Write a code for distance measurement in radar using correlation.

Import modules

```
In [171]:
```

```
# import modules
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

Helper function for plotting

```
In [172]:
```

Folding

In [173]:

```
def folding(arr, n):
    # sanity check for length of timestamp and signal array must be same
    assert len(arr) == len(n)
    # print(n)
    n = np.array(n)
    #print(n)
    index_0 = np.where(n == 0)[0][0]
    # initiate an empty array to store our updated array
    new arr = []
    # push all the positive timestamps to our new arr
    # for example in our case
    \# [-1, 0, 1, 2] will be [-2, -1, 0, 1] and corresponding array values will be updat
ed accordingly
    # push from 2 to 1 in reverse order
    for i in range(len(n) - 1, index_0 - 1, -1):
        new_arr.append(arr[i])
    # push from 0 to -1 in the same order
    for j in arr[:index_0][::-1]:
        new_arr.append(j)
    # our n is now [2, 1, 0, -1] hence return the negative sorted values i.e [-2, -1, -1]
 0, 1] which is our folded timestamp
    return np.array(new_arr), sorted(-n)
```

Padding

In [174]:

Calculate the Convolution

In [175]:

```
def calculate_convolution(x, h):
   parameters:
   x -> zero padded signal of len = max_len i.e l1 + l2 - 1
    h -> our folded h(n) signal
    # initiate the matrix as said above
    ans = np.zeros((x.shape[0], x.shape[0]))
    # keep stacking the linear kernels which will be later passed on our padded signal
    for i in range(ans.shape[0]):
        if i < len(h):</pre>
            ans[i, :i + 1] = h[-i - 1:]
        else:
            ans[i, i - len(h)+1: i+1] = h
    # print to observe
    # print('\nStack of linear kernels: \n\n')
    # take the transpose
    ans = np.transpose(ans)
    # return matrix multiplication of our padded signal and our kernel matrix, this is
 our desired result
    return np.matmul(x, ans)
```

Calculate Correlation

In [176]:

```
def Convolution main(x1, n1, x2, n2):
   Calculates the convolution of x1 and x2 where
   x1 -> original signal
   x2 -> filter/kernel
   n1 -> timestamps of x1
   n2 -> timestamps of x2
    # show signal x1
    print("Signal X is: ")
    # print("\nTime stamp of X is: ")
    plot_graph(x1, n1, y_label='$X(n)$', x_label='timestamp', graph_title='Barker Seque
nce')
    # show signal x2
    print("\nShifted Signal Y is: ")
    # print("\nTimestamp of H is: ")
    plot_graph(x2, n2, y_label='$Y(n)$', x_label='timestamp', graph_title='Shifted Sign
al $Y(n)$')
    # apply folding on second signal
    folded H, neg timestamp = folding(x2, n2)
    print("\nFolded H is: ")
    # print("\nTimestamp of H is: ")
    plot_graph(folded_H, neg_timestamp, x_label='timestamp', y_label='$Y(-n)$', graph_t
itle='Y(-n)')
    # create the resutant timestamp
    # take the min of min of timestamps
    left_most_timestamp = min(min(n1), min(neg_timestamp))
    # calculate the maximum sequence length
    \max len result = len(n1) + len(neg timestamp) - 1
    # initialize the resultant convolution array with zeroes
    result_time_stamp = np.arange(left_most_timestamp, left_most_timestamp + max_len_re
sult, 1)
   # print("\nResultant timestamp would be: ")
    # pad our Signal X upto the len of max len
    # 3 is obtained from result_time_stamp - len(x1)
   X = zero pad(x1, right pad=len(result time stamp) - len(x1))
    # Here is our resultant convolution
    result = calculate convolution(X, folded H)
    return result, result_time_stamp
```

In [177]:

