Hashing II

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Background

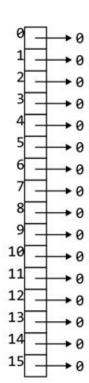
- We want to store objects in an array of size M
- We want to quickly calculate the bin where we want to store the object
 - \circ We need to come up with hash function that are hopefully $\Theta(1)$
 - Perfect hash functions (no collisions) are difficult to design
- We will look at some schemes for dealing with collisions

Consider associating each bin with a linked list:

```
template <class Type>
class Chained_hash_table {
    private:
        int table_capacity;
        int table_size;
        Single list<Type> *table;
        unsigned int hash( Type const & );
    public:
        Chained hash table( int = 16 );
        int count( Type const & ) const;
        void insert( Type const & );
        int erase( Type const & );
        // ...
```

The constructor creates an array of n linked lists

```
template <class Type>
Chained_hash_table::Chained_hash_table( int n ):
table_capacity( std::max( n, 1 ) ),
table_size( 0 ),
table( new Single_list<Type>[table_capacity] ) {
    // empty constructor
}
```

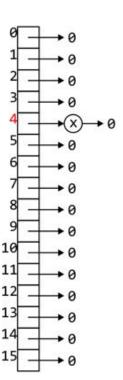


```
The function hash will determine the bin of an object
 template <class Type>
 int Chained hash table::hash( Type const &obj ) {
     return hash M( obj.hash(), capacity() );
                                                              hash(x)
Here, the hash M() function returns 0, ..., M-1:
unsigned int hash_M( unsigned int n, unsigned int M ) {
     return n % M;
```

Other functions map to corresponding linked list functions:

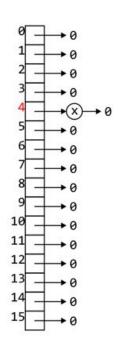
```
template <class Type>
void Chained_hash_table::insert( Type const &obj ) {
    unsigned int bin = hash( obj );

if ( table[bin].count( obj ) == 0 ) {
    table[bin].push_front( obj );
    ++table_size;
  }
}
```



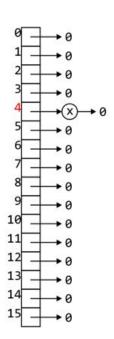
Other functions map to corresponding linked list functions:

```
template <class Type>
int Chained_hash_table::count( Type const &obj ) const {
    return table[hash( obj )].count( obj );
}
```



Other functions map to corresponding linked list functions:

```
template <class Type>
int Chained_hash_table::erase( Type const &obj ) {
    unsigned int bin = hash( obj );
    if ( table[bin].erase( obj ) ) {
        --table_size;
        return 1;
    } else {
        return 0;
```



Load Factor

To describe the length of the linked lists, we define the load factor of the hash table:

$$\lambda = \frac{n}{M}$$

This is the average number of objects per bin

This assumes an even distribution

Load Factor

If the load factor becomes too large, access times will start to increase: $O(\lambda)$

The most obvious solution is to double the size of the hash table

Unfortunately, the hash function must now change

Problems with Linked Lists

- One significant issue with chained hash tables using linked lists
 - It requires extra memory
 - It uses dynamic memory allocation
- For faster access, we could replace each linked list with an AVL tree (assuming we can order the objects)
 - The access time drops to $O(\ln(\lambda))$
 - \circ The memory requirements are increased by $\Theta(n)$, as each node will require two pointers

Chained hash tables require special memory allocation

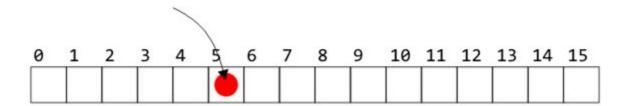
• Can we create a hash table without significant memory allocation?

