

# Programming Assignment 4

1. Install and configure OpenAI's Gym from [here](#).
2. Clone the environment repo of a 2D Maze from [here](#) and get familiar with various parameters defining the environment.
3. In the first phase of the assignment is to implement Q- Learning with the objective to find the optimal path to move from Source to Goal. Implement Q-Learning for a static environment(5x5), ie. fix the Maze you are going to train your agent upon.
  - a. Train an agent on the environment. Include learning curve showing the performance of your implementation.
  - b. Study and reason the impact of various hyperparameters of Q-learning.
  - c. For this part, initialize the Q-table such that each action has an equal probability of occurrence. Select a state and observe the changes upon the probabilistic occurrence of each action as the learning proceeds.
  - d. Modify the Q-Learning algorithm to add random exploration regulated by parameter (say  $\alpha$ ) where  $\alpha$  lies between 0 and 1. Vary the parameter and report the effect upon learning with respect to the best parameters found in part (b).
  - e. Train an agent with the parameters resulting in the best agent, reason and observe the state value of 2 separate intermediate states.
4. Create a new 5x5 Maze and use the agent trained in 3. Report and reason upon the performance. If you see any problem how can you solve this problem?

**(Bonus)** Implement State-Action-Reward-State-Action(SARSA) and train the agent on environment made in 3.

## Assessment Criteria

The assessment will be done on basis of the following components:

1. Working codes
2. Analysis and clarity of results (drawing comparisons across different parts) & clarity of the report
3. Understanding the theoretical concepts and the choice of hyperparameters.

