INSA Lyon ACM-ICPC Notebook 2018 (Python)

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1 Utilities

1.1 Bisect

```
from bisect import bisect_left, bisect_right, insort

data = [10, 20, 30, 40]  # Must be sorted
insort(data, 25)  # Insert 25 into the correct position
print(data)  # Output: [10, 20, 25, 30, 40]

# Find the position to insert 35 while maintaining order
pos = bisect_left(data, 35)
print(pos)  # Output: 4 (index where 35 should be inserted)

# Find the range of elements between 20 and 35
start = bisect_left(data, 20)
```

```
end = bisect_right(data, 35)
print(data[start:end]) # Output: [20, 25, 30]
```

1.2 Default Dictionary

```
from collections import defaultdict

# Using defaultdict with list
d = defaultdict(list)
d['a'].append(1)
d['b'].append(2)
print(d) # Output: defaultdict(<class 'list'>, {'a': [1], 'b': [2]}))

# Using defaultdict with int
d_int = defaultdict(int)
d_int['a'] += 1
d_int['b'] += 2
print(d_int) # Output: defaultdict(<class 'int'>, {'a': 1, 'b': 2})
```

1.3 Array Input

```
arr = list(map(int, input().split()))
```

1.4 Heap Queue

```
import heapq
# Create an empty priority queue (heap)
pq = []
# Insert elements into the priority queue
heapq.heappush (pq. 15)
heapq.heappush (pq. 31)
heapq.heappush (pq. 3)
heapq.heappush (pq. 3)
heapq.heappush (pq. 482)
# Pop the smallest element
print(heapq.heappop(pq)) # Output: 3
# The next smallest element
print(heapq.heappop(pq)) # Output: 15
```

1.5 Binary Tree

9

10

10

```
class TreeNode:
    def __init__(self, key, value):
         self.key = key
         self.value = value
         self.left = None
         self.right = None
         self.height = 1 # Height of this node
class BTreeMap:
    def __init__(self):
        self.root = None
    def _height(self, node):
         return node.height if node else 0
    def _balance_factor(self, node):
         return self._height(node.left) - self._height(node.right) if node else 0
    def _rotate_left(self, z):
        y = z.right
T2 = y.left
         y.left = z
         z.right = T2
        z.height = 1 + max(self_height(z.left), self_height(z.right))
y.height = 1 + max(self_height(y.left), self_height(y.right))
         return y
    def _rotate_right(self, z):
         y = z.left
```

```
T3 = y.right
    y.right = z
    z.height = 1 + max(self._height(z.left), self._height(z.right))
    y.height = 1 + max(self._height(y.left), self._height(y.right))
    return y
def _balance(self, node):
    balance = self._balance_factor(node)
    if balance > 1: # Left heavy
        if self._balance_factor(node.left) < 0:</pre>
            node.left = self._rotate_left(node.left)
        return self. rotate right (node)
    if balance < -1: # Right heavy
       if self._balance_factor(node.right) > 0:
    node.right = self._rotate_right(node.right)
        return self._rotate_left(node)
    return node
def insert(self, key, value):
    def _insert(node, key, value):
        if node is None:
            return TreeNode(key, value)
        if key < node.key:</pre>
            node.left = _insert(node.left, key, value)
        elif kev > node.kev:
            node.right = _insert(node.right, key, value)
        else:
            node.value = value # Update existing kev
        node.height = 1 + max(self._height(node.left), self._height(node.right))
        return self._balance(node) # return node if not balancing
    self.root = _insert(self.root, key, value)
def get(self, key):
    def _get (node, key):
        if node is None:
            return None
        if key < node.key:</pre>
            return _get (node.left, key)
        elif key > node.key:
            return _get (node.right, key)
        else:
           return node.value
    return get(self.root, key)
def remove(self, key):
    def _remove(node, key):
        if node is None:
            return None
        if key < node.key:</pre>
            node.left = _remove(node.left, key)
        elif key > node.key:
            node.right = _remove(node.right, key)
        else.
            # Node with one or no children
            if node.left is None:
                return node.right
            if node.right is None:
                return node.left
            # Node with two children: find inorder successor
            succ = node.right
            while succ.left:
                succ = succ.left
            node.key, node.value = succ.key, succ.value
            node.right = _remove(node.right, succ.key)
        node.height = 1 + max(self._height(node.left), self._height(node.right))
        return self. balance(node) # return node if not balancing
    self.root = _remove(self.root, key)
def range(self, lower, upper):
    def _range(node, lower, upper):
        if node is None:
            return
        if lower is None or node.key >= lower:
            yield from _range(node.left, lower, upper)
        if (lower is None or node.key >= lower) and (upper is None or node.key < upper):</pre>
            yield (node key, node value)
        if upper is None or node.key < upper:</pre>
            yield from _range(node.right, lower, upper)
    yield from _range(self.root, lower, upper)
```

1.6 Binary Tree Set

```
class TreeNode:
    def __init__(self, key):
        self.key = key
        self.left = None
```

```
self.right = None
    self.height = 1 # Height of this node
def __init__(self):
    self.root = None
def _height(self, node):
    return node.height if node else 0
def _balance_factor(self, node):
    return self._height (node.left) - self._height (node.right) if node else 0
def rotate left(self, z):
    y = z.right
T2 = y.left
    y.left = z
    z.right = T2
    z.height = 1 + max(self._height(z.left), self._height(z.right))
    y.height = 1 + max(self._height(y.left), self._height(y.right))
    return v
def _rotate_right(self, z):
    y = z.left
T3 = y.right
    y.right = z
    z.left = T3
    z.height = 1 + max(self._height(z.left), self._height(z.right))
    y.height = 1 + max(self._height(y.left), self._height(y.right))
    return v
def _balance(self, node):
    balance = self._balance_factor(node)
    if balance > 1: # Left heavy
        if self._balance_factor(node.left) < 0:</pre>
            node.left = self._rotate_left(node.left)
        return self._rotate_right(node)
    if balance < -1: # Right heavy</pre>
        if self._balance_factor(node.right) > 0:
            node.right = self._rotate_right(node.right)
        return self. rotate left(node)
    return node
def insert(self, key):
    def insert (node, key):
        if node is None:
            return TreeNode (key)
        if key < node.key:</pre>
            node.left = _insert(node.left, key)
        elif key > node.key:
            node.right = _insert(node.right, key)
        return self._balance(node) # return node if not balancing
    self.root = _insert(self.root, key)
def remove (self, kev):
    def remove (node, kev):
        if node is None:
           return None
        if key < node.key:</pre>
            node.left = _remove(node.left, key)
        elif key > node.key:
            node.right = _remove(node.right, key)
        else:
            # Node with one or no children
            if node.left is None:
                return node.right
            if node.right is None:
                return node.left
            # Node with two children: find inorder successor
            succ = node.right
            while succ.left:
                succ = succ.left
            node.kev = succ.kev
            node.right = _remove(node.right, succ.key)
        return self._balance(node) # return node if not balancing
    self.root = _remove(self.root, key)
def contains(self, key):
    def _contains(node, key):
        if node is None:
            return False
        if key < node.key:</pre>
            return contains (node.left, kev)
        elif kev > node.kev:
            return contains (node, right, key)
        else:
            return True
    return _contains(self.root, key)
def range(self, lower, upper):
    def _range(node, lower, upper):
        if node is None:
```

```
return
if lower is None or node.key >= lower:
    yield from _range(node.left, lower, upper)
if (lower is None or node.key >= lower) and (upper is None or node.key < upper):
    yield node.key
if upper is None or node.key < upper:
    yield from _range(node.right, lower, upper)
yield from _range(self.root, lower, upper)</pre>
```

1.7 Trie

```
class TrieNode:
    def init (self):
        self.children = {}
        self.is_end_of_word = False
    def __init__(self):
        self.root = TrieNode()
    def insert (self, word):
         node = self.root
        for char in word:
            if char not in node.children:
               node.children[char] = TrieNode()
            node = node.children[char]
        node.is_end_of_word = True
    def search(self, word):
        node = self.root
        for char in word:
            if char not in node.children:
                return False
            node = node.children[char]
        return node.is_end_of_word
    def starts with(self, prefix):
        node = self.root
        for char in prefix:
            if char not in node.children:
              return False
            node = node.children[char]
        return True
    def _find_words_with_prefix(self, node, prefix, result):
        if node.is_end_of_word:
            result.append(prefix)
        for char, child in node.children.items():
            self._find_words_with_prefix(child, prefix + char, result)
    def list_words_with_prefix(self, prefix):
        node = self.root
result = []
        for char in prefix:
            if char not in node.children:
                return result # No words start with this prefix
            node = node.children[char]
        self._find_words_with_prefix(node, prefix, result)
        return result
    def remove(self, word):
        def _remove(node, word, index):
            if index == len(word):
                if not node.is_end_of_word:
                    return False # Word not found
                node.is end of word = False # Unmark the end of word
                return len(node.children) == 0 # If no children, remove node
            char = word[index]
            if char not in node.children:
               return False # Word not found
            child_node = node.children[char]
            should_delete_child = _remove(child_node, word, index + 1)
            if should_delete_child:
                del node.children[char] # Delete the child node if no other word depends on it
                return len(node.children) == 0 and not node.is_end_of_word
            return False
        _remove(self.root, word, 0)
# Example usage
trie = Trie()
trie.insert("apple")
trie.insert("app")
trie.insert("bat")
trie.insert("banana")
trie.insert("batman")
print(trie.search("apple")) # Output: True
print(trie.search("app")) # Output: True
```

```
print(trie.search("batman"))  # Output: True

trie.remove("app")
print(trie.search("app"))  # Output: False
print(trie.search("apple"))  # Output: True

print(trie.list_words_with_prefix("app"))  # Output: ['apple']
print(trie.list_words_with_prefix("ba"))  # Output: ['bat', 'banana', 'batman']
```

2 Dynamic Programming

2.1 Max Sum Subarray (Kadane's Algorithm)

```
def maxSubArraySum(a,size):
    max_so_far = 0
    max_ending_here = 0
    for i in range(0, size):
        max_ending_here = max_ending_here + a[i]
    if max_ending_here < 0:
        max_ending_here = 0
    elif (max_so_far < max_ending_here):
        max_so_far = max_ending_here
    return max_so_far</pre>
```

2.2 Longest Common Subsequence

```
# find the length of the strings
m = len(X)
n = len(Y)
# declaring the array for storing the dp values
L = [[None] * (n+1)  for i in xrange (m+1)]
"""Following steps build L[m+1][n+1] in bottom up fashion
Note: L[i][j] contains length of LCS of X[0..i-1] and Y[0..j-1]"""
for i in range(m+1):
    for j in range (n+1):
        if i == 0 or j == 0 :
            L[i][j] = 0
        elif X[i-1] == Y[j-1]:
            L[i][j] = L[i-1][j-1]+1
        else.
            L[i][j] = max(L[i-1][j], L[i][j-1])
# L[m][n] contains the length of LCS of X[0..n-1] & Y[0..m-1]
return L[m][n]
```

2.3 Levenshtein Distance

```
def levenshtein(s1, s2):
    if len(s1) < len(s2):
        return levenshtein(s2, s1)
    \# len(s1) >= len(s2)
    if len(s2) == 0:
        return len(s1)
    previous row = range(len(s2) + 1)
    for i, c1 in enumerate(s1):
        current_row = [i + 1]
        for j, c2 in enumerate(s2):
            insertions = previous_row[j + 1] + 1 # j+1 instead of j since previous_row and current_row
                 are one character longer
            deletions = current_row[j] + 1
            substitutions = previous_row[j] + (c1 != c2)
            current_row.append(min(insertions, deletions, substitutions))
        previous_row = current_row
    return previous_row[-1]
```

2.4 Longest Increasing Subsequence

```
def lis(arr):
   n = len(arr)
   # Declare the list (array) for LIS and initialize LIS
    # values for all indexes
   lis = [1] *n
   # Compute optimized LIS values in bottom up manner
   for i in range (1, n):
        for j in range(0 , i):
           if arr[i] > arr[j] and lis[i] < lis[j] + 1:
               lis[i] = lis[j]+1
   # Initialize maximum to 0 to get the maximum of all
   maximum = 0
    # Pick maximum of all LIS values
   for i in range (n):
       maximum = max(maximum , lis[i])
   return maximum
```

3 Geometry

3.1 Convex Hull

```
def convex_hull(points):
    """Computes the convex hull of a set of 2D points.
    Input: an iterable sequence of (x, y) pairs representing the points.
    Output: a list of vertices of the convex hull in counter-clockwise order,
      starting from the vertex with the lexicographically smallest coordinates.
     Implements Andrew's monotone chain algorithm. O(n log n) complexity.
    # Sort the points lexicographically (tuples are compared lexicographically).
    # Remove duplicates to detect the case we have just one unique point.
    points = sorted(set(points))
    # Boring case: no points or a single point, possibly repeated multiple times.
    if len(points) <= 1:</pre>
        return points
    # 2D cross product of OA and OB vectors, i.e. z-component of their 3D cross product.
    # Returns a positive value, if OAB makes a counter-clockwise turn,
    # negative for clockwise turn, and zero if the points are collinear.
        return (a[0] - o[0]) * (b[1] - o[1]) - (a[1] - o[1]) * (b[0] - o[0])
    # Build lower hull
    for p in points:
        while len(lower) >= 2 and cross(lower[-2], lower[-1], p) <= 0:</pre>
             lower.pop()
        lower.append(p)
    # Build upper hull
    for p in reversed(points):
        while len(upper) >= 2 and cross(upper[-2], upper[-1], p) <= 0:</pre>
            upper.pop()
        upper.append(p)
    # Concatenation of the lower and upper hulls gives the convex hull.
    # Last point of each list is omitted because it is repeated at the beginning of the other list.
    return lower[:-1] + upper[:-1]
# Example: convex hull of a 10-by-10 grid.
assert convex\_hull([(i//10, i%10) for i in range(100)]) == [(0, 0), (9, 0), (9, 9), (0, 9)]
```