```
def correlation main(x, n1, h, n2):
    Calculates the corelation of x and h where
       x -> original signal
       h -> filter/kernel
       n1 -> timestamps of x
       n2 -> timestamps of h
    steps to follow:
        1. flip our signal H(n) given to get H(-n)
        2. Call our main() function to calculate the convolution of the original signal
and the flipped signal
    ####################
    # Flip the signal H(n) to get H(-n)
    flipped_h, flipped_n = folding(h, n2)
    # call our convolution function that we defined above
    # pass the arguments, x as main signal and flipped_h as kernel
    result, result_time = Convolution_main(x, n1, flipped_h, flipped_n)
    print('\nCorrelation of Signal X(n) and Y(n) is: ')
    plot_graph(result, result_time, x_label='timestamp', y_label='$X(n) * Y(-n) $', gra
ph_title='Correlation Result')
    return result
```

(a) Consider 13-point Barker sequence.

Consider a timestamp of length 50

48 49 50 51 52 53 54]

In [178]:

```
# taking the timestamp from -30 to 30 for all
t = np.arange(0, 55, 1)
print(t)

[ 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23
24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47
```

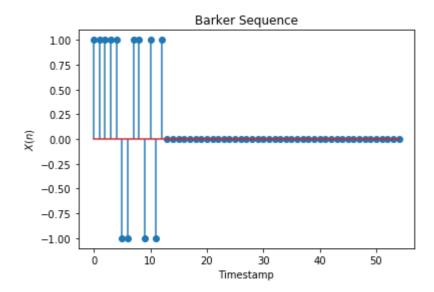
In [179]:

```
# consider a 13-point Barker sequence
X_n = np.array([1, 1, 1, 1, 1, -1, -1, 1, 1, -1, 1, 1])
print('Our Original Signal is: ', X_n)

# pad the X(n) to have same Length as our time steps
X_n = zero_pad(X_n, right_pad=42)
print('Our padded signal with same length as timestamp: \n')

plot_graph(X_n, t, x_label='Timestamp', y_label='$X(n)$', graph_title='Barker Sequence')
```

Our Original Signal is: [1 1 1 1 1 -1 -1 1 1 -1 1]
Our padded signal with same length as timestamp:



b) Take V (n) be a Gaussian random sequence with zero mean and variance.

$$\mu = 0, \sigma = 0.01$$

In [180]:

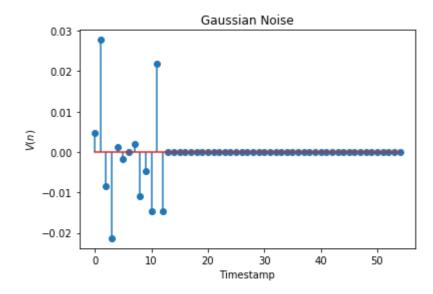
```
# Generate a gaussian random sequence with 0 maen and 0.01 std var
V_n = np.random.normal(0, 0.01, 13)
print('Our random Gaussian Noise is: \n', V_n)

# pad the X(n) to have same Length as our time steps
V_n = zero_pad(V_n, right_pad=42)
print('Our padded signal with same length as timestamp: \n')

plot_graph(V_n, t, x_label='Timestamp', y_label='$V(n)$', graph_title='Gaussian Noise')
Our pandom Gaussian Noise is:
```

Our random Gaussian Noise is:

Our padded signal with same length as timestamp:



c) Generate a sequence Y(n), Where

$$Y(n) = aX(n-D) + V(n)$$

• Take Delay D = 20, a = 0.9

In [181]:

```
def shift_d(x, d):
    # as we are shiting it forward with D timesteps
    new_x = np.zeros((x.shape))

new_x[d:] = x[:-d]
    new_x[:d] = np.zeros((d))

return new_x
```

In [182]:

