
Algorithm 1: MS-EPSO pseudocode

Input: Objective function $f(x)$, D , LB , UB , NP , NFE , τ , CP , NR , MLL
Output: Best solution found $P_g = \{x_1, x_2, x_3, \dots, x_D\}$
// After each function evaluation:
// 1) Increment FEs counter;
// 2) Check for a possible new global best;
// 3) Check the stopping criteria.

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1   $FES \leftarrow 0$ 
2   $MaxV \leftarrow \text{abs}(UB - LB)$ 
3   $MinV \leftarrow MaxV * -1$ 
4  for  $i \leftarrow 0$  to  $NP$  do
5      Initialize particle ( $x_i$ ) between  $[LB, UB]$ 
6      Initialize velocity ( $v_i$ ) between  $[MinV, MaxV]$ 
7      Initialize strategic weights ( $w_{i1}^*, w_{i2}^*, w_{i3}^*, w_{i4}^*$ ) between  $[0, 1]$ 
8      Initialize local limit ( $PLL_i$ )  $\leftarrow 0$ 
9      Initialize exploration mode ( $EXP_i$ )  $\leftarrow 1$ 
10      $x_{i\mu} \leftarrow \mu(x_i)$ 
11      $x_{i\sigma} \leftarrow \sigma(x_i)$ 
12      $x_{if} \leftarrow f(x_i)$ 
13 end
14 Save all local best information ( $\hat{x}_i, \hat{x}_{if}, \hat{x}_{i\mu}, \hat{x}_{i\sigma}$ )
15 Save global best information ( $x_g, x_{gf}, x_{g\mu}, x_{g\sigma}$ )
16 repeat
17     for  $i \leftarrow 0$  to  $NP$  do
18          $Rule_1 \leftarrow PLL_i < MLL \wedge EXP_i ? 1 : 0$ 
19          $Rule_2 \leftarrow PLL_i < MLL \wedge \neg EXP_i ? 1 : 0$ 
20          $Rule_3 \leftarrow PLL_i \geq MLL ? 1 : 0$ 
21         if  $Rule_1$  then
22              $x_{new} \leftarrow \text{DrawFromGaussianDistribution}(x_{g\mu}, x_{g\sigma}, D)$  //  $D$  samples
23              $x_{newf} \leftarrow f(x_{new})$ 
24              $best_{replica} \leftarrow \text{GenerateReplicas}(NR, w_i^*, \tau)$  // EPSO strategy
25              $best_{replicaf} \leftarrow f(best_{replica})$ 
26         end
27         if  $Rule_2$  then
28              $best_{replica} \leftarrow \text{GenerateReplicas}(NR, w_i^*, \tau)$  // EPSO strategy
29              $best_{replicaf} \leftarrow f(best_{replica})$ 
30              $x_{new} \leftarrow \text{MoveParticle}(x_i, v_i, \hat{x}_i, x_g, CP)$  // EPSO Movement
31              $x_{newf} \leftarrow f(x_{new})$ 
32         end
33         if  $Rule_3$  then
34              $x_{new} \leftarrow \text{DrawFromGaussianDistribution}(\hat{x}_{i\mu}, \hat{x}_{i\sigma}, D)$  //  $D$  samples
35              $x_{newf} \leftarrow f(x_{new})$ 
36              $best_{replica} \leftarrow \text{GenerateReplicas}(NR, w_i^*, \tau)$  // EPSO strategy
37              $best_{replicaf} \leftarrow f(best_{replica})$ 
38              $PLL_i \leftarrow 0$ 
39              $EXP_i \leftarrow 0$ 
40         end
41          $x_i, x_{if}, v_i, w_i^* \leftarrow \text{Compare}(x_{new}, best_{replica})$ 
42          $\hat{x}_i, \hat{x}_{if}, \text{NewLocalBest?} \leftarrow \text{Compare}(x_i, \hat{x}_i)$ 
43         if  $\text{NewLocalBest}$  then
44              $\hat{x}_{i\mu} \leftarrow \mu(\hat{x}_i)$ 
45              $\hat{x}_{i\sigma} \leftarrow \sigma(\hat{x}_i)$ 
46         else
47              $PLL_i \leftarrow PLL_i + 1$ 
48         end
49     end
50 until  $FES == NFE$ 
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