08 / Lab: Object Detection in Autoware.Auto

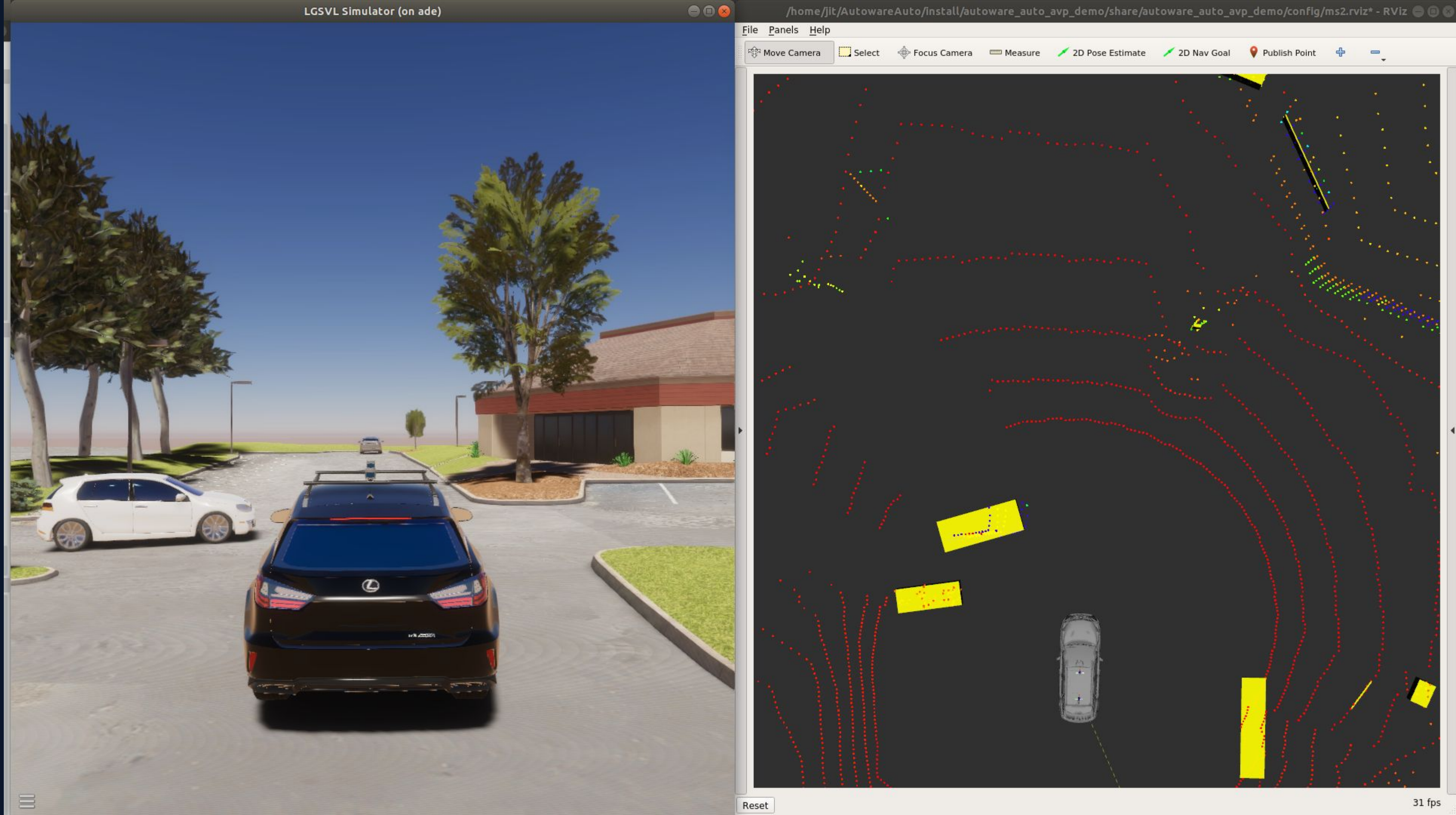# Running the Object Detection Stack in Autoware.auto

