## SMAI-S25-09: Regression and Regularization

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### Recap:

- Problems of interest:
  - Learn a function  $y = f(\mathbf{W}, \mathbf{x})$  from the data.
    - (a) Classification (b) Regression
  - Learn Feature Transformations  $\mathbf{x}' = \mathbf{W}\mathbf{x}$  or  $\mathbf{x}' = f(\mathbf{W}, \mathbf{x})$
- Algorithms/Approaches:
  - Nearest Neighbour Algorithm
  - Linear Classification:  $sign(\mathbf{w}^T\mathbf{x})$
  - Decide as  $\omega_1$  if  $P(\omega_1|\mathbf{x}) \geq P(\omega_2|\mathbf{x})$  else  $\omega_2$ .
  - Linear Regression
- Performance Metrics:
  - Classification: Accuracy, TP/FP etc., Confusion Matrix; Ranking: Precision, Recall, F-Score, AP
- Supervised Learning:
  - Notion of Training, Validation and Testing
  - Notion of Loss Function, MSE, Regularization (today)
  - Role of Optimization, Convex and non-Convex optimization
  - Closed form solution, Gradient Descent, eigen vector (today)

### Linear Regression

Given N examples  $\mathcal{D} = \{(\mathbf{x}_i, y_i)\}$ . Our goal is to find a solution of the form:  $y_i = mx_i + c$ ; or  $y_i = w_1x_i + w_2$  or

$$\hat{y}_i = \mathbf{w}^T \mathbf{x}_i$$

Problem:

$$\mathbf{w} = \arg\min_{\mathbf{w}} \sum_{i=1}^{N} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

#### Two Solutions

1. Closed Form Solution

$$\mathbf{w}^* = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

2. Gradient Descent Solution

$$\mathbf{w}^{k+1} \leftarrow \mathbf{w}^k - \eta \nabla J$$

$$\min_{\mathbf{w}} J(\mathbf{w}) = \min_{\mathbf{w}} \frac{1}{N} \sum_{i=1}^{N} (y_i - \mathbf{w}^\mathsf{T} \mathbf{x_i})^2$$

$$\nabla J = \frac{2}{N} \sum_{i=1}^{N} (y_i - \mathbf{w}^\mathsf{T} \mathbf{x_i}) (-\mathbf{x_i})$$

### Regularization

- Prefer some type of solutions (eg. prefer sparse solutions).
- Frequently used in solving ill-posed problems (eg. avoid singularities such as inverting a near singular matrix)
- A set of methods for reducing overfitting in machine learning models.
- In short, critical for managing model complexity, improving generalization to new data, and addressing specific issues
- Example: Add an additional function to the loss function

$$J = f(\mathbf{w}, \mathbf{x}, y) + \lambda g(\mathbf{w})$$

### Regularize with L0, L1 and L2

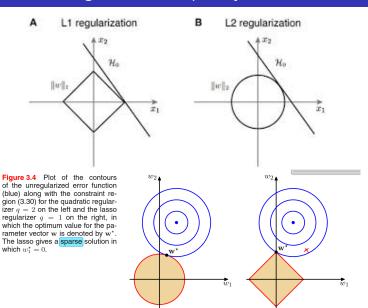
$$J = f(\mathbf{w}) + \lambda ||\mathbf{w}||$$

It is common to regularize with L2, L1 (ideally L0; why?) norms. Recap:  $L_p$  norm of of  $\mathbf{x}$  is defined as

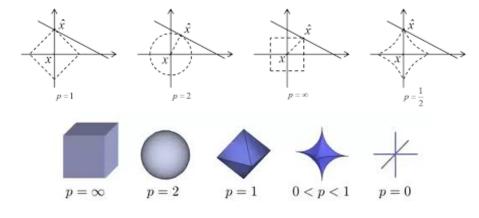
$$||\mathbf{x}|| = (\sum_{i=1}^{d} |x_i|^p)^{\frac{1}{p}}$$

- L1: (when d=2):  $||\mathbf{x}||_1 = |x_1| + |x_2|$
- L2: (when d=2):  $||\mathbf{x}||_2 = \sqrt{x_1^2 + x_2^2}$
- The L0 norm of a vector counts the number of non-zero elements in the vector.
- The L-infinity norm, also known as the "max norm," is a vector norm that measures the maximum absolute value of the vector elements.