3.2 Misc Geometry Functions (C++)

```
// C++ routines for computational geometry.
#include <iostream>
#include <vector>
#include <cmath>
#include <cassert>
using namespace std;
```

```
double INF = 1e100;
double EPS = 1e-12;
  double x, y;
  PT() {}
  PT(double x, double y) : x(x), y(y) {}
  PT(const PT &p) : x(p.x), y(p.y)
  PT operator + (const PT &p) const { return PT(x+p.x, y+p.y);
  PT operator - (const PT &p) const { return PT(x-p.x, y-p.y);
  PT operator * (double c)
                               const { return PT(x*c, y*c ); ]
 PT operator / (double c)
                               const { return PT(x/c, y/c ); }
double dot (PT p, PT q)
                           { return p.x*q.x+p.y*q.y; }
double dist2(PT p, PT q)
                          { return dot(p-q,p-q); }
double cross(PT p, PT q) { return p.x*q.y-p.y*q.x; }
ostream &operator<<(ostream &os, const PT &p) {
 os << "(" << p.x << "," << p.y << ")";
// rotate a point CCW or CW around the origin
PT RotateCCW90(PT p) { return PT(-p.y,p.x);
PT RotateCW90(PT p)
                      { return PT(p.y,-p.x); }
PT RotateCCW(PT p, double t) {
 return PT(p.x*cos(t)-p.y*sin(t), p.x*sin(t)+p.y*cos(t));
// project point c onto line through a and b
// assuming a != b
PT ProjectPointLine(PT a, PT b, PT c) {
  return a + (b-a) *dot (c-a, b-a) /dot (b-a, b-a);
// project point c onto line segment through a and b
PT ProjectPointSegment(PT a, PT b, PT c) {
  double r = dot(b-a,b-a);
  if (fabs(r) < EPS) return a;</pre>
  r = dot(c-a, b-a)/r;
  if (r < 0) return a;
  if (r > 1) return b;
 return a + (b-a) *r:
// compute distance from c to segment between a and b
double DistancePointSegment(PT a, PT b, PT c) {
 return sqrt(dist2(c, ProjectPointSegment(a, b, c)));
// compute distance between point (x,y,z) and plane ax+by+cz=d
double DistancePointPlane(double x, double y, double z,
                          double a, double b, double c, double d)
  return fabs(a*x+b*v+c*z-d)/sgrt(a*a+b*b+c*c);
// determine if lines from a to b and c to d are parallel or collinear
bool LinesParallel(PT a, PT b, PT c, PT d) {
 return fabs(cross(b-a, c-d)) < EPS;
bool LinesCollinear(PT a, PT b, PT c, PT d) {
  return LinesParallel(a, b, c, d)
      && fabs(cross(a-b, a-c)) < EPS
      && fabs(cross(c-d, c-a)) < EPS;
// determine if line segment from a to b intersects with
// line segment from c to d
bool SegmentsIntersect(PT a, PT b, PT c, PT d) {
 if (LinesCollinear(a, b, c, d)) {
   if (dist2(a, c) < EPS || dist2(a, d) < EPS ||</pre>
      dist2(b, c) < EPS || dist2(b, d) < EPS) return true;
    if (dot(c-a, c-b) > 0 && dot(d-a, d-b) > 0 && dot(c-b, d-b) > 0)
  if (cross(d-a, b-a) * cross(c-a, b-a) > 0) return false;
  if (cross(a-c, d-c) * cross(b-c, d-c) > 0) return false;
  return true;
// compute intersection of line passing through a and b
// with line passing through c and d, assuming that unique
// intersection exists; for segment intersection, check if
// segments intersect first
PT ComputeLineIntersection(PT a, PT b, PT c, PT d) {
 b=b-a; d=c-d; c=c-a;
  assert(dot(b, b) > EPS && dot(d, d) > EPS);
  return a + b*cross(c, d)/cross(b, d);
```

```
// compute center of circle given three points
PT ComputeCircleCenter(PT a, PT b, PT c) {
 b = (a+b)/2;
  c = (a + c) / 2;
  return ComputeLineIntersection(b, b+RotateCW90(a-b), c, c+RotateCW90(a-c));
// determine if point is in a possibly non-convex polygon (by William
// Randolph Franklin); returns 1 for strictly interior points, 0 for
\ensuremath{//} strictly exterior points, and 0 or 1 for the remaining points.
// Note that it is possible to convert this into an *exact* test using
// integer arithmetic by taking care of the division appropriately
// (making sure to deal with signs properly) and then by writing exact // tests for checking point on polygon boundary
bool PointInPolygon(const vector<PT> &p, PT q) {
  bool c = 0;
  for (int i = 0; i < p.size(); i++) {</pre>
    int j = (i+1)%p.size();
    if ((p[i].y <= q.y && q.y < p[j].y ||</pre>
      p[j].y \le q.y && q.y < p[i].y) &&
      q.x < p[i].x + (p[j].x - p[i].x) * (q.y - p[i].y) / (p[j].y - p[i].y))
  return c;
// determine if point is on the boundary of a polygon
bool PointOnPolygon(const vector<PT> &p, PT q) {
  for (int i = 0; i < p.size(); i++)</pre>
    if (dist2(ProjectPointSegment(p[i], p[(i+1)%p.size()], q), q) < EPS)</pre>
      return true;
// compute intersection of line through points a and b with
// circle centered at c with radius r >
vector<PT> CircleLineIntersection(PT a, PT b, PT c, double r) {
  vector<PT> ret;
  b = b-a;
  a = a-c:
  double A = dot(b, b);
  double B = dot(a, b);
  double C = dot(a, a) - r*r;
double D = B*B - A*C;
  if (D < -EPS) return ret;</pre>
  ret.push_back(c+a+b*(-B+sqrt(D+EPS))/A);
  if (D > EPS)
    ret.push_back(c+a+b*(-B-sqrt(D))/A);
  return ret;
// compute intersection of circle centered at a with radius r
// with circle centered at b with radius R
vector<PT> CircleCircleIntersection(PT a, PT b, double r, double R) {
  vector<PT> ret:
  double d = sqrt(dist2(a, b));
  if (d > r+R || d+min(r, R) < max(r, R)) return ret;</pre>
  double x = (d*d-R*R+r*r)/(2*d);
  double y = sqrt(r*r-x*x);
  PT v = (b-a)/d;
  ret.push_back(a+v*x + RotateCCW90(v)*y);
  if(y > 0)
    ret.push_back(a+v*x - RotateCCW90(v)*y);
  return ret;
// This code computes the area or centroid of a (possibly nonconvex)
// polygon, assuming that the coordinates are listed in a clockwise or
// counterclockwise fashion. Note that the centroid is often known as
// the "center of gravity" or "center of mass".
double ComputeSignedArea(const vector<PT> &p) {
  double area = 0;
  for(int i = 0; i < p.size(); i++) {</pre>
    int j = (i+1) % p.size();
    area += p[i].x*p[j].y - p[j].x*p[i].y;
  return area / 2.0;
double ComputeArea(const vector<PT> &p) {
  return fabs(ComputeSignedArea(p));
PT ComputeCentroid(const vector<PT> &p) {
 PT c(0,0);
  double scale = 6.0 * ComputeSignedArea(p);
  for (int i = 0; i < p.size(); i++){</pre>
    int j = (i+1) % p.size();
    c = c + (p[i]+p[j])*(p[i].x*p[j].y - p[j].x*p[i].y);
  return c / scale;
```

```
// tests whether or not a given polygon (in CW or CCW order) is simple
bool IsSimple(const vector<PT> &p) {
  for (int i = 0; i < p.size(); i++)</pre>
    for (int k = i+1; k < p.size(); k++) {
     int j = (i+1) % p.size();
int l = (k+1) % p.size();
     if (i == 1 \mid \mid j == k) continue;
      \textbf{if} \ (\texttt{SegmentsIntersect}(p[i], \ p[j], \ p[k], \ p[l]))
        return false;
  return true:
int main() {
  // expected: (-5,2)
  cerr << RotateCCW90(PT(2,5)) << endl;
  // expected: (5,-2)
  cerr << RotateCW90(PT(2,5)) << endl;</pre>
  // expected: (-5,2)
  cerr << RotateCCW(PT(2,5),M_PI/2) << endl;</pre>
  // expected: (5.2)
  cerr << ProjectPointLine(PT(-5,-2), PT(10,4), PT(3,7)) << endl;</pre>
  // expected: (5.2) (7.5.3) (2.5.1)
  << ProjectPointSegment(PT(-5,-2), PT(2.5,1), PT(3,7)) << endl;
  // expected: 6.78903
  cerr << DistancePointPlane(4,-4,3,2,-2,5,-8) << endl;</pre>
  // expected: 1 0 1
  // expected: 0 0 1
  cerr << LinesCollinear(PT(1,1), PT(3,5), PT(2,1), PT(4,5)) << " "</pre>
       << LinesCollinear(PT(1,1), PT(3,5), PT(2,0), PT(4,5)) << " "
       << LinesCollinear(PT(1,1), PT(3,5), PT(5,9), PT(7,13)) << endl;
  // expected: 1 1 1 0
  cerr << SegmentsIntersect(PT(0,0), PT(2,4), PT(3,1), PT(-1,3)) << " "
       << SegmentsIntersect(PT(0,0), PT(2,4), PT(4,3), PT(0,5)) << " "
       << SegmentsIntersect(PT(0,0), PT(2,4), PT(2,-1), PT(-2,1)) << " "
       << SegmentsIntersect(PT(0,0), PT(2,4), PT(5,5), PT(1,7)) << endl;
  // expected: (1.2)
  cerr << ComputeLineIntersection(PT(0,0), PT(2,4), PT(3,1), PT(-1,3)) << endl;</pre>
  // expected: (1.1)
  cerr << ComputeCircleCenter(PT(-3,4), PT(6,1), PT(4,5)) << endl;</pre>
  vector<PT> v;
  v.push_back(PT(0,0));
  v.push_back(PT(5,0));
  v.push_back(PT(5,5));
  v.push_back(PT(0,5));
  // expected: 1 1 1 0 0
  cerr << PointInPolygon(v, PT(2,2)) << " "</pre>
       << PointInPolygon(v, PT(2,0)) << " "
       << PointInPolygon(v, PT(0,2)) << " "
       << PointInPolygon(v, PT(5,2)) << " "
       << PointInPolygon(v, PT(2,5)) << endl;
  // expected: 0 1 1 1 1
  cerr << PointOnPolygon(v, PT(2,2)) << " "
       << PointOnPolygon(v, PT(2,0)) << " "
       << PointOnPolygon(v, PT(0,2)) << " "
       << PointOnPolygon(v, PT(5,2)) << " "
       << PointOnPolygon(v, PT(2,5)) << endl;
               (5,4) (4,5)
               blank line
               (4,5) (5,4)
               blank line
              (4.5) (5.4)
  vector<PT> u = CircleLineIntersection(PT(0,6), PT(2,6), PT(1,1), 5);
  for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
  u = CircleLineIntersection(PT(0,9), PT(9,0), PT(1,1), 5);
  for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
  u = CircleCircleIntersection(PT(1,1), PT(10,10), 5, 5);
  for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
```

```
u = CircleCircleIntersection(PT(1,1), PT(8,8), 5, 5);
for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
u = CircleCircleIntersection(PT(1,1), PT(4.5,4.5), 10, sqrt(2.0)/2.0);
for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
u = CircleCircleIntersection(PT(1,1), PT(4.5,4.5), 5, sqrt(2.0)/2.0);
for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
// area should be 5.0
// centroid should be (1.1666666, 1.166666)
PT pa[] = { PT(0,0), PT(5,0), PT(1,1), PT(0,5) };
vector<PT> p(pa, pa+4);
PT c = ComputeCentroid(p);
cerr << "Area: " << ComputeArea(p) << endl;
cerr << "Centroid: " << c << endl;
return 0;</pre>
```

4 Graphs/Trees

4.1 Graph structure example for our DFS and BFS algorithms

4.2 Breadth-First Search

```
def bfs(graph, start):
    visited, queue = set(), [start]
    while queue:
        vertex = queue.pop(0)
        if vertex not in visited:
            visited.add(vertex)
            queue.extend(graph[vertex] - visited)
    return visited

bfs(graph, 'A') # {'B', 'C', 'A', 'F', 'D', 'E'}
```

4.3 Breadth-First Search Paths

4.4 Breadth-First Search Shortest Path

```
def shortest_path(graph, start, goal):
    try:
        return next(bfs_paths(graph, start, goal))
    except StopIteration:
        return None
shortest_path(graph, 'A', 'F') # ['A', 'C', 'F']
```

4.5 Depth-First Search

```
def dfs(graph, start):
    visited, stack = set(), [start]
    while stack:
        vertex = stack.pop()
        if vertex not in visited:
            visited.add(vertex)
            stack.extend(graph[vertex] - visited)
    return visited

dfs(graph, 'A') # {'E', 'D', 'F', 'A', 'C', 'B'}
```

4.6 Depth-First Search Paths

```
#Returns all paths from start to goal
def dfs_paths(graph, start, goal):
    stack = [(start, [start])]
    while stack:
        ((vertex, path) = stack.pop()
        for next in graph[vertex] - set(path):
            if next == goal:
                  yield path + [next]
        else:
            stack.append((next, path + [next]))

list(dfs_paths(graph, 'A', 'F')) # [['A', 'C', 'F'], ['A', 'B', 'E', 'F']]
```

