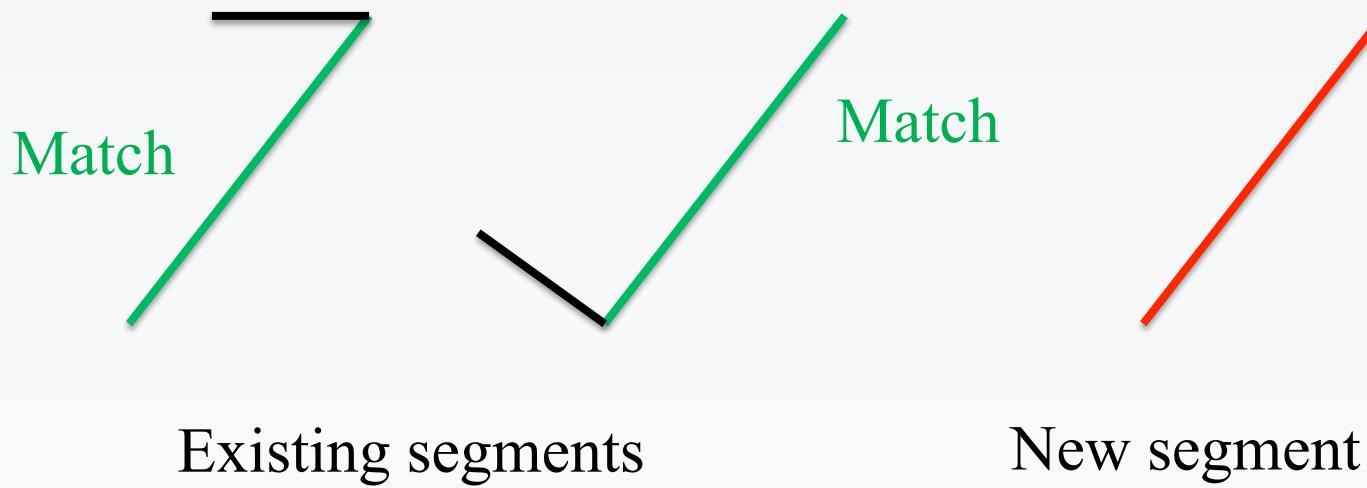
2. Prediction Algorithm



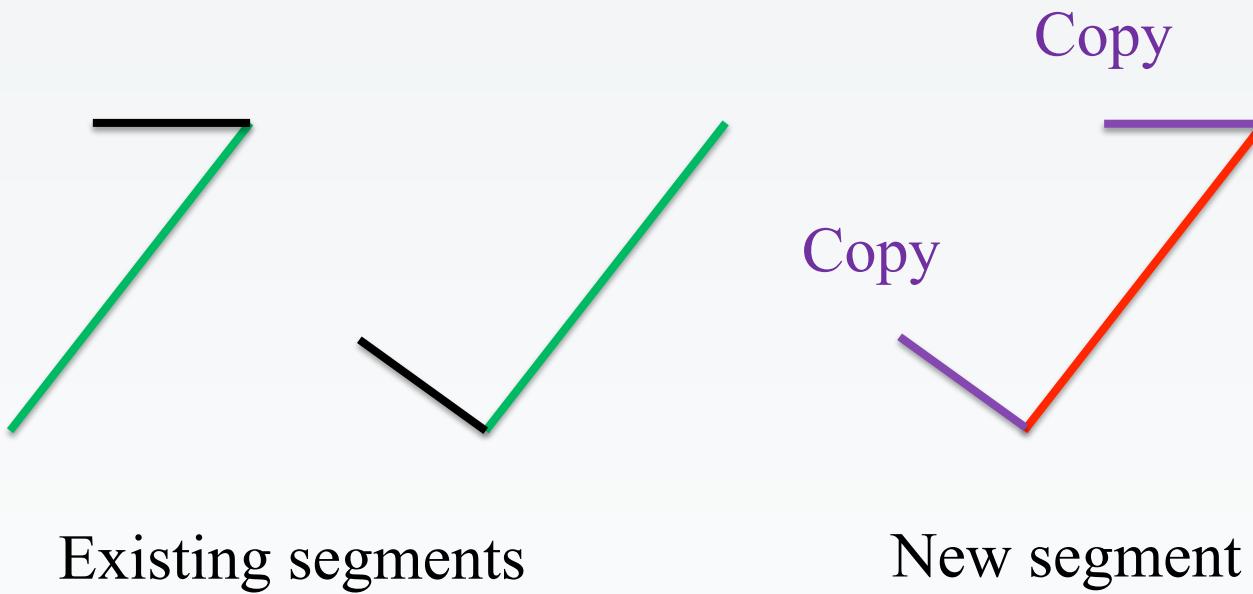
Existing segments

New segment

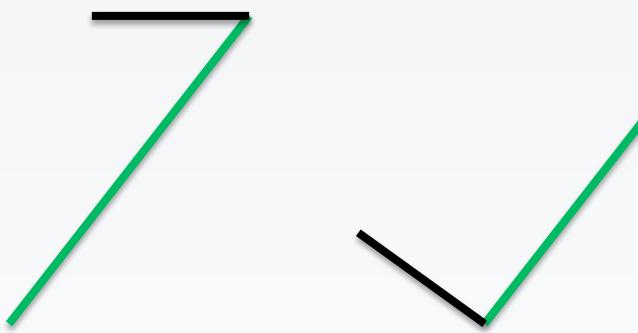
2. Prediction Algorithm



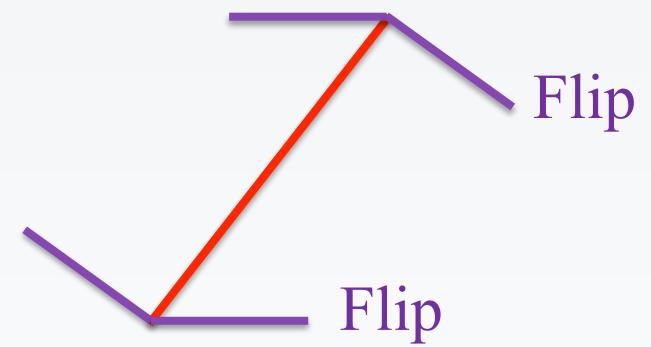
2. Prediction Algorithm



2. Prediction Algorithm



Existing segments



New segment

To Learn More...