Terminal 1
```
ade$ RMW_IMPLEMENTATION=rmw_cyclonedds_cpp \
/opt/lgsvl/simulator
```
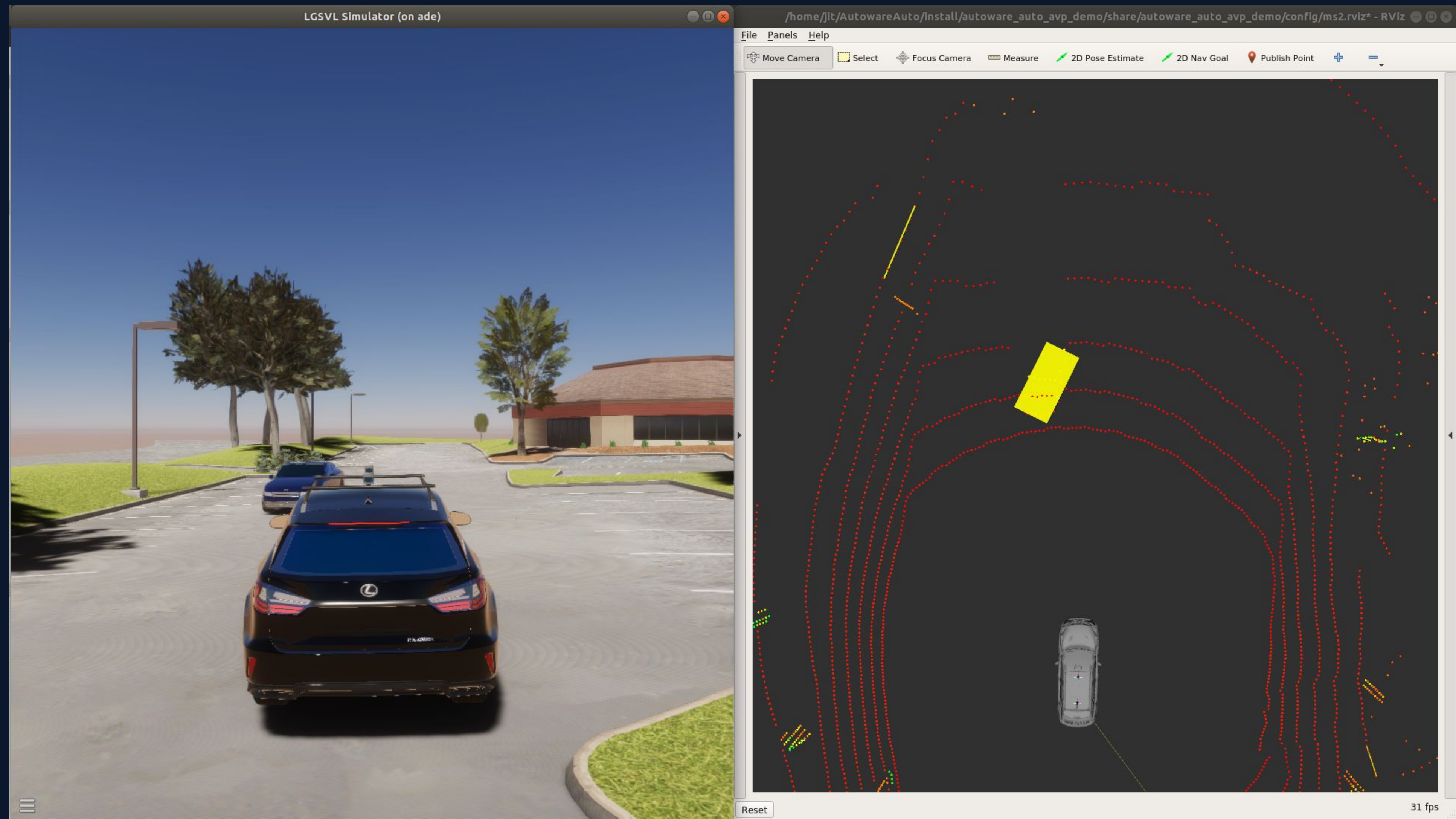
Terminal 2
```
ade$ source /opt/AutowareAuto/setup.bash
ade$ ros2 launch autoware_demos \
lidar_bounding_boxes_lgsvl.launch.py
```

Showcase

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Showcase

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