

0.1 Ensemble Theory

0.1.1 Space

描述 gas model 的方法: 列出所有气体粒子的 (q, p) .

0.1.1.1 μ -space by Ehrenfest

(x, y, z, v_x, v_y, v_z) 6-dim space. 其中的一个点描述的是一个粒子的状态. 共需 $N \sim N_A$ 个点进行描述.

$$\sum_i \delta(x - x_i) \delta(y - y_i) \delta(z - z_i) \delta(v_x - v_{xi}) \delta(v_y - v_{yi}) \delta(v_z - v_{zi})$$

Distribution function: $f(\vec{x}, \vec{v}, t) d^3\vec{x} d^3\vec{v}$

随着时间推移, $H = \int f \ln f$ 总是趋向于减小. 在达成最小/细致平衡时: \vec{x} : 均匀; \vec{v} : Maxwell 分布.

[Discussion] 质疑: 令某一时刻 t 下 $\vec{v} \rightarrow -\vec{v}$, 难道不会使 H 回升吗?

0.1.1.2 Γ -space

$\{q_1, q_2, q_3, p_1, p_2, p_3, q_4, q_5, q_6, p_4, p_5, p_6, \dots\}$, 6N-dim. 空间中的一个点描述的是整团气体某时刻下的状态. 系统的演化即点的运动.

在 μ -空间中的通过 course-graining 分割的一个 $|k\rangle$ 状态格子中, 有着 n_k 个粒子. 该格子的体积为 6-dim phase volume $\omega_k = \Delta \vec{q}_k \Delta \vec{p}_k$. 相应地, 在 Γ 空间中由这 n_k 个粒子所占据的空间体积为 $\prod_{\alpha=1}^{n_k} \Delta \vec{q}_\alpha \Delta \vec{p}_\alpha = \prod_{\alpha=1}^{n_k} \omega_k = \omega_k^{n_k}$. 因此所有粒子所占据的空间为 $\prod_k \omega_k^{n_k}$

在给定的 $\{n_k\}$ 中, 同状态 $|k\rangle$ 的粒子间交换不会产生新的状态数, 因此修正: $W' = \frac{N!}{\prod_k n_k!} \prod_k \omega_k^{n_k}$. 该体积和状态数成正比, 那么寻找在 $\sum_k n_k = N$, $\sum_k \varepsilon_k n_k = E$ 约束下使得空间体积/状态数极大的 $n_k^* = A \omega_k e^{-\beta \varepsilon_k}$.

0.1.1.3 Geomtry of High-Dimensional Space

0.1.1.3.1 An Illustrative Example: Sphere in n -dim Space

3-dim space: S^2, B^3 ; n -dim space: S^{n-1}, B^n .

在 n -dim 欧式空间中的一个点 $x = (x_1, x_2, \dots, x_n)$. \vec{x} 的长度为 $|x| = \sqrt{\sum_{i=1}^n x_i^2}$.

体积: $V(B_R^n) = C_n R^n$, $C_n = \frac{\pi^{n/2}}{\Gamma(\frac{n}{2} + 1)}$, $\Gamma(z + 1) \equiv \int_0^\infty t^z e^{-t} dt \stackrel{z \in \mathbb{Z}}{\approx} z! \approx \sqrt{2\pi z} \left(\frac{z}{e}\right)^z$

$$C_n \stackrel{n \text{ even}}{\approx} \frac{\pi^{n/2}}{\left(\frac{n}{2}\right)!} \Rightarrow V(B_R^n) \simeq \frac{1}{\sqrt{n\pi}} \left(\sqrt{\frac{2\pi e}{n}}\right)^n R^n, \quad \text{unit sphere: } V(B_R^n) = 1 \Leftrightarrow R = \sqrt{\frac{n}{2\pi e}}$$

设两共心球半径分别为 $R, R(1 + \varepsilon)$. 求夹层(Shell)体积为 $V_{\text{shell}} = V(R)[(1 + \varepsilon)^n - 1^n]$. 即使 ε 很小, 也会随着 $n \uparrow$ 使得 $V[R(1 + \varepsilon)]$ 急剧上升. 即高维空间中体积集中在 "边缘".

[Example] 高维酒杯. 要求填满圆锥形酒杯的一半, 随着维度升高, 酒面高度也会升高, 趋近于酒杯边缘.

[Example] 密度均匀, n -dim, 半径为 R 的高维球 B_R^n . 只取单个轴 x , 另一个轴作为垂直 x 分量的 B_R^n 球切片 $B_{R'}^{n-1}$, 其中 $R' = R \sqrt{1 - \frac{x^2}{R^2}}$. 存在 $\int_{-R}^R \rho(x) dx = \int_{-R}^R V(B_{R'}^{n-1}) dx = V(B_R^n)$, 求 $\rho(x)$ 表达式.

$$\frac{V(B_{R'}^{n-1})}{V(B_R^{n-1})} = \left(\frac{R'}{R}\right)^{n-1} = \left(1 - \frac{x^2}{R^2}\right)^{\frac{n-1}{2}} \simeq e^{-(n-1)x^2/2R^2}; \text{ For a unit ball, } R = \sqrt{\frac{n}{e}} \Rightarrow \rho(x) \simeq e^{-ex^2/2} V(B_1^{n-1})$$

0.1.1.3.2 The Geometric Deviation Principle Minkowski 求和. 点集 $A + B$ 对应于 $\vec{a} + \vec{b}$. A, B 本身具有一定的形状.

Brunn-Minkowski inequality: $[V(A+B)]^{1/n} \geq [V(A)]^{1/n} + [V(B)]^{1/n}$. A 和 B 为齐形凸体, 即 $A = \alpha B + x$ 时取等.

Isoperimetric principle: 等面积, 求周长最小; 等体积, 求表面积最小.