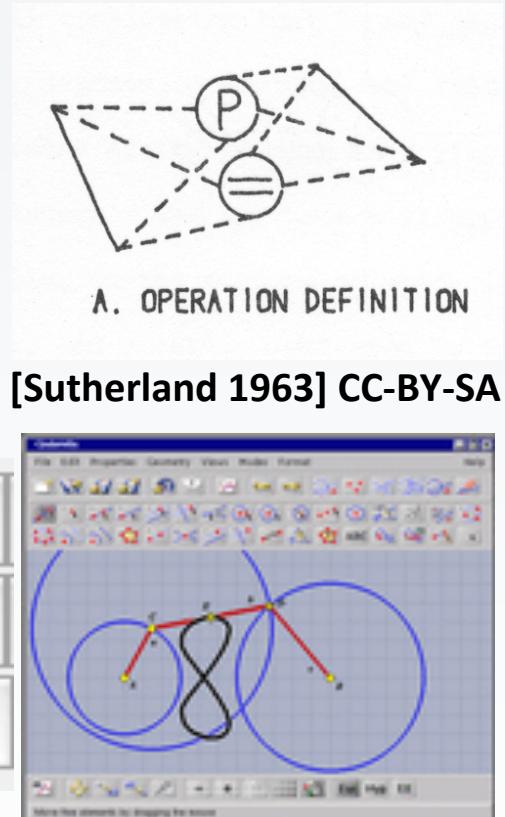
The original paper:

- Igarashi, et al. Interactive Beautification: A Technique for Rapid Geometric Design. UIST 1997.

Constraint-based Drawing:

- Sutherland. Sketchpad: A Man-Machine Graphical Communication System, Spring Joint Comp. Conf. 1963.
<http://www.youtube.com/watch?v=BKM3CmRqK2o>

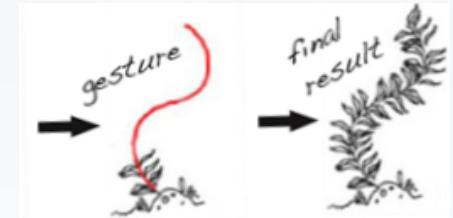
- Richter-Gebert. Cinderella.2.
<http://cinderella.de/>



©1997-2011 Jürgen Richter-Gebert and Ulrich Kortenkamp
(Figure obtained from cinderella.de with permission)

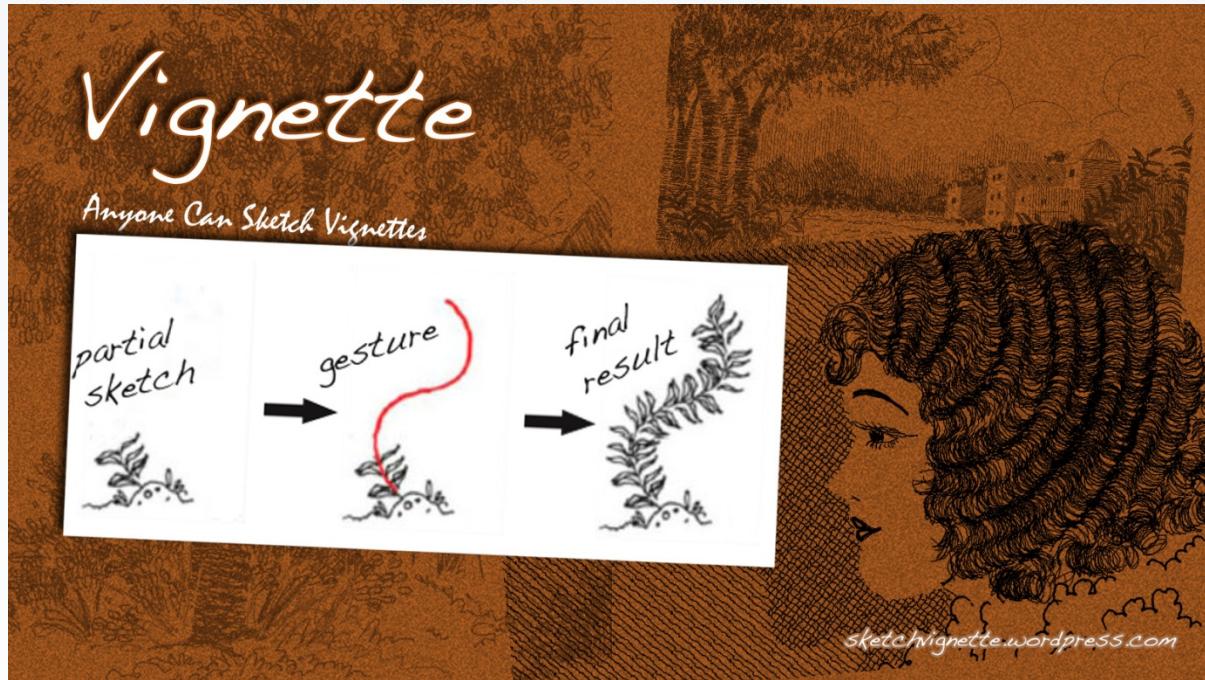
2D Drawings and Animations

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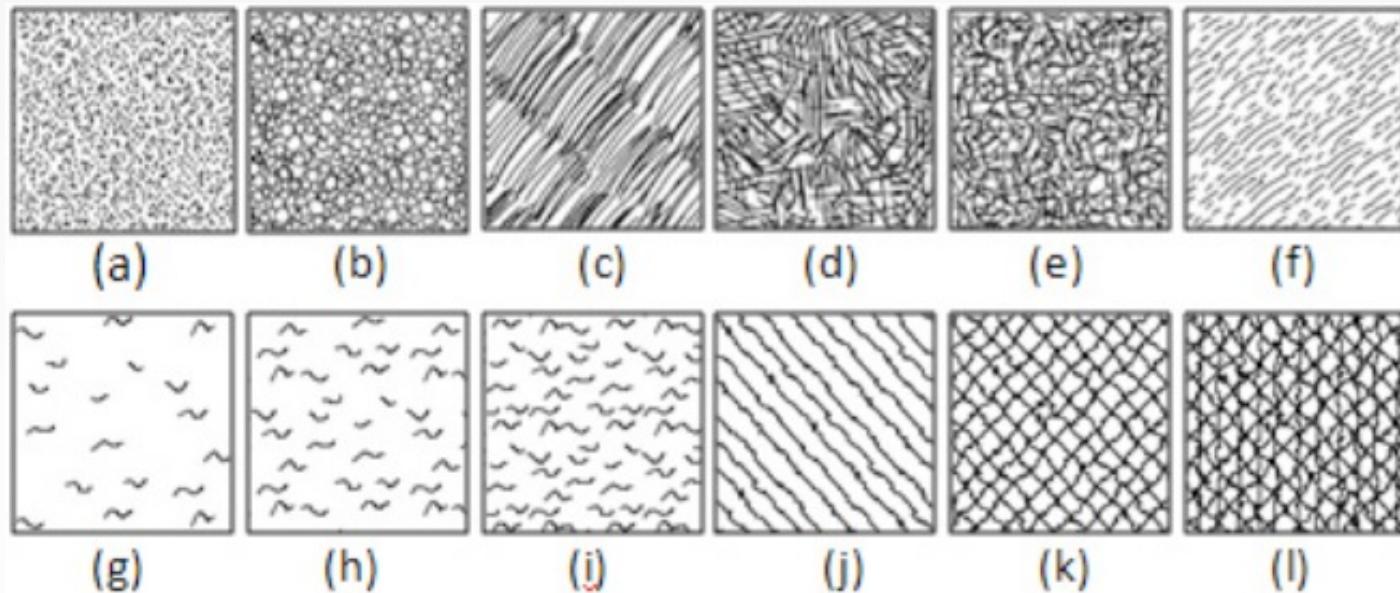
Vignette: Interactive Texture Design and Manipulation with Freeform Gestures for Pen-and-ink Illustration

