17. Shadow Arm:

A 5 DOF robotic arm was developed to pick and place object of various shapes. This arm was controlled wirelessly using a pair of Bluetooth and flex sensors were used to obtain angular data from the user.
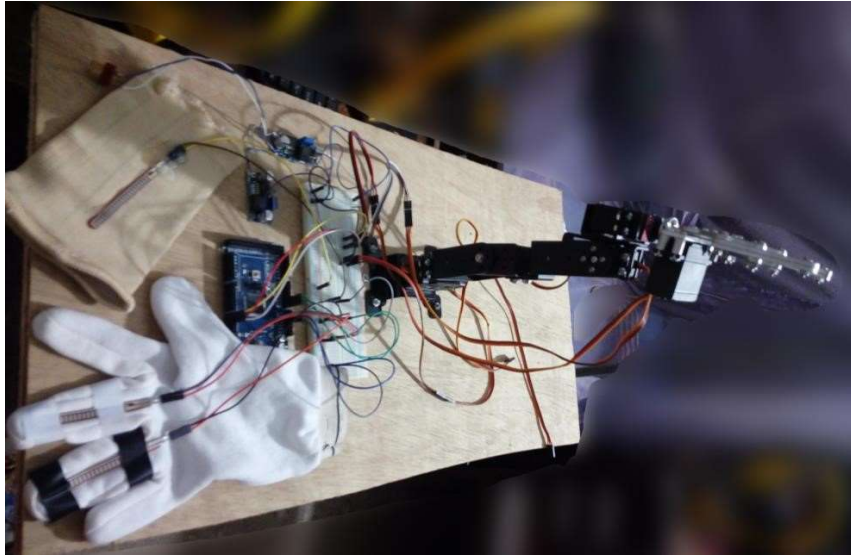

Fig: Shadow Arm