view frames Result Recorded at time: 2868.522 odom Broadcaster: /gazebo Average rate: 10.204 Buffer length: 4.9 Most recent transform: 2868.417 Oldest transform: 2863.517 robot footprint Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 chassis Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: 10.204 Average rate: 10.204 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 2868.417 Most recent transform: 2868.417 Oldest transform: 0.0 Oldest transform: 2863.517 Oldest transform: 2863.517 left wheel right wheel Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera rgb frame Broadcaster: /robot state publisher

camera Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera depth frame Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 camera depth optical frame camera rgb optical frame