Rubaiat Habib Kazi, Takeo Igarashi, Shengdong Zhao, Richard Davis



Problem

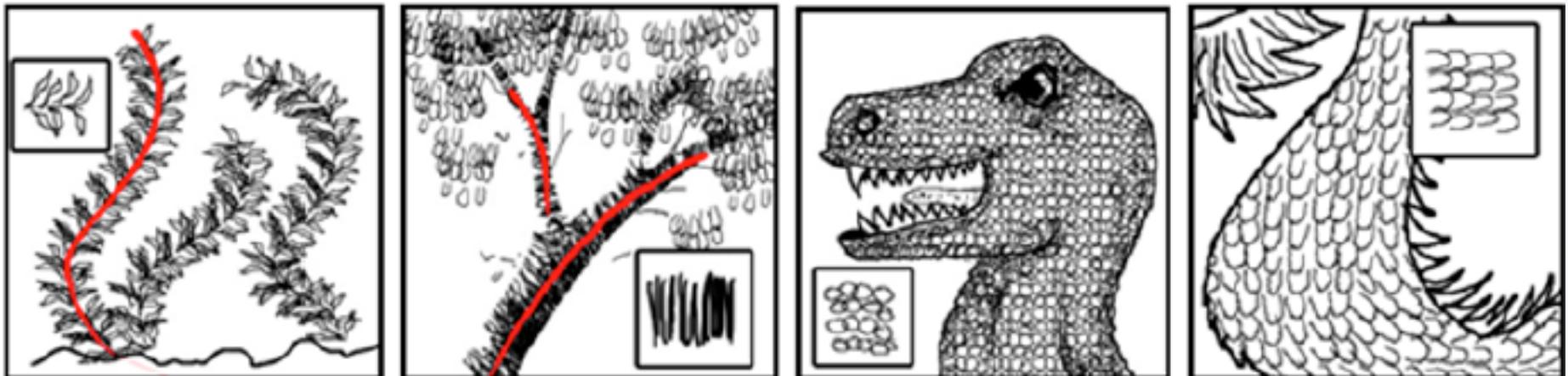
It is tedious to draw detailed patterns manually.
Naïve copy-and-paste looks artificial.



Our Approach

Leverage example-based texture synthesis.

[Ma, et al Discrete Element Textures 2011]



The user draws a part, and the system synthesizes the rest.

Video

vignette



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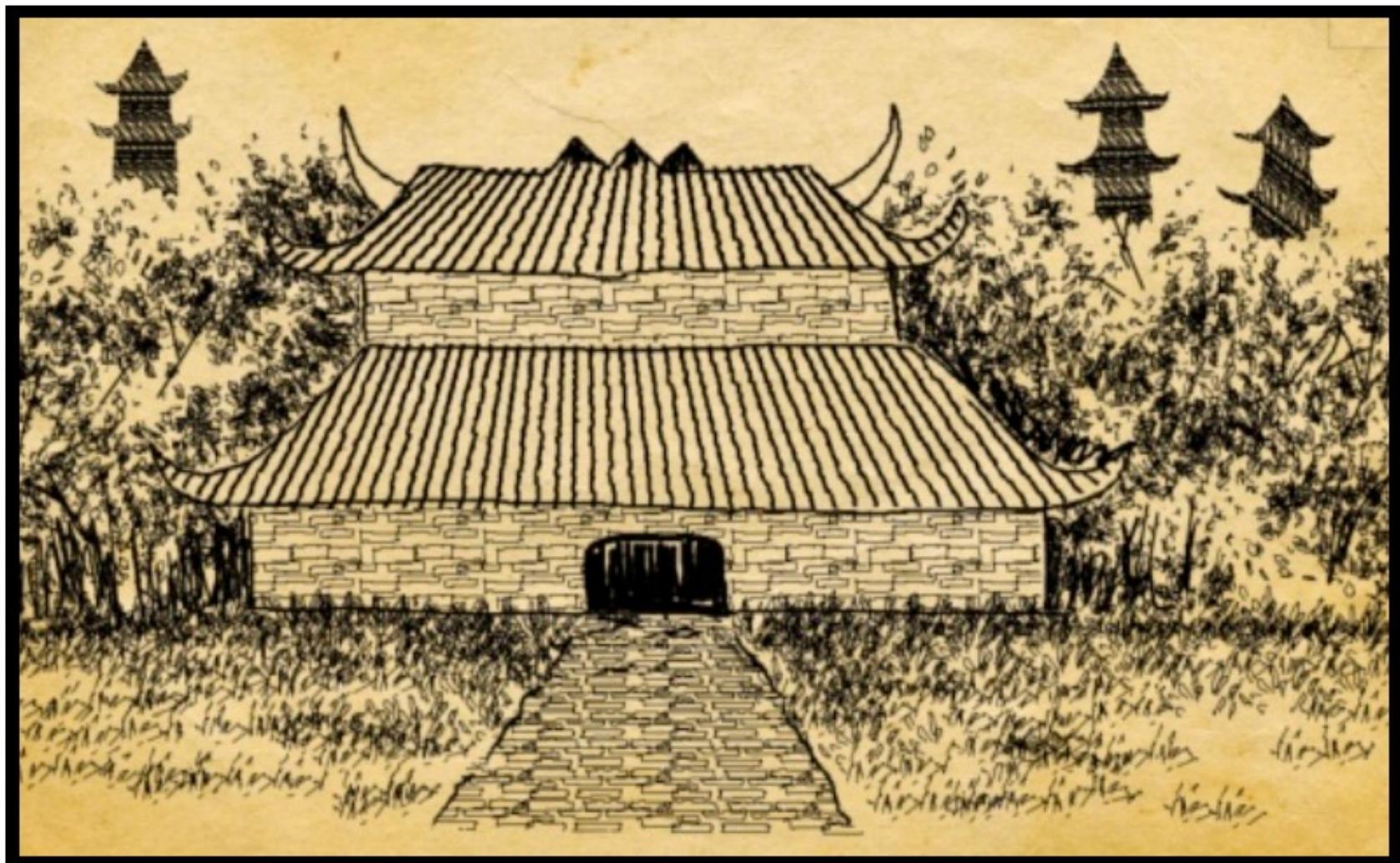
Results