4.7 Dijkstra's Algorithm

```
from collections import defaultdict
from heapq import *
def dijkstra(edges, f, t):
    g = defaultdict(list)
   for 1, r, c in edges:
       g[1].append((c,r))
   q, seen = [(0,f,())], set()
   while q:
        (cost, v1, path) = heappop(q)
        if v1 not in seen:
            seen.add(v1)
            path = (v1, path)
            if v1 == t: return (cost, path)
            for c, v2 in g.get(v1, ()):
                 if v2 not in seen:
                     heappush(q, (cost+c, v2, path))
   return float("inf")
#Code example
edges = [("A", "B", 7), ("A", "D", 5), ("B", "C", 8), ("B", "D", 9), ("B", "E", 7), ("C", "E", 5)]
print "A -> E:"
print dijkstra(edges, "A", "E") #(14, ('E', ('B', ('A', ()))))
```

4.8 Kruskal's Algorithm (including Merge-Find set)

```
parent = dict()
rank = dict()
def make set(vertice):
    parent[vertice] = vertice
    rank[vertice] = 0
    if parent[vertice] != vertice:
        parent[vertice] = find(parent[vertice])
    return parent[vertice]
def union(vertice1, vertice2):
    root1 = find(vertice1)
    root2 = find(vertice2)
    if root1 != root2:
   if rank[root1] > rank[root2]:
            parent[root2] = root1
        else:
            parent[root1] = root2
        if rank[root1] == rank[root2]: rank[root2] += 1
```

```
def kruskal(graph):
    for vertice in graph['vertices']:
        make_set(vertice)
        minimum_spanning_tree = set()
        edges = list(graph['edges'])
        edges.sort()
        #print edges
    for edge in edges:
        weight, vertice1, vertice2 = edge
        if find(vertice1) != find(vertice2):
             union(vertice1, vertice2)
              minimum_spanning_tree.add(edge)
    return sorted(minimum_spanning_tree)
```

4.9 Bellman-Ford Algorithm

```
# Step 1: For each node prepare the destination and predecessor
def initialize(graph, source):
    d = {} # Stands for destination
             p = {} # Stands for predecessor
             for node in graph:
                        d[node] = float('Inf') # We start admiting that the rest of nodes are very very far
                        p[node] = None
            d[source] = 0 # For the source we know how to reach
            return d, p
def relax(node, neighbour, graph, d, p):
              # If the distance between the node and the neighbour is lower than the one I have now
            if d[neighbour] > d[node] + graph[node][neighbour]:
                         # Record this lower distance
                        d[neighbour] = d[node] + graph[node][neighbour]
                        p[neighbour] = node
 def bellman_ford(graph, source):
            d, p = initialize(graph, source)
             for i in range(len(graph)-1): #Run this until is converges
                        for u in graph:
                                     \begin{tabular}{ll} \be
                                               relax(u, v, graph, d, p) #Lets relax it
             # Step 3: check for negative-weight cycles
            for u in graph:
                        for v in graph[u]:
                                   assert d[v] \leftarrow d[u] + graph[u][v]
            return d, p
 def test():
            graph = {
                        'a': {'b': -1, 'c': 4},
                        'b': {'c': 3, 'd': 2, 'e': 2},
                       'c': {},
'd': {'b': 1, 'c': 5},
'e': {'d': -3}
           d, p = bellman_ford(graph, 'a')
    # d = {'a':0, 'b':-1, 'c':2, 'd':-2, 'e':1},
    # p = {'a':None, 'b':'a', 'c':'b', 'd':'e', 'e':'b'}
```

4.10 Floyd-Warshall Algorithm

```
# Number of vertices in the graph
V = 4

# Define infinity as the large enough value. This value will be
# used for vertices not connected to each other
INF = 99999

# Solves all pair shortest path via Floyd Warshall Algorithm
def floydWarshall(graph):

""" dist[][] will be the output matrix that will finally
have the shortest distances between every pair of vertices """
"" initializing the solution matrix same as input graph matrix
OR we can say that the initial values of shortest distances
are based on shortest paths considerting no
intermedidate vertices """
dist = map(lambda i : map(lambda j : j , i) , graph)

""" Add all vertices one by one to the set of intermediate
vertices.
```

```
---> Before start of a iteration, we have shortest distances
     between all pairs of vertices such that the shortest
     distances consider only the vertices in set
    \{0, 1, 2, \ldots k-1\} as intermediate vertices.
        --> After the end of a iteration, vertex no. k is
     added to the set of intermediate vertices and the
    set becomes {0, 1, 2, .. k}
    for k in range (V):
        # pick all vertices as source one by one
        for i in range(V):
            # Pick all vertices as destination for the
            # above picked source
            for j in range(V):
                \# If vertex k is on the shortest path from
                # i to j, then update the value of dist[i][j]
                dist[i][j] = min(dist[i][j],
                                  dist[i][k]+ dist[k][j]
    printSolution(dist)
            10
       (0) ----> (3)
       (1) ----> (2)
graph = [[0,5,INF,10],
             [INF, 0, 3, INF],
             [INF, INF, 0, 1],
             [INF, INF, INF, 0]
floydWarshall(graph) # [[0,5,8,9],[INF,0,3,4],[INF,INF,0,1],[INF,INF,INF,0]]
```

4.11 Max Flow (Ford-Fulkerson Algorithm)

```
from collections import defaultdict
#This class represents a directed graph using adjacency matrix representation
    def __init__(self,graph):
        self.graph = graph # residual graph
self.ROW = len(graph)
        \#self.COL = len(gr[0])
    ""Returns true if there is a path from source 's' to sink 't' in
    residual graph. Also fills parent[] to store the path ''
    def BFS(self,s, t, parent):
        # Mark all the vertices as not visited
        visited =[False] * (self.ROW)
        # Create a queue for BFS
        queue=[]
        # Mark the source node as visited and enqueue it
        queue.append(s)
        visited[s] = True
        # Standard BFS Loop
        while queue:
             #Dequeue a vertex from queue and print it
            u = queue.pop(0)
            \# Get all adjacent vertices of the dequeued vertex \mathbf{u}
             # If a adjacent has not been visited, then mark it
             # visited and enqueue it
            for ind, val in enumerate(self.graph[u]):
                if visited[ind] == False and val > 0 :
                    queue.append(ind)
                    visited[ind] = True
                    parent[ind] = u
        # If we reached sink in BFS starting from source, then return
        # true, else false
        return True if visited[t] else False
```

```
# Returns the maximum flow from s to t in the given graph
    def FordFulkerson(self, source, sink):
         # This array is filled by BFS and to store path
        parent = [-1] * (self.ROW)
        max_flow = 0 # There is no flow initially
        # Augment the flow while there is path from source to sink
        while self.BFS(source, sink, parent) :
             \# Find minimum residual capacity of the edges along the \# path filled by BFS. Or we can say find the maximum flow
             # through the path found.
            path_flow = float("Inf")
             while(s != source):
                path_flow = min (path_flow, self.graph[parent[s]][s])
                  s = parent[s]
             # Add path flow to overall flow
            max_flow += path_flow
             # update residual capacities of the edges and reverse edges
             # along the path
             v = sink
             while (v != source):
                 u = parent[v]
                 self.graph[u][v] -= path_flow
                 self.graph[v][u] += path_flow
                 v = parent[v]
        return max_flow
# Create a graph given in the above diagram
graph = [[0, 16, 13, 0, 0, 0],
         [0, 0, 10, 12, 0, 0],
         [0, 4, 0, 0, 14, 0],
         [0, 0, 9, 0, 0, 20],
         [0, 0, 0, 7, 0, 4],
         [0, 0, 0, 0, 0, 0]]
g = Graph (graph)
source = 0; sink = 5
print ("The maximum possible flow is %d " % g.FordFulkerson(source, sink))
```

5 Mathematics

5.1 Gauss-Jordan Elimination (Matrix inversion and linear system solving)

```
def gauss_jordan(m, eps = 1.0/(10**10)):
  """Puts given matrix (2D array) into the Reduced Row Echelon Form.
     Returns True if successful, False if 'm' is singular.
     NOTE: make sure all the matrix items support fractions! Int matrix will NOT work!
     Written by Jarno Elonen in April 2005, released into Public Domain"""
  (h, w) = (len(m), len(m[0]))
  for y in range(0,h):
   maxrow = v
   for y2 in range(y+1, h): # Find max pivot
     if abs(m[y2][y]) > abs(m[maxrow][y]):
       maxrow = v2
    (m[y], m[maxrow]) = (m[maxrow], m[y])
   if abs(m[y][y]) <= eps:
   for y^2 in range (y+1, h):
                               # Eliminate column y
       = m[y2][y] / m[y][y]
     for x in range(y, w):
       m[y2][x] = m[y][x] * c
  for y in range(h-1, 0-1, -1): # Backsubstitute
      = m[y][y]
   for y^2 in range (0, y):
     for x in range (w-1, y-1, -1):
       m[y2][x] = m[y][x] * m[y2][y] / c
   for x in range(h, w):
                               # Normalize row v
     m[y][x] /= c
  return True
```

```
def solve(M, b):
  solves M*x = b
  return vector x so that M*x = b
  :param M: a matrix in the form of a list of list
  :param b: a vector in the form of a simple list of scalars
  m2 = [row[:]+[right] for row, right in zip(M,b) ]
  return [row[-1] for row in m2] if gauss_jordan(m2) else None
def inv(M):
  return the inv of the matrix M
  #clone the matrix and append the identity matrix
  \# [int(i==j) for j in range_M] is nothing but the i(th row of the identity matrix
  m2 = [row[:]+[int(i==j) for j in range(len(M))] for i,row in enumerate(M)]
  # extract the appended matrix (kind of m2[m:,...]
  return [row[len(M[0]):] for row in m2] if gauss_jordan(m2) else None
def zeros( s , zero=0):
    return a matrix of size 'size'
    :param size: a tuple containing dimensions of the matrix
    :param zero: the value to use to fill the matrix (by default it's zero )
    return [zeros(s[1:]) for i in range(s[0])] if not len(s) else zero
```

5.2 Miller-Rabin Primality Test

```
def miller_rabin(n, k):
    # The optimal number of rounds (k) for this test is 40
    # for justification
    if n == 2:
        return True
    if n % 2 == 0:
       return False
    r, s = 0, n - 1
    while s % 2 == 0:
        r += 1
        s //= 2
    for \_ in xrange(k):
        a = random.randrange(2, n - 1)
        x = pow(a, s, n)
        if x == 1 or x == n - 1:
           continue
        for in xrange(r - 1):
            x = pow(x, 2, n)
            if x == n - 1:
        else:
           return False
    return True
```

5.3 Segment Tree

```
#encoding:utf-8
class SegmentTree(object):
   def __init__(self, start, end):
       self.start = start
       self.end = end
       self.max value = {}
       self.sum value = {}
       self.len_value = {}
       self. init(start, end)
   def add(self, start, end, weight=1):
       start = max(start, self.start)
        end = min(end, self.end)
        self._add(start, end, weight, self.start, self.end)
       return True
   def query_max(self, start, end):
       return self._query_max(start, end, self.start, self.end)
   def query_sum(self, start, end):
       return self._query_sum(start, end, self.start, self.end)
   def query len(self, start, end):
       return self._query_len(start, end, self.start, self.end)
```

```
def _init(self, start, end):
    self.max_value[(start, end)] = 0
    self.sum_value[(start, end)] = 0
    self.len_value[(start, end)] = 0
    if start < end:</pre>
        mid = start + int((end - start) / 2)
        self._init(start, mid)
        self._init(mid+1, end)
def _add(self, start, end, weight, in_start, in_end):
   key = (in_start, in_end)
if in start == in end:
        self.max_value[key] += weight
        self.sum_value[key] += weight
self.len_value[key] = 1 if self.sum_value[key] > 0 else 0
    mid = in_start + int((in_end - in_start) / 2)
    if mid >= end:
        self._add(start, end, weight, in_start, mid)
    elif mid+1 <= start:</pre>
        self._add(start, end, weight, mid+1, in_end)
        self._add(start, mid, weight, in_start, mid)
        self._add(mid+1, end, weight, mid+1, in_end)
   self.max_value[key] = max(self.max_value[(in_start, mid)], self.max_value[(mid+1, in_end)])
self.sum_value[key] = self.sum_value[(in_start, mid)] + self.sum_value[(mid+1, in_end)]
    self.len_value[key] = self.len_value[(in_start, mid)] + self.len_value[(mid+1, in_end)]
def _query_max(self, start, end, in_start, in_end):
    if start == in_start and end == in_end:
        ans = self.max_value[(start, end)]
        mid = in_start + int((in_end - in_start) / 2)
        if mid >= end:
            ans = self._query_max(start, end, in_start, mid)
        elif mid+1 <= start:</pre>
            ans = self._query_max(start, end, mid+1, in_end)
        else:
            ans = max(self._query_max(start, mid, in_start, mid),
                     self._query_max(mid+1, end, mid+1, in_end))
    #print start, end, in_start, in_end, ans
    return ans
def _query_sum(self, start, end, in_start, in_end):
    if start == in_start and end == in_end:
        ans = self.sum_value[(start, end)]
        mid = in_start + int((in_end - in_start) / 2)
        if mid >= end:
            ans = self._query_sum(start, end, in_start, mid)
        elif mid+1 <= start:</pre>
            ans = self._query_sum(start, end, mid+1, in_end)
        else:
            ans = self._query_sum(start, mid, in_start, mid) + self._query_sum(mid+1, end, mid+1,
                   in_end)
    return ans
def _query_len(self, start, end, in_start, in_end):
    if start == in_start and end == in_end:
        ans = self.len_value[(start, end)]
        mid = in_start + int((in_end - in_start) / 2)
        if mid >= end:
            ans = self._query_len(start, end, in_start, mid)
        elif mid+1 <= start:</pre>
            ans = self._query_len(start, end, mid+1, in_end)
        else:
            ans = self._query_len(start, mid, in_start, mid) + self._query_len(mid+1, end, mid+1,
                   in end)
    #print start, end, in_start, in_end, ans
    return ans
```