## Some Intuitive Arguments on Sparsity



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## Ridge Regression

In ridge regression, we improve the objective as

$$J = \sum_{i=1}^{N} (y_i - \mathbf{w}^T \mathbf{x})^2 + \lambda \sum_{j=1}^{d} w_j^2$$
$$= \sum_{i=1}^{N} (y_i - \mathbf{w}^T \mathbf{x})^2 + \lambda ||\mathbf{w}||_2^2.$$

Let us come back to ridge regression objective. It can be done as:

$$J(\mathbf{w}) = \frac{1}{N} (\mathbf{Y}^T \mathbf{Y} + \mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w} - 2 \mathbf{w}^T (\mathbf{X}^T \mathbf{Y}) + \lambda \mathbf{w}^T \mathbf{w}))$$

Optimization of the above objective function leads to:

$$\mathbf{w} = (\mathbf{X}^T \mathbf{X} + \lambda I)^{-1} \mathbf{X}^T \mathbf{Y}$$

### Lasso Regression

Lasso is another variant of the regression where the objective has L1 norm of the **w** instead of L2.

$$J = \sum_{i=1}^{N} (y_i - \mathbf{w}^T \mathbf{x})^2 + \lambda \sum_{i=1}^{d} |w_i|$$
$$= \sum_{i=1}^{N} (y_i - \mathbf{w}^T \mathbf{x})^2 + \lambda ||\mathbf{w}||_1.$$

In Lasso, we not only penalize the high value of some of the coefficients, optimization also leads to zero for irrelevant variables.

The change in the norm of the penalty may seem like only a minor difference, however the behavior of the L1-norm is significantly different than that of the L2-norm.

## Eigen Values and Vectors (recap)

## Recap

$$\mathbf{A}\mathbf{v}=\lambda\mathbf{v}$$

Solutions to this:

- Eigen values:  $\lambda_1, \lambda_2 \dots$
- Eigen vector:  $\mathbf{v}_1, \mathbf{v}_2 \dots$

Often  $\lambda_i$ s are sorted in decreasing order Often  $\mathbf{v}_i$  are normalized to unit norm.

# Optimization problems with Eigen Vectors as Solutions $^1$

**Problem:** Maximize  $\mathbf{w}^T \mathbf{A} \mathbf{w}$  such that  $\mathbf{w}^T \mathbf{w} = 1$  (or  $||\mathbf{w}|| = 1$ )

We form an objective with the help of a lagrangian  $(\lambda)$  as

$$J(\mathbf{w}, \lambda) = \mathbf{w}^T \mathbf{A} \mathbf{w} - \lambda (\mathbf{w}^T \mathbf{w} - 1)$$

Differentiating wrt  $\mathbf{w}$  and equating to zero leads to:

$$\mathbf{A}\mathbf{w}=\lambda\mathbf{w}$$

Or  $\mathbf{w}$  is the eigen vector corresponding to the largest eigen value.

<sup>&</sup>lt;sup>1</sup>Benyamin Ghojogh et al, Eigenvalue and Generalized Eigenvalue Problems: Tutorial, Arxiv, 2023. An excellent read beyond this course.

#### Problem 1

We are interested in solving an overdetermined system of homogeneous equations

$$\mathbf{A}\mathbf{x} = \mathbf{0}$$

where **A** is  $m \times n$ .

Problem is formulated as:

$$\arg\min_{\mathbf{x}} ||\mathbf{A}\mathbf{x}||$$
 Subject to:  $||\mathbf{x}|| = 1$ 

Solution to this problem is:

- (a) Eigen Vector corresponding to the largerst eigen value of  $\mathbf{A}\mathbf{A}^T$ .
- (b) Eigen Vector corresponding to the largerst eigen value of  $\mathbf{A}^T \mathbf{A}$ .
- (c) Eigen Vector corresponding to the smallest eigen value of  $\mathbf{A}\mathbf{A}^T$ .
- (d) Eigen Vector corresponding to the smallest eigen value of  $\mathbf{A}^T \mathbf{A}$ .

