

Data Structure

A data structure is a way of organizing and storing the data so operations like updating, searching, deleting can be done efficiently

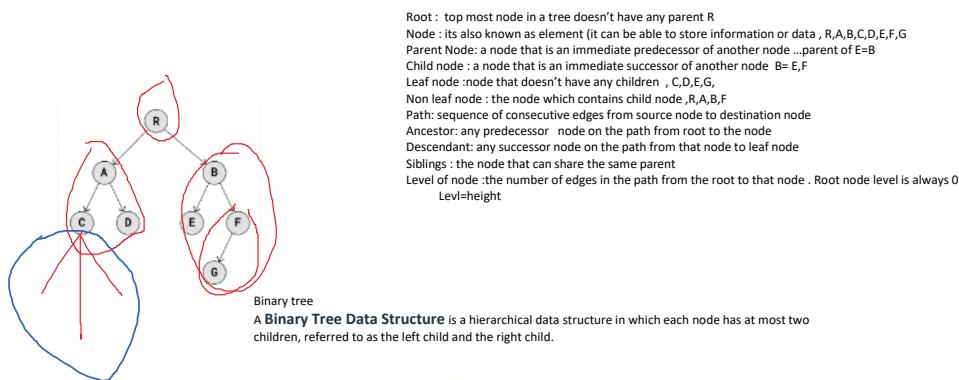
Why efficiency?

- Time complexity
- Memory usage
- CPU operations

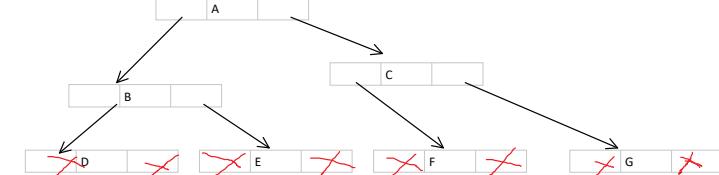
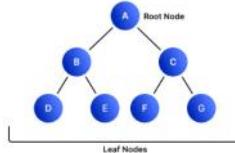
Common Data Structures

Array	Sequential data
Linked lists	Dynamic data
Stack	Undo/back operations (LIFO)
Queue	Scheduling (FIFO)
Hash Table	Quick lookup
Trees	Hierarchical data
Graphs	Network

Tree Data Structure : Tree can be defined as a collection of entities(Nodes) linked together to simulate hierarchy



Binary Tree in Data Structure



Maximum number of children nodes 2
 No rule for ordering to insert elements
 Depth can be grow large
 Not necessarily balanced
 Search : O(n)
 Insert/delete o(n)

Trees are always non-linear data structures:
 Data is in a tree is not stored in sequentially, instead it is organized across multiple levels, forming a hierarchical structure. Because of this arrangement a tree is classified in to linear data structure

Representation of a node using collection of nodes .each node can be represented with help of class or structs

```
Class node :  

Def __init__(self,x):  

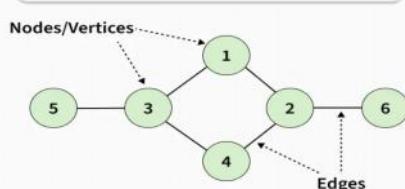
  Self.data=x  

  Self.chikdren =[]
```

Graphs data structure:

A graph is a non-linear data structure made up of vertices (node) and edges (connection) that represent relationship between the objects .

INTRODUCTION TO GRAPHS

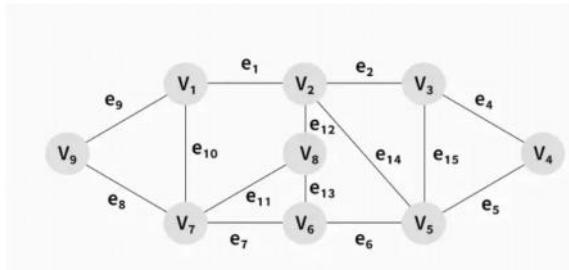


Components :
 Vertices : vertices are the fundamental units of the graph
 Edges: Edges are drawn or used to connect two nodes of the graph .