5.4 Prime Number Sieve (generator)

```
from itertools import count
def postponed_sieve():
                                         # postponed sieve, by Will Ness
    yield 2; yield 3; yield 5; yield 7;
                                        # original code David Eppstein,
                                            Alex Martelli, ActiveState Recipe 2002
    sieve = {}
    ps = postponed sieve()
                                         # a separate base Primes Supply:
    p = next(ps) and next(ps)
                                        # (3) a Prime to add to dict
                                        # (9) its sQuare
    for c in count (9, 2):
                                         # the Candidate
       if c in sieve:
                                     # c's a multiple of some base prime
```

```
s = sieve.pop(c)
                                  i.e. a composite ; or
elif c < q:</pre>
    yield c
     continue
                              # or the next base prime's square:
    s=count(q+2*p,2*p)
                                (9+6, by 6 : 15,21,27,33,...)
    p=next(ps)
                                  (5)
for m in s:
                             # the next multiple
   if m not in sieve:
                             # no duplicates
       break
sieve[m] = s
                             # original test entry: ideone.com/WFv4f
```

5.5 GCD and Euler's Totient Function

```
# Function to return gcd of a and b
def gcd(a, b):
    if a == 0:
        return b
    return gcd(b%a, a)

# A simple method to evaluate Euler Totient Function
def phi(n):
    result = 1
    for i in range(2, n):
        if gcd(i, n) == 1:
            result = result + 1
    return result
```

6 Strings

6.1 Knuth-Morris-Pratt Algorithm (fast pattern matching)

```
def KnuthMorrisPratt(text, pattern):
    "'Yields all starting positions of copies of the pattern in the text.
Calling conventions are similar to string.find, but its arguments can be
lists or iterators, not just strings, it returns all matches, not just
the first one, and it does not need the whole text in memory at once.
Whenever it yields, it will have read the text exactly up to and including
the match that caused the yield.'''
    # allow indexing into pattern and protect against change during yield
    # build table of shift amounts
    shifts = [1] * (len(pattern) + 1)
    shift = 1
    for pos in range(len(pattern)):
        while shift <= pos and pattern[pos] != pattern[pos-shift]:</pre>
           shift += shifts[pos-shift]
        shifts[pos+1] = shift
    # do the actual search
    startPos = 0
        while matchLen == len(pattern) or \
             matchLen >= 0 and pattern[matchLen] != c:
            startPos += shifts[matchLen]
            matchLen -= shifts[matchLen]
        matchLen += 1
        if matchLen == len(pattern):
            vield startPos
```

6.2 Rabin-Karp Algorithm (multiple pattern matching)

```
# d is the number of characters in input alphabet
d = 256
# pat -> pattern
# txt -> text
# q -> A prime number

def search(pat, txt, q):
```

```
M = len(pat)
    N = len(txt)
    \mathbf{p} = 0
              # hash value for pattern
    t = 0
              # hash value for txt
    # The value of h would be "pow(d, M-1)%q"
    for i in xrange(M-1):
        h = (h*d) %q
    # Calculate the hash value of pattern and first window
    # of text
    for i in xrange(M):
    p = (d*p + ord(pat[i]))%q
    t = (d*t + ord(txt[i]))%q
    # Slide the pattern over text one by one
    for i in xrange (N-M+1):
         # Check the hash values of current window of text and
         # pattern if the hash values match then only check
         # for characters on by one
             # Check for characters one by one
             for j in xrange(M):
                 if txt[i+j] != pat[j]:
                     break
             # if p == t and pat[0...M-1] = txt[i, i+1, ...i+M-1]
                print "Pattern found at index " + str(i)
         # Calculate hash value for next window of text: Remove
         # leading digit, add trailing digit
        if i < N-M:
             t = (d*(t-ord(txt[i])*h) + ord(txt[i+M])) %q
             # We might get negative values of t, converting it to
             # positive
             if t < 0:
                t = t + \alpha
# Driver program to test the above function
txt = "GEEKS FOR GEEKS"
pat = "GEEK"
q = 101 # A prime number
search (pat, txt, q)
```

7 Techniques

7.1 Various algorithm techniques

```
Recursion
Divide and conquer
       Finding interesting points in N log N
Greedy algorithm
        Scheduling
        Max contigous subvector sum
        Invariants
        Huffman encoding
Graph theory
        Dynamic graphs (extra book-keeping)
        Breadth first search
        Depth first search
        * Normal trees / DFS trees
        Dijkstra's algoritm
        MST: Prim's algoritm
        Bellman-Ford
        Konig's theorem and vertex cover
        Min-cost max flow
        Lovasz toggle
        Matrix tree theorem
        Maximal matching, general graphs
        Hopcroft-Karp
        Hall's marriage theorem
        Graphical sequences
        Flovd-Warshall
       Eulercykler
Flow networks
        * Augumenting paths
        * Edmonds-Karp
        Bipartite matching
        Min. path cover
```

```
Strongly connected components
        Cutvertices, cutedges och biconnected components
        Edge coloring
        * Trees
        Vertex coloring
        * Bipartite graphs (=> trees)
        * 3^n (special case of set cover)
        Diameter and centroid
        K'th shortest path
        Shortest cycle
Dynamic programmering
        Knapsack
        Coin change
        Longest common subsequence
        Longest increasing subsequence
        Number of paths in a dag
        Shortest path in a dag
        Dynprog over intervals
        Dynprog over subsets
        Dynprog over probabilities
        Dynprog over trees
        3^n set cover
        Divide and conquer
        Knuth optimization
        Convex hull optimizations
        RMQ (sparse table a.k.a 2^k-jumps)
        Bitonic cycle
        Log partitioning (loop over most restricted)
Combinatorics
        Computation of binomial coefficients
        Pigeon-hole principle
        Inclusion/exclusion
        Catalan number
        Pick's theorem
Number theory
        Integer parts
        Divisibility
        Euklidean algorithm
        Modular arithmetic
        * Modular multiplication
        * Modular inverses
        * Modular exponentiation by squaring
        Chinese remainder theorem
        Fermat's small theorem
        Euler's theorem
        Phi function
        Frobenius number
        Quadratic reciprocity
        Pollard-Rho
        Miller-Rabin
        Hensel lifting
        Vieta root jumping
Game theory

Combinatorial games
        Game trees
        Mini-max
        Nim
        Games on graphs
        Games on graphs with loops
        Grundy numbers
        Bipartite games without repetition
        General games without repetition
        Alpha-beta pruning
Probability theory
Optimization
        Binary search
        Ternary search
        Unimodality and convex functions
        Binary search on derivative
Numerical methods
        Numeric integration
        Newton's method
        Root-finding with binary/ternary search
        Golden section search
Matrices
        Gaussian elimination
        Exponentiation by squaring
Sorting
        Radix sort
Geometry
Coordinates and vectors
        * Cross product
        * Scalar product
        Convex hull
        Polygon cut
        Closest pair
        Coordinate-compression
        All segment-segment intersection
```

Topological sorting

```
Sweeping
```

Discretization (convert to events and sweep) Angle sweeping Line sweeping
Discrete second derivatives

Strings

Longest common substring Palindrome subsequences Knuth-Morris-Pratt Knuth-Morris-Fract
Tries
Rolling polynom hashes
Suffix array
Suffix tree
Aho-Corasick
Manacher's algorithm
Letter position lists
Combinatorial search
Meet in the middle

Brute-force with pruning Best-first (A*) Bidirectional search Iterative deepening DFS / A* LCA (2 k-jumps in trees in general)
Pull/push-technique on trees
Heavy-light decomposition Centroid decomposition Centroid decomposition
Lazy propagation
Self-balancing trees
Convex hull trick (wcipeg.com/wiki/Convex_hull_trick)
Monotone queues / monotone stacks / sliding queues
Sliding queue using 2 stacks
Persistent segment tree

f(n) = O(g(n))	iff \exists positive c, n_0 such that	$n = n(n+1)$ $n = n(n+1)(2n+1)$ $n = n(2(n+1))^2$
	$0 \le f(n) \le cg(n) \ \forall n \ge n_0.$	$\sum_{i=1}^{n} i = \frac{n(n+1)}{2}, \sum_{i=1}^{n} i^2 = \frac{n(n+1)(2n+1)}{6}, \sum_{i=1}^{n} i^3 = \frac{n^2(n+1)^2}{4}.$
$f(n) = \Omega(g(n))$	iff \exists positive c, n_0 such that $f(n) \geq cg(n) \geq 0 \ \forall n \geq n_0$.	In general:
$f(n) = \Theta(g(n))$	iff $f(n) = O(g(n))$ and $f(n) = \Omega(g(n))$.	$\sum_{i=1}^{n} i^{m} = \frac{1}{m+1} \left[(n+1)^{m+1} - 1 - \sum_{i=1}^{n} \left((i+1)^{m+1} - i^{m+1} - (m+1)i^{m} \right) \right]$
f(n) = o(g(n))	iff $\lim_{n\to\infty} f(n)/g(n) = 0$.	$\sum_{i=1}^{n-1} i^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k n^{m+1-k}.$
$\lim_{n \to \infty} a_n = a$	iff $\forall \epsilon > 0$, $\exists n_0$ such that $ a_n - a < \epsilon$, $\forall n \ge n_0$.	Geometric series:
$\sup S$	least $b \in \mathbb{R}$ such that $b \geq s$, $\forall s \in S$.	$\sum_{i=0}^{n} c^{i} = \frac{c^{n+1} - 1}{c - 1}, c \neq 1, \sum_{i=0}^{\infty} c^{i} = \frac{1}{1 - c}, \sum_{i=1}^{\infty} c^{i} = \frac{c}{1 - c}, c < 1,$
$\inf S$	greatest $b \in \mathbb{R}$ such that $b \le s$, $\forall s \in S$.	$\sum_{i=0}^{n} ic^{i} = \frac{nc^{n+2} - (n+1)c^{n+1} + c}{(c-1)^{2}}, c \neq 1, \sum_{i=0}^{\infty} ic^{i} = \frac{c}{(1-c)^{2}}, c < 1.$
$ \liminf_{n \to \infty} a_n $	$\lim_{n \to \infty} \inf \{ a_i \mid i \ge n, i \in \mathbb{N} \}.$	Harmonic series: $n = n + n = n + n = n = n = n = n = n = $
$\limsup_{n \to \infty} a_n$	$\lim_{n \to \infty} \sup \{ a_i \mid i \ge n, i \in \mathbb{N} \}.$	$H_n = \sum_{i=1}^n \frac{1}{i}, \qquad \sum_{i=1}^n iH_i = \frac{n(n+1)}{2}H_n - \frac{n(n-1)}{4}.$
$\binom{n}{k}$	Combinations: Size k subsets of a size n set.	$\sum_{i=1}^{n} H_i = (n+1)H_n - n, \sum_{i=1}^{n} {i \choose m} H_i = {n+1 \choose m+1} \left(H_{n+1} - \frac{1}{m+1} \right).$
$\begin{bmatrix} n \\ k \end{bmatrix}$	Stirling numbers (1st kind): Arrangements of an n element set into k cycles.	1. $\binom{n}{k} = \frac{n!}{(n-k)!k!}$, 2. $\sum_{k=0}^{n} \binom{n}{k} = 2^{n}$, 3. $\binom{n}{k} = \binom{n}{n-k}$,
$\binom{n}{k}$	Stirling numbers (2nd kind): Partitions of an n element set into k non-empty sets.	$4. \binom{n}{k} = \frac{n}{k} \binom{n-1}{k-1}, \qquad \qquad 5. \binom{n}{k} = \binom{n-1}{k} + \binom{n-1}{k-1}, \\ 6. \binom{n}{m} \binom{m}{k} = \binom{n}{k} \binom{n-k}{m-k}, \qquad \qquad 7. \sum_{k=0}^{n} \binom{r+k}{k} = \binom{r+n+1}{n},$
$\langle {n \atop k} \rangle$	1st order Eulerian numbers: Permutations $\pi_1\pi_2\pi_n$ on $\{1,2,,n\}$ with k ascents.	8. $\sum_{k=0}^{n} {k \choose m} = {n+1 \choose m+1},$ 9. $\sum_{k=0}^{n} {r \choose k} {s \choose n-k} = {r+s \choose n},$
$\langle\!\langle {n \atop k} \rangle\!\rangle$	2nd order Eulerian numbers.	10. $\binom{n}{k} = (-1)^k \binom{k-n-1}{k}$, 11. $\binom{n}{1} = \binom{n}{n} = 1$,
C_n	Catalan Numbers: Binary trees with $n+1$ vertices.	12. $\binom{n}{2} = 2^{n-1} - 1$, 13. $\binom{n}{k} = k \binom{n-1}{k} + \binom{n-1}{k-1}$,
$14. \begin{bmatrix} n \\ 1 \end{bmatrix} = (n-1)$	15. $\begin{bmatrix} n \\ 2 \end{bmatrix} = (n - 1)^n$	$16. \begin{bmatrix} n \\ n \end{bmatrix} = 1, \qquad \qquad 17. \begin{bmatrix} n \\ k \end{bmatrix} \ge \begin{Bmatrix} n \\ k \end{Bmatrix},$
18. $\begin{bmatrix} n \\ k \end{bmatrix} = (n-1)$	$\binom{n-1}{k} + \binom{n-1}{k-1}, 19. \ \binom{n}{n-1}$	
$22. \left\langle {n \atop 0} \right\rangle = \left\langle {n \atop n-1} \right\rangle$	$\binom{n}{-1} = 1,$ 23. $\binom{n}{k} = \binom{n}{k}$	$\binom{n}{n-1-k}$, $24. \left\langle \binom{n}{k} \right\rangle = (k+1) \left\langle \binom{n-1}{k} \right\rangle + (n-k) \left\langle \binom{n-1}{k-1} \right\rangle$,
25. $\left\langle {0\atop k}\right\rangle = \left\{ {1\atop 0}\right\}$	if $k = 0$, otherwise 26. $\begin{cases} r \\ 1 \end{cases}$	$\binom{n}{2} = 2^n - n - 1,$ 27. $\binom{n}{2} = 3^n - (n+1)2^n + \binom{n+1}{2},$
28. $x^n = \sum_{k=0}^n \binom{n}{k}$	$\left\langle {x+k \choose n}, \qquad $ 29. $\left\langle {n \atop m} \right\rangle = \sum_{k=1}^m$	
		32. $\left\langle \left\langle \begin{array}{c} n \\ 0 \end{array} \right\rangle = 1,$ 33. $\left\langle \left\langle \begin{array}{c} n \\ n \end{array} \right\rangle = 0$ for $n \neq 0$,
$34. \; \left\langle \!\! \left\langle \!\! \begin{array}{c} n \\ k \end{array} \!\! \right\rangle = (k + 1)^n$	-1 $\left\langle \left\langle \begin{pmatrix} n-1 \\ k \end{pmatrix} \right\rangle + (2n-1-k) \left\langle \left\langle \begin{pmatrix} n-1 \\ k \end{pmatrix} \right\rangle \right\rangle$	
$36. \left\{ \begin{array}{c} x \\ x-n \end{array} \right\} = \sum_{k}^{n} \left\{ \begin{array}{c} x \\ x \end{array} \right\}$	$\sum_{k=0}^{n} \left\langle \!\! \left\langle n \atop k \right\rangle \!\! \right\rangle \!\! \binom{x+n-1-k}{2n},$	37. $\binom{n+1}{m+1} = \sum_{k} \binom{n}{k} \binom{k}{m} = \sum_{k=0}^{n} \binom{k}{m} (m+1)^{n-k},$

