## **Problem Statement**

- 1. Use the below given data set
- 2. Perform the below given activities:
- a. Create classification model using logistic regression model

- b. verify model goodness of fit
- c. Report the accuracy measures
- f. interpret the results
- g. visualize the results

for questions (b,c,f,g) - Ans is as below

```
> model<-
glm(input1~raw_timestamp_part_1+raw_timestamp_part_2+cvtd_timestamp+num_window+roll_belt+pitch_belt+yaw_belt+total_accel_belt,data = input)
 mode1
Call: glm(formula = input1 ~ raw_timestamp_part_1 + raw_timestamp_part_2
    cvtd_timestamp + num_window + roll_belt + pitch_belt + yaw_belt +
    total_accel_belt, data = input)
Coefficients:
                       (Intercept)
raw_timestamp_part_2
2011 11:25
                                                          cvtd_timestamp05-12-
                                                         7.440e-04
                     -9.841e+05
                                 -1.869e+02
1.242e-07
                                                                    -1.870e+02
cvtd_timestamp05-12-2011 14:22
                                  cvtd_timestamp05-12-2011 14:23
cvtd_timestamp28-11-2011 14:15
                                  cvtd_timestamp30-11-2011 17:12
num_window
                     -1.949e+02
                                                        -1.949e+02
2.554e+02
                                  1.192e+02
                                                                    -8.201e-04
                       roll_belt
                                                        pitch_belt
yaw_belt
                          total_
                                _accel_belt
                     -4.217e-04
                                                        -4.897e-04
9.792e-05
                                  2.525e-03
Degrees of Freedom: 4023 Total (i.e. Null); 4010 Residual
Null Deviance:
                     86.08
Residual Deviance: 80.79
                                 AIC: -4277
```

```
summary(model)
Call:
glm(formula = input1 ~ raw_timestamp_part_1 + raw_timestamp_part_2 +
cvtd_timestamp + num_window + roll_belt + pitch_belt + yaw_belt +
total_accel_belt, data = input)
Deviance Residuals:
                              Median
                                          3Q
0.01123
 -0.25039
              -0.04901
                           -0.01883
                                                         0.96934
Coefficients:
                                           (Intercept)
               ump_part
 raw_timestamp_part_
                                             1.242e-07
                                                            7.888e-0<u>9</u>
                                                                           15.747
                                                                                        <2e-16 ***
 cvtd_timestamp05-12-2011
cvtd_timestamp05-12-2011
                                              .869e+02
.870e+02
                                                           9.069e+02
9.072e+02
                                                                                           83
                                                                           -Ŏ
                                                           9.455e+02
9.455e+02
 cvtd_timestamp05-12-2011
                                            1.949e+02
                                                                           -0.206
                                                                                        0.837
cvtd_timestamp05-12-2011
cvtd_timestamp28-11-2011
cvtd_timestamp30-11-2011
hum_window
                                  14:23
14:15
17:12
                                            ·1.949e+02
                                                                           -0.206
                                                                                        0.837
                                               554e+02
192e+02
                                                           1.239e+03
5.766e+02
                                                                            0.206
0.207
                                                                                        0.837
                                                                            0 194
 roll_belt
                                            4.217e-04
                                                                           -0.839
                                                                                         0.402
                                                                           -0.426
0.839
1.332
pitch_belt
                                                           1.151e-03
                                                                                        0.670
                                            9.792e-05
2.525e-03
                                                              168e-04
 yaw_belt
                                                              896e-03
total_accel_belt
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
(Dispersion parameter for gaussian family taken to be 0.02014796)
                                                 degrees of freedom degrees of freedom
     Null deviance: 86.076
                                     on 4023
Residual deviance: 80.793
                                     on 4010
AIC: -4276.7
Number of Fisher Scoring iterations: 2
```

d. Report the variable importance

Ans: variables highlighted in pink are important variables

e. Report the unimportant variables

Ans: variables highlighted in green are unimportant variables