Results

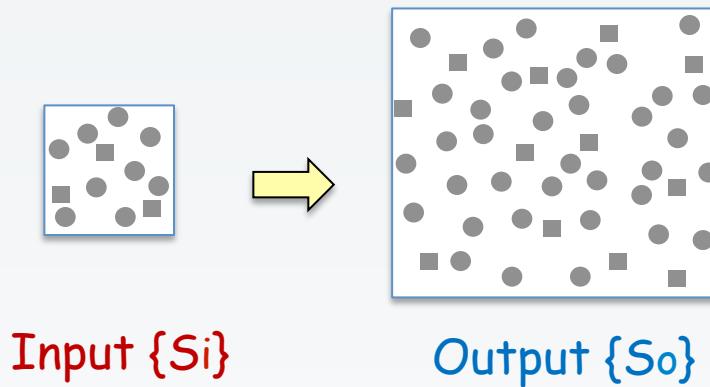


Results

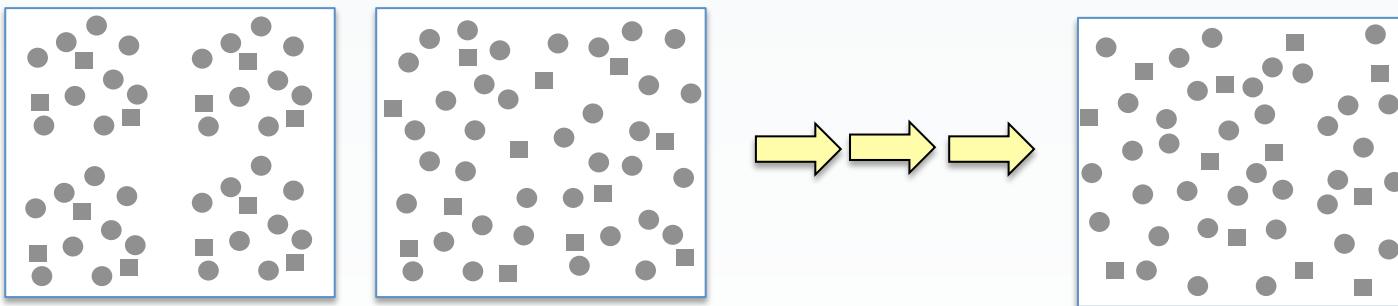


Discrete Element Texture Synthesis

[Ma, et al 2011]



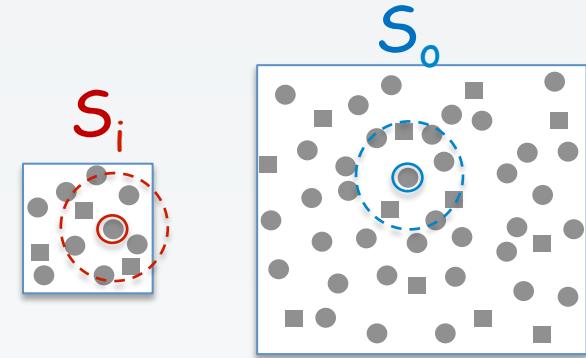
Start with patch-copy, and then iteratively refine it.



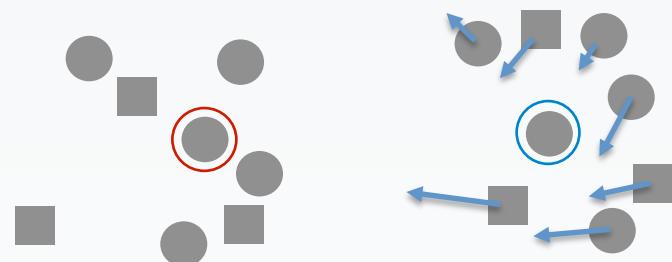
Iterative Refinement

Repeat {

1. For each S_o , find S_i that has similar neighborhood (match).



2. For each match, compute ideal position for neighbors $\{S'_o\}$.



3. Update S_o as average of the ideal positions.

}

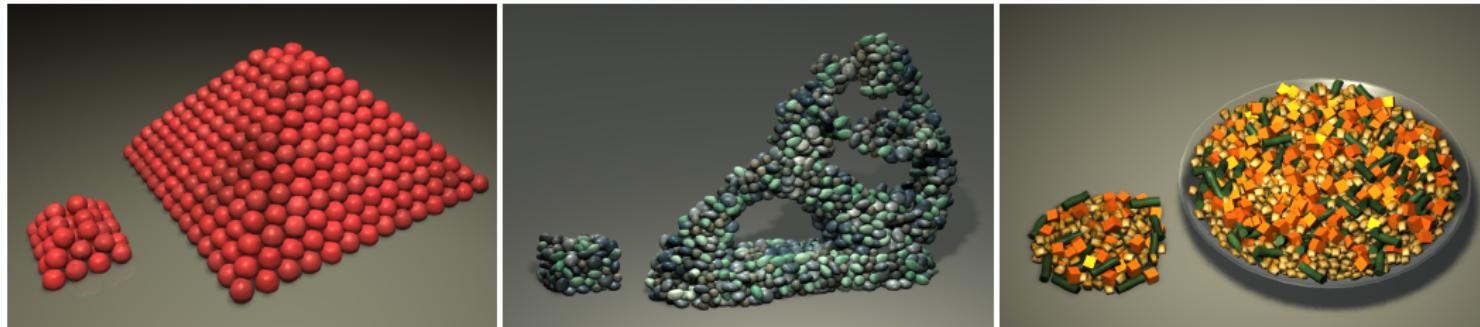
To Learn More...

The original paper:

- Kazi, et al. Vignette: Interactive Texture Design and Manipulation with Freeform Gestures for Pen-and-ink Illustration. CHI 2012.

Element Texture Synthesis:

- Ma, et al. Discrete Element Textures. SIGGRAPH 2011.