38.
$$\binom{n+1}{m+1} = \sum_{k} \binom{n}{k} \binom{k}{m} = \sum_{k=0}^{n} \binom{k}{m} n^{\frac{n-k}{m}} = n! \sum_{k=0}^{n} \frac{1}{k!} \binom{k}{m}$$
, 39. $\binom{x}{x-n} = \sum_{k=0}^{n} \binom{n}{k} \binom{x+k}{2n}$, 40. $\binom{n}{m} = \sum_{k} \binom{n}{k} \binom{k+1}{m+1} (-1)^{n-k}$, 41. $\binom{n}{m} = \sum_{k} \binom{n+1}{k+1} \binom{k}{m} (-1)^{m-k}$, 42. $\binom{m+n+1}{m} = \sum_{k=0}^{m} k \binom{n+k}{k}$, 43. $\binom{m+n+1}{m} = \sum_{k=0}^{m} k(n+k) \binom{n+k}{k}$, 44. $\binom{n}{m} = \sum_{k} \binom{n+1}{k+1} \binom{k}{m} (-1)^{m-k}$, 45. $\binom{n-m}{m} = \sum_{k} \binom{n+1}{k+1} \binom{k}{m} (-1)^{m-k}$, for $n \ge m$,

$$\mathbf{46.} \ \, \left\{ \begin{matrix} n \\ n-m \end{matrix} \right\} = \sum_{k} \binom{m-n}{m+k} \binom{m+n}{n+k} \binom{m+k}{k}, \qquad \mathbf{47.} \ \, \left[\begin{matrix} n \\ n-m \end{matrix} \right] = \sum_{k} \binom{m-n}{m+k} \binom{m+n}{n+k} \binom{m+k}{k},$$

48.
$${n \choose \ell+m} {\ell+m \choose \ell} = \sum_{k} {k \choose \ell} {n-k \choose m} {n \choose k},$$
 49.
$${n \choose \ell+m} {\ell+m \choose \ell} = \sum_{k} {k \choose \ell} {n-k \choose m} {n \choose k}.$$

$$\mathbf{49.} \begin{bmatrix} n \\ \ell + m \end{bmatrix} \begin{pmatrix} \ell + m \\ \ell \end{pmatrix} = \sum_{k} \begin{bmatrix} k \\ \ell \end{bmatrix} \begin{bmatrix} n - k \\ m \end{bmatrix} \begin{pmatrix} n \\ k \end{pmatrix}.$$

Every tree with nvertices has n-1edges.

Kraft inequality: If the depths of the leaves of a binary tree are

$$d_1, \dots, d_n$$
:

$$\sum_{i=1}^{n} 2^{-d_i} \le 1,$$

and equality holds only if every internal node has 2 sons.

Recurrences

Master method:

$$T(n) = aT(n/b) + f(n), \quad a \ge 1, b > 1$$

If $\exists \epsilon > 0$ such that $f(n) = O(n^{\log_b a - \epsilon})$

$$T(n) = \Theta(n^{\log_b a}).$$

If
$$f(n) = \Theta(n^{\log_b a})$$
 then $T(n) = \Theta(n^{\log_b a} \log_2 n)$.

If $\exists \epsilon > 0$ such that $f(n) = \Omega(n^{\log_b a + \epsilon})$, and $\exists c < 1$ such that $af(n/b) \leq cf(n)$ for large n, then

$$T(n) = \Theta(f(n)).$$

Substitution (example): Consider the following recurrence

$$T_{i+1} = 2^{2^i} \cdot T_i^2, \quad T_1 = 2.$$

Note that T_i is always a power of two. Let $t_i = \log_2 T_i$. Then we have

$$t_{i+1} = 2^i + 2t_i, \quad t_1 = 1.$$

Let $u_i = t_i/2^i$. Dividing both sides of the previous equation by 2^{i+1} we get

$$\frac{t_{i+1}}{2^{i+1}} = \frac{2^i}{2^{i+1}} + \frac{t_i}{2^i}$$

Substituting we find

$$u_{i+1} = \frac{1}{2} + u_i, \qquad u_1 = \frac{1}{2},$$

which is simply $u_i = i/2$. So we find that T_i has the closed form $T_i = 2^{i2^{i-1}}$. Summing factors (example): Consider the following recurrence

$$T(n) = 3T(n/2) + n$$
, $T(1) = 1$.

Rewrite so that all terms involving Tare on the left side

$$T(n) - 3T(n/2) = n.$$

Now expand the recurrence, and choose a factor which makes the left side "telescope"

$$1(T(n) - 3T(n/2) = n)$$

$$3(T(n/2) - 3T(n/4) = n/2)$$

$$\vdots \quad \vdots \quad \vdots$$

$$3^{\log_2 n - 1}(T(2) - 3T(1) = 2)$$

Let $m = \log_2 n$. Summing the left side we get $T(n) - 3^m T(1) = T(n) - 3^m =$ $T(n) - n^k$ where $k = \log_2 3 \approx 1.58496$.

Summing the right side we get
$$\sum_{i=0}^{m-1} \frac{n}{2^i} 3^i = n \sum_{i=0}^{m-1} \left(\frac{3}{2}\right)^i.$$

Let
$$c = \frac{3}{2}$$
. Then we have
$$n \sum_{i=0}^{m-1} c^i = n \left(\frac{c^m - 1}{c - 1} \right)$$
$$= 2n(c^{\log_2 n} - 1)$$
$$= 2n(c^{(k-1)\log_c n} - 1)$$
$$= 2n^k - 2n.$$

and so $T(n) = 3n^k - 2n$. Full history recurrences can often be changed to limited history ones (example): Consider

$$T_i = 1 + \sum_{j=0}^{i-1} T_j, \quad T_0 = 1.$$

Note that

$$T_{i+1} = 1 + \sum_{j=0}^{i} T_j.$$

Subtracting we find

$$T_{i+1} - T_i = 1 + \sum_{j=0}^{i} T_j - 1 - \sum_{j=0}^{i-1} T_j$$

= T_i .

And so $T_{i+1} = 2T_i = 2^{i+1}$.

Generating functions:

- 1. Multiply both sides of the equation by x^i .
- 2. Sum both sides over all i for which the equation is valid.
- 3. Choose a generating function G(x). Usually $G(x) = \sum_{i=0}^{\infty} x^i g_i$.
- 3. Rewrite the equation in terms of the generating function G(x).
- 4. Solve for G(x).
- 5. The coefficient of x^i in G(x) is q_i . Example:

$$g_{i+1} = 2g_i + 1, \quad g_0 = 0.$$

$$\sum_{i \geq 0} \operatorname{Multiply} \text{ and sum:} \\ \sum_{i \geq 0} 2g_i x^i + \sum_{i \geq 0} x^i.$$

We choose $G(x) = \sum_{i \geq 0} x^i g_i$. Rewrite in terms of G(x):

$$\frac{G(x) - g_0}{x} = 2G(x) + \sum_{i \ge 0} x^i.$$

Simplify

$$\frac{G(x)}{x} = 2G(x) + \frac{1}{1-x}.$$

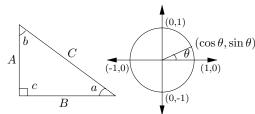
Solve for
$$G(x)$$
:

$$G(x) = \frac{x}{(1-x)(1-2x)}.$$

Expand this using partial fractions:
$$G(x) = x \left(\frac{2}{1 - 2x} - \frac{1}{1 - x} \right)$$
$$= x \left(2 \sum_{i \geq 0} 2^i x^i - \sum_{i \geq 0} x^i \right)$$
$$= \sum_{i \geq 0} (2^{i+1} - 1) x^{i+1}.$$

So
$$g_i = 2^i - 1$$
.

1	$n \sim 0.17100$,	€ ~ 2.1	1020, $I \sim 0.01121$, $\varphi = \frac{1}{2} \sim$	1.01000, $\psi = \frac{1}{2} \sim 0.01000$
i	2^i	p_i	General	Probability
1	2	2	Bernoulli Numbers ($B_i = 0$, odd $i \neq 1$):	Continuous distributions: If
2	4	3	$B_0 = 1, B_1 = -\frac{1}{2}, B_2 = \frac{1}{6}, B_4 = -\frac{1}{30},$	$\Pr[a < X < b] = \int_{a}^{b} p(x) dx,$
3	8	5	$B_6 = \frac{1}{42}, B_8 = -\frac{1}{30}, B_{10} = \frac{5}{66}.$	J a
4	16	7	Change of base, quadratic formula:	then p is the probability density function of X . If
5	32	11	$\log_b x = \frac{\log_a x}{\log_a b}, \qquad \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$	$\Pr[X < a] = P(a),$
6	64	13	34	then P is the distribution function of X . If
7	128	17	Euler's number e:	P and p both exist then
8	256	19	$e = 1 + \frac{1}{2} + \frac{1}{6} + \frac{1}{24} + \frac{1}{120} + \cdots$	$P(a) = \int_{-a}^{a} p(x) dx.$
9	512	23	$\lim_{n\to\infty} \left(1+\frac{x}{n}\right)^n = e^x.$	$J-\infty$
10	1,024	29	$(1+\frac{1}{x})^n < e < (1+\frac{1}{x})^{n+1}$.	Expectation: If X is discrete
11	2,048	31	(11) (11)	$E[g(X)] = \sum_{x} g(x) \Pr[X = x].$
12	4,096	37	$\left(1 + \frac{1}{n}\right)^n = e - \frac{e}{2n} + \frac{11e}{24n^2} - O\left(\frac{1}{n^3}\right).$	If X continuous then
13	8,192	41	Harmonic numbers:	
14	16,384	43	$1, \frac{3}{2}, \frac{11}{6}, \frac{25}{12}, \frac{137}{60}, \frac{49}{20}, \frac{363}{140}, \frac{761}{280}, \frac{7129}{2520}, \dots$	$\mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x)p(x) dx = \int_{-\infty}^{\infty} g(x) dP(x).$
15	32,768	47	/ 2/ 6/ 12/ 60/ 20/ 140/ 280/ 2520/	Variance, standard deviation:
16	65,536	53	$ \ln n < H_n < \ln n + 1, $	$VAR[X] = E[X^2] - E[X]^2,$
17	131,072	59	$H_n = \ln n + \gamma + O\left(\frac{1}{n}\right).$	$\sigma = \sqrt{\text{VAR}[X]}.$
18	262,144	61	(10)	For events A and B :
19	524,288	67	Factorial, Stirling's approximation:	$\Pr[A \vee B] = \Pr[A] + \Pr[B] - \Pr[A \wedge B]$
20	1,048,576	71	$1, 2, 6, 24, 120, 720, 5040, 40320, 362880, \dots$	$\Pr[A \wedge B] = \Pr[A] \cdot \Pr[B],$
21	2,097,152	73	$-(n)^n$	iff A and B are independent.
22	4,194,304	79	$n! = \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \left(1 + \Theta\left(\frac{1}{n}\right)\right).$	$\Pr[A B] = \frac{\Pr[A \land B]}{\Pr[B]}$
23	8,388,608	83	Ackermann's function and inverse:	
24	16,777,216	89	$a(i,j) = \begin{cases} 2^j & i = 1\\ a(i-1,2) & j = 1\\ a(i-1,a(i,j-1)) & i,j \ge 2 \end{cases}$	For random variables X and Y : $E[X \cdot Y] = E[X] \cdot E[Y],$
25	33,554,432	97	$a(i,j) = \begin{cases} a(i-1,2) & j=1 \\ a(i-1,a(i-i-1)) & i \neq 2 \end{cases}$	if X and Y are independent.
26	67,108,864	101		$\mathrm{E}[X+Y]=\mathrm{E}[X]+\mathrm{E}[Y],$
27	134,217,728	103	$\alpha(i) = \min\{j \mid a(j,j) \ge i\}.$	$\operatorname{E}[cX] = c\operatorname{E}[X].$
28	268,435,456	107	Binomial distribution:	Bayes' theorem:
29	536,870,912	109	$\Pr[X=k] = \binom{n}{k} p^k q^{n-k}, \qquad q = 1 - p,$	
30	1,073,741,824	113		$\Pr[A_i B] = \frac{\Pr[B A_i]\Pr[A_i]}{\sum_{j=1}^n \Pr[A_j]\Pr[B A_j]}.$
31	2,147,483,648	127	$E[X] = \sum_{k=1}^{n} k \binom{n}{k} p^k q^{n-k} = np.$	Inclusion-exclusion:
32	4,294,967,296	131	k=1 Poisson distribution:	$\Pr\left[\bigvee_{i=1}^{n} X_i\right] = \sum_{i=1}^{n} \Pr[X_i] +$
	Pascal's Triangl	e		$\begin{bmatrix} \mathbf{V} & \mathbf{I} & \mathbf{I} \\ i & \mathbf{I} \end{bmatrix} \sum_{i=1}^{r} \mathbf{I} \begin{bmatrix} \mathbf{I} & \mathbf{I} \end{bmatrix}$
	1		$\Pr[X = k] = \frac{e^{-\lambda} \lambda^k}{k!}, E[X] = \lambda.$	$\sum_{k=1}^{n} (x_k)^{k+1} \sum_{k=1}^{n} \sum_{k=1}^{n} [A, Y_k]$
1 1			Normal (Gaussian) distribution:	$\sum_{k=2}^{n} (-1)^{k+1} \sum_{i_i < \dots < i_k} \Pr\left[\bigwedge_{j=1}^{k} X_{i_j}\right].$
1 2 1			$p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}, E[X] = \mu.$	Moment inequalities:
1 3 3 1			$\sqrt{2\pi\sigma}$ The "coupon collector": We are given a	$\Pr\left[X \ge \lambda \operatorname{E}[X]\right] \le \frac{1}{\lambda},$
1 4 6 4 1 1 5 10 10 5 1			random coupon each day, and there are n	^ _
1 6 15 20 15 6 1			different types of coupons. The distribu-	$\Pr\left[\left X - \mathrm{E}[X]\right \ge \lambda \cdot \sigma\right] \le \frac{1}{\sqrt{2}}.$
1 7 21 35 35 21 7 1			tion of coupons is uniform. The expected	Geometric distribution:
1 8 28 56 70 56 28 8 1			number of days to pass before we to collect all n types is	$\Pr[X = k] = pq^{k-1}, \qquad q = 1 - p,$
1 9 36 84 126 126 84 36 9 1			nH_n .	\sim
			····n.	$E[X] = \sum_{k=1}^{\infty} kpq^{k-1} = \frac{1}{p}.$
1 10 45 120 210 252 210 120 45 10 1				$\kappa=1$