Types of Graphs:
 Based on the different properties we can divide the graphs
 Such as edges,directions,connectivity and more

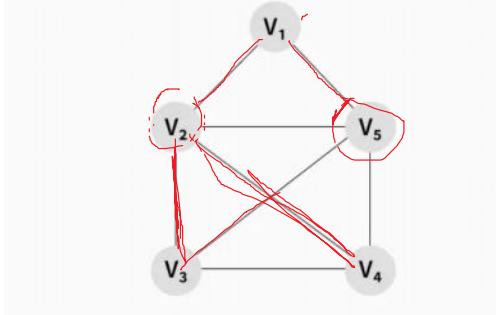
Based on weight :
 Weighed graphs and unweighted graphs

1. Weighted graph :A weighted graph is a graph where each edge has a number(weight) that represents distance,time,cost.



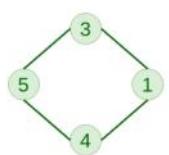
Example; travelling from source to destination (we are having distance in kM, time in mi/hr)

2. Unweighted Graph : where all edges are treated equally ,with no extra values like, distance, cost

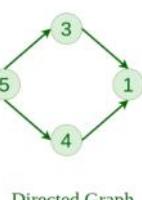


Based on edges we have divided in to directed and undirected graph :

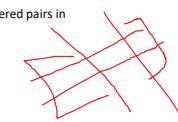
Undirected graph: a graph in which edges do not have any direction the nodes are ordered pairs in the definition of every edge
 Directed graph : a graph in which edges are having direction



Undirected Graph

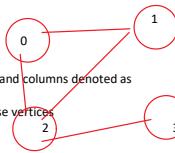


Directed Graph



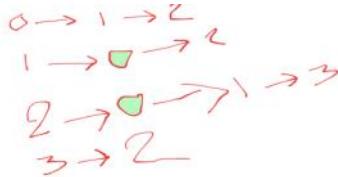
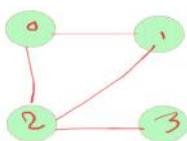
Representation of graphs

Adjacency matrix : graph is stored in the form of 2D matrix where rows and columns denoted as columns .
 Each entry in the matrix represents the weight of the edge between those vertices
 $\text{Matrix}[i][j] = 1$ if there is an edge between vertex i and vertex j
 $\text{Matrix}[i][j] = 0$ if there is no edge



	0	1	2	3
0	0	1	1	0
1	1	0	1	0
2	1	1	0	1
3	0	0	1	0

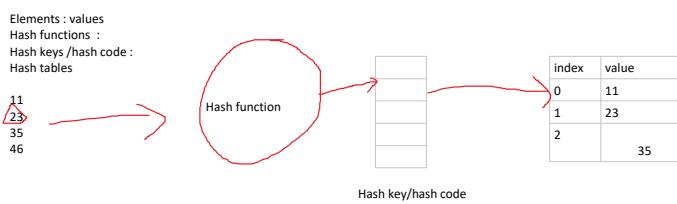
Adjacency list representation of a graph
 This graph represented as collection of array list .there is an array of pointer which points to the edges connected to the vertex



$[0,1,2]$
 $[1,0,2]$
 $[2,0,1,3]$
 $[3,2]$

- Applications:
1. Social networks
 2. Computer networks
 3. Transportation network
 4. Neural network:-
 5. Compilers
 6. Network optimizations

