

# Trigonometry Cheatsheet - Exercise 9.3

## 1. Verifying Trigonometric Identities

### 1.1 Angle Sum and Difference Identities

Use identities to verify expressions involving multiple angles:

- $\sin(A - B) = \sin A \cos B - \cos A \sin B$

**Example:** Verify  $\sin 60^\circ \cos 30^\circ - \cos 60^\circ \sin 30^\circ = \sin 30^\circ$ .

$$\begin{aligned}\text{LHS} &= \sin 60^\circ \cos 30^\circ - \cos 60^\circ \sin 30^\circ \\ &= \left(\frac{\sqrt{3}}{2}\right) \left(\frac{\sqrt{3}}{2}\right) - \left(\frac{1}{2}\right) \left(\frac{1}{2}\right) = \frac{3}{4} - \frac{1}{4} = \frac{2}{4} = \frac{1}{2} \\ \text{RHS} &= \sin 30^\circ = \frac{1}{2} \\ \text{LHS} &= \text{RHS}\end{aligned}$$

### 1.2 Pythagorean Identities

Use to simplify or verify expressions:

- $\sin^2 \theta + \cos^2 \theta = 1$

**Example:** Verify  $\sin^2 \frac{\pi}{6} + \sin^2 \frac{\pi}{3} + \tan^2 \frac{\pi}{4} = 2$ .

$$\begin{aligned}\text{LHS} &= \left(\sin \frac{\pi}{6}\right)^2 + \left(\sin \frac{\pi}{3}\right)^2 + \left(\tan \frac{\pi}{4}\right)^2 \\ &= \left(\frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2 + (1)^2 = \frac{1}{4} + \frac{3}{4} + 1 = 2 \\ \text{RHS} &= 2\end{aligned}$$

## 2. Evaluating Trigonometric Expressions

### 2.1 Tangent Difference Formula

$$\tan(A - B) = \frac{\tan A - \tan B}{1 + \tan A \tan B}$$

**Example:** Evaluate  $\frac{\tan \frac{\pi}{3} - \tan \frac{\pi}{6}}{1 + \tan \frac{\pi}{3} \tan \frac{\pi}{6}}$ .

$$\begin{aligned} &= \frac{\tan 60^\circ - \tan 30^\circ}{1 + \tan 60^\circ \tan 30^\circ} = \frac{\sqrt{3} - \frac{1}{\sqrt{3}}}{1 + \sqrt{3} \cdot \frac{1}{\sqrt{3}}} \\ &= \frac{\frac{3-1}{\sqrt{3}}}{1+1} = \frac{2}{\sqrt{3}} \cdot \frac{1}{2} = \frac{1}{\sqrt{3}} = \frac{\sqrt{3}}{3} \end{aligned}$$

## 2.2 Double Angle Identities

Use to verify or evaluate expressions:

- $\sin 2\theta = 2 \sin \theta \cos \theta$
- $\cos 2\theta = \cos^2 \theta - \sin^2 \theta = 2 \cos^2 \theta - 1 = 1 - 2 \sin^2 \theta$
- $\tan 2\theta = \frac{2 \tan \theta}{1 - \tan^2 \theta}$

**Example:** Verify  $\sin 2\theta = 2 \sin \theta \cos \theta$  for  $\theta = 30^\circ$ .

$$\begin{aligned} \text{LHS} &= \sin 60^\circ = \frac{\sqrt{3}}{2} \\ \text{RHS} &= 2 \sin 30^\circ \cos 30^\circ = 2 \cdot \frac{1}{2} \cdot \frac{\sqrt{3}}{2} = \frac{\sqrt{3}}{2} \\ \text{LHS} &= \text{RHS} \end{aligned}$$

## 3. Solving Trigonometric Equations

Solve for variables in equations involving trigonometric functions. **Example:** Find  $x$  if  $\tan^2 45^\circ - \cos^2 60^\circ = x \sin 45^\circ \cos 45^\circ \tan 60^\circ$ .

$$\begin{aligned} \text{LHS} &= (1)^2 - \left(\frac{1}{2}\right)^2 = 1 - \frac{1}{4} = \frac{3}{4} \\ \text{RHS} &= x \cdot \frac{1}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \cdot \sqrt{3} = x \cdot \frac{\sqrt{3}}{2} \\ \frac{3}{4} &= x \cdot \frac{\sqrt{3}}{2} \Rightarrow x = \frac{3}{4} \cdot \frac{2}{\sqrt{3}} = \frac{\sqrt{3}}{2} \end{aligned}$$

## 4. Quadrantal Angles

Evaluate trigonometric functions at angles that are multiples of  $\frac{\pi}{2}$  or  $90^\circ$ .

- Use coterminal angles:  $\theta = 2k\pi + \alpha$  (radians) or  $\theta = k \cdot 360^\circ + \alpha$  (degrees).
- Common values:

$\theta$	0	$\frac{\pi}{2}$	$\pi$	$\frac{3\pi}{2}$	$2\pi$
$\sin \theta$	0	1	0	-1	0
$\cos \theta$	1	0	-1	0	1
$\tan \theta$	0	undef.	0	undef.	0

**Example:** Find trigonometric functions for  $-\pi$ .

$$\begin{aligned} -\pi &= -2\pi + \pi = \pi \\ \sin(-\pi) &= \sin \pi = 0, \quad \cos(-\pi) = \cos \pi = -1, \quad \tan(-\pi) = \tan \pi = 0 \end{aligned}$$

## 5. Non-Quadrantal Angles

Reduce large or negative angles to coterminal angles in  $[0, 2\pi)$  or  $[0^\circ, 360^\circ)$ .

- For radians:  $\theta = 2k\pi + \alpha$
- For degrees:  $\theta = k \cdot 360^\circ + \alpha$

**Example:** Find trigonometric functions for  $390^\circ$ .

$$\begin{aligned} 390^\circ &= 360^\circ + 30^\circ \\ \sin 390^\circ &= \sin 30^\circ = \frac{1}{2}, \quad \cos 390^\circ = \cos 30^\circ = \frac{\sqrt{3}}{2}, \quad \tan 390^\circ = \tan 30^\circ = \frac{1}{\sqrt{3}} \end{aligned}$$

## 6. Applications

- **Physics:** Use double-angle identities in harmonic motion.
- **Engineering:** Apply angle difference formulas in signal processing.