Pythagorean theorem:

$$C^2 = A^2 + B^2.$$

Definitions:

$$\sin a = A/C, \quad \cos a = B/C,$$

$$\csc a = C/A, \quad \sec a = C/B,$$

$$\tan a = \frac{\sin a}{\cos a} = \frac{A}{B}, \quad \cot a = \frac{\cos a}{\sin a} = \frac{B}{A}.$$

Area, radius of inscribed circle:

$$\frac{1}{2}AB$$
, $\frac{AB}{A+B+C}$

Identities:

$$\sin x = \frac{1}{\csc x}, \qquad \cos x = \frac{1}{\sec x},$$

$$\tan x = \frac{1}{\cot x}, \qquad \sin^2 x + \cos^2 x = 1,$$

$$1 + \tan^2 x = \sec^2 x, \qquad 1 + \cot^2 x = \csc^2 x,$$

$$\sin x = \cos\left(\frac{\pi}{2} - x\right), \qquad \sin x = \sin(\pi - x),$$

$$\cos x = -\cos(\pi - x), \qquad \tan x = \cot\left(\frac{\pi}{2} - x\right),$$

$$\cot x = -\cot(\pi - x), \qquad \csc x = \cot\frac{x}{2} - \cot x,$$

$$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y,$$

 $\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y$,

$$\tan(x \pm y) = \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y},$$
$$\cot(x \pm y) = \frac{\cot x \cot y \mp 1}{\cot x \pm \cot y},$$

$$\sin 2x = 2 \sin x \cos x,$$
 $\sin 2x = \frac{2 \tan x}{1 + \tan^2 x},$
 $\cos 2x = \cos^2 x - \sin^2 x,$ $\cos 2x = 2 \cos^2 x - 1,$
 $\cos 2x = 1 - 2 \sin^2 x,$ $\cos 2x = \frac{1 - \tan^2 x}{1 + \tan^2 x},$

$$\cos 2x = 1 - 2\sin^2 x,$$
 $\cos 2x = \frac{1 + \tan^2 x}{1 + \tan^2 x},$ $\cot 2x = \frac{\cot^2 x - 1}{2\cot x},$

$$\sin(x+y)\sin(x-y) = \sin^2 x - \sin^2 y,$$

$$\cos(x+y)\cos(x-y) = \cos^2 x - \sin^2 y.$$

Euler's equation:

$$e^{ix} = \cos x + i\sin x, \qquad e^{i\pi} = -$$

v2.02 ©1994 by Steve Seiden sseiden@acm.org http://www.csc.lsu.edu/~seiden Multiplication:

$$C = A \cdot B, \quad c_{i,j} = \sum_{k=1}^{n} a_{i,k} b_{k,j}.$$

Determinants: $\det A \neq 0$ iff A is non-singular.

$$\det A \cdot B = \det A \cdot \det B,$$

$$\det A = \sum_{\pi} \prod_{i=1}^{n} \operatorname{sign}(\pi) a_{i,\pi(i)}.$$

 2×2 and 3×3 determinant:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc,$$

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = g \begin{vmatrix} b & c \\ e & f \end{vmatrix} - h \begin{vmatrix} a & c \\ d & f \end{vmatrix} + i \begin{vmatrix} a & b \\ d & e \end{vmatrix}$$

aei + bfg + cdh

-ceq - fha - ibd.

Permanents:

$$\operatorname{perm} A = \sum_{\pi} \prod_{i=1}^{n} a_{i,\pi(i)}.$$

Hyperbolic Functions

Definitions:

$$\begin{aligned} \sinh x &= \frac{e^x - e^{-x}}{2}, & \cosh x &= \frac{e^x + e^{-x}}{2}, \\ \tanh x &= \frac{e^x - e^{-x}}{e^x + e^{-x}}, & \operatorname{csch} x &= \frac{1}{\sinh x}, \\ \operatorname{sech} x &= \frac{1}{\cosh x}, & \operatorname{coth} x &= \frac{1}{\tanh x}. \end{aligned}$$

Identities:

$$\cosh^2 x - \sinh^2 x = 1, \qquad \tanh^2 x + \operatorname{sech}^2 x = 1,$$

$$\coth^2 x - \operatorname{csch}^2 x = 1, \qquad \sinh(-x) = -\sinh x,$$

$$\cosh(-x) = \cosh x, \qquad \tanh(-x) = -\tanh x,$$

$$\sinh(x+y) = \sinh x \cosh y + \cosh x \sinh y,$$

$$\cosh(x+y) = \cosh x \cosh y + \sinh x \sinh y,$$

$$\sinh 2x = 2\sinh x \cosh x,$$

$$\cosh 2x = \cosh^2 x + \sinh^2 x,$$

$$\cosh x + \sinh x = e^x, \qquad \cosh x - \sinh x = e^{-x}.$$

	*	
$\cosh x + \sinh x = e^x,$	$\cosh x - \sinh$	$x = e^{-x}$
$(\cosh x + \sinh x)^n = \cosh$	$nnx + \sinh nx$,	$n \in \mathbb{Z}$,
$2\sinh^2\frac{x}{2} = \cosh x - 1,$	$2\cosh^2\frac{x}{2} = \cot^2\frac{x}{2}$	$\sinh x + 1$

θ	$\sin \theta$	$\cos \theta$	$\tan \theta$
0	0	1	0
$\frac{\pi}{6}$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{3}}{3}$
$\frac{\pi}{4}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{2}}{2}$	1
	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$
$\frac{\pi}{3}$ $\frac{\pi}{2}$	$\overline{1}$	0	∞

... in mathematics you don't understand things, you just get used to them.

– J. von Neumann



Law of cosines: $c^2 = a^2 + b^2 - 2ab \cos C.$ Area:

$$\begin{split} A &= \frac{1}{2}hc, \\ &= \frac{1}{2}ab\sin C, \\ &= \frac{c^2\sin A\sin B}{2\sin C}. \end{split}$$

Heron's formula:

$$A = \sqrt{s \cdot s_a \cdot s_b \cdot s_c},$$

$$s = \frac{1}{2}(a+b+c),$$

$$s_a = s-a,$$

$$s_b = s-b,$$

$$s_c = s-c.$$

More identities:

whose identities.
$$\sin \frac{x}{2} = \sqrt{\frac{1 - \cos x}{2}},$$

$$\cos \frac{x}{2} = \sqrt{\frac{1 + \cos x}{2}},$$

$$\tan \frac{x}{2} = \sqrt{\frac{1 - \cos x}{1 + \cos x}},$$

$$= \frac{1 - \cos x}{\sin x},$$

$$= \frac{\sin x}{1 + \cos x},$$

$$\cot \frac{x}{2} = \sqrt{\frac{1 + \cos x}{1 - \cos x}},$$

$$= \frac{1 + \cos x}{\sin x},$$

$$= \frac{\sin x}{1 - \cos x},$$

$$\sin x = \frac{e^{ix} - e^{-ix}}{2i},$$

$$\cos x = \frac{e^{ix} + e^{-ix}}{2},$$

$$\tan x = -i\frac{e^{ix} - e^{-ix}}{e^{ix} + e^{-ix}},$$

$$= -i\frac{e^{2ix} - 1}{2i},$$

 $\sin x = \frac{\sinh ix}{i}$

 $\cos x = \cosh ix$,

 $\tan x = \frac{\tanh ix}{i}$

The Chinese remainder theorem: There exists a number C such that:

 $C \equiv r_1 \mod m_1$

: : :

 $C \equiv r_n \mod m_n$

if m_i and m_j are relatively prime for $i \neq j$. Euler's function: $\phi(x)$ is the number of positive integers less than x relatively prime to x. If $\prod_{i=1}^{n} p_i^{e_i}$ is the prime factorization of x then

$$\phi(x) = \prod_{i=1}^{n} p_i^{e_i - 1} (p_i - 1).$$

Euler's theorem: If a and b are relatively prime then

$$1 \equiv a^{\phi(b)} \bmod b$$
.

Fermat's theorem:

$$1 \equiv a^{p-1} \bmod p.$$

The Euclidean algorithm: if a > b are integers then

$$gcd(a, b) = gcd(a \mod b, b).$$

If $\prod_{i=1}^{n} p_i^{e_i}$ is the prime factorization of x

$$S(x) = \sum_{d|x} d = \prod_{i=1}^{n} \frac{p_i^{e_i+1} - 1}{p_i - 1}.$$

Perfect Numbers: x is an even perfect number iff $x = 2^{n-1}(2^n - 1)$ and $2^n - 1$ is prime. Wilson's theorem: n is a prime iff

$$(n-1)! \equiv -1 \bmod n.$$

$$\mu(i) = \begin{cases} (n-1)! = -1 \mod n. \\ \text{M\"obius inversion:} \\ \mu(i) = \begin{cases} 1 & \text{if } i = 1. \\ 0 & \text{if } i \text{ is not square-free.} \\ (-1)^r & \text{if } i \text{ is the product of} \\ r & \text{distinct primes.} \end{cases}$$
 If

 If

$$G(a) = \sum_{d|a} F(d),$$

$$F(a) = \sum_{d|a} \mu(d) G\left(\frac{a}{d}\right).$$

Prime numbers:

$$p_n = n \ln n + n \ln \ln n - n + n \frac{\ln \ln n}{\ln n}$$

$$+O\left(\frac{n}{\ln n}\right),$$

$$\pi(n) = \frac{n}{\ln n} + \frac{n}{(\ln n)^2} + \frac{2!n}{(\ln n)^3} + O\left(\frac{n}{(\ln n)^4}\right).$$

Definitions:

Loop An edge connecting a vertex to itself.

Directed Each edge has a direction. SimpleGraph with no loops or multi-edges.

WalkA sequence $v_0e_1v_1\ldots e_\ell v_\ell$. TrailA walk with distinct edges. Pathtrail with distinct

vertices.

ConnectedA graph where there exists a path between any two

vertices.

connected ComponentΑ maximal

subgraph. TreeA connected acyclic graph. Free tree A tree with no root. DAGDirected acyclic graph. EulerianGraph with a trail visiting each edge exactly once.

Hamiltonian Graph with a cycle visiting each vertex exactly once.

CutA set of edges whose removal increases the number of components.

Cut-setA minimal cut. Cut edge A size 1 cut.

k-Connected A graph connected with the removal of any k-1vertices.

k-Tough $\forall S \subseteq V, S \neq \emptyset$ we have $k \cdot c(G - S) \le |S|$.

A graph where all vertices k-Regular have degree k.

k-Factor Α k-regular spanning subgraph.

Matching A set of edges, no two of which are adjacent.

CliqueA set of vertices, all of which are adjacent.

Ind. set A set of vertices, none of which are adjacent.

Vertex cover A set of vertices which cover all edges.

Planar graph A graph which can be embeded in the plane.

Plane graph An embedding of a planar

$$\sum_{v \in V} \deg(v) = 2m.$$

If G is planar then n - m + f = 2, so

$$f \le 2n - 4, \quad m \le 3n - 6.$$

Any planar graph has a vertex with degree ≤ 5 .

