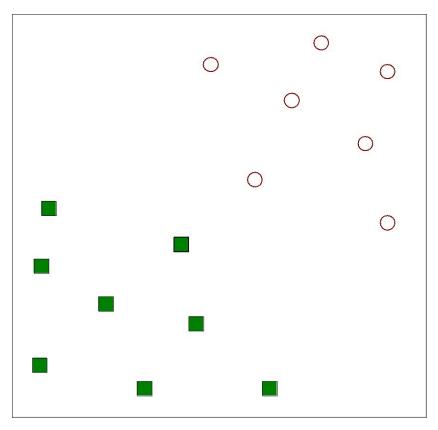
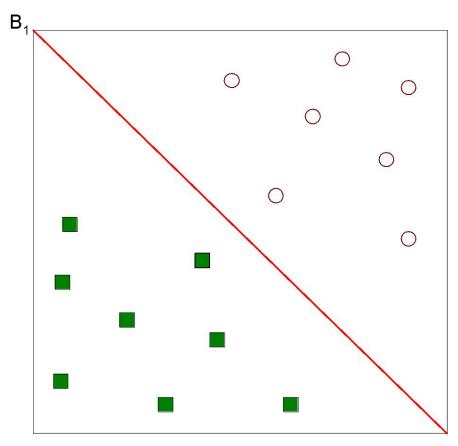
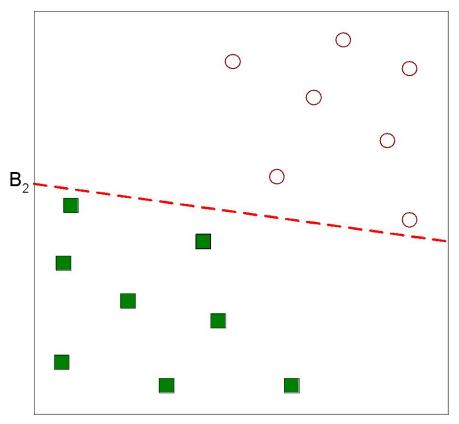
CS4104 Applied Machine Learning Support Vector Machines (SVM)



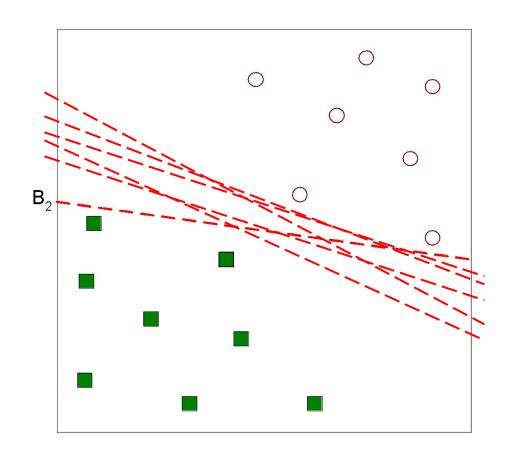
• Find a linear hyperplane (decision boundary) that will separate the data



