# Chapter I: Probability

Probability is the mathematical quantification of uncertainty.

The probability theorem consists of three major things: Sample Space, Outcomes, and Events.

Sample space is the set of all possible outcomes of a standard experiment. Each point in the set are the outcomes of the experiment. An event is a subset of the sample space that can contain one or more outcomes.

**Example:** Tossing a coin twice will create a sample space of  $\Omega = \{HH, HT, TH, TT\}$  these possible outcomes. Here  $\{HT\}$  and  $\{TT\}$  are both separate outcomes, and also are separate subsets of  $\Omega$ . The probability of the first toss is heads is called an event (A), which is also a subset of  $\Omega$ ;  $A = \{HH, HT\}$ .

The complement of an event is denoted as A<sup>C</sup>, which means it contains all outcomes in the sample space that are not in event A.

A sure event is  $\Omega$  itself (probability=1) and the null event  $\phi$  is the empty set (probability=0). Any event is a subset of  $\Omega$ .

For a finite sample space,  $\Omega = \{\omega_1, \omega_2, \omega_3..., \omega_n\}$ , if all outcomes are equally likely, then the probability of event A can be denoted as:  $\mathbb{P}(A) = \frac{|A|}{|\Omega|}$ , which is called the **uniform probability distribution.** 

#### Independent Events

If tossing a fair coin twice has a sample space of {HH, HT, TH, TT}, then the probability of two heads could be determined as follows:

The first toss has half (1/2) the probability of heads. Then the second toss has the same half (1/2) probability of heads. We consider the two tosses separate, or more specifically, independent. Therefore, the probability of two heads will be multiplied, and the results would be  $(1/2 \times 1/2) = 1/4$ .

### Conditional Probability (The base of Bayes' Theorem)

The probability of an event occurring, given that another event is already known to have occurred, is called the conditional probability. Let assume that event B has already occurred, and the probability of event B is greater than zero,  $\mathbb{P}(B) > 0$ . Then the conditional probability of event A given B is:  $\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cdot B)}{\mathbb{P}(B)}$ .

**Example:** A medical test for a disease D has outcomes + (positive) and - (negative). The given probabilities are:

 $\begin{array}{c|cccc} & D & D^C \\ \hline + & 0.009 & 0.099 \\ - & 0.001 & 0.891 \end{array}$ 

Now, from the conditional probabilistic definition,

 $\mathbb{P}(+|D) = \frac{\mathbb{P}(+\cap D)}{\mathbb{P}(D)} = \frac{0.009}{0.009 + 0.001} = 0.9$ Conditional probability of + given D is:

and,

 $\mathbb{P}(-|D^{C}) = \frac{\mathbb{P}(-\cap D^{C})}{\mathbb{P}(D^{C})} = \frac{0.891}{0.891 + 0.099} = 0.9$ Conditional probability of – given  $D^C$  is:

But here is a catch. What if you go for a test and get a positive (+) result, then what is the probability of you having the disease? You may say it's the same as the result is +ve given that you have the disease, which is 0.9. But the correct answer is:

 $\mathbb{P}(D|+) = \frac{\mathbb{P}(+\cap D)}{\mathbb{P}(+)} = \frac{0.009}{0.009 + 0.099} = 0.08.$ Conditional probability of D given + is:

#### A Lemma from Conditional Probability (A base for Bayes'):

 $\mathbb{P}(A|B) = \mathbb{P}(A)$ . If A and B are independent events then,

 $\mathbb{P}(AB) = \mathbb{P}(A|B) \mathbb{P}(B) = \mathbb{P}(B|A) \mathbb{P}(A).$ Also, for any pair of events A and B:

**Example:** Draw two cards from a deck, without replacing it. Let A be the event that the first draw is the Ace of Clubs (•) and let B the event that the second draw is the Queen of Diamonds (•).  $\mathbb{P}(AB) = \mathbb{P}(A) \mathbb{P}(B|A) = (1/52) \times (1/51).$ Then,

## Bayes' Theorem

Bayes' theorem is the basis of "expert systems" and "Bayes' nets" which are considered to be mimicking the decision-making ability of a human expert in a specific area. **Bayesian Networks** (Bayes' Nets) are a probabilistic graphical model that represents relationship between variables using a directed graph and do reasoning inferences based on available evidence.

The Law of Total Probability: Let  $A_1,...,A_k$  be a partition of  $\Omega$ . Then for any event B,

$$\begin{split} \mathbb{P}(B) &= \mathbb{P}(B|A_1)\mathbb{P}(A_1) + \dots + \mathbb{P}(B|A_k)\mathbb{P}(A_k) \\ \mathbb{P}(B) &= \sum_{i=1}^k \mathbb{P}(B|A_i)\mathbb{P}(A_i) \end{split}$$

Here, we call:

 $\mathbb{P}(A_i)$  the prior probability, or the *Priori* of A.

 $\mathbb{P}(A_i|B)$  the posterior probability, or the *Posteriori* of A.

$$\mathbb{P}(A_i | B) = \frac{\mathbb{P}(A_i B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B | A_i) \mathbb{P}(A_i)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B | A_i) \mathbb{P}(A_i)}{\sum_{i} \mathbb{P}(B | A_i) \mathbb{P}(A_i)}$$