

lab-4

KNN (k nearest Neighbour algorithm)

import numpy as np

import matplotlib.pyplot as plt

from sklearn.datasets import make_classification

from sklearn.model_selection import train_test_split

x, y = make_classification (n_samples=200, n_features=2,
n_clusters=2, random_state=42,
n_informative=2, n_redundant=0, n_excluded=0)

x_train, x_test, y_train, y_test = train_test_split
(x, y, test_size=0.3, random_state=42)

Scaler = StandardScaler()

x_train = Scaler.fit_transform(x_train)

x_test = Scaler.transform(x_test)

knn = KNeighborsClassifier(n_neighbors=3)

knn.fit(x_train, y_train)

y_pred = knn.predict(x_test)

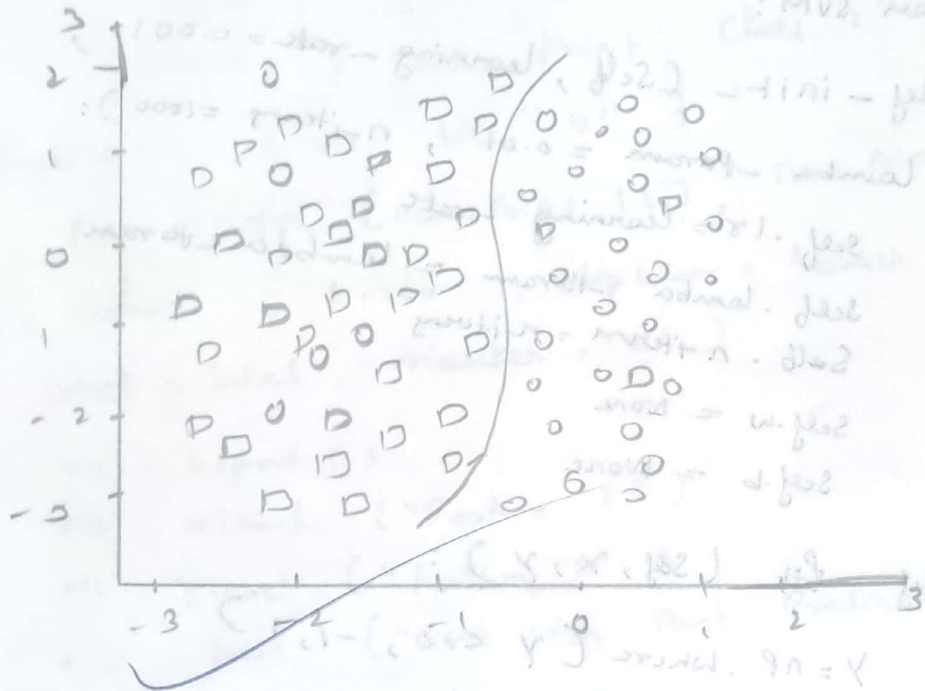
h=0.2
x_min, x_max = x_train[:, 0].min() - 1,
x_train[:, 0].max() + 1

y_min, y_max = x_train[:, 1].min() - 1,
x_train[:, 1].max() + 1

xx, yy = np.meshgrid(np.arange(x_min, x_max,
h), np.arange(y_min, y_max, h))

Z = knn.predict(np.c_[xx.ravel(),
yy.ravel()])

plt.figure(figsize=(10,6))
 plt.xlabel('lower decision boundary')
 plt.ylabel('boundary 1')
 plt.legend()
 plt.show()



SVM

```
import numpy as np
import matplotlib.pyplot as plt
```

```
class SVM:
```

```
def __init__(self, learning_rate=0.001,
```

```
lambda_param=0.01, n_iters=1000):
```

```
    self.lr = learning_rate
```

```
    self.lambda_param = lambda_param
```

```
    self.n_iters = n_iters
```

```
    self.w = None
```

```
    self.b = None
```

```
def fit(self, X, Y):
```

```
    Y = np.where(Y <= 0, -1, 1)
```

```
    n_samples, n_features = X.shape
```

```
    self.w = np.zeros(n_features)
```

```
    self.b = 0
```

```
    for _ in range(self.n_iters):
```

```
        for idx, x_i in enumerate(X):
```

```
            condition = Y[idx] * (np.dot(x_i, self.w)
```

```
                + self.b) >= 1
```

```
            if condition:
```

```
                self.w -= self.lr * (2 * self.lambda_param * self.w)
```

```
            else:
```

```
                self.w -= self.lr * (2 * self.lambda_param
```

```
                    + np.dot(x_i, Y[idx]))
```

def Predict (self, x):

approx = np.dot(x, self.w) + self.b

return np.sign (approx)

if new-point is not None:

Color = 'green' if Prediction == 1 else 'orange'

label = f 'New Point: Class {1}' if

Prediction == 1 else "0" }

plt.scatter (New-Point [0], new-point [1],
c = Color, s = 100, edgecolor = 'black',

label = label, marker = '*')

ax . legend ()

plt . xlabel ("Feature 1")

plt . ylabel ("Feature 2")

plt . title ("svm with Point Prediction")

plt . grid (True)

plt . show ()