设 n -dim 无定形点集 C 和 n -dim 球点集 B , 两者体积相同 $V(C) = V(B) = V(B_R^n)$. 设 $\epsilon \rightarrow 0$, $C + \epsilon B$ 使得在 C 表面增加薄壳. 那么 C 的 $(n-1)$ -dim 表面积(Area)可借该薄壳体积除以厚度 ϵ 得到: $\text{Area} = \lim_{\epsilon \rightarrow 0} \frac{V(C + \epsilon B) - V(C)}{\epsilon}$. 不等式: $V(C + \epsilon B)^{1/n} \geq V(C)^{1/n} + V(\epsilon B)^{1/n} = V(B)^{1/n} + (\epsilon^n V(B))^{1/n} \Rightarrow \text{Area} \geq \lim_{\epsilon \rightarrow 0} \frac{[(1+\epsilon)^n - 1]}{\epsilon} V(B) \approx n \cdot V(B)$, C 为球时取等. 于是 "等体积, 表面积最小时为球" 得证.

[Example] 取两铁环沾肥皂水, 铁环间由肥皂水薄膜相连. 几何: curvature; 物理: surface tension. Laplace preessure: $p \propto \sigma \bar{H}$.

[Example] 悬链线(Catenary Curve).

类比不等式 $\frac{x+y}{2} \geq \sqrt{xy}$, 那么 $\sqrt{[V(C)V(D)]} \leq V\left[\frac{C+D}{2}\right] \leq \left(1 - \frac{\epsilon^2}{8}\right)^n V(B)$. ϵ 为不对齐程度.

设单位体积球点集 B , 而 C 占据 B 体积的 $\frac{1}{2}$, 剩下的 $\frac{1}{2}$ 体积为 D . 即有 $V(C) = \frac{1}{2}V(B)$. 那么 $M = \frac{C+D}{2}$ 所能占据的体积是有限的. 代入 $V(B) = 1$ 得 $V(D) \leq 2(1 - \frac{1}{8}\epsilon^2)^{2n} \times V(B) = 2e^{-n\epsilon^2/4}V(B)$.

[Example] 考虑 n -dim 球的球面 S^{n-1} , 在球面上有一分布函数 f 且随球面坐标缓慢变化. 找到 f 的中位数 M , 分界为 $S_1(f < M)$ 和 $S_2(f > M)$. 令 S_1 向 S_2 方向膨胀微薄一层, 得到 $f = M + \epsilon$ 界线; 同样地, S_2 向 S_1 方向膨胀后, 得到 $f = M - \epsilon$ 界线. 因为 $V(S_1) \ll V(S^{n-1})$ 且 $V(S_2) \ll V(S^{n-1})$, 说明球面上大部分数值都集中在中值 M 附近.

0.1.1.3.3 Probability Perspective @ Levy, 1980 Uniform distribution of dots \rightarrow volume interpreted as the probability.

[Example] Probability theory of large deviation. Toss coin(抛掷硬币): $X_i = 0, 1$; 均值 $M_N = \frac{1}{N} \sum_{i=1}^N X_i$. 令 $x \in \left(\frac{1}{2}, 1\right)$,

$P(M_N > x) < e^{-NI(x)}$, 其中 $I(x) = x \ln x + (1-x) \ln(1-x) + \ln 2$. 令 $x = \frac{1}{2} + \epsilon$, 则 $P(M_N > \frac{1}{2} + \epsilon) < e^{-2N\epsilon^2}$.

M_N , "macrostate". microstates: $C_N^{NM_N} = C_N^k$.

$C_N^k = \frac{N!}{k!(N-k)!} \Rightarrow \ln C_k = \ln \left[\frac{N!}{k!(N-k)!} \right] \simeq -N \ln x \ln x - N(1-x) \ln(1-x) = -N[I(x) - \ln 2]$

$S = k_B \ln C_N^k$

[Example] $[-1, 1] \otimes [-1, 1]$ 空间内随机撒点. 设 $x+y=0$ 分割线, 该线上的点有 $\lim_{n \rightarrow \infty} \sum_i^n x_i = 0$; 相应地, 若 $\lim_{n \rightarrow \infty} x+y = \epsilon$ 描述了偏离中心线的程度.

0.1.2 From Dynamics to Probability Description

Measurement: time-avarage. Phase space with macroscopic constraint: ensemble-avarage. Poincare recurrence theorem(庞加莱回归定理)

时间平均: $\langle f \rangle_t = \frac{\sum_i f_i \tau_i}{\sum_i \tau_i}$

Course-grained description of phase space: $f_i = f_\alpha, \quad \forall i \in \alpha$.

$$\begin{aligned} \langle f \rangle_t &= \frac{1}{T} \sum_\alpha f_\alpha t_\alpha, \quad t_\alpha = \sum_{i \in \alpha} \tau_i \\ &= \sum_\alpha f_\alpha \times \left(\frac{t_\alpha}{T} \right) = \sum_\alpha f_\alpha p_\alpha, \quad \text{prob description: } p_\alpha = \frac{t_\alpha}{T} \end{aligned}$$

Formal presentation: in equilibrium,

$$\begin{aligned}\langle f \rangle_e &= \langle \langle f \rangle_e \rangle_t = \langle \langle f \rangle_t \rangle_e \\ \left\langle \lim_{T \rightarrow \infty} \langle f \rangle_t \right\rangle_e &= \lim_{T \rightarrow \infty} \langle f \rangle_t : \quad \text{ergodic (各态历经), 初态无关} \\ \langle f \rangle_e &= \lim_{T \rightarrow \infty} \langle f \rangle_t\end{aligned}$$

不同情况下的 microstate: 1. In Γ -space($6N$ -dim), (q, p) ; 2. $|n\rangle$; 3. $\sigma = \pm 1$; 4. $\sigma = \{0, 1\}$...