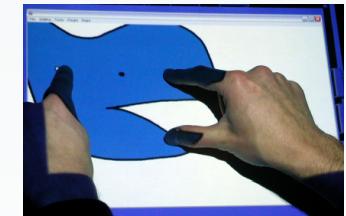


[Ma, et al. 2011]

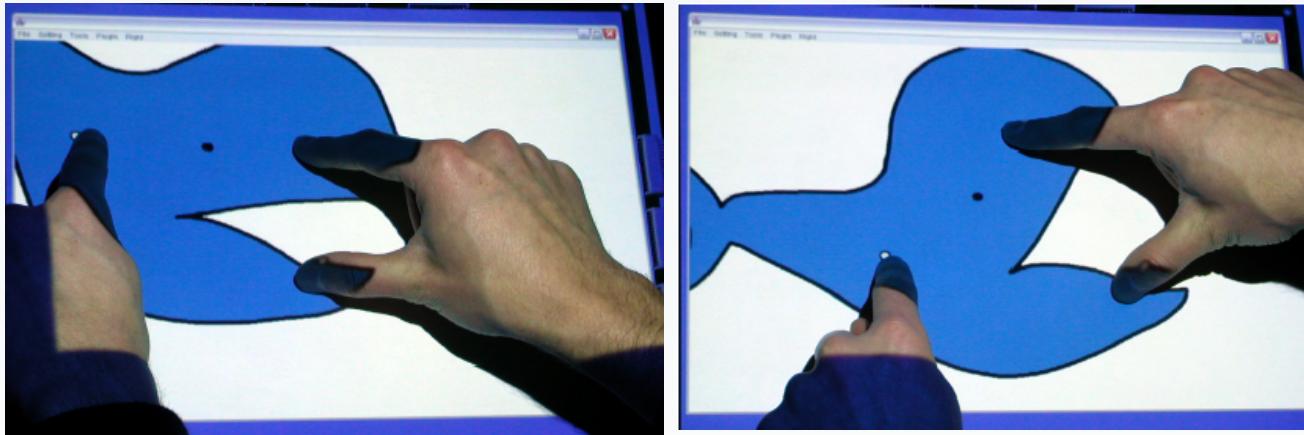
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2D Drawings and Animations

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As-Rigid-As-Possible Shape Manipulation



Takeo Igarashi, Tomer Moscovich, John F. Hughes

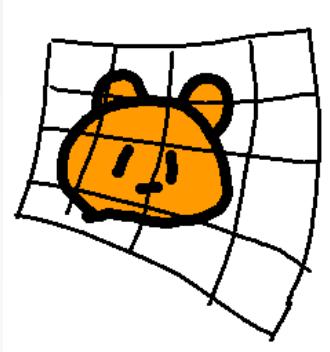
The University of Tokyo / Brown University

Goal

Move and deform 2D shapes
as if manipulating real objects



Space-Warp



Deform space, not object.
Different from reality...

Physics (mass-spring model)



Slow to converge...
Unstable, need tuning...

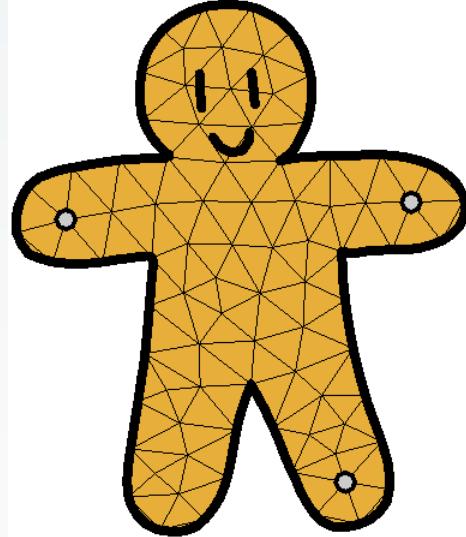
Demo

rigid

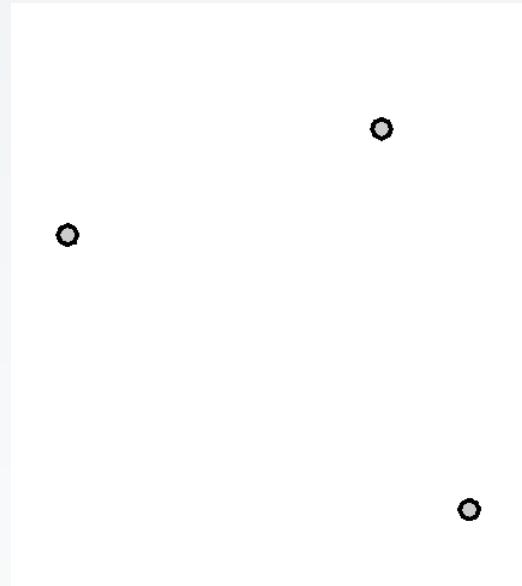


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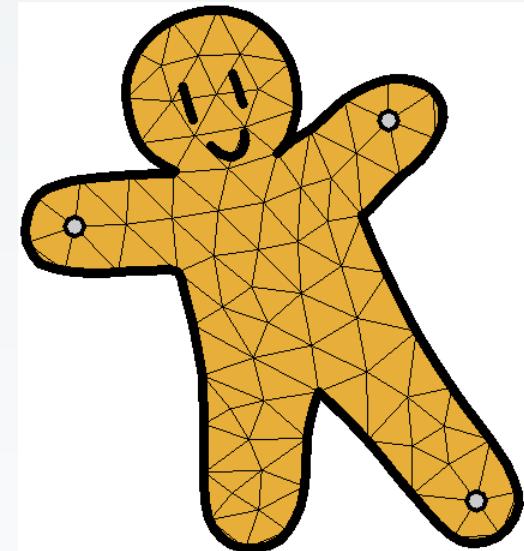
Algorithm



Rest shape



Handles



Output

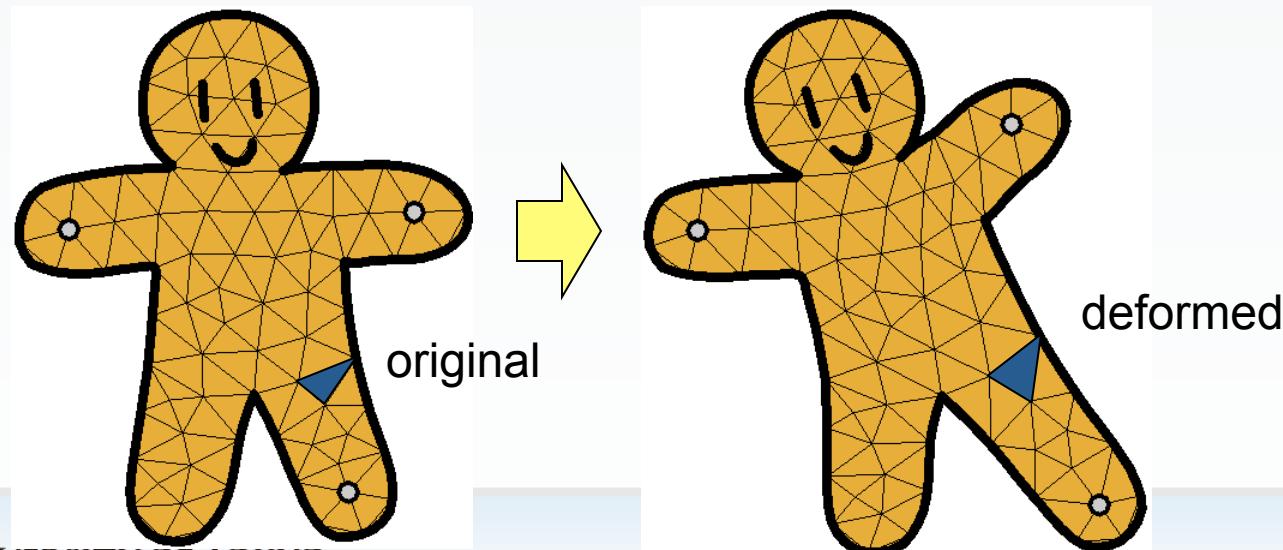
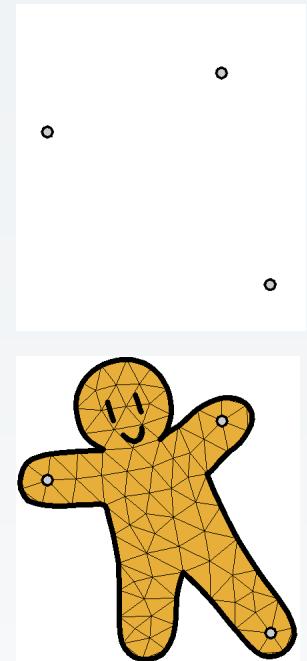
Minimize shape distortion, satisfying constraints.