```
def gen_Yn(x, v, a, d):
    X_nd = shift_d(x, d)
    v_nd = shift_d(v, d)
    y = (a * X_nd) + v_nd
    return y
```

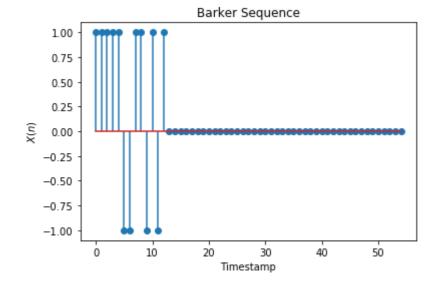
In [183]:

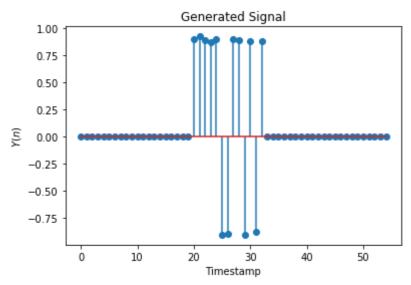
```
# our generated sequence Y_n
Y_n = gen_Yn(X_n, V_n, a=0.9, d=20)
```

d) Plot the Signal

In [184]:

```
plot_graph(X_n, t, x_label='Timestamp', y_label='$X(n)$', graph_title='Barker Sequence'
)
plot_graph(Y_n, t, x_label='Timestamp', y_label='$Y(n)$', graph_title='Generated Signa
l')
```



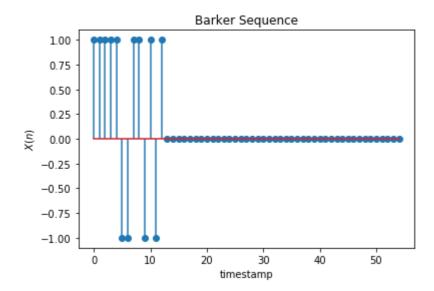


f) Compute and plot the cross correlation result

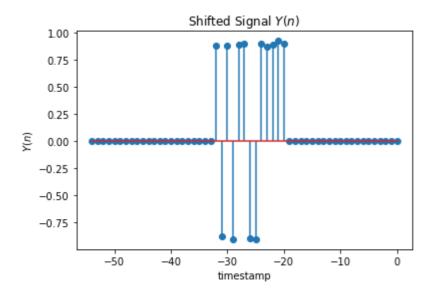
In [185]:

call the correlation function we have defined above
correlation_result = correlation_main(X_n, t, gen_Yn(X_n, V_n, a=0.9, d=20), t)

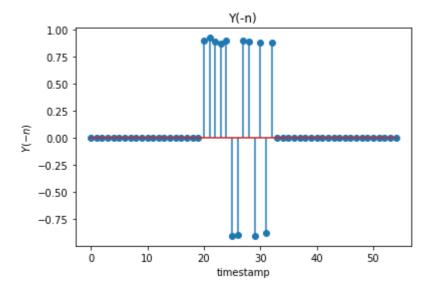
Signal X is:



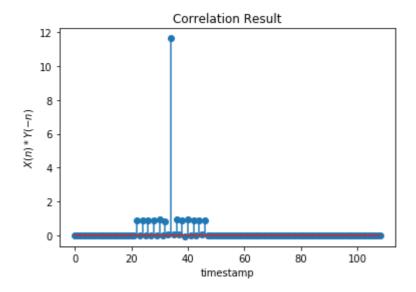
Shifted Signal Y is:



Folded H is:



Correlation of Signal X(n) and Y(n) is:



Distance Calculation

Using cross-correlation, we can calculate delay where the spike occurs, i.e the time step where cross-correlation is maximum. We can visualize the same as, this is the time stam where both of the signals are overlapping completely. The correlation value will be maximum at the last index/timestamp of Y because that's where X(n) and Y(n) overlaps completely. **Kindly correct me if I am wrong.**

In [186]:

```
last_idx_Y = correlation_result.argmax() - 1 # subtracted 1 because of 0-based indexing print('Last Index of Y is: ', last_idx_Y)

# delay would be last Index where Peak occured subtracted by Time period
# i.e in our case it would be 33 - 13 = 20

delay = last_idx_Y - 13
print("Delay is: ", delay)
```

Last Index of Y is: 33 Delay is: 20

$$R = (c * delay)/2$$

where, $c=3\times 10e8$ m/s and R is the distance

In [187]:

```
c = 3 * 10e8
R = (c * delay)/2
print('Calculated Distance is: {} m/s'.format(R))
```

Calculated Distance is: 30000000000.0 m/s

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