Representative point \leftrightarrow one gas. Density function(continuum description) $\sum_i \delta(x - x_i) \rightarrow \rho(x)$.

$$\langle f \rangle = \frac{\sum_{\alpha} f_{\alpha} p_{\alpha, t}}{\sum_{\alpha} p_{\alpha, t}} \Rightarrow \frac{\int f(q, p) \rho(q, p, t) d^{3N} q d^{3N} p}{\int \rho(q, p, t) d^{3N} q d^{3N} p}$$

equilibrium condition: $\langle f \rangle$ time-invariant $\rightarrow \frac{\partial \rho}{\partial t} = 0$

[Discussion] 若 $\rho(q, p, t) = q(q, p)f(t)$, $\langle f \rangle$ 在数学上也是平衡的. 这种情况下需要考虑到

$$\int g(q, p) f(t) d^{3N} q d^{3N} p = N \Rightarrow f(t) = \text{const.} \Rightarrow \frac{\partial \rho}{\partial t} = 0.$$

0.1.2.1 Dynamics

0.1.2.1.1 A Single Representative Point in Γ -Space

Hamiltonian 力学: $\dot{q}_i = \frac{\partial H}{\partial p_i}$, $\dot{p}_i = -\frac{\partial H}{\partial q_i}$. 特征: 1. 轨迹不可能自相交; 2. 回归定理.

0.1.2.1.2 Multiple Representative Points 在 Γ -空间中选取一个体积 ω , 将会有 $\int_{\omega} \rho(q, p, t) d\omega$ 个代表点. 其表面为 $\partial\omega$. 代表点在 Γ -空间中的运动速度为 $\vec{v}_i = \{\dot{q}_i, \dot{p}_i\}$. 那么存在关系

$$\begin{aligned}\frac{\partial}{\partial t} \int_{\omega} \rho(q, p, t) d\omega &= - \int_{\partial\omega} \rho \vec{v} \cdot \hat{n} d\sigma = - \int_{\omega} \nabla \cdot (\rho \vec{v}) d\omega, \quad \nabla = \left(\frac{\partial}{\partial \mathbf{q}}, \frac{\partial}{\partial \mathbf{p}} \right) \\ \Rightarrow \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) &= 0, \quad \text{Continuity Equation}\end{aligned}$$

Material derivative. 设 $g(\vec{x}, t)$, flow field: $\vec{v}(\vec{x}, t)$.

$$g(\vec{x} + \delta\vec{x}, t + \delta t) - g(\vec{x}, t) = g(\vec{x}, t) + \delta\vec{x} \frac{\partial g}{\partial \vec{x}} + \delta t \frac{\partial g}{\partial t} - g(\vec{x}, t) = \delta\vec{x} \frac{\partial g}{\partial \vec{x}} + \delta t \frac{\partial g}{\partial t} = \delta t \left(\vec{v} \cdot \frac{\partial g}{\partial \vec{x}} + \frac{\partial g}{\partial t} \right)$$

$$\frac{Dg}{Dt} \equiv \frac{g(\vec{x} + \delta\vec{x}, t + \delta t) - g(\vec{x}, t)}{\delta t} = \vec{v} \cdot \frac{\partial g}{\partial \vec{x}} + \frac{\partial g}{\partial t}$$

$$\begin{aligned}\text{Liouville's theorem: } \frac{D\rho(q, p, t)}{Dt} &= \frac{\partial \rho}{\partial t} + \vec{v} \cdot \nabla \rho = \frac{\partial \rho}{\partial t} + \sum_i \left(\dot{q}_i \frac{\partial \rho}{\partial q_i} + \dot{p}_i \frac{\partial \rho}{\partial p_i} \right) \\ &= \frac{\partial \rho}{\partial t} + \sum_i \left(\frac{\partial H}{\partial p_i} \frac{\partial \rho}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial \rho}{\partial p_i} \right) = \boxed{\frac{\partial \rho}{\partial t} + \{\rho, H\} = 0}\end{aligned}$$

[Discussion] How to understand $\frac{D\rho}{Dt} = 0$? 1. canonical transform; 2. incompressibility ($\nabla \cdot \vec{v} = 0$)

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0 \Rightarrow \frac{\partial \rho}{\partial t} + \vec{v} \cdot \nabla \rho + \rho \nabla \cdot \vec{v} = 0 \Rightarrow \nabla \cdot \vec{v} = 0$$

$$\text{check: } \nabla \cdot \vec{v} = \sum_i \left(\frac{\partial}{\partial q_i} \dot{q}_i + \frac{\partial}{\partial p_i} \dot{p}_i \right) = \sum_i \left(\frac{\partial}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial}{\partial p_i} \frac{\partial H}{\partial q_i} \right) = 0$$

H -dynamics \Leftrightarrow incompressibility of representative points.

若 ρ 为 H 函数 $\rho(H)$, 则 $\{\rho, H\} = 0 \Rightarrow \frac{\partial \rho}{\partial t} = 0$, 即达成 equilibrium; 两种可能: 1. $\rho = \text{const.}$; 2. @Gibbs: canonical $\Rightarrow \ln \rho \propto H$

0.1.3 Microcanonical Ensemble

气体模型 macrostate: (E, N, V) , to construct an ensemble of microstates. surface of $(6N - 1)$ -dim.

