

TypeScript

Version 0.0.1

Contents

1	Inti	roduction	3
2	Alg	orithm Analysis	4
		•	4
3	Dat	a Structures and Algorithms	5
	3.1	Bits	6
		3.1.1 Bit Parity	6
		3.1.2 Bit Shift Operator	7
	3.2		7
			7
	3.3		7
4	Pro	blem Solving Methods	8
	4.1	Greedy Algorithms	8
		4.1.1 Overview	8
		4.1.2 Dijkstra's Shortest Path Algorithm	8
	4.2		8
			9
	4.3		9
5	Dor	main Specific 1	0
	5.1	Language	0
		5.1.1 This	0
		5.1.2 Event Loop	0
		5.1.3 Asynchronous Programming	0
		5.1.4 Runtime Environments	0
		5.1.5 Reactivity	0

6	\mathbf{App}	oendix														11	L
	6.1	Resources														1.	1

Introduction

In-progress book about algorithms and data structures in TypeScript.

Algorithm Analysis

2.1 Amortized Analysis

The motivation for amortized analysis is that looking at the worst-case run time can be too pessimistic. Instead, amortized analysis averages the running times of operations in a sequence over that sequence. Amortized analysis is a useful tool that complements other techniques such as worst-case and average-case analysis.

— https://en.wikipedia.org/wiki/Amortized_analysis

Imagine a dynamic list backed by a fixed size array that doubles once capacity is reached and require n inserts into the new fixed size array.

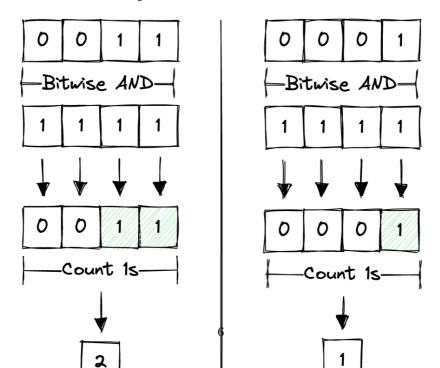
n	# of inserts
1	1
2	1
3	1
	1
\mathbf{n}	n
	n + 1

$$\frac{\text{\# of inserts}}{n} \to \frac{n+n+1}{n} \to \frac{2n+1}{n} \to \frac{2n}{n} \to 2$$

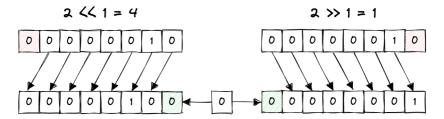
Data Structures and Algorithms

3.1 Bits

3.1.1 Bit Parity



3.1.2 Bit Shift Operator



3.2 Stacks and Queues

3.2.1 Fixed Stack

3.3 Graphs

Problem Solving Methods

4.1 Greedy Algorithms

4.1.1 Overview

A greedy algorithm is any algorithm that follows the problem-solving heuristic of making the locally optimal choice at each stage. In many problems, a greedy strategy does not produce an optimal solution, but a greedy heuristic can yield locally optimal solutions that approximate a globally optimal solution in a reasonable amount of time.

— https://en.wikipedia.org/wiki/Greedy_algorithm

4.1.2 Dijkstra's Shortest Path Algorithm

Dijkstra's shortest path algorithm is a search algorithm that finds the shortest path between a vertex and other vertices in a weighted graph.

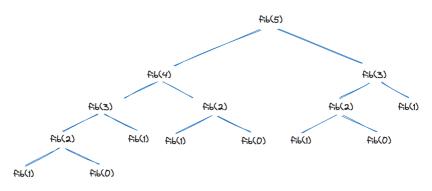
4.2 Recursion

The power of recursion evidently lies in the possibility of defining an infinite set of objects by a finite statement. In the same manner, an infinite number of computations can be described by a finite recursive program, even if this program contains no explicit repetitions.

4.2.1 Fibonacci Sequence

$$F_0 = 0$$

 $F_1 = 1$
 $F_n = F_{n-1} + F_{n-2}$ for $n > 1$



```
\begin{split} F_n &= F_{n-1} + F_{n-2} \\ F_5 &= F_4 + F_3 \\ F_5 &= (F_3 + F_2) + (F_2 + F_1) \\ F_5 &= ((F_2 + F_1) + (F_1 + F_0)) + ((F_1 + F_0) + F_1) \\ F_5 &= (((F_1 + F_0) + F_1) + (F_1 + F_0)) + ((F_1 + F_0) + F_1) \\ F_5 &= (((1 + 0) + 1) + (1 + 0)) + ((1 + 0) + 1) \\ F_5 &= 5 \\ \\ \text{export function fib(n: } \underline{\text{number}}) : \underline{\text{number}} \; \{ \\ \text{ if } (n == 0 \mid \mid n == 1) \; \{ \\ \text{ return n} \\ \} \\ \text{ return fib(n - 1) + fib(n - 2)} \} \end{split}
```

4.3 Probability

¹https://archive.org/details/algorithmsdatast00wirt/page/126]

Domain Specific

- 5.1 Language
- 5.1.1 This
- 5.1.2 Event Loop
- 5.1.3 Asynchronous Programming
- 5.1.3.1 Promises
- 5.1.3.2 Async/Await
- 5.1.4 Runtime Environments
- 5.1.4.1 Browser
- 5.1.4.2 Server
- 5.1.5 Reactivity

Appendix

6.1 Resources

- LeetCode
- Project Euler
- The Algorithm Design Manual
- Elements of Programming Interviews