Closed-form solution, not iterative.

Input: coordinates of handles (q)

Output: coordinates of mesh vertices (u)

Minimize: distortion of triangles



Minimize Distortion of Triangles

$$\arg \min_{u \in MeshVertices} \sum_{t \in Triangles} E_t(u)$$

We want such E that...

Translation, Rotation (rigid transformation) ~ $E=0$
Scale, Stretch, Shear ~ $E>0$

E should be quadratic in u

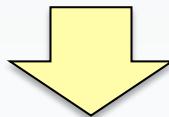
Ideally,

Translation, Rotation	$\sim E = 0$
Scale, Stretch, Shear	$\sim E > 0$

Ideally,

Translation, Rotation	$\sim E = 0$
Scale, Stretch, Shear	$\sim E > 0$

Unfortunately, there is no such “quadratic” energy!



We therefore combine two complementary energies.

Ideally,

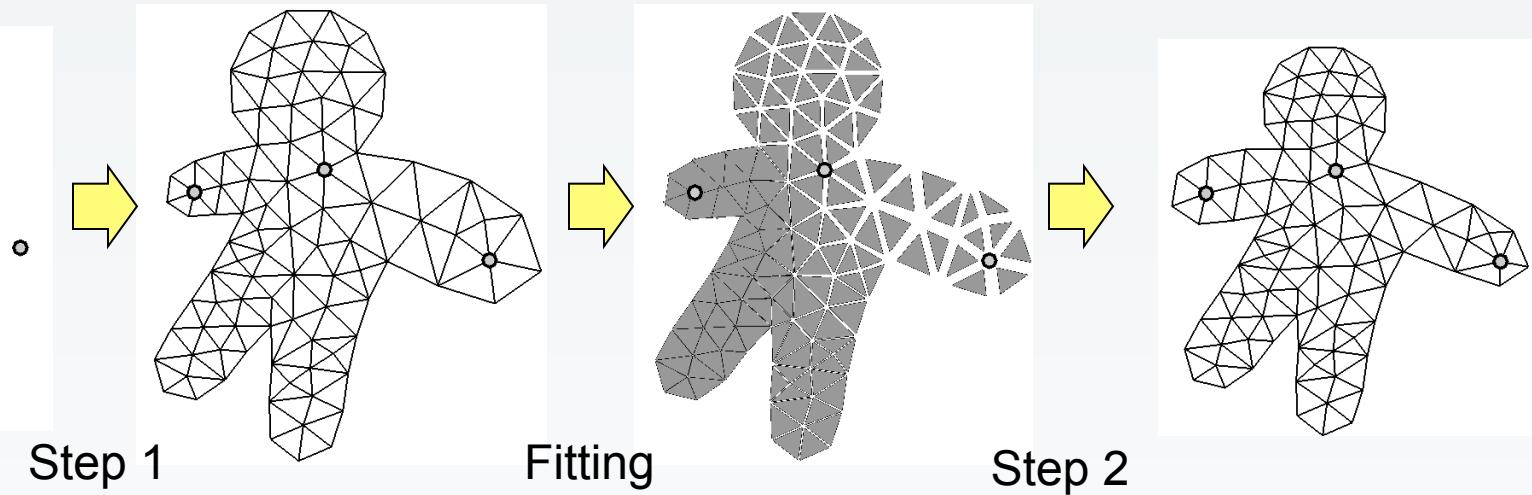
Translation, Rotation	$\sim E = 0$
Scale, Stretch, Shear	$\sim E > 0$

We combine two quadratic energies.

E_1 Translation, Rotation, Scale $\sim E_1 = 0$
Stretch, Shear $\sim E_1 > 0$

E_2 Translation $\sim E_2 = 0$
Rotation, Scale, Stretch, Shear $\sim E_2 > 0$

Two-Step Algorithm



Step 1: Obtain intermediate result by using E_1 , allowing scaling.

Fitting: Fit correct-sized individual triangle to the result.

Step 2: Stitch fitted triangles by using E_2 .

To Learn More...

The original paper:

- Igarashi, et al. As-Rigid-As-Possible Shape Manipulation, ACM Transactions on Computer Graphics. SIGGRAPH 2005.

Space warp deformation:

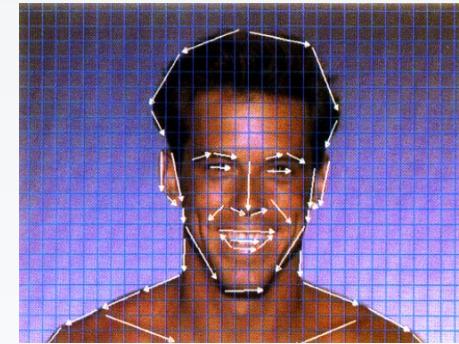
- Beier and Neely. Feature-based image metamorphosis. SIGGRAPH 1992.

Shape interpolation:

- Alexa, et al. As-rigid-as-possible shape interpolation. SIGGRAPH 2000.

Shape deformation:

- Botsch and Sorkine-Hornung. On Linear Variational Surface Deformation Methods, TVCG 2008.