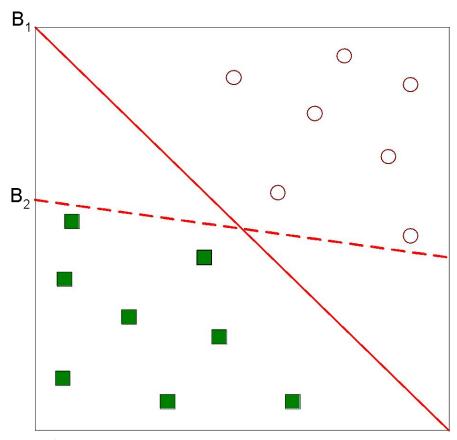
• One Possible Solution



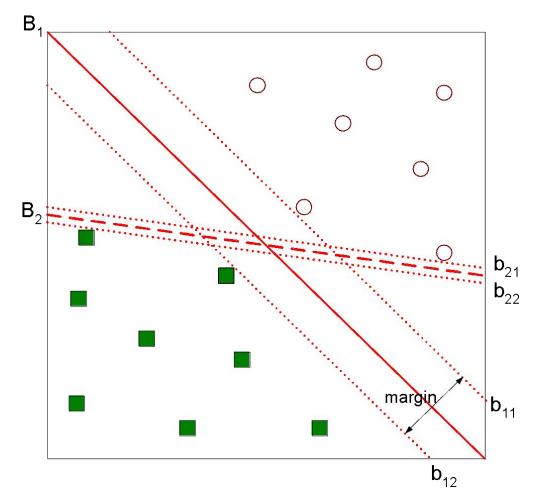
Another possible solution



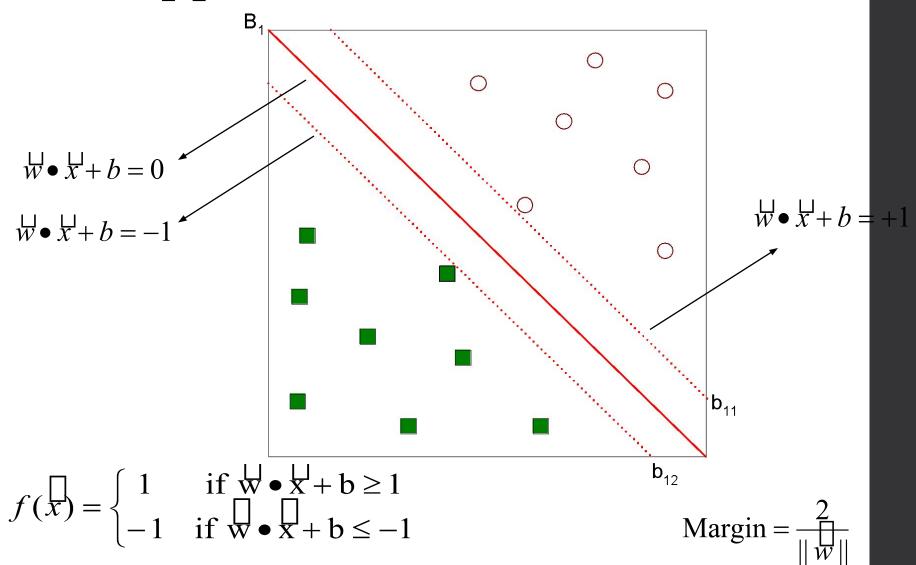
Other possible solutions



- Which one is better? B1 or B2?
- How do you define better?



• Find hyperplane maximizes the margin => B1 is better than B2



Linear SVM

Linear model:

$$f(x) = \begin{cases} 1 & if \quad w. \, x + b \ge 1 \\ -1 & if \quad w. \, x + b \le -1 \end{cases}$$

- Learning the model is equivalent to determining the values of *W* and *b*.
 - How to find *W* and *b* from training data?

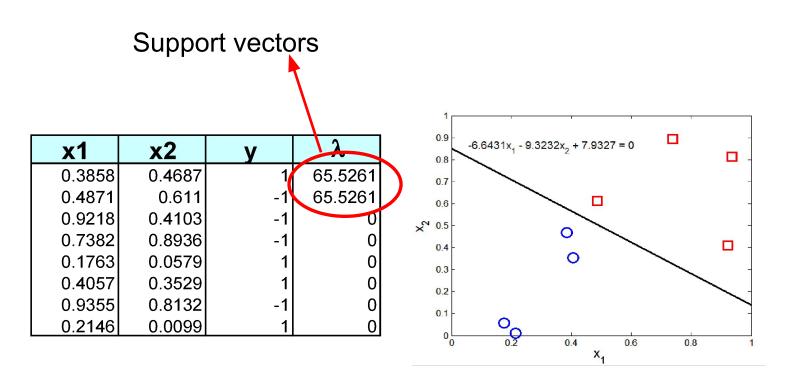
Learning Linear SVM

- Objective is to maximize:
 - $Margin = \frac{2}{|W|}$
- Which is equivalent to minimizing:
 - $L(W) = \frac{|W|^2}{2}$
- Subject to the following constraints:

$$\cdot \ y_i = \begin{cases} 1 & if \quad w. \, x_i + b \ge 1 \\ -1 & if \quad w. \, x_i + b \le -1 \end{cases}$$

- OR
 - $y_i(w.x_i + b) \ge 1 : i = 1,2,3,...,N$
- This is a constrained optimization problem
- Solve it using Lagrange multiplier method

