

CSE 221: Algorithms

Divide and Conquer

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References

- 1 T. H. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein, *Introduction to Algorithms, Second Edition*. The MIT Press, September 2001.
- 2 Erik Demaine and Charles Leiserson, *6.046J Introduction to Algorithms*. MIT OpenCourseWare, Fall 2005. Available from: ocw.mit.edu/OcwWeb/Electrical-Engineering-and-Computer-Science/6-046JFall-2005/CourseHome/index.htm

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Divide-and-Conquer design strategy

- 1 *Divide* the problem (instance) into subproblems.
- 2 *Conquer* the subproblems by solving these recursively.
- 3 *Combine* the solutions to the subproblems.

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Example (of D&C strategy)

- 1 *Binary search* – divide the problem into half, and recursively search the appropriate 1 subproblem.
- 2 *Mergesort* – divide the problem into half, and recursively sort 2 subproblems, and then merge the results into a complete sorted sequence.
- 3 Computing x^n , computing fibonacci numbers, multiplying matrices (using *Strassen's algorithm*), etc.

Binary search

The problem

Find an element in a sorted array:

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Example (Searching for 9)



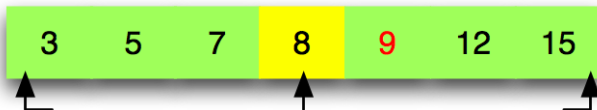
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3

5

7

8

9

12

15

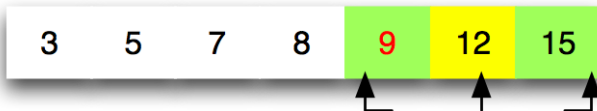
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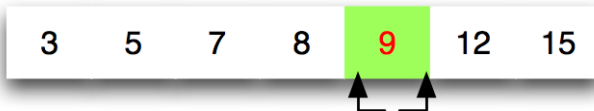
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Analysis

$$n^{\log_b a} = n^{\log_2 1} = n^0 = 1 \Rightarrow \text{CASE 2 } (k = 0)$$

$$\Rightarrow T(n) = \Theta(n^{\log_b a} \lg^{k+1} n) = \Theta(\lg n)$$

Merge sort

The problem

Find an element in a sorted array:

- 1 *Divide*: Trivial.
- 2 *Conquer*: Recursively sort 2 subarrays.
- 3 *Combine*: Merge the sorted subarrays in $\Theta(n)$ time.

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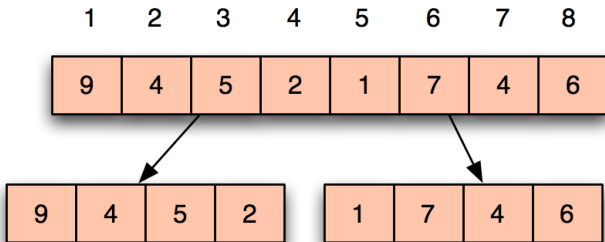
Key subroutine

MERGE – to merge two sorted arrays in linear-time.

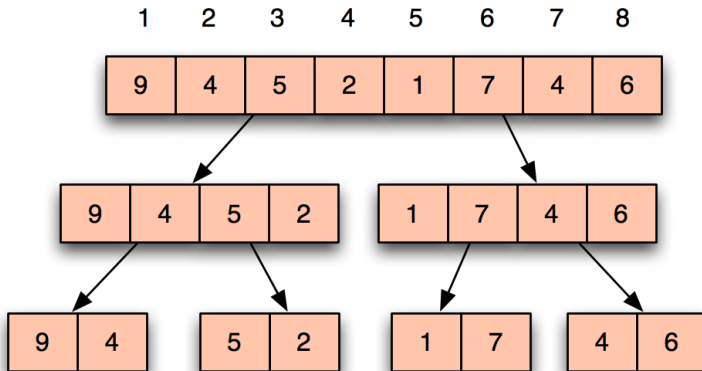
Merge sort in action

1	2	3	4	5	6	7	8
9	4	5	2	1	7	4	6

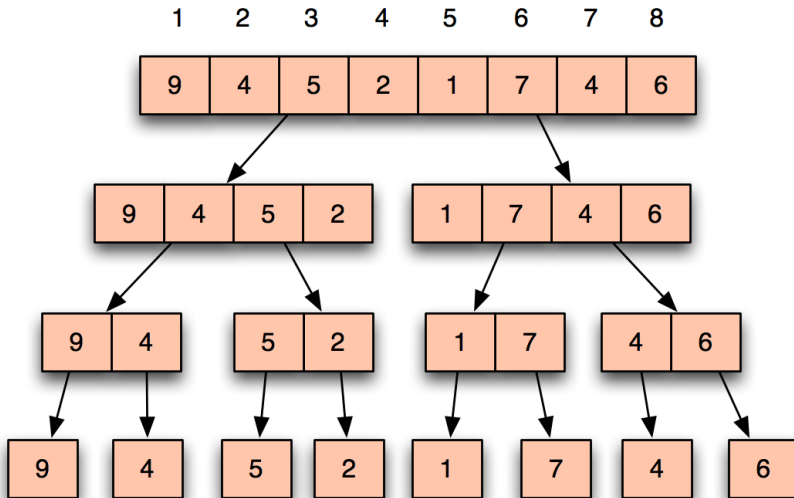
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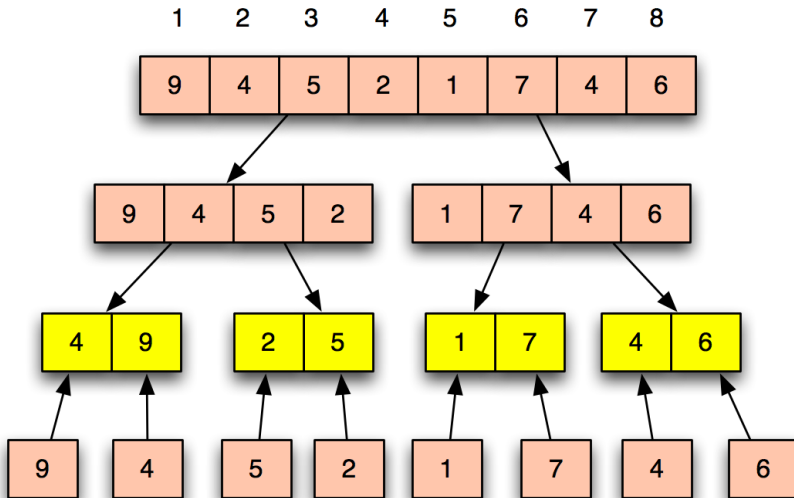
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