[Discussion] 可能总动量 $\vec{P} \neq \vec{0}$, 总角动量 $\vec{L} \neq \vec{0}$. 以动量为例子:

$$\underbrace{p_{1x}^2 + p_{1y}^2 + p_{1z}^2}_{\text{1st particle}} + p_{2x}^2 + \cdots + p_{Nz}^2 \stackrel{\text{ideal gas}}{=} 2mE, \quad P_z = \sum_{i=1}^N p_{iz} \rightarrow 0, \text{ due to high dimension.}$$

[Example] 2-state system. $|1\rangle : N_1, |2\rangle : N_2$. $P_1 = \frac{N_1}{N_1 + N_2}, P_2 = \frac{N_2}{N_1 + N_2} \Rightarrow \langle f \rangle = f_1 P_1 + f_2 P_2$.

$$\text{Equilibrium density function? } \rho(q, p) = \begin{cases} \text{const.} & H(q, p) \in \lim_{\Delta \rightarrow 0} \left[E - \frac{\Delta}{2}, E + \frac{\Delta}{2} \right] \\ 0, & \text{others} \end{cases}$$

Foudation of equilibrium: 等概率假设, 且为 ergodicity(各态历经).

Closed system: $S = k_B \ln \Omega$, $\Omega = \frac{\omega}{\omega_0}$, ω : allowed region of motion, ω_0 : some constant

$$\delta q \delta p \sim h \Rightarrow (\delta \mathbf{q} \delta \mathbf{p}) \sim h^{3N} \Rightarrow \omega_0 = h^{3N}$$

$$\Omega = \frac{1}{N! h^{3N}} \int_{\omega} d^3 \vec{q}_1 d^3 \vec{q}_2 \cdots d^3 \vec{q}_N d^3 \vec{p}_1 d^3 \vec{p}_2 \cdots d^3 \vec{p}_N, \quad \text{N! to make } S \text{ is extensive}$$

\Rightarrow indistinguishability of microscopic particles

0.1.3.1 Equation of State for Ideal Gas

Derive the equation of state by microcanonical ensemble method.

理想气体的内能表达式: $\sum_{i=1}^N |\vec{p}_i|^2 = 2mE$. 等能面为 $(3N - 1)$ 维球面, 且球面半径约为 \sqrt{E} . 那么相空间体积/微观态数

$$\Omega \sim (\sqrt{E})^{3N-1} \sim E^{3N/2}. \text{ 克劳修斯熵 } S = k_B \ln \Omega = \frac{3}{2} k_B N \ln E + \text{const.}; \text{ 1st law: } \frac{1}{T} = \left(\frac{\partial S}{\partial E} \right)_V \Rightarrow E = \frac{3}{2} N k_B T.$$

在 1D 下存在关系 $p \cdot L \sim \pi \Rightarrow p \sim \frac{1}{L} \Rightarrow \delta p \sim \frac{1}{L}$, 则更良的微观态数表达式为 $\Omega \sim \frac{(\sqrt{E})^{3N-1}}{(\delta p)^{3N}} \xrightarrow{V \sim L^3} (E^{3/2} V)^N$,

$$S = k_B \ln \Omega = N k_B \left(\frac{3}{2} \ln E + \ln V + \text{const.} \right) \Rightarrow \left(\frac{\partial S}{\partial V} \right)_E = \frac{N k_B}{V} \Rightarrow dS = \frac{3}{2} N k_B \frac{dE}{E} + N k_B \frac{dV}{V} = \frac{dE}{T} + \frac{PdV}{T},$$

观察比较得到 $N k_B \frac{dV}{V} = \frac{PdV}{T} \Rightarrow P = \frac{N}{V} k_B T$.

0.1.3.2 Dilute Hard Sphere System

各小球可占体积为因各自体积而相互减少. 设小球半径为 a , 体积为 $\omega_e = \frac{4}{3} \pi (2a)^3$. 接触距离至少为球心间距所以是 $2a$.

微观态数为 $\Omega = \frac{1}{N! h^N} \int d^3 \vec{q}_1 d^3 \vec{q}_2 \cdots d^3 \vec{q}_N d^3 \vec{p}_1 d^3 \vec{p}_2 \cdots d^3 \vec{p}_N$, 其中

$$\int d^3 \vec{q}_1 \cdots d^3 \vec{q}_N = V(V - \omega_e)(V - 2\omega_e) \cdots [V - (N-1)\omega_e] = \prod_{i=0}^{N-1} (V - i\omega_e) \stackrel{\ln}{\Rightarrow} \ln \prod_{i=0}^{N-1} (V - i\omega_e) = \sum_{i=0}^{N-1} \ln(V - i\omega_e).$$

使用极限 $\ln(x + \delta x) \Leftrightarrow \ln x + \frac{1}{x} \delta x$, 则 $\sum_{i=0}^{N-1} \ln(V - i\omega_e) = \sum_{i=0}^{N-1} \left(\ln V - \frac{i\omega_e}{V} \right) = N \ln V - \frac{\omega_e}{V} \frac{(N-1)N}{2}$

$$\simeq N \left(\ln V - \frac{\omega_e N}{2V} \right) \simeq N \ln \left(V - \frac{\omega_e N}{2} \right) \Rightarrow \int d^{3N} q = \left(V - \frac{\omega_e N}{2} \right)^N$$

[Exercise] 设有 N 个硬球, 半径 a , 约定 $\omega_e = \frac{4}{3} \pi (2a)^3$, 体系能量为 E , 总体积为 V , 温度为 T . 尝试计算 $S(E, V)$, 状态方程.

$$[\text{Hint: Area}(S^{n-1}) = \frac{2\pi^{\frac{n}{2}}}{\Gamma(\frac{n}{2})} R^{n-1}]$$

0.1.3.3 Einstein's Model for Heat Capacity of Solid(1907)

Excitations \rightarrow Solid property? Quantum?