Example of Linear SVM

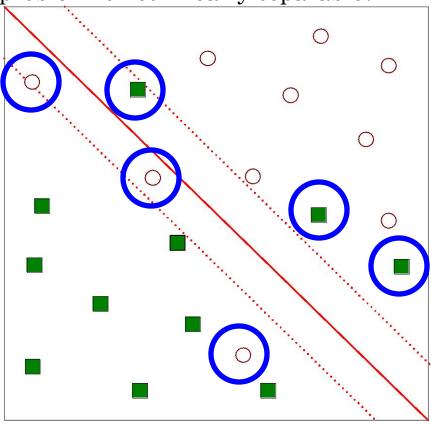


Learning Linear SVM

- Decision boundary depends only on support vectors
 - If you have data set with same support vectors, decision boundary will not change
 - How to classify using SVM once ${\bf w}$ and b are found? Given a test record, ${\bf x_i}$

$$f(x) = \begin{cases} 1 & if \quad w. \, x + b \ge 1 \\ -1 & if \quad w. \, x + b \le -1 \end{cases}$$

• What if the problem is not linearly separable?



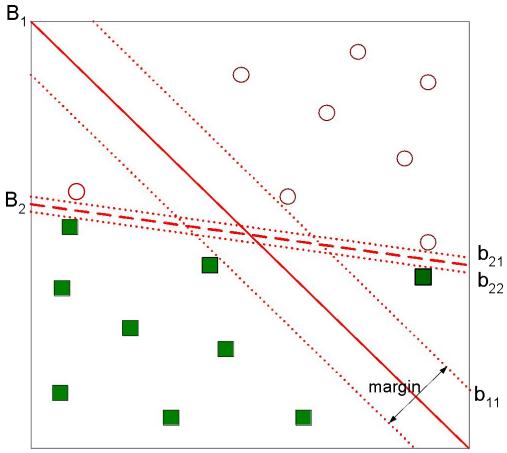
- What if the problem is not linearly separable?
 - Introduce slack variables
 - Need to minimize:

$$L(w) = \frac{\|\overrightarrow{w}\|^2}{2} + C\left(\sum_{i=1}^N \xi_i^k\right)$$

• Subject to:

$$y_i = \begin{cases} 1 & \text{if } \mathbf{w} \bullet \mathbf{x}_i + b \ge 1 - \xi_i \\ -1 & \text{if } \mathbf{w} \bullet \mathbf{x}_i + b \le -1 + \xi_i \end{cases}$$

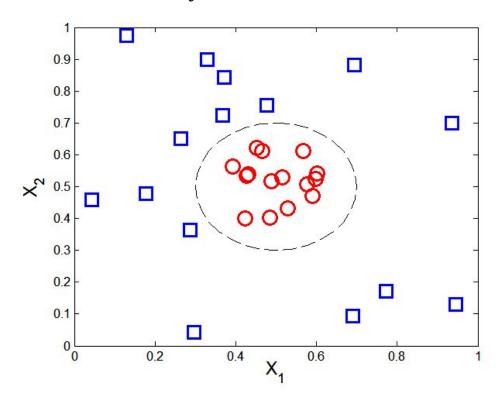
• If k is 1 or 2, this leads to similar objective function as linear SVM but with different constraints (see textbook)



• Find the hyperplane that optimizes both factors bare

Nonlinear Support Vector Machines

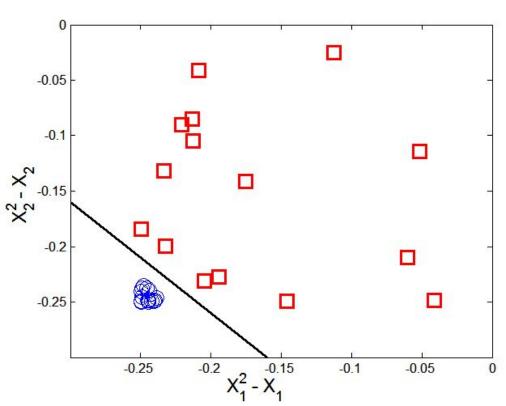
What if decision boundary is not linear?



$$y(x_1, x_2) = \begin{cases} 1 & \text{if } \sqrt{(x_1 - 0.5)^2 + (x_2 - 0.5)^2} > 0.2 \\ -1 & \text{otherwise} \end{cases}$$