We will deal with collisions by storing collisions elsewhere

We will define an implicit rule which tells us where to look next

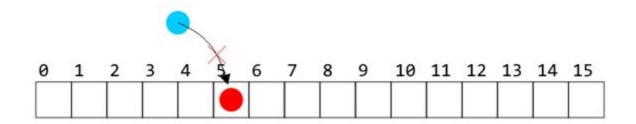
Suppose an object hashes to bin 5

If bin 5 is empty, we can copy the object into that entry



Suppose, however, another object hashes to bin 5

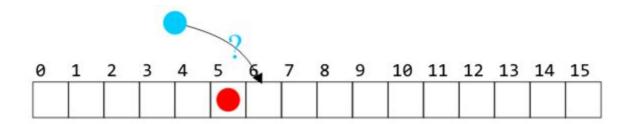
Without a linked list, we cannot store the object in that bin



We could have a rule which says:

Look in the next bin to see if it is occupied

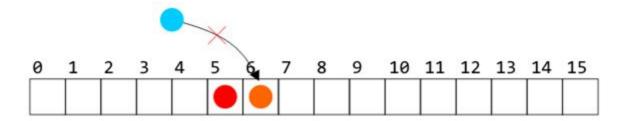
Such a rule is implicit—we do not follow an explicit link



The rule must be general enough to deal with the fact that the next cell could also be occupied

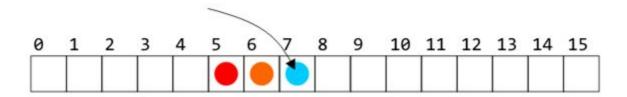
For example, continue searching until the first empty bin is found

The rule must be simple to follow—i.e., fast



We could then store the object in the next location

Problem: we can only store as many objects as there are entries in the array



Of course, whatever rule we use in placing an object must also be used when searching for or removing objects



- Recall, however, that our goal is $\Theta(1)$ access times
 - We cannot, on average, be forced to access too many bins
- There are numerous strategies for defining the order in which the bins should be searched:
 - Linear probing
 - Quadratic probing
 - Double hashing

Linear Probing

The easiest method to probe the bins of the hash table is to search forward linearly

Assume we are inserting into bin k:

- If bin k is empty, we occupy it
 - Otherwise, check bin k + 1, k + 2, and so on, until an empty bin is found
- If we reach the end of the array, we start at the front (bin 0)

Consider a hash table with M = 16 bins

- Given a 3-digit hexadecimal number:
 - The least-significant digit is the primary hash function (bin)
 - Example: for 6B72A₁₆, the initial bin is A

Insert these numbers into this initially empty hash table:

19A, 207, 3AD, 488, 5BA, 680, 74C, 826, 946, ACD, B32, C8B, DBE, E9C

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F

Start with the first four values:

19A, 207, 3AD, 488

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F

Start with the first four values:

19A, 207, 3AD, 488

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
							207	488		19A			3AD		

Next we must insert 5BA

Bin A is occupied

We search forward for the next empty bin

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
							207	488		19A	5BA		3AD		

Next we are adding 680, 74C, 826

All the bins are empty—simply insert them

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680						826	207	488		19A	5BA	74C	3AD		

Next, we must insert 946

Bin 6 is occupied

The next empty bin is 9

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Ε	F
680						826	207	488	946	19A	5BA	74C	3AD		

Next, we must insert ACD

Bin D is occupied

The next empty bin is E

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680						826	207	488	946	19A	5BA	74C	3AD	ACD	

Next, we insert B32

Bin 2 is unoccupied

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32				826	207	488	946	19A	5BA	74C	3AD	ACD	

Next, we insert C8B

Bin B is occupied

The next empty bin is F

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32				826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Next, we insert D59

Bin 9 is occupied

The next empty bin is 1

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32				826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Finally, insert E9C

Bin C is occupied

The next empty bin is 3

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E9C			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Having completed these insertions:

The load factor is $\lambda = 14/16 = 0.875$

The average number of probes is $38/14 \approx 2.71$

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Searching

Testing for membership is similar to insertions:

- Start at the appropriate bin, and searching forward until
 - The item is found,
 - An empty bin is found, or
 - We have traversed the entire array

The third case will only occur if the hash table is full (load factor of 1)

Quadratic Probing

Linear probing causes primary clustering

All entries follow the same search pattern for bins:

```
int initial = hash_M( x.hash(), M );
for ( int k = 0; k < M; ++k ) {
    bin = (initial + k) % M;
    // ...
}</pre>
```



Quadratic Probing

Quadratic probing suggests moving forward by different amounts For example,

```
int initial = hash_M( x.hash(), M );
  for ( int k = 0; k < M; ++k ) {
    bin = (initial + k*k) % M;
}</pre>
```

Problem:

Will initial + k*k step through all of the bins?