#### Read later<sup>2</sup>

https://cw.fel.cvut.cz/old/\_media/courses/a3m33iro/overdetermined\_homogenous\_linear\_equations.pdf

#### Problem 2

- Consider the  $d \times N$  data matrix **X** with every column as data elements. Show that  $\mathbf{A} = \mathbf{XX}^T$  is Symmetric. Show that  $\mathbf{A}$  is PSD. <sup>3</sup>
- Consider a data matrix X where every column is mean subtracted samples. We compute A = XX<sup>T</sup>. Then A (agree/disagree)
  - is a  $d \times d$  matrix
  - is a  $N \times N$  matrix
  - is a symmetric matrix
  - is a scaled version of the covariance matrix

<sup>&</sup>lt;sup>3</sup>A matrix A is PSD if  $z^T A z \ge 0 \ \forall z \in R^d$ .

#### Problem 3

Consider a square matrix **A** with eigen values  $\lambda_i$  and eigen vectors  $\mathbf{v}_i$ . Then for  $\mathbf{A}^T$ ,

- (a) Eigen values and eigen vectors are the same as that of A.
- ullet (b) Eigen values are the same. Eigen vectors are  $ullet^T$ .
- (c) Eigen values are  $\frac{1}{\lambda_i}$
- (d) We can comment for symmetric matrix A. But not for other square matrices.
- (e) None of the above.

The the eigen values of **A** are  $\lambda_i$ , what are the eigen values of  $\alpha$ **A**, where  $\alpha$  is a scalet.

- (a)  $\lambda_i$  itself.
- (b)  $\frac{\alpha}{\lambda_i}$
- (c)  $\alpha \lambda_i$
- (d)  $\frac{1}{\alpha}\lambda_i$
- (e) None of the above.

### Problem 4: Probabilistic Interpretation of LR

We know that the problem is modelled as

$$y_i = \mathbf{w}^T \mathbf{x} + \epsilon_i$$

We assume that the  $\epsilon_i$  are distributed IID (Independently and Identically Distributed) according to a Gaussian/Normal distribution with zero mean and variance  $\sigma^2$ 

$$p(\epsilon_i) = \frac{1}{\sqrt{2\pi}\sigma} exp\left(-\frac{\epsilon_i^2}{2\sigma^2}\right)$$

This leads to

$$p(y_i|\mathbf{x}_i,\mathbf{w}) = \frac{1}{\sqrt{2\pi}\sigma} exp\left(-\frac{(y_i - \mathbf{w}^T\mathbf{x})^2}{2\sigma^2}\right)$$

This represents the distribution of  $y_i$  given  $\mathbf{x_i}$  and parameterized by  $\mathbf{w}$ . We model this as  $\mathcal{N}(\mathbf{w}^T\mathbf{x}, \sigma^2)$ 

## Problem 4: Probabilistic Interpretation of LR

Our problem is now to find the MLE estimate of  $\mathbf{w}$  from the data. Given the data  $(\mathbf{X}, Y)$ , we can do a maximum likelihood estimate of  $\mathbf{w}$ .

$$L(\mathbf{w}) = L(\mathbf{w}, \mathbf{X}, \mathbf{Y}) = \prod_{i=1}^{N} p(y_i | \mathbf{x}_i, \mathbf{w}) = \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} exp\left(-\frac{(y_i - \mathbf{w}^T \mathbf{x})^2}{2\sigma^2}\right)$$

Instead of max  $L(\mathbf{w})$ , we maximize the log-likelihood. (why? correct?)

$$I(\mathbf{w}) = \log L(\mathbf{w}) = \log \prod_{i=1}^{N} \frac{1}{\sqrt{2\pi}\sigma} exp\left(-\frac{(y_i - \mathbf{w}^T \mathbf{x})^2}{2\sigma^2}\right)$$
$$= \sum_{i=1}^{N} \log \frac{1}{\sqrt{2\pi}\sigma} exp\left(-\frac{(y_i - \mathbf{w}^T \mathbf{x})^2}{2\sigma^2}\right) = \kappa \frac{1}{2} \sum_{i=1}^{N} (y_i - \mathbf{w}^T \mathbf{x})^2$$

Where K is a constant. (why? expression?) This imply now that the MSE objective is only a scaled version of the MLE estimate objective!!.

$$\Rightarrow \min_{\mathbf{w}} J(\mathbf{w}) = \min_{\mathbf{w}} \sum_{i=1}^{N} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$