N atoms, 等效于 $3N$ independent oscillators. Total energy: U , distributed to $3N$ oscillators. 等效为将 $\frac{U}{\hbar\omega_0}$ 个竖隔板插入由 $3N$ 个球间隔出的 $(3N-1)$ 的缝隙中.

$$\text{微观态数 } W = \frac{\left[(3N-1) + \left(\frac{U}{\hbar\omega_0}\right)\right]!}{(3N-1)! \left(\frac{U}{\hbar\omega_0}\right)!}, \text{ 则每 1 mol 原子的熵为 } s(u) = k_B \ln W \simeq 3R \left[\ln \left(1 + \frac{u}{u_0}\right) + \frac{u}{u_0} \ln \left(1 + \frac{u_0}{u}\right) \right],$$

其中 $s = \frac{S}{N/N_A}$, $u = \frac{U}{N/N_A}$, $u_0 = 3N_A \hbar\omega_0$. 压强是某量对体积的偏导数 $P = \frac{\partial \#}{\partial V}$, $\# : U, S \dots$, 热容则是 $c = T \frac{\partial S}{\partial T}$.

温度 $\frac{1}{T} = \left[\frac{\partial S(U)}{\partial U} \right] = \frac{k_B}{\hbar\omega_0} \ln \left(1 + \frac{3}{u} \hbar\omega_0\right)$, 代入即有 $\frac{1}{3N_A} u(T) = \frac{\hbar\omega_0}{e^{\hbar\omega_0/k_B T} - 1}$, 正是 Boson 行为.

$$\text{热容为 } c = \frac{\partial u}{\partial T} = 3N_A k_B \left(\frac{\hbar\omega_0}{k_B T} \right)^2 e^{-\frac{\hbar\omega_0}{k_B T}}.$$

0.1.4 Canonical Ensemble

Macrostate: (N, V, T) . 能量允许涨落. 又名: Entropy representation.

Equilibrium density function? @Gibbs: $\frac{\partial \rho}{\partial t} = -\vec{v} \cdot \nabla \rho$. If equilibrium $\frac{\partial \rho}{\partial t} = 0$, then $\vec{v} \cdot \nabla \rho = 0$.

$$\sum_i \left(\dot{q}_i \frac{\partial \rho}{\partial q_i} + \dot{p}_i \frac{\partial \rho}{\partial p_i} \right) = 0 \Rightarrow \sum_i \left(\frac{\partial H}{\partial p_i} \frac{\partial \rho}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial \rho}{\partial p_i} \right) = 0. \text{ 若 } \rho \text{ 为 } H \text{ 函数 } \rho(H), \text{ 则方程自动满足.}$$

$$\rho_{1+2} = \rho_1 \times \rho_2, \quad H_{1+2} = H_1 + H_2 \Rightarrow \ln \rho \propto \alpha H \Rightarrow \rho \propto e^{\alpha H}$$

0.1.4.1 Connection to Microcanonical Ensemble

0.1.4.1.1 Environment & System Perspective 设环境为 A' , 处于态 $|r'\rangle$; 体系为 A , 处于态 $|r\rangle$, $A + A'$ 整体是孤立系统. 那么有 $E_r + E_{r'} = E^{(0)} = \text{const.}$; 设 Ω' 为环境微观态数, 则体系处于态 $|r\rangle$ 的概率 $P_r \propto \Omega'(E_r) = \Omega'(E^{(0)} - E_r)$. 假定体系所占能量足够小, 即 $E_r \ll E^{(0)}$, 则可 Taylor 展开: $\ln \Omega'(E^{(0)} - E_r) = \ln \Omega'(E^{(0)}) + \frac{\partial \ln \Omega'}{\partial E'} \bigg|_{E'=E^{(0)}} (-E_r) + \dots = \text{const.} - \beta E_r$

$$\text{于是得到 Boltzmann factor/Canonical distribution } P_r = \frac{e^{-\beta E_r}}{\sum_r e^{-\beta E_r}}.$$

[Discussion] Taylor 展开时, 为何不需要保留更高次? \Rightarrow 为了保持 S 的广延性.

0.1.4.1.2 Multiple Systems Perspective 制备 N 个正则系综, 整体组成一个微正则系综. 设 n_r 个系统处于状态 $|r\rangle$, 能量为 E_r . 则存在约束条件 $\sum_r n_r = N$, $\sum_r n_r E_r = NU = N \langle E_r \rangle$. 微观态数为 $W = \frac{N!}{\prod_r n_r!}$, 寻找 $\{n_r\}$ 使得 W 最大化.

$$\Rightarrow \frac{n_r^*}{N} = \frac{e^{-\beta E_r}}{\sum_r e^{-\beta E_r}}.$$

[Discussion] Why is $\ln \rho \propto \alpha E \Rightarrow \rho \propto e^{\alpha E}$ simple: 1. No dynamics information; 2. Time-reversal symmetry. Detailed-balance(细致平衡); 3. 具有可加性. 引申为 $\ln \rho = \alpha + \beta E$; 4. 设 $f(\epsilon)$ 为体系处于能量 ϵ 的概率, 则有 $\frac{f(\epsilon_1)}{f(\epsilon_2)} = \frac{f(\epsilon_1 + \epsilon)}{f(\epsilon_2 + \epsilon)}$. 定义

$$f(\epsilon) = g(\epsilon - \epsilon_2) \Rightarrow g(\epsilon)g(\epsilon_1 - \epsilon_2) = g(0)g(\epsilon_1 - \epsilon_2 - \epsilon) \Rightarrow g(\epsilon) = g(0)e^{-\beta \epsilon} \Rightarrow \frac{f(\epsilon_1)}{f(\epsilon_2)} = e^{-\beta(\epsilon_1 - \epsilon_2)}$$

0.1.4.2 Revisit Maxwell Distribution

0.1.4.2.1 Galton's Statistical Model

0.1.4.2.2 Based on Symmetry 各向同性: $f(\vec{v}) = f(v) = f_0(v_x)f_0(v_y)f_0(v_z)$

0.1.4.2.3 Boltzmann 能量离散化. $\exists \{n_r\}$, s.t. $W = \frac{N!}{\prod_{\alpha} n_{\alpha}!}$

0.1.4.2.4 Based on Ensemble Theory 能量中动量和位置分离: $E(q, p) = K(p) + U(q)$

因此统计独立: $\rho(q, p) \propto e^{-\beta E(q, p)} \Rightarrow \rho(q, p) = A e^{-\beta[K(p)+U(q)]} = A e^{-\beta K(p)} \cdot e^{-\beta U(q)}$.

