





Sub System	Function Requirements	Constraints
Communication Backend	- Receive HTTP requests	- Work on home PC via
	with data packets	simple method (port
	- Process requests in short	forwarding)
	amount of time in order to not	
	miss any incoming requests	
	- Display basic information	
	from database	
GPS System	- Get GPS coordinates from	- Be able to connect inside a
	satellites and relay	car while moving
	information to	
	microcontroller	
CAN Bus System	- Get CAN data from car's	- Get required data (speed,
	CAN Bus on the OBDII port	ABS data, etc.) from car
	- Decode data successfully	(2010 Toyota Matrix)
	and create data structure with	
	relevant data	