[Beier and Neely 1992]

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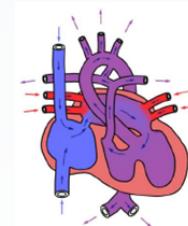


[Alexa, et al. 2000]

(Figure obtained from http://www.math.tau.ac.il/~dcor/online_papers/abs.html with permission)

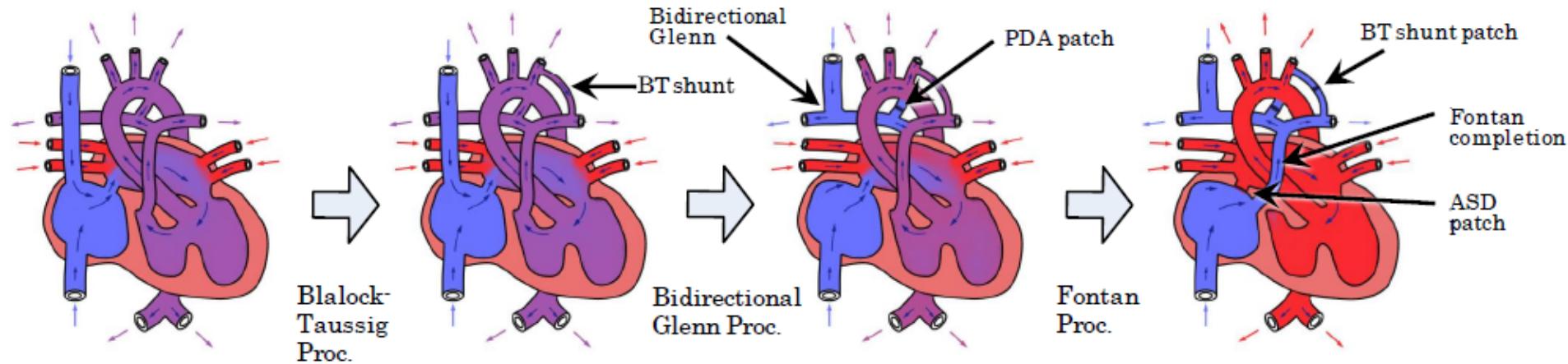
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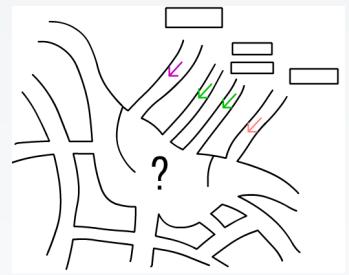
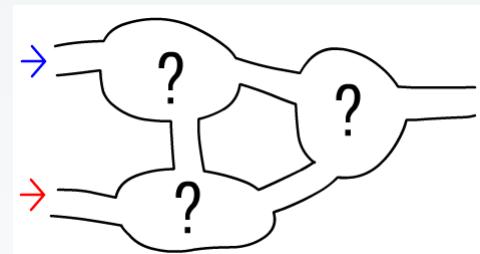
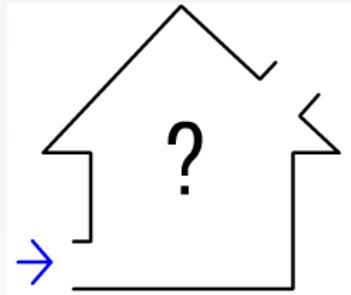
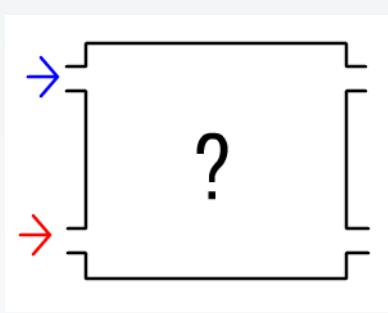


Sketch-based Dynamic Illustration of Fluid Systems

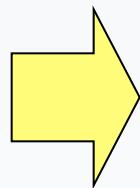
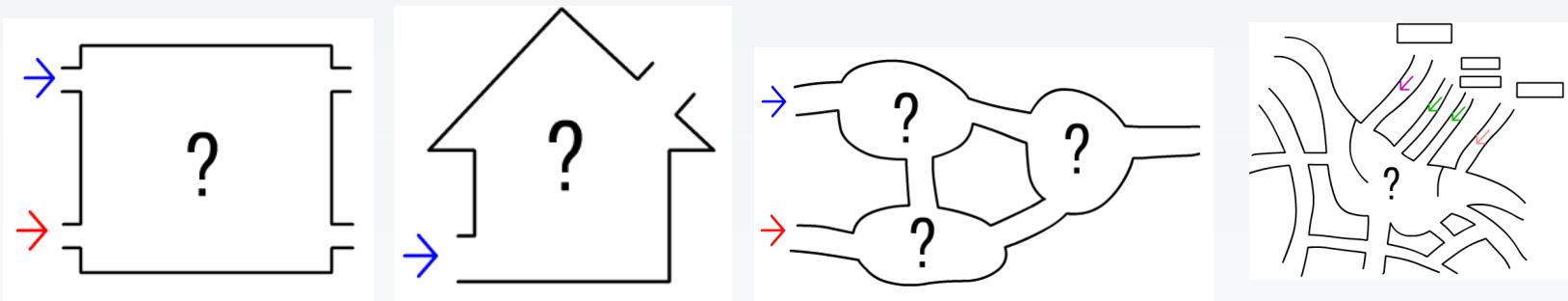
B. Zhu, M. Iwata, R. Haraguchi, T. Ashihara,
N. Umetani, T. Igarashi, K. Nakazawa



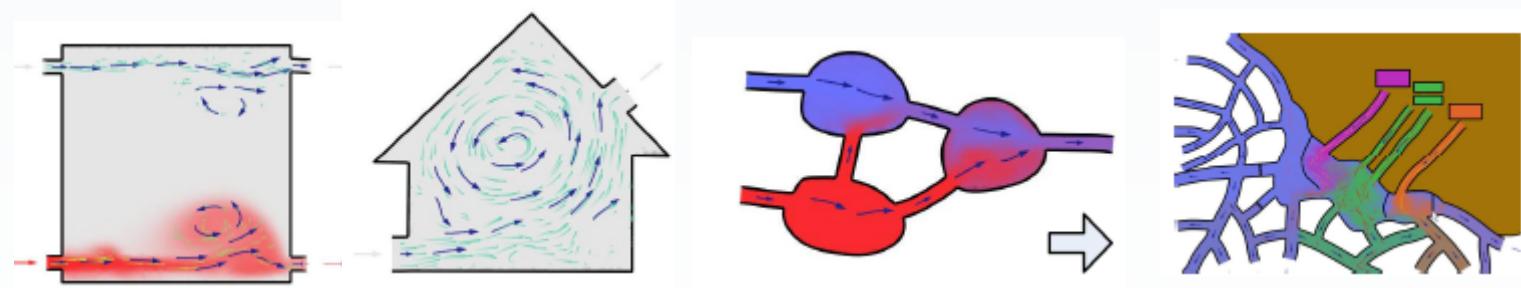
Tedious to illustrate fluid flow...



Tedious to illustrate fluid flow...