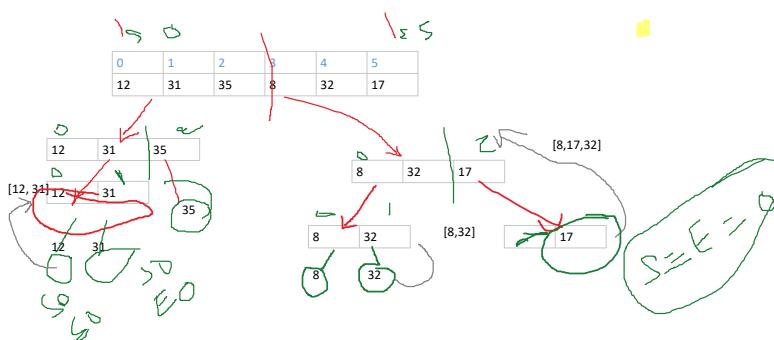
Hashing Table:
It is a technique in data structure to improve efficiency in store and retrieve the data
- the data is stored in the form of key-value pair



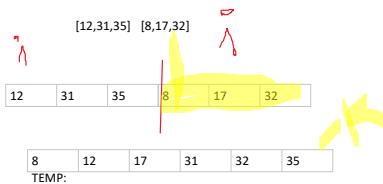
- Applications:
Login systems,
Dictionary loops
Caching
Compilers
Searching phone contact



Merge sort:
1 divide the array(mid)
2 divide the same process until
single element is remains
3. Merge parts to create
sorted array

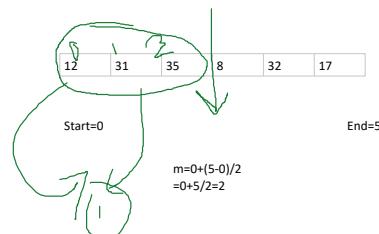


12>8
12>17



Pseudo code:

```
Mergesort(A, left, right)
if( left < right
    mid=left+(right-left)/2
    Mergesort(A, left ,mid )...left
    Mergesort(A, mid+1,right )-right
Merge(A,Left , mid,right)
```



Merge (A, left, mid ,right)

```
create an empty Array temp
i=left
j=mid+1
k=0

while i<=mid and j<=right )
    if A[i] <= A[j]
        temp[k]=A[i]
        i=i+1;
        else :
            temp[k]=A[i]
            j=j+
            k=k+
    while i<=mid
        temp[k]=A[i]
        i=i+
        k=k+
    while j<= right;
        temp[k]=A[i]
```

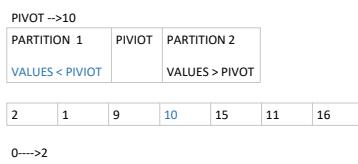
```

j=j+1
k=k+1
for f=0 to k-1
    A[ left+f ] =temp[x]

```

Quick Sort :

10	15	1	2	9	16	11
----	----	---	---	---	----	----



7	6	10	5	9	2	1	15	7
Start								end

PIVOT= 7
7<=pivot=7
6<=pivot=7
10<=pivot=7 false

7	6	10	5	9	2	1	15	7
	Start							end

7> pivot=7 false
Swap end value start with end

7	6	7	5	9	2	1	15	10
	Start							end

7<=pivot=7 if true move start point
5<=pivot=7 if true
9<=pivot=7 false

7	6	7	5	9	2	1	15	10
		Start				end		

10> pivot=7 true
15> pivot=7
1>pivot=7 false

7	6	7	5	1	2	9	15	10
				start		end		

1<=pivot=7
2<=pivot=7
9<=pivot=7 false

9> 7
2>7 we canot do the swap because
starting index is greater than the ending index.
Swap pivot element with end value

2	6	7	5	1	7	9	15	10
				start				

Tim complex = O(n^2)
=O(log n)

Partition(A, lb ,ub)

```

Pivot =A[lb]
start=lb;
end =ub;

while(start < end)
{
    while( A[start] <= pivot)
    {
        start++;
    }
    while ( A[end] > pivot )
    {
        end--;
    }
    if (start < end)
    {
        swap(A[start] ,A[end])
    }
}

swap(A[lb] ,A [end]) ; return end

Quicksort( A, Lb, Ub)
if( lb < ub)
{
    loc=partition(A, lb,bb)
    quicksort(A, lb, loc-1);
    quicksort( A, loc+1, ub);
}

```