Brief Reasons for Each Question

Each correct option is equally weighted. For example, if 2 out of 3 correct options were marked, +2 marks will be awarded for that question.

- 1. Question 1: Correct options: (a), (d)
 - (a) Both X^TX and XX^T have the same eigenvalues. This follows from the fact that X^TX and XX^T share the same non-zero eigenvalues (they have the same singular values).
 - (d) X contains the eigenvalues of X^TX on its diagonal. In the SVD $X = UDV^T$, the diagonal entries of D are the singular values, which are the square roots of the eigenvalues of X^TX .
- 2. Question 2: Correct options: (a), (d) or (a), (c), (d)
 - (a) Often states that the rank of X is related to the non-zero singular values.
 - (c) If included, typically addresses that X has a particular form/behavior (e.g., full column rank) that connects B or D to rank properties.
 - (d) Can involve diagonalization arguments or how the nullity and rank interplay with X and its factors.

The ambiguity in (d) due to -A— not being defined anywhere is handled by awarding (a),(d) or (a),(c),(d)

- 3. Question 3: Correct options: (a), (b), (c), (d)
- (a)–(d) This question concerns a set of 2D points where all points share the same second coordinate $x_2 = 5$, leading to dependencies among the coordinates.
 - The covariance matrix is computed as:

$$\Sigma = \begin{bmatrix} \operatorname{Var}(X_1) & 0 \\ 0 & 0 \end{bmatrix}$$

where $Var(X_1)$ is the variance of the first coordinate values $\{1, 2, 3, 4, 5\}$.

• The variance of X_1 is given by:

$$Var(X_1) = \frac{1}{5} \sum_{i=1}^{5} (x_i - \bar{x})^2 = 2.$$

• Thus, the covariance matrix simplifies to:

$$\Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

• The eigenvalues of Σ are the diagonal entries:

$$\lambda_1 = 2, \quad \lambda_2 = 0.$$

- Since $\lambda_1 > \lambda_2$, statement (a) holds.
- 4. Question 4: Correct options: (a), (c), (d)
 - (a) Increasing training data helps reduce overfitting.
 - (c) Reducing model complexity (e.g. fewer parameters/features) also combats over-fitting.
 - (d) Proper regularization can reduce overfitting by penalizing large weights or complex models.
- 5. Question 5: Correct options: (a), (b)
 - If A is an $n \times n$ matrix with orthonormal columns, then $A^T A = I$ and $||a_i|| = 1$.
 - (a) Typically $A^T = A^{-1}$ for an orthonormal (orthogonal) matrix.
 - (b) Each column is unit norm and orthogonal to the others, matching the given conditions.
- 6. Question 6: Correct options: (a), (c), (d)
 - Overfitting can be reduced by:
 - (a) Getting more data,
 - (c) Increasing regularization or decreasing model complexity,
 - (d) Early stopping or other gradient-based methods that prevent overfitting.
- 7. Question 7: Correct options: (a), (d), (g), (h)
 - As per definitions
- 8. Question 8: Correct option: (a)
 - If the set of points $\{x_i\}$ lies on a single line, then the rank of the sum $\sum x_i x_i^T$ is 1. Hence only (a) is correct.
- 9. Question 9: Correct options: (a), (c), (d)
 - (a) Gradient descent requires the loss to be differentiable for a direct gradient-based update.
 - (c) It is used for optimizing continuous parameters in many ML problems.
 - (d) It can be extended for non-convex problems, though convergence is not guaranteed to the global optimum.
- 10. Question 10: Correct options: (a), (d)
 - (a) k-Nearest Neighbors is indeed a "lazy" learning algorithm.
 - (d) L_2 regularization is a common choice (e.g. ridge regression) that is popular because it is differentiable and helps control model complexity.

Answer to Q2.3: Relationship between the eigenvalues of A^TA and the singular values of A

Given: The Singular Value Decomposition (SVD) of a matrix A is

$$\mathbf{A} = \mathbf{U}\mathbf{D}\mathbf{V}^T$$
,

where:

- U is an orthogonal matrix ($\mathbf{U}^T\mathbf{U} = \mathbf{I}$).
- **V** is an orthogonal matrix ($\mathbf{V}^T\mathbf{V} = \mathbf{I}$).
- **D** is a diagonal matrix whose diagonal entries are the singular values $\sigma_i \geq 0$.

Derivation:

$$\mathbf{A}^T \mathbf{A} = \left(\mathbf{U} \mathbf{D} \mathbf{V}^T \right)^T \left(\mathbf{U} \mathbf{D} \mathbf{V}^T \right) = \mathbf{V} \mathbf{D}^T \mathbf{U}^T \mathbf{U} \mathbf{D} \mathbf{V}^T = \mathbf{V} \mathbf{D}^T \mathbf{D} \mathbf{V}^T = \mathbf{V} \mathbf{D}^2 \mathbf{V}^T,$$
since $\mathbf{U}^T \mathbf{U} = \mathbf{I}$ and $\mathbf{D}^T = \mathbf{D}$ (diagonal).

- The columns of V are the eigenvectors of A^TA .
- The diagonal entries of \mathbf{D}^2 (i.e. σ_i^2) are the corresponding eigenvalues of $\mathbf{A}^T \mathbf{A}$.

Hence, if σ_i are the singular values of \mathbf{A} , and λ_i are the eigenvalues of $\mathbf{A}^T \mathbf{A}$, then:

$$\lambda_i = \sigma_i^2$$
.

Marking Scheme (6 marks)

Note: Partial marks can be awarded for correct steps with minor errors or alternative valid derivations.