Notation:

E(G)Edge set Vertex set V(G)

c(G)Number of components

G[S]Induced subgraph

deg(v)Degree of vMaximum degree $\Delta(G)$

 $\delta(G)$ Minimum degree

 $\chi(G)$ Chromatic number $\chi_E(G)$ Edge chromatic number

 G^c Complement graph K_n Complete graph

 K_{n_1,n_2} Complete bipartite graph

Ramsev number

Geometry

Projective coordinates: (x, y, z), not all x, y and z zero.

$$(x, y, z) = (cx, cy, cz) \quad \forall c \neq 0.$$

Cartesian Projective (x, y)(x, y, 1)y = mx + b(m, -1, b)

x = c(1,0,-c)Distance formula, L_p and L_{∞}

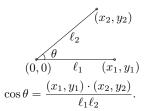
$$\sqrt{(x_1 - x_0)^2 + (y_1 - y_0)^2},$$
$$[|x_1 - x_0|^p + |y_1 - y_0|^p]^{1/p},$$

$$\lim_{n \to \infty} \left[|x_1 - x_0|^p + |y_1 - y_0|^p \right]^{1/p}.$$

Area of triangle $(x_0, y_0), (x_1, y_1)$ and (x_2, y_2) :

$$\frac{1}{2} \operatorname{abs} \begin{vmatrix} x_1 - x_0 & y_1 - y_0 \\ x_2 - x_0 & y_2 - y_0 \end{vmatrix}.$$

Angle formed by three points:



Line through two points (x_0, y_0) and (x_1, y_1) :

$$\begin{vmatrix} x & y & 1 \\ x_0 & y_0 & 1 \\ x_1 & y_1 & 1 \end{vmatrix} = 0.$$

Area of circle, volume of sphere:

$$A = \pi r^2, \qquad V = \frac{4}{3}\pi r^3.$$

If I have seen farther than others, it is because I have stood on the shoulders of giants.

- Issac Newton

Wallis' identity:
$$\pi = 2 \cdot \frac{2 \cdot 2 \cdot 4 \cdot 4 \cdot 6 \cdot 6 \cdots}{1 \cdot 3 \cdot 3 \cdot 5 \cdot 5 \cdot 7 \cdots}$$

Brouncker's continued fraction expansion:

$$\frac{\pi}{4} = 1 + \frac{1^2}{2 + \frac{3^2}{2 + \frac{5^2}{2 + \frac{7^2}{2 + \dots}}}}$$

Gregrory's series:
$$\frac{\pi}{4} = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \frac{1}{9} - \cdots$$

Newton's series:

$$\frac{\pi}{6} = \frac{1}{2} + \frac{1}{2 \cdot 3 \cdot 2^3} + \frac{1 \cdot 3}{2 \cdot 4 \cdot 5 \cdot 2^5} + \cdots$$

Sharp's series:

$$\frac{\pi}{6} = \frac{1}{\sqrt{3}} \left(1 - \frac{1}{3^1 \cdot 3} + \frac{1}{3^2 \cdot 5} - \frac{1}{3^3 \cdot 7} + \cdots \right)$$

Euler's series:

$$\frac{\pi^2}{6} = \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \frac{1}{5^2} + \cdots$$

$$\frac{\pi^2}{8} = \frac{1}{1^2} + \frac{1}{3^2} + \frac{1}{5^2} + \frac{1}{7^2} + \frac{1}{9^2} + \cdots$$

$$\frac{\pi^2}{12} = \frac{1}{1^2} - \frac{1}{2^2} + \frac{1}{3^2} - \frac{1}{4^2} + \frac{1}{5^2} - \cdots$$

Partial Fractions

Let N(x) and D(x) be polynomial functions of x. We can break down N(x)/D(x) using partial fraction expansion. First, if the degree of N is greater than or equal to the degree of D, divide N by D, obtaining

$$\frac{N(x)}{D(x)} = Q(x) + \frac{N'(x)}{D(x)},$$

where the degree of N' is less than that of D. Second, factor D(x). Use the following rules: For a non-repeated factor:

$$\frac{N(x)}{(x-a)D(x)} = \frac{A}{x-a} + \frac{N'(x)}{D(x)},$$

$$A = \left[\frac{N(x)}{D(x)}\right]_{x=a}.$$

For a repeated factor:

$$\frac{N(x)}{(x-a)^m D(x)} = \sum_{k=0}^{m-1} \frac{A_k}{(x-a)^{m-k}} + \frac{N'(x)}{D(x)},$$

$$A_k = \frac{1}{k!} \left[\frac{d^k}{dx^k} \left(\frac{N(x)}{D(x)} \right) \right]_{x=a}.$$

The reasonable man adapts himself to the world; the unreasonable persists in trying to adapt the world to himself. Therefore all progress depends on the unreasonable. George Bernard Shaw

Derivatives:

1.
$$\frac{d(cu)}{dx} = c\frac{du}{dx}$$
, 2. $\frac{d(u+v)}{dx} = \frac{du}{dx} + \frac{dv}{dx}$, 3. $\frac{d(uv)}{dx} = u\frac{dv}{dx} + v\frac{du}{dx}$

4.
$$\frac{d(u^n)}{dx} = nu^{n-1}\frac{du}{dx}, \quad \textbf{5.} \quad \frac{d(u/v)}{dx} = \frac{v\left(\frac{du}{dx}\right) - u\left(\frac{dv}{dx}\right)}{v^2}, \quad \textbf{6.} \quad \frac{d(e^{cu})}{dx} = ce^{cu}\frac{du}{dx}$$

$$\frac{du}{dx} = nu^{n-1}\frac{du}{dx}, \qquad 5. \quad \frac{du}{dx} = -\frac{du}{dx} \qquad \frac{du}{dx}$$

$$=\frac{v\left(\frac{du}{dx}\right)-u\left(\frac{dv}{dx}\right)}{v^2}, \quad \mathbf{6.} \quad \frac{d(e^{cu})}{dx}=ce^{cu}\frac{du}{dx},$$

7.
$$\frac{d(c^u)}{dx} = (\ln c)c^u \frac{du}{dx},$$

$$8. \ \frac{d(\ln u)}{dx} = \frac{1}{u} \frac{du}{dx},$$

$$9. \ \frac{d(\sin u)}{dx} = \cos u \frac{du}{dx},$$

$$10. \ \frac{d(\cos u)}{dx} = -\sin u \frac{du}{dx},$$

11.
$$\frac{d(\tan u)}{dx} = \sec^2 u \frac{du}{dx}$$

$$12. \ \frac{d(\cot u)}{dx} = \csc^2 u \frac{du}{dx},$$

$$\mathbf{13.} \ \frac{d(\sec u)}{dx} = \tan u \, \sec u \frac{du}{dx},$$

$$\mathbf{14.} \ \frac{d(\csc u)}{dx} = -\cot u \, \csc u \, \frac{du}{dx},$$

15.
$$\frac{d(\arcsin u)}{dx} = \frac{1}{\sqrt{1-u^2}} \frac{du}{dx}$$

16.
$$\frac{d(\arccos u)}{dx} = \frac{-1}{\sqrt{1-u^2}} \frac{du}{dx}$$

17.
$$\frac{d(\arctan u)}{dx} = \frac{1}{1+u^2} \frac{du}{dx}$$

18.
$$\frac{d(\operatorname{arccot} u)}{dx} = \frac{-1}{1+u^2} \frac{du}{dx}$$

19.
$$\frac{d(\operatorname{arcsec} u)}{dx} = \frac{1}{u\sqrt{1-u^2}} \frac{du}{dx}$$

$$20. \ \frac{d(\arccos u)}{dx} = \frac{-1}{u\sqrt{1-u^2}} \frac{du}{dx}$$

21.
$$\frac{d(\sinh u)}{dx} = \cosh u \frac{du}{dx}$$

23.
$$\frac{d(\tanh u)}{dx} = \operatorname{sech}^2 u \frac{du}{dx}$$

24.
$$\frac{d(\coth u)}{dx} = -\operatorname{csch}^2 u \frac{du}{dx}$$

25.
$$\frac{d(\operatorname{sech} u)}{dx} = -\operatorname{sech} u \tanh u \frac{du}{dx}$$

26.
$$\frac{d(\operatorname{csch} u)}{dx} = -\operatorname{csch} u \operatorname{coth} u \frac{du}{dx}$$

27.
$$\frac{d(\operatorname{arcsinh} u)}{dx} = \frac{1}{\sqrt{1+u^2}} \frac{du}{dx},$$

28.
$$\frac{d(\operatorname{arccosh} u)}{dx} = \frac{1}{\sqrt{u^2 - 1}} \frac{du}{dx}$$

29.
$$\frac{d(\operatorname{arctanh} u)}{dx} = \frac{1}{1 - u^2} \frac{du}{dx}$$

30.
$$\frac{d(\operatorname{arccoth} u)}{dx} = \frac{1}{u^2 - 1} \frac{du}{dx}$$

31.
$$\frac{d(\operatorname{arcsech} u)}{dx} = \frac{-1}{u\sqrt{1-u^2}}\frac{du}{dx}$$

32.
$$\frac{d(\operatorname{arccsch} u)}{dx} = \frac{-1}{|u|\sqrt{1+u^2}} \frac{du}{dx}$$

Integrals:

$$1. \int cu \, dx = c \int u \, dx,$$

$$2. \int (u+v) \, dx = \int u \, dx + \int v \, dx,$$

3.
$$\int x^n dx = \frac{1}{n+1} x^{n+1}, \quad n \neq -1$$

3.
$$\int x^n dx = \frac{1}{n+1}x^{n+1}$$
, $n \neq -1$, 4. $\int \frac{1}{x} dx = \ln x$, 5. $\int e^x dx = e^x$,

6.
$$\int \frac{dx}{1+x^2} = \arctan x,$$

7.
$$\int u \frac{dv}{dx} dx = uv - \int v \frac{du}{dx} dx,$$

8.
$$\int \sin x \, dx = -\cos x,$$

$$9. \int \cos x \, dx = \sin x,$$

$$10. \int \tan x \, dx = -\ln|\cos x|,$$

11.
$$\int \cot x \, dx = \ln|\cos x|,$$

$$12. \int \sec x \, dx = \ln|\sec x + \tan x|,$$

12.
$$\int \sec x \, dx = \ln|\sec x + \tan x|$$
, **13.** $\int \csc x \, dx = \ln|\csc x + \cot x|$,

14.
$$\int \arcsin \frac{x}{a} dx = \arcsin \frac{x}{a} + \sqrt{a^2 - x^2}, \quad a > 0,$$

60. $\int x\sqrt{x^2 \pm a^2} \, dx = \frac{1}{3}(x^2 \pm a^2)^{3/2},$

61. $\int \frac{dx}{x\sqrt{x^2 + a^2}} = \frac{1}{a} \ln \left| \frac{x}{a + \sqrt{a^2 + x^2}} \right|,$

$$62. \int \frac{dx}{x\sqrt{x^2 - a^2}} = \frac{1}{a} \arccos \frac{a}{|x|}, \quad a > 0, \qquad 63. \int \frac{dx}{x^2\sqrt{x^2 \pm a^2}} = \mp \frac{\sqrt{x^2 \pm a^2}}{a^2 x},$$

$$64. \int \frac{x \, dx}{\sqrt{x^2 \pm a^2}} = \sqrt{x^2 \pm a^2}, \qquad 65. \int \frac{\sqrt{x^2 \pm a^2}}{x^4} \, dx = \mp \frac{(x^2 + a^2)^{3/2}}{3a^2 x^3},$$

$$66. \int \frac{dx}{ax^2 + bx + c} = \begin{cases} \frac{1}{\sqrt{b^2 - 4ac}} \ln \left| \frac{2ax + b - \sqrt{b^2 - 4ac}}{2ax + b + \sqrt{b^2 - 4ac}} \right|, & \text{if } b^2 > 4ac, \\ \frac{2}{\sqrt{4ac - b^2}} \arctan \frac{2ax + b}{\sqrt{4ac - b^2}}, & \text{if } b^2 < 4ac, \end{cases}$$

67.
$$\int \frac{dx}{\sqrt{ax^2 + bx + c}} = \begin{cases} \frac{1}{\sqrt{a}} \ln \left| 2ax + b + 2\sqrt{a}\sqrt{ax^2 + bx + c} \right|, & \text{if } a > 0, \\ \frac{1}{\sqrt{-a}} \arcsin \frac{-2ax - b}{\sqrt{b^2 - 4ac}}, & \text{if } a < 0, \end{cases}$$

68.
$$\int \sqrt{ax^2 + bx + c} \, dx = \frac{2ax + b}{4a} \sqrt{ax^2 + bx + c} + \frac{4ax - b^2}{8a} \int \frac{dx}{\sqrt{ax^2 + bx + c}},$$

69.
$$\int \frac{x \, dx}{\sqrt{ax^2 + bx + c}} = \frac{\sqrt{ax^2 + bx + c}}{a} - \frac{b}{2a} \int \frac{dx}{\sqrt{ax^2 + bx + c}},$$

70.
$$\int \frac{dx}{x\sqrt{ax^2 + bx + c}} = \begin{cases} \frac{-1}{\sqrt{c}} \ln \left| \frac{2\sqrt{c}\sqrt{ax^2 + bx + c} + bx + 2c}{x} \right|, & \text{if } c > 0, \\ \frac{1}{\sqrt{-c}} \arcsin \frac{bx + 2c}{|x|\sqrt{b^2 - 4ac}}, & \text{if } c < 0, \end{cases}$$

71.
$$\int x^3 \sqrt{x^2 + a^2} \, dx = \left(\frac{1}{3}x^2 - \frac{2}{15}a^2\right)(x^2 + a^2)^{3/2}$$

72.
$$\int x^n \sin(ax) \, dx = -\frac{1}{a} x^n \cos(ax) + \frac{n}{a} \int x^{n-1} \cos(ax) \, dx,$$

73.
$$\int x^n \cos(ax) \, dx = \frac{1}{a} x^n \sin(ax) - \frac{n}{a} \int x^{n-1} \sin(ax) \, dx$$

74.
$$\int x^n e^{ax} dx = \frac{x^n e^{ax}}{a} - \frac{n}{a} \int x^{n-1} e^{ax} dx,$$

75.
$$\int x^n \ln(ax) \, dx = x^{n+1} \left(\frac{\ln(ax)}{n+1} - \frac{1}{(n+1)^2} \right),$$

