```cpp
// C++ code
// Motor control
int n =11,p=10;
void setup()
{
  pinMode(p,OUTPUT);
  pinMode(n,OUTPUT);
}
void loop()
{
  analogWrite(p,150);
  analogWrite(n,0);
  delay(2000);
  analogWrite(p,0);
  analogWrite(n,150);
  delay(2000);
}
```