其中动能部分: $e^{-\beta K(p)} = \exp \left[-\beta \left(\frac{p_1^2}{2m} + \frac{p_1^2}{2m} + \dots + \frac{p_N^2}{2m} \right) \right] = e^{-\beta \frac{p_{1x}^2}{2m}} e^{-\beta \frac{p_{1y}^2}{2m}} e^{-\beta \frac{p_{1z}^2}{2m}} \dots e^{-\beta \frac{p_{Nx}^2}{2m}} e^{-\beta \frac{p_{Ny}^2}{2m}} e^{-\beta \frac{p_{Nz}^2}{2m}}$

New perspective on gas model: 将各粒子单独视为一个系统, 只有 E 交换而没有 N 交换: $\rho_1 = A e^{-\beta \frac{p_1^2}{2m}}$

0.1.4.2.5 Geometric Viewpoint 在 $(p_{1x}, p_{1y}, p_{1z}, p_{2x}, p_{2y}, \dots)$ $3N$ -dim 空间中, 挑任意一轴(以 p_{1x} 为例), 系统处于该轴上的概率分布为? $\Rightarrow \rho(p_{1x}) \sim e^{-\beta p_{1x}^2}$ (Energy partition theorem).

[Example] 受热浴谐振子: $H = \alpha p^2 + \beta q^2$; $\langle \alpha p^2 \rangle = \int \alpha p^2 A^{-\beta H} dq dp = \frac{1}{2} k_B T$.

[Example] 推广: $H = \sum_i \alpha p_i^n$, $E_i = \alpha p_i^n$, $\langle E_i \rangle = \int E_i e^{-\beta E_i} dE_i / \int e^{-\beta E_i} dE_i = -\frac{\partial}{\partial \beta} \ln \left(\int e^{-\beta E_i} dp_i \right)$.

Let $y = \beta^{\frac{1}{n}} p_i \Rightarrow \int e^{-\beta E_i} dp_i = \beta^{-\frac{1}{n}} \int e^{-\alpha y^n} dy \Rightarrow \langle E_i \rangle = \frac{1}{n} k_B T$.

0.1.4.3 Thermodynamics

[Discussion] 已知 1st law: $dU = TdS - pdV$, 如何将 $U(V, S)$ 转变为 V 和 T 的未知函数 $U(V, T)$.

定义 $F \equiv U - TS$, 全微分 $dF = -pdV - SdT \Rightarrow F(V, T)$. 因此正则系综 (N, V, T) 也被称作 F -representation.

类似地, 定义 $G \equiv F + PV$ 从而得到 P 和 T 的函数 $G(P, T)$. $G = \mu N$.

平均能量 $\langle E_r \rangle = \frac{\sum_r E_r e^{-\beta E_r}}{\sum_r e^{-\beta E_r}} = -\frac{\partial}{\partial \beta} \ln \left(\sum_r e^{-\beta E_r} \right)$

内能 $U = F + TS = F - T \left(\frac{\partial F}{\partial T} \right)_{N, V} = \frac{\partial}{\partial (1/T)} \left(\frac{F}{T} \right)_{N, V}$

记 $\beta = \frac{1}{k_B T}$, 则自由能 $F = -k_B T \ln Q_N(V, T)$, 其中正则配分函数对状态 $|r\rangle$ 求和形式为 $Q_N = \sum_r e^{-\beta E_r}$.

求 $\langle \ln P_r \rangle = \left\langle \ln \left(\frac{e^{-\beta E_r}}{Q_N} \right) \right\rangle = -\ln Q_N - \beta \langle E_r \rangle = \beta(F - U) = -\frac{S}{k_B} \Rightarrow S = -k_B \sum_r P_r \ln P_r$, 正是 Gibbs entropy 形式.

对能量 i 求和形式: $Q_N = \sum_i g_i e^{-\beta E_i} = \int g(E) e^{-\beta E} dE$, 其中 g_i 为 degeneracy of energy level E_i (能级的简并度).

微观态数/相空间体积的形式: $Q_N = \frac{1}{N! h^{3N}} \int e^{-\beta H(q, p)} d^{3N} q d^{3N} p$

[Discussion] $Q_N = \sum_r e^{-\beta E_r}$, 根据 $e^{-\beta E_r}$ 能定论 $E_r = 0$ 是概率最高的能量吗? $(E_r)_{\text{most prob}} = U$. 因为还存在着 $g(E)$ 调控了概率, 使得 U 才是真正概率最高的能量. $e^{-\beta U} e^{S/k_B}$.