76.
$$\int x^n (\ln ax)^m \, dx = \frac{x^{n+1}}{n+1} (\ln ax)^m - \frac{m}{n+1} \int x^n (\ln ax)^{m-1} \, dx.$$

Difference, shift operators:

$$\Delta f(x) = f(x+1) - f(x),$$

 E $f(x) = f(x+1).$

Fundamental Theorem:

$$f(x) = \Delta F(x) \Leftrightarrow \sum_{i} f(x)\delta x = F(x) + C.$$
$$\sum_{i}^{b} f(x)\delta x = \sum_{i}^{b-1} f(i).$$

$$\Delta(cu) = c\Delta u, \qquad \Delta(u+v) = \Delta u + \Delta v,$$

$$\Delta(uv) = u\Delta v + \mathbf{E}\,v\Delta u,$$

$$\Delta(x^{\underline{n}}) = nx^{\underline{n}-1},$$

$$\Delta(H_x) = x^{-1}, \qquad \Delta(2^x) = 2^x,$$

$$\Delta(H_x) = x \xrightarrow{x}, \qquad \Delta(2^x) = 2^x,$$

$$\Delta(c^x) = (c-1)c^x, \qquad \Delta\binom{x}{m} = \binom{x}{m-1}.$$

Sums:

$$\sum cu \, \delta x = c \sum u \, \delta x,$$

$$\sum (u+v)\,\delta x = \sum u\,\delta x + \sum v\,\delta x,$$

$$\sum u \Delta v \, \delta x = uv - \sum \mathbf{E} \, v \Delta u \, \delta x,$$

$$\sum x^{\underline{n}} \, \delta x = \frac{x^{\underline{n+1}}}{m+1}, \qquad \qquad \sum x^{\underline{-1}} \, \delta x = H_x,$$

$$\sum c^x \, \delta x = \frac{c^x}{c-1}, \qquad \sum \binom{x}{m} \, \delta x = \binom{x}{m+1}.$$

Falling Factorial Powers:

$$x^{\underline{n}} = x(x-1)\cdots(x-n+1), \quad n > 0,$$

 $x^{\underline{0}} = 1,$

$$x^{\underline{n}} = \frac{1}{(x+1)\cdots(x+|n|)}, \quad n < 0,$$

$$x^{\underline{n+m}} = x^{\underline{m}}(x-m)^{\underline{n}}.$$

Rising Factorial Powers:

$$x^{\overline{n}} = x(x+1)\cdots(x+n-1), \quad n > 0,$$

$$x^{\overline{0}} = 1,$$

$$x^{\overline{n}} = \frac{1}{(x-1)\cdots(x-|n|)}, \quad n < 0,$$

$$x^{\overline{n+m}} = x^{\overline{m}} (x+m)^{\overline{n}}.$$

$$x^{\underline{n}} = (-1)^n (-x)^{\overline{n}} = (x - n + 1)^{\overline{n}}$$

= $1/(x + 1)^{\overline{-n}}$,

$$x^{\overline{n}} = (-1)^n (-x)^{\underline{n}} = (x+n-1)^{\underline{n}}$$

$$x^n = \sum_{k=1}^n \binom{n}{k} x^{\underline{k}} = \sum_{k=1}^n \binom{n}{k} (-1)^{n-k} x^{\overline{k}},$$

$$x^{\underline{n}} = \sum_{k=0}^{n} \begin{bmatrix} n \\ k \end{bmatrix} (-1)^{n-k} x^k,$$

$$x^{\overline{n}} = \sum_{k=1}^{n} \begin{bmatrix} n \\ k \end{bmatrix} x^k.$$

Taylor's series:

$$f(x) = f(a) + (x - a)f'(a) + \frac{(x - a)^2}{2}f''(a) + \dots = \sum_{i=0}^{\infty} \frac{(x - a)^i}{i!}f^{(i)}(a).$$
sions:

Expansions:

Expansions:
$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} x^i,$$

$$\frac{1}{1-cx} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} c^i x^i,$$

$$\frac{1}{1-cx} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} c^i x^i,$$

$$\frac{1}{1-x^n} = 1 + x^n + x^{2n} + x^{3n} + \cdots = \sum_{i=0}^{\infty} x^{ni},$$

$$\frac{x}{(1-x)^2} = x + 2x^2 + 3x^3 + 4x^4 + \cdots = \sum_{i=0}^{\infty} i x^i,$$

$$x^k \frac{d^n}{dx^n} \left(\frac{1}{1-x}\right) = x + 2^n x^2 + 3^n x^3 + 4^n x^4 + \cdots = \sum_{i=0}^{\infty} i^n x^i,$$

$$e^x = 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3 + \cdots = \sum_{i=0}^{\infty} (-1)^{i+1} \frac{x^i}{i},$$

$$\ln(1+x) = x - \frac{1}{2}x^2 + \frac{1}{3}x^3 - \frac{1}{4}x^4 - \cdots = \sum_{i=0}^{\infty} (-1)^{i+1} \frac{x^i}{i},$$

$$\sin x = x - \frac{1}{3}x^3 + \frac{1}{6}x^5 - \frac{1}{17}x^7 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$\cos x = 1 - \frac{1}{2}x^2 + \frac{1}{4}x^4 - \frac{1}{6!}x^6 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2}x^2 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2}x^2 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$\frac{1}{(1-x)^{n+1}} = 1 + (n+1)x + \binom{n+2}{2}x^2 + \cdots = \sum_{i=0}^{\infty} \binom{i}{i}x^i,$$

$$\frac{1}{x^i} = 1 + x + 2x^2 + 5x^3 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{\sqrt{1-4x}} = 1 + x + 2x^2 + 6x^3 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{\sqrt{1-4x}} = 1 + (2+n)x + \binom{4+n}{2}x^2 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{1-x} \ln \frac{1}{1-x} = x + \frac{3}{2}x^2 + \frac{1}{16}x^3 + \frac{25}{212}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{1}{2}\left(\ln \frac{1}{1-x}\right)^2 = \frac{1}{2}x^2 + \frac{3}{4}x^3 + \frac{11}{24}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{x}{1-x} = x + \frac{3}{2}x^2 + \frac{1}{16}x^3 + \frac{25}{212}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{x}{1-x} = x^2 + x^2 + 2x^3 + 3x^4 + \cdots = \sum_{i=0}^{\infty} F_{i}x^i.$$

Ordinary power series:

$$A(x) = \sum_{i=0}^{\infty} a_i x^i.$$

Exponential power series:

$$A(x) = \sum_{i=0}^{\infty} a_i \frac{x^i}{i!}.$$

Dirichlet power series:

$$A(x) = \sum_{i=1}^{\infty} \frac{a_i}{i^x}.$$

Binomial theorem

$$(x+y)^n = \sum_{k=0}^n \binom{n}{k} x^{n-k} y^k.$$

$$x^{n} - y^{n} = (x - y) \sum_{k=0}^{n-1} x^{n-1-k} y^{k}.$$

For ordinary power se

$$\alpha A(x) + \beta B(x) = \sum_{i=0}^{\infty} (\alpha a_i + \beta b_i) x^i,$$

$$x^k A(x) = \sum_{i=k}^{\infty} a_{i-k} x^i,$$

$$\frac{A(x) - \sum_{i=0}^{k-1} a_i x^i}{x^k} = \sum_{i=0}^{\infty} a_{i+k} x^i,$$

$$A(cx) = \sum_{i=0}^{\infty} c^i a_i x^i,$$

$$A'(x) = \sum_{\infty}^{i=0} (i+1)a_{i+1}x^{i},$$

$$xA'(x) = \sum_{i=1}^{\infty} ia_i x^i,$$

$$\int A(x) dx = \sum_{i=1}^{\infty} \frac{a_{i-1}}{i} x^{i},$$

$$\frac{A(x) + A(-x)}{2} = \sum_{i=1}^{\infty} a_{2i} x^{2i},$$

$$\frac{A(x) - A(-x)}{2} = \sum_{i=0}^{\infty} a_{2i+1} x^{2i+1}.$$

Summation: If $b_i = \sum_{i=0}^i a_i$ then

$$B(x) = \frac{1}{1-x}A(x).$$

Convolution:

$$A(x)B(x) = \sum_{i=0}^{\infty} \left(\sum_{j=0}^{i} a_j b_{i-j}\right) x^i.$$

God made the natural numbers; all the rest is the work of man. Leopold Kronecker

Expansions:

$$\frac{1}{(1-x)^{n+1}} \ln \frac{1}{1-x} = \sum_{i=0}^{\infty} (H_{n+i} - H_n) \binom{n+i}{i} x^i, \qquad \left(\frac{1}{x}\right)^{\frac{n}{n}} = \sum_{i=0}^{\infty} \binom{i}{n} x^i, \\ x^{\overline{n}} = \sum_{i=0}^{\infty} \binom{n}{i} x^i, \qquad (e^x - 1)^n = \sum_{i=0}^{\infty} \binom{i}{n} \frac{n! x^i}{i!}, \\ \left(\ln \frac{1}{1-x}\right)^n = \sum_{i=0}^{\infty} \binom{n}{i} \frac{n! x^i}{i!}, \qquad x \cot x = \sum_{i=0}^{\infty} \frac{(-4)^i B_{2i} x^{2i}}{(2i)!}, \\ \tan x = \sum_{i=1}^{\infty} (-1)^{i-1} \frac{2^{2i} (2^{2i} - 1) B_{2i} x^{2i-1}}{(2i)!}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \qquad \zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^x}, \\ \zeta(x) =$$

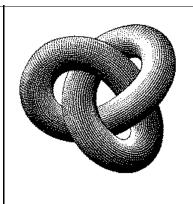
$$\left(\frac{1}{x}\right)^{\overline{-n}} = \sum_{i=0}^{\infty} \begin{Bmatrix} i \\ n \end{Bmatrix} x^{i},$$

$$\left(e^{x} - 1\right)^{n} = \sum_{i=0}^{\infty} \begin{Bmatrix} i \\ n \end{Bmatrix} \frac{n! x^{i}}{i!},$$

$$x \cot x = \sum_{i=0}^{\infty} \frac{(-4)^{i} B_{2i} x^{2i}}{(2i)!},$$

$$\zeta(x) = \sum_{i=1}^{\infty} \frac{1}{i^{x}},$$

$$\frac{\zeta(x-1)}{\zeta(x)} = \sum_{i=1}^{\infty} \frac{\phi(i)}{i^{x}},$$



Stieltjes Integration

If G is continuous in the interval [a, b] and F is nondecreasing then

$$\int_a^b G(x) \, dF(x)$$

exists. If a < b < c then

$$\int_{a}^{c} G(x) \, dF(x) = \int_{a}^{b} G(x) \, dF(x) + \int_{b}^{c} G(x) \, dF(x).$$

$$\int_{a}^{b} (G(x) + H(x)) dF(x) = \int_{a}^{b} G(x) dF(x) + \int_{a}^{b} H(x) dF(x),$$

$$\int_{a}^{b} G(x) d(F(x) + H(x)) = \int_{a}^{b} G(x) dF(x) + \int_{a}^{b} G(x) dH(x),$$

$$\int_{a}^{b} c \cdot G(x) dF(x) = \int_{a}^{b} G(x) d(c \cdot F(x)) = c \int_{a}^{b} G(x) dF(x),$$

$$\int_{a}^{b} G(x) dF(x) = G(b)F(b) - G(a)F(a) - \int_{a}^{b} F(x) dG(x).$$

If the integrals involved exist, and F possesses a derivative F' at every point in [a, b] then

$$\int_a^b G(x) dF(x) = \int_a^b G(x)F'(x) dx.$$

If we have equations:

$$a_{1,1}x_1 + a_{1,2}x_2 + \dots + a_{1,n}x_n = b_1$$

$$a_{2,1}x_1 + a_{2,2}x_2 + \dots + a_{2,n}x_n = b_2$$

$$\vdots \qquad \vdots$$

$$a_{n,1}x_1 + a_{n,2}x_2 + \dots + a_{n,n}x_n = b_n$$

Let $A = (a_{i,j})$ and B be the column matrix (b_i) . Then there is a unique solution iff $\det A \neq 0$. Let A_i be Awith column i replaced by B. Then

$$x_i = \frac{\det A_i}{\det A}.$$

Improvement makes strait roads, but the crooked roads without Improvement, are roads of Genius.

William Blake (The Marriage of Heaven and Hell)

 $00 \ \ 47 \ \ 18 \ \ 76 \ \ 29 \ \ 93 \ \ 85 \ \ 34 \ \ 61 \ \ 52$ 86 11 57 28 70 39 94 45 02 63 37 08 75 19 92 84 66 23 50 41 14 25 36 40 51 62 03 77 88 99 21 32 43 54 65 06 10 89 97 78 42 53 64 05 16 20 31 98 79 87

The Fibonacci number system: Every integer n has a unique representation

$$n = F_{k_1} + F_{k_2} + \dots + F_{k_m},$$

where $k_i \ge k_{i+1} + 2$ for all i ,
 $1 \le i < m$ and $k_m \ge 2$.

Fibonacci Numbers

 $1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, \dots$ Definitions:

$$F_{i} = F_{i-1} + F_{i-2}, \quad F_{0} = F_{1} = 1,$$

$$F_{-i} = (-1)^{i-1} F_{i},$$

$$F_{i} = \frac{1}{\sqrt{5}} \left(\phi^{i} - \hat{\phi}^{i} \right),$$

Cassini's identity: for i > 0:

$$F_{i+1}F_{i-1} - F_i^2 = (-1)^i.$$

Additive rule:

$$F_{n+k} = F_k F_{n+1} + F_{k-1} F_n,$$

$$F_{2n} = F_n F_{n+1} + F_{n-1} F_n.$$

Calculation by matrices:

$$\begin{pmatrix} F_{n-2} & F_{n-1} \\ F_{n-1} & F_n \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^n.$$