Automatic flow visualization.



Video

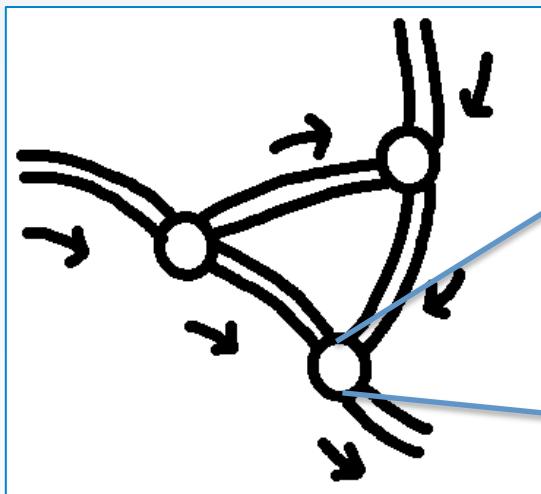
fluid



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Hybrid Fluid Simulation

Global network

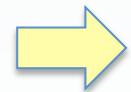


Local region



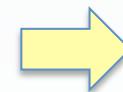
Hydraulics

Node Inflow



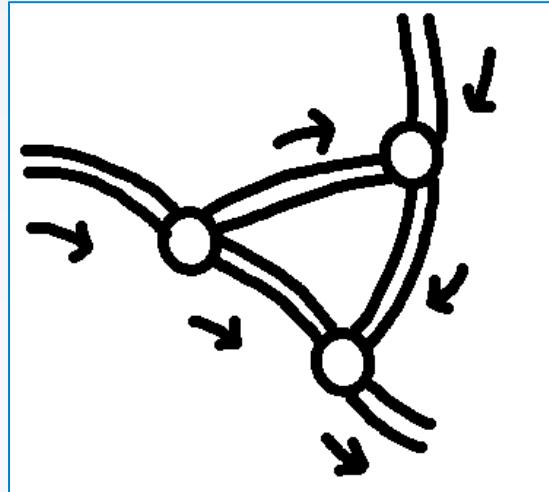
Pipe Flow
Node Pressure

Hydrodynamics



Details within
regions

Global network



Hydraulics

Node Inflow

Pipe flow

$$Q_n = -\mathbf{M} Q_e$$

Pipe flow

Pipe pressure drop

$$Q_e = \mathbf{D}_e P_e$$

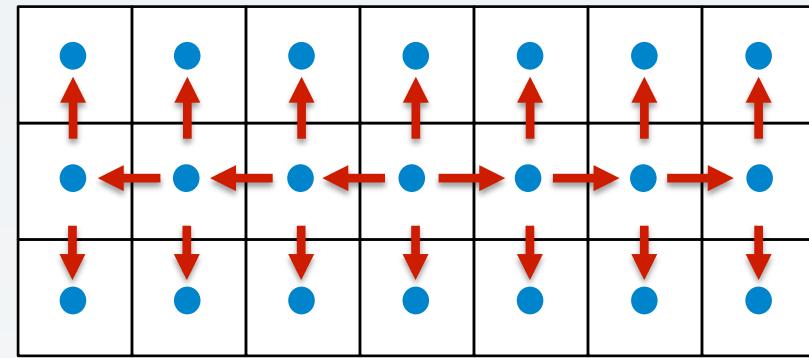
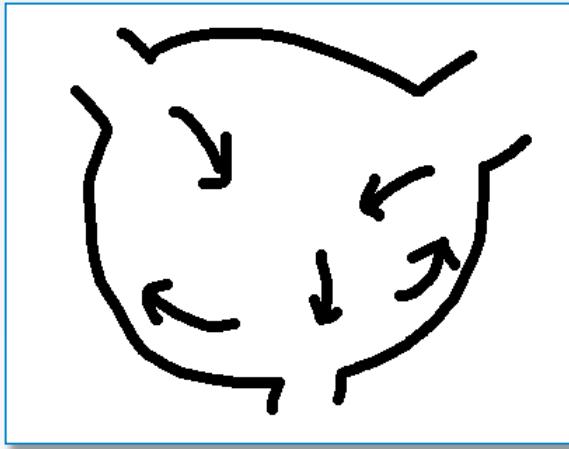
Pipe pressure drop

Node pressure

$$P_e = -\mathbf{M}^T P_n$$

Solve a global linear system.

Local region



Velocity ↑

Pressure •

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho} \nabla p + \mathbf{g} + \nu \nabla \cdot \nabla \mathbf{u},$$
$$\nabla \cdot \mathbf{u} = 0,$$

(Navier-Stokes Equation)

Solve this on grid cells inside each region.

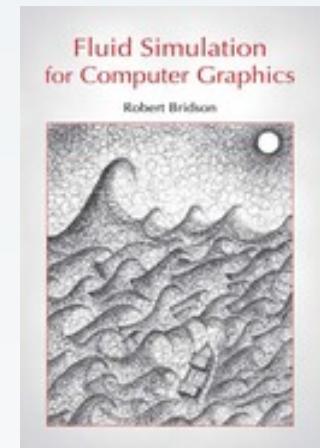
To Learn More...

The original paper:

- Zhu, et al. Sketch-based Dynamic Illustration of Fluid Systems. SIGGRAPH ASIA 2011.

Fluid Simulation:

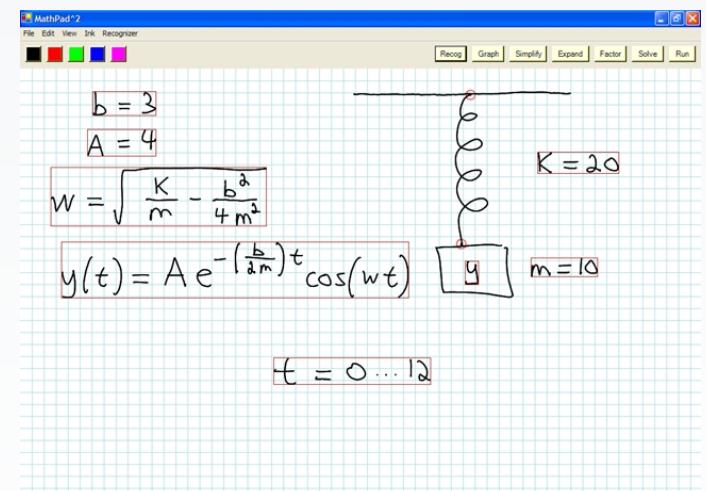
- Bridson. Fluid Simulation for Computer Graphics. AK Peters 2008.



[Bridson 2008]

Illustrative Animation:

- LaViola and Zeleznik. MathPad2: A System for the Creation and Exploration of Mathematical Sketches. SIGGRAPH 2004.



[LaViola and Zeleznik 2004]

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