0.1.4.4 Fluctuations

已知内能 U 可通过对正则配分函数求 β 偏导得到: $U = -\frac{\partial}{\partial \beta} \left(\ln \sum_r e^{-\beta E_r} \right)$. 若再对 U 求一次 β 偏导, 则有

$$\frac{\partial U}{\partial \beta} = -\frac{\sum_r E_r^2 e^{-\beta E_r}}{\sum_r e^{-\beta E_r}} + \left(\frac{\sum_r E_r e^{-\beta E_r}}{\sum_r e^{-\beta E_r}} \right)^2 = -\langle E^2 \rangle + \langle E \rangle^2 \equiv \langle (\Delta E)^2 \rangle = k_B T^2 C_v$$

定义相对变化量/涨落为 $\frac{\sqrt{\langle (\Delta E)^2 \rangle}}{\langle E \rangle} = \frac{\sqrt{k_B T^2 C_v}}{U} \sim N^{-\frac{1}{2}}$

[Example] Classical harmonic oscillator ($\varepsilon_n = nh\nu$). Single oscillator:

$$\langle E_1 \rangle = \frac{\sum_n \varepsilon_n e^{-\beta \varepsilon_n}}{\sum_n e^{-\beta \varepsilon_n}} = \frac{h\nu}{e^{\beta h\nu} - 1}. \quad \langle E_1^2 \rangle = (h\nu)^2 \frac{1 + e^{\beta h\nu}}{(e^{\beta h\nu} - 1)^2}, \quad \langle (\Delta E_1)^2 \rangle = (h\nu)^2 \frac{e^{\beta h\nu}}{(e^{\beta h\nu} - 1)^2}, \quad \frac{\sqrt{\langle (\Delta E_1)^2 \rangle}}{\langle E_1 \rangle} = e^{\frac{1}{2}\beta h\nu}. \quad T \rightarrow 0,$$

涨落趋于发散.

$$N \text{ oscillators: } \langle (\Delta E)^2 \rangle = N \langle (\Delta E_1)^2 \rangle, \quad \frac{\sqrt{\langle (\Delta E)^2 \rangle}}{\langle E \rangle} = N^{-\frac{1}{2}} \frac{\sqrt{\langle (\Delta E_1)^2 \rangle}}{\langle E_1 \rangle}.$$

[Example] Relative fluctuation of speed in Maxwell distribution. $f(v) = A \exp \left\{ -\frac{mv^2}{2k_B T} \right\} v^2 dv$, where v^2 for 3D gas.

$$\langle g(v) \rangle = \frac{\int g(v) f(v) dv}{\int f(v) dv}, \quad \frac{\sqrt{\langle v^2 \rangle}}{\langle v \rangle} = \sqrt{\frac{3\pi}{8}} - 1$$

[Example] Ideal gas. $H = \sum_{i=1}^N \frac{\vec{p}_i^2}{2m}$.

1. 使用正则系综方法. 配分函数为

$$Q_N(V, T) = \sum_r e^{-\beta E_r} = \frac{1}{N! h^{3N}} \int e^{-\beta \sum_{i=1}^N \frac{\vec{p}_i^2}{2m}} d^{3N} q d^{3N} p = \frac{1}{N!} \left(\frac{1}{h^3} \int_{-\infty}^{+\infty} e^{-\beta \frac{p_1^2}{2m}} 4\pi p_1^2 dp_1 \underbrace{\int_V d^3 \vec{q}_1}_{V} \right)^N = \frac{Q_1(T, V)^N}{N!},$$

即各粒子统计独立. 单粒子配分函数 $Q_1 = \frac{V}{h^3} (2\pi m k_B T)^{\frac{3}{2}} = \frac{V}{\lambda_T^3}$, 其中 $\lambda_T = \frac{h}{\sqrt{2\pi m k_B T}}$ 为热波长. 粒子间平均间距可估算为 $a \sim \left(\frac{V}{N} \right)^{\frac{1}{3}}$. 若 $\lambda_T \ll a$, 即可认为 $h \rightarrow 0$, 无量子效应. 更一般性地, 若 Hamiltonian 仅为动量 p 的函数 $H = H(p)$, 则单粒子配分函数形为 $Q_1 = V f(T)$. 当 $H = \sum_i \frac{p_i^2}{2m}$ 特殊情形时, 有 $f(T) = \lambda_T^{-3}$. 继续一般性的讨论:

$$\ln Q_N = \ln \left[\frac{(V f(T))^N}{N!} \right] = N \ln f(T) + \ln \frac{V^N}{N!} = N \ln f(T) + \ln \left(\frac{e^N}{N^N} V^N \right) = N \ln f(T) + N \ln \left(\frac{eV}{N} \right)$$

记 $n = \frac{N}{V}$, 则 $\frac{F}{V} = n k_B T \left[\ln \left(\frac{n}{f} \right) - 1 \right] \Rightarrow P = \left(\frac{\partial F}{\partial V} \right)_{N, T} = \frac{N k_B T}{V}$, 和理想气体相同. 这说明满足该形式的状态方程, 真正重要的是各粒子统计独立.

$$S = - \left(\frac{\partial F}{\partial T} \right)_{N, V} = k_B V \left[-n \ln \left(\frac{n}{f} \right) + \frac{5}{2} n \right], \text{ extensive by adding } N!$$

2. 通过态密度分析配分函数. $Q_N = \int g(E) e^{-\beta E} dE$, $g(E) \sim E^{\frac{3N}{2}-1}$. 那么概率则是 $P(E) dE = g(E) e^{-\beta E} dE$. 概率 $P(E)$ 对能量 E 导数为 0 以寻找极值点 E_0 :

$$\begin{aligned} \frac{\partial}{\partial E} [g(E) e^{-\beta E}] &= g'(E) e^{-\beta E} + g(E) (-\beta) e^{-\beta E} = \left(\frac{3N}{2} - 1 \right) E^{\frac{3N}{2}-2} e^{-\beta E} + E^{\frac{3N}{2}-1} (-\beta) e^{-\beta E} \\ &= \left[\left(\frac{3N}{2} - 1 \right) E^{-1} - \beta \right] \times \# = 0 \Rightarrow E_0 = \left(\frac{3N}{2} - 1 \right) \frac{1}{\beta} \Rightarrow \lim_{N \rightarrow \infty} E_0 = \frac{3N}{2} k_B T \end{aligned}$$

[Example] Colored Ideal Gas. N red atoms, N blue atoms, N green atoms. Statistically independent. microstate: (q, p, color)

