

# 1 Review

**Definition 1** Suppose we have outcomes  $\lambda$  which occur with probability  $\mathcal{P}(\lambda)$ . Then the expectation value of the process  $X$  of measuring these outcomes is defined as:

$$\mathbf{E}(X) = \sum_{\lambda} \lambda \mathcal{P}(\lambda) \quad (1)$$

**Theorem 1** Suppose we are able to prepare a system to be in state  $\psi$  each time. The expectation value of making a measurement associated with observable  $A$  is then given by<sup>1</sup>:

$$\langle A \rangle_{\psi} \equiv \mathbf{E}(A) = \langle \psi, A\psi \rangle \quad (2)$$

**Definition 2** Suppose we have a process  $X$  of measuring some outcomes with expectation value  $\mathbf{E}(X)$ . The standard deviation is defined as:

$$\sigma_X^2 \cong E((X - \mathbf{E}(X))^2) = \sum_{\lambda} (\lambda - E(X))^2 \mathcal{P}(\lambda) \quad (3)$$

**Theorem 2** Suppose we prepare a system to be in a state  $\psi$  each time. We then consider the measurement associated with observable  $A$ . We call the standard deviation of this measurement the uncertainty. It is then computed via:

$$\sigma_X^2 = \langle (A - \langle A \rangle_{\psi})^2 \rangle_{\psi} \quad (4)$$

**Definition 3** Let  $A, B$  be two linear operators. We define the commutator to be:

$$[A, B] = AB - BA$$

**Postulate 1** The dynamics of a quantum state over time is given via the solution to the equation:

$$i\hbar \partial_t |\psi(t)\rangle = H |\psi(t)\rangle$$

## 2 Suggested Exercises

- I) **Warmup.** Suppose we have some two-level spin system. This means that we have some observable associated to a spin measurement, which in the  $|\uparrow\rangle, |\downarrow\rangle$

$$S_z = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

- i) For each of the following states, what is the probability to measure  $\uparrow$ ? What about  $\downarrow$ ?

$$\begin{aligned} |\psi_1\rangle &= \frac{1}{\sqrt{2}} (|\uparrow\rangle + |\downarrow\rangle) & |\psi_2\rangle &= \frac{3}{5} |\uparrow\rangle + \frac{4}{5} |\downarrow\rangle \\ |\psi_3\rangle &= |\uparrow\rangle & |\psi_4\rangle &= \frac{8}{10} |\uparrow\rangle + \frac{6}{10} |\downarrow\rangle \end{aligned} \quad (5)$$

- ii) For each of the states above, compute the expectation value of  $S_z$ .

- iii) Now let's define this basis<sup>2</sup>

$$|\uparrow\rangle_x = \frac{1}{\sqrt{2}} (|\uparrow\rangle + |\downarrow\rangle) \quad |\downarrow\rangle_x = \frac{1}{\sqrt{2}} (|\uparrow\rangle - |\downarrow\rangle)$$

Suppose that we have some other observable that in this basis is:

$$S_x = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

- What is the expectation value of  $S_x$  in state  $|\psi_1\rangle$ ? What about  $|\psi_2\rangle$ ?
- Suppose we are in state  $|\psi_2\rangle$ . A measurement associated to  $S_x$  is made, and we get  $\frac{\hbar}{2}$ . What is the probability that if we did the measurement associated with  $S_z$  we also got  $\frac{\hbar}{2}$ ?

<sup>1</sup>We now change conventions for the inner product to be linear in the second entry

<sup>2</sup>It is indeed a basis.

## II) Uncertainty Principle.

- i) During our session we showed theorems (1) and (2) in the case where all eigenvalues are distinct (non-degenerate case). Show that the theorems still hold if there are different eigenvectors with the same eigenvalue (degenerate case).
- ii) We also showed that if you have observables  $p$  and  $x$  with  $[x, p] = i\hbar$  then the following inequality is satisfied:

$$\sigma_x \sigma_p \geq \frac{\hbar}{2}$$

Now suppose we had any two observables  $A, B$  with  $[A, B] = k$ . Derive an uncertainty principle for this case? What if we set  $k = 0$ ? Why does this make sense?

## III) Particle in a Box Revisited.

Recall we considered the “particle in a box example”. For a box of size  $L$  we had the following Hilbert Space.

$$\mathcal{H} = \{f : [0, L] \rightarrow \mathbb{C} \mid \int_0^L |f|^2 < \infty, f(0) = f(L) = 0\}$$

Where the inner product is give via:

$$\langle f, g \rangle = \int_0^L \bar{g} f$$

We also defined operators:

$$p = -i\partial_x \quad x = x \cdot$$

Where  $x$  is just multiplication by  $x$ :  $\psi(x) \rightarrow x \cdot \psi(x)$ .

We then define the Hamiltonian (observable associated with energy).

$$H = \frac{p^2}{2m}$$

One thing I have not previously told you (and we will discuss in more detail later), is that the probability of the particle to be found in the region  $[a, b] \subseteq [0, L]$  is given via:

- i) Find the eigenstates of the Hamiltonian and their eigenvalues. What is their physical significance?
- ii) Compute the following commutators:

$$[x, p] \quad [x, p^2] \quad [x, p^n]$$

*Hint: Use Induction for the last one*

- iii) Let  $|E_n\rangle$  be the state associated to the  $n$ th energy level. Let  $\psi(t=0, x) = \frac{1}{\sqrt{2}}(|E_0\rangle + |E_1\rangle)$ . What is  $\psi(t, x)$ ?
- iv) Compute the expectation value of the operator  $x$  as a function of time  $t$ .
- v) Setting all constants ( $\hbar, m, L$  etc.) to 1, write code in python that plots  $|\psi(t, x)|^2$  on the range of  $[0, L]$ . Make a plots over a range of time of your choice and save them as .pngs. Then combine that in a gif and see how the particle “moves” around. How does this relate to your answer in the previous part?
- vi) Write down equations of motion for  $\langle x \rangle_\psi$  and  $\langle p \rangle_\psi$  for arbitrary  $\psi$  (*Hint: Use Schrödinger equation and maybe assume a product rule for inner products*)