

12. Line Follower Robot:

A robotic system that is designed to follow a line using a PID controller. This task was achieved using IR sensors as input devices, microcontroller as processing unit and wheel mounted in motors as output of the system.

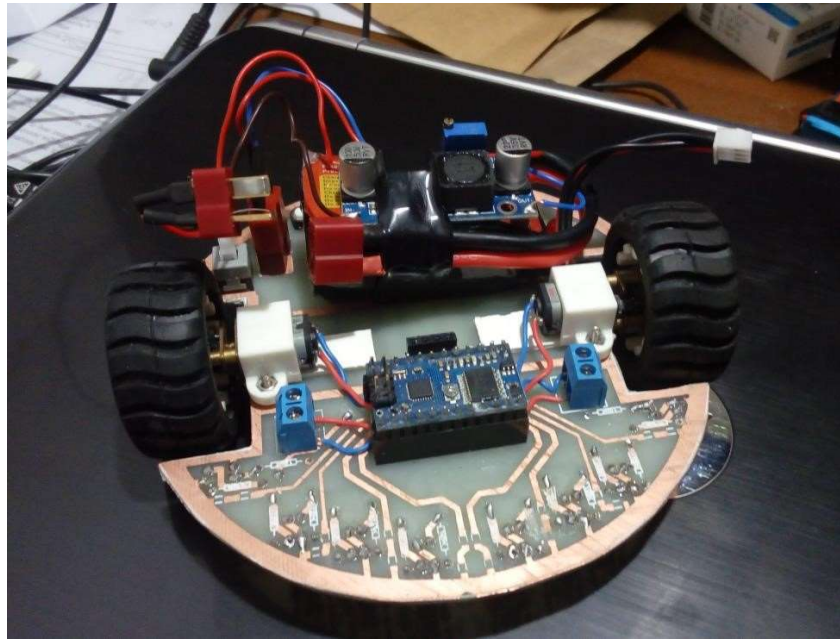


Fig: Line Follower Robot.