1. 存在三种颜色时的熵 S_{3c} : 单种颜色的配分函数 $Q_N(T, V) = \frac{1}{N!} \left(\frac{V}{\lambda_T} \right)^N$, 则三种颜色总共的配分函数为 $Q = Q_N^3$. 那么自由能为 $F = -k_B T \ln Q = -3k_B T \ln \left(\frac{V}{N \lambda_T} \right)$. 熵为 $S_{3c} = - \left(\frac{\partial F}{\partial T} \right)_{N, V} = 3N k_B \ln \left(\frac{eV}{N} \right) - 3N f'(T)$

2. 只存在一种颜色时的熵 S_{1c} : $S_{1c} = 3N k_B \ln \left(\frac{eV}{3N} \right) - 3N f'$

比较以上两个结果, 就会发现由于多出颜色自由度产生的混合熵 $\Delta S = S_{3c} - S_{1c} = k_B \ln 3^{3N}$.

[Discussion] 1. How to understand $\ln 3^{3N}$? statistically independent \rightarrow analyze a single particle. 底数 3: 3 种颜色/状态. 2.

$S_{\text{tot}} = S_{\{q,p\}} + S_{\text{color}}$. 新的自由度独立于 (q, p) , 则熵直接相加.

[Example] 2-state. $|1\rangle : P_1 = r; |2\rangle : P_2 = 1 - r$. For a single particle,

$$\tilde{S}_{\text{mix}} = -k_B \sum_{r=1}^2 P_r \ln P_r = -k_B [r \ln r + (1-r) \ln (1-r)]. \text{ 取极值: } r = \frac{1}{2} \Rightarrow \tilde{S}_{\text{mix}} = k_B \ln 2$$

0.1.5 Grand Canonical Ensemble

exchange energy, matter. (T, V, μ) . $|rs\rangle$: 粒子数为 N_r , 能量为 E_r . 令该系统 A 与环境 A' 整体组成一个孤立系统.

$$P_{rs} = \frac{e^{-\alpha N_r - \beta E_s}}{\sum_{r,s} e^{-\alpha N_r - \beta E_s}}$$

系综中能量的延拓: $U(S, V, N) \xrightarrow{F=U-TS} F(T, V, N) \xrightarrow{\Phi=F-\mu N} \Phi(T, V, \mu)$, 即 Grand potential.

$$\langle N \rangle = \sum_{r,s} N P_{rs} = \frac{\sum_{r,s} N_r e^{-\alpha N_r - \beta E_s}}{\sum_{r,s} e^{-\alpha N_r - \beta E_s}} = -\frac{\partial q}{\partial \alpha}, q = \ln \left(\sum_{r,s} e^{-\alpha N_r - \beta E_s} \right). \text{ 可类比于 } \langle E \rangle = -\frac{\partial q}{\partial \beta} \Rightarrow \text{q-potential}$$

$$Q(Z, V, T) = \sum_{N_r=0}^{\infty} Z^{N_r} Q_{N_r}(V, T), \quad Z \equiv e^{-\alpha}, \text{ fugacity(逸度)}$$

导出 Gibbs entropy(for open system): $\langle \ln P_{rs} \rangle = \sum_{r,s} P_{rs} (\ln P_{rs}) \Rightarrow S = -k_B \sum_{r,s} P_{rs} \ln P_{rs}$.

$$\text{粒子数涨落: } \langle (\Delta N)^2 \rangle = \frac{\langle N \rangle^2 k_B T \kappa_T}{V} \Rightarrow \frac{\langle (\Delta n)^2 \rangle}{\langle n^2 \rangle} = \frac{k_B T}{V} \kappa_T, \quad \kappa_T = -\frac{1}{V} \left(\frac{\partial V}{\partial T} \right).$$

[Example] **Ideal gas**. $Q_N(V, T) = \frac{Q_1^N}{N!}$, $Q_1(V, T) = \frac{1}{h^3} \int e^{-\beta \frac{p^2}{2m}} d^3 \vec{q} d^3 \vec{p} = \frac{V}{\lambda_T^3}$. 若 $H = H(p)$, 则形式为 $Q_1(V, T) = V f(T)$.

从巨正则系综角度出发, 配分函数为 $Q(Z, V, T) = \sum_{N_r=0}^{\infty} Z^{N_r} \frac{[V f(T)]^{N_r}}{N_r!} = e^{Z V f(T)}$, 其中 $Z = e^{-\alpha}$.

那么 q-potential 为 $q(Z, V, T) = \ln Q = Z V f(T)$. 各热力学量根据与 q 的关系分别导出: 压强 $P = \frac{k_B T}{V} q = Z k_B T f(T)$;

粒子数 $N = -\frac{\partial q}{\partial \alpha} = Z V f(T)$; 内能 $U = -\frac{\partial q}{\partial \beta} = Z V k_B T^2 f'(T)$; 状态方程 $PV = N k_B T$.

[Example] Fluctuation of number of particles. 考虑体系 (V, N) 中的小区域 Ω , 体积为 v , 粒子数为 n . 则 Ω 中有 n 个粒子的概率 $P_n = \frac{\sum_s e^{-\alpha n - \beta E_n^{(s)}}}{Q}$. 猜测平均粒子数为 $\langle n \rangle = \frac{N}{V} v$. 独立同分布. 单个粒子在/不在 Ω 中的概率: $P_1 = \frac{v}{V}$, $P_0 = 1 - \frac{v}{V}$. 则

Ω 中有 n 个粒子的概率为 $P(n) = \frac{N!}{(N-n)! n!} P_1^n P_0^{N-n}$, $\lim_{N \rightarrow \infty} P(n)$ 将化为 Poisson 分布: $P(n) = \frac{\langle n \rangle^n}{n!} e^{-\langle n \rangle}$, 其中 $\langle n \rangle = \frac{N}{V} v$.