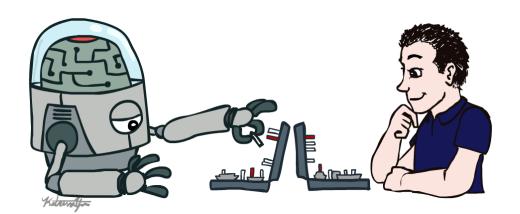
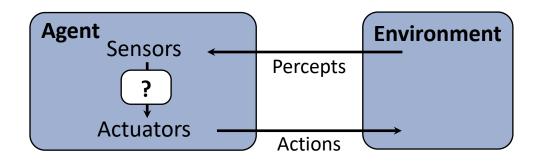
# **Artificial Intelligence**

Lecture 2: Agents



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# Agents and environments



- An agent perceives its environment through sensors and acts upon it through actuators (or effectors, depending on whom you ask)
- The agent function maps percept sequences to actions
- It is generated by an agent program running on a machine

#### **Agents**

 An agent is anything that can be viewed as perceiving its environment through sensors and acting upon that environment through actuators

#### Human agent:

- eyes, ears, and other organs for sensors;
- legs, mouth, and other body parts for actuators

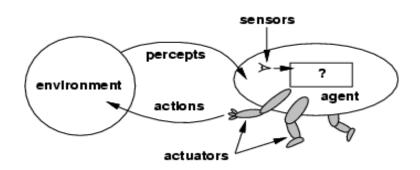
#### Robotic agent:

- cameras and infrared range finders for sensors;
- various motors for actuators
- Software agents or softbots that have some functions as sensors and some functions as actuators.

#### **Glossary**

- Percept agents perceptual inputs
- Percept sequenceHistory of everything the agent has perceived
- Agent function
   Describes agent's behaviour maps any percept to an action
- Agent programImplements agent function

#### Agents and environments



The agent function maps from percept histories to actions:

$$[f: P^* \rightarrow A]$$

 The agent program runs on the physical architecture to produce f

agent = architecture + program

### **Intelligent Agents**

- The fundamental faculties of intelligence are
  - Acting
  - Sensing
  - Understanding, reasoning, learning
- An Intelligent Agent must sense, must act, must be autonomous (to some extent).
- It also
  - must be rational
- Al is about building rational agents.

#### Rational Agent

- An agent should strive to "do the right thing", based on what it can perceive and the actions it can perform.
- What is the right thing?

Causes the agent to be most successful

Caution: Rationality is not the same as Perfection. Rationality maximizes "Expected Performance".

Perfection maximizes "Actual Performance"

■ **Performance measure** — is a criteria to measure an agent's behavior e.g., performance measure of a vacuum-cleaner agent could be amount of dirt cleaned up, amount of time taken, amount of electricity consumed, amount of noise generated, etc.

Performance is measured according to what is wanted in the environment instead of how the agent should behave.

#### Rationality - Cont'd

- What is rationality? Depends on four things:
  - The performance measure
  - The agent's prior knowledge of the environment
  - The actions the agent can perform
  - The agent's percept sequence to date

#### A rational agent is:

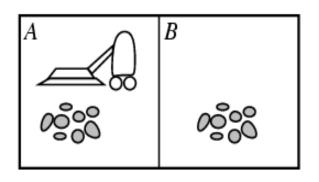
For each possible percept sequence, a rational agent should select an action that is expected to maximize its performance measure, given the evidence provided by the percept sequence and what ever built in knowledge the agent has.

#### Rational Agents - Cont'd

- Rationality is distinct from omniscience (all-knowing with infinite knowledge)
- Agents can perform actions in order to modify future percepts so as to obtain useful information (information gathering, exploration – an important part of rationality)
- An agent is autonomous if its behavior is determined by its own experience (with ability to learn and adapt) – a rational agent should be autonomous ….!

Rational ⇒ exploration, learning, autonomy

## Example: Vacuum-cleaner Agent



☐ **Environment**: square A and B

☐ **Percepts**: [location and content] e.g. [A, Dirty]

☐ **Actions**: left, right, suck, and no-op

A simple **agent function** may be "if the current square is dirty, then clean or move to the other square.."

# Example: Vacuum-cleaner Agent

Percept sequence	Action
[A,Clean]	Right
[A, Dirty]	Suck
[B, Clean]	Left
[B, Dirty]	Suck
[A, Clean],[A, Clean]	Right
[A, Clean],[A, Dirty]	Suck
 B. Ombuki-Berman, COSC 3P71	

#### **Agent Program!**

function REFLEX-VACUUM-AGENT( [location, status]) returns action

**if** status = Dirty then return Clean

**else if** *location = A then return Right* 

**else if** *location = B then return Left* 

### Is our vacuum-cleaner agent rational?

#### Keeping in view four aspects to measure rationality:

- The **performance measure** awards one point for each clean square at each time step over 10000 time steps.
- The geography of the **environment** is known.
  - Clean squares stay clean and sucking cleans the current square.
- Only actions are left, right, suck, and NoOp
- The agent correctly **perceives** its location and whether that location contains dirt.

#### What's your Answer -- Yes/No

# Building Rational Agents PEAS Description to Specify Task Environments

To design a rational agent we need to specify a *task environment, and* a problem specification for which the agent is a solution *PEAS*:

- P: Performance Measure
- **E:** Environment
- A: Actuators
- S: Sensors

#### **Environment** Agent Types of Agent |Simple reflex Agents Model-based reflex Agents Goal based Agents **Utility-based Agents** Examples of Agent It can be Artificial Program Intelligence Chatbot Robot Machine Car

Player **Others** 

Types of Environments Observable, Unobservable

Competitive, Cooperative Multi-agent

Deterministic, Stochastic

Nondeterministic Static, Dynamic

Episodic, Sequential

Known, Unknown

Discrete, Continuous

#### Examples of Environment

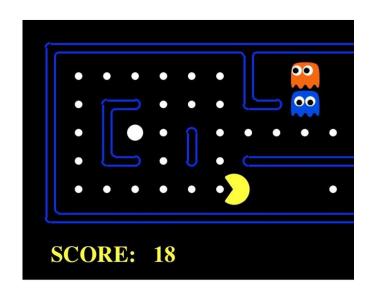
It depends on the application for example chess, Maze, outer space, etc.,

# A human agent in Pacman



### The task environment - PEAS

- Performance measure
  - -1 per step; + 10 food; +500 win; -500 die;+200 hit scared ghost
- Environment
  - Pacman dynamics (incl ghost behavior)
- Actuators
  - Left Right Up Down or NSEW
- Sensors
  - Entire state is visible (except power pellet duration)



#### **PEAS:** Automated taxi

#### Performance measure

 Income, happy customer, vehicle costs, fines, insurance premiums

#### Environment

US streets, other drivers, customers, weather, police...

#### Actuators

Steering, brake, gas, display/speaker

#### Sensors

 Camera, radar, accelerometer, engine sensors, microphone, GPS



Image: http://nypost.com/2014/06/21/how-google-might-put-taxi-drivers-out-of-business/

# PEAS: Medical diagnosis system

- Performance measure
  - Patient health, cost, reputation
- Environment
  - Patients, medical staff, insurers, courts
- Actuators
  - Screen display, email
- Sensors
  - Keyboard/mouse