Nonlinear Support Vector Machines

· Transform data into higher dimensional space



$$x_1^2 - x_1 + x_2^2 - x_2 = -0.46.$$

$$\Phi:(x_1,x_2)\longrightarrow (x_1^2,x_2^2,\sqrt{2}x_1,\sqrt{2}x_2,1).$$

$$w_4x_1^2 + w_3x_2^2 + w_2\sqrt{2}x_1 + w_1\sqrt{2}x_2 + w_0 = 0.$$

Decision boundary:

$$\stackrel{\square}{w} \bullet \Phi(\stackrel{\square}{x}) + b = 0$$

Learning Nonlinear SVM

• Optim:
$$\min_{\boldsymbol{w}} \frac{\|\mathbf{w}\|^2}{2}$$
 subject to
$$y_i(\boldsymbol{w} \cdot \Phi(\boldsymbol{x}_i) + b) \ge 1, \ \forall \{(\boldsymbol{x}_i, y_i)\}$$

Which leads to the same set of equations (but involve Φ (x) instead of x)

$$L_D = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j) \qquad \mathbf{w} = \sum_i \lambda_i y_i \Phi(\mathbf{x}_i)$$

$$\lambda_i \{ y_i (\sum_j \lambda_j y_j \Phi(\mathbf{x}_j) \cdot \Phi(\mathbf{x}_i) + b) - 1 \} = 0,$$

$$f(\mathbf{z}) = sign(\mathbf{w} \cdot \Phi(\mathbf{z}) + b) = sign(\sum_{i=1}^{n} \lambda_i y_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{z}) + b).$$

Learning NonLinear SVM

- Issues:
 - What type of mapping function Φ should be used?
 - How to do the computation in high dimensional space?
 - Most computations involve dot product $\Phi(x_i) \cdot \Phi(x_j)$
 - Curse of dimensionality?

Learning Nonlinear SVM

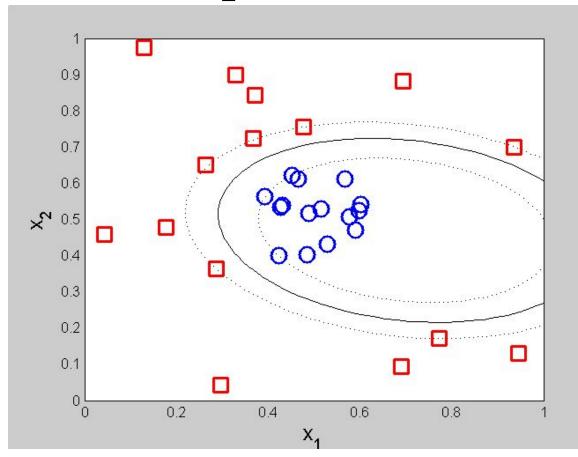
- Kernel Trick:
 - $\Phi(\mathbf{x}_{i}) \cdot \Phi(\mathbf{x}_{j}) = K(\mathbf{x}_{i}, \mathbf{x}_{j})$
 - $K(x_i, x_j)$ is a kernel function (expressed in terms of the coordinates in the original space)
 - Examples:

$$K(\mathbf{x}, \mathbf{y}) = (\mathbf{x} \cdot \mathbf{y} + 1)^{p}$$

$$K(\mathbf{x}, \mathbf{y}) = e^{-\|\mathbf{x} - \mathbf{y}\|^{2}/(2\sigma^{2})}$$

$$K(\mathbf{x}, \mathbf{y}) = \tanh(k\mathbf{x} \cdot \mathbf{y} - \delta)$$

Example of Nonlinear SVM



SVM with polynomia degree 2 kernel

Learning Nonlinear SVM

- Advantages of using kernel:
 - Don't have to know the mapping function Φ
 - Computing dot product $\Phi(x_i) \cdot \Phi(x_j)$ in the original space avoids curse of dimensionality
- Not all functions can be kernels
 - Must make sure there is a corresponding Φ in some high-dimensional space
 - Mercer's theorem (see textbook)

- · The earling problem is formulated as a convex of tin cration problem
 - Efficient algorithms are available to find the global minima
 - Many of the other methods use greedy approaches and find locally optimal solutions
 - High computational complexity for building the model
- Robust to noise
- Overfitting is handled by maximizing the margin of the decision boundary,
- SVM can handle irrelevant and redundant better than many other techniques
- The user needs to provide the type of kernel function and cost function
- Difficult to handle missing values

• What about categorical variables?