Generalization

More generally, we could consider an approach like:

```
int initial = hash_M( x.hash(), M );
for ( int k = 0; k < M; ++k ) {
    bin = (initial + c1*k + c2*k*k) % M;
}</pre>
```

Generalization

This only works for powers of two

```
If we ensure M = 2^m then choose
c1 = c2 = \frac{1}{2}
       int initial = hash M( x.hash(), M );
         for ( int k = 0; k < M; ++k ) {
             bin = (initial + (k + k*k)/2) % M;
Note that k + k*k is always even
The growth is still \Theta(k^2)
This guarantees that all M entries are visited before the pattern repeats
```

Generalization

There is an even easier means of calculating this approach

```
int bin = hash_M( x.hash(), M );
for ( int k = 0; k < M; ++k ) {
   bin = (bin + k) % M;
}</pre>
```

Double Hashing

- Problems with linear and quadratic probing
 - Linear probing causes primary clustering
 - Quadratic probing causes secondary clustering
- An alternate solution?
 - Give each object (with high probability) a different jump size

Double Hashing

Associate with each object an initial bin and a jump size For example,

```
int initial = hash_M( x.hash(), M );
  int jump = hash2_M( x.hash(), M );
  for ( int k = 0; k < M; ++k ) {
     bin = (initial + k*jump) % M;
}</pre>
```

Double Hashing

The jump size and the number of bins M must be coprime

They must share no common factors

There are two ways of ensuring this:

- Make M a prime number
- Restrict the prime factors

Consider a hash table with M = 16 bins

Given a 3-digit hexadecimal number:

- The least-significant digit is the primary hash function (bin)
- The next digit is the secondary hash function (jump size)

Insert these numbers into this initially empty hash table

19A, 207, 3AD, 488, 5BA, 680, 74C, 826, 946, ACD, B32, C8B, DBE, E9C

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F

Start with the first four values:

19A, 207, 3AD, 488

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
							207	488		19A			3AD		

Next we must insert 5BA

Bin A is occupied

The jump size is B is already odd

A jump size of B is equal to a jump size of B – $10_{16} = -5$

0	1	2	3	4	5	6	7	8	9	A	В	С	D	E	F
	4				5BA		207	488		19A			3AD		

Next we are adding 680, 74C, 826

All the bins are empty—simply insert them

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680					5BA	826	207	488		19A		74 C	3AD		

Next, we must insert 946

Bin 6 is occupied

The second digit is 4, which is even

The jump size is 4 + 1 = 5

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680					5BA	826	207	488		19A	946	74C	3AD		

Next, we must insert ACD

Bin D is occupied

The jump size is C is even, so C + 1 = D is odd

A jump size of D is equal to a jump size of D – $10_{16} = -3$

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680				ACD	5BA	826	207	488		19A	946	74C	3AD		

The sequence of bins is D, A, 7, 4

Next, we insert B32

Bin 2 is unoccupied

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32		ACD	5BA	826	207	488		19A	946	74C	3AD		

Next, we insert C8B

Bin B is occupied

The jump size is 8 is even, so 8 + 1 = 9 is odd

A jump size of 9 is equal to a jump size of $9 - 10_{16} = -7$



The sequence of bins is B, 4, D, 6, F

Inserting D59, we note that bin 9 is unoccupied

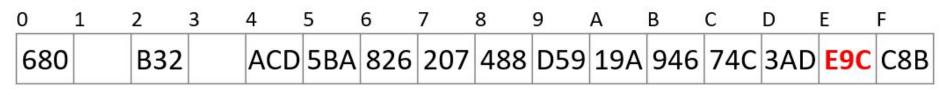
0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32		ACD	5BA	826	207	488	D59	19A	946	74C	3AD		C8B

Finally, insert E9C

Bin C is occupied

The jump size is 9 is odd

A jump size of 9 is equal to a jump size of 9 – $10_{16} = -7$



The sequence of bins is C, 5, E

Having completed these insertions:

The load factor is $\lambda = 14/16 = 0.875$

The average number of probes is $25/14 \approx 1.79$

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32		ACD	5BA	826	207	488	D59	19A	946	74C	3AD	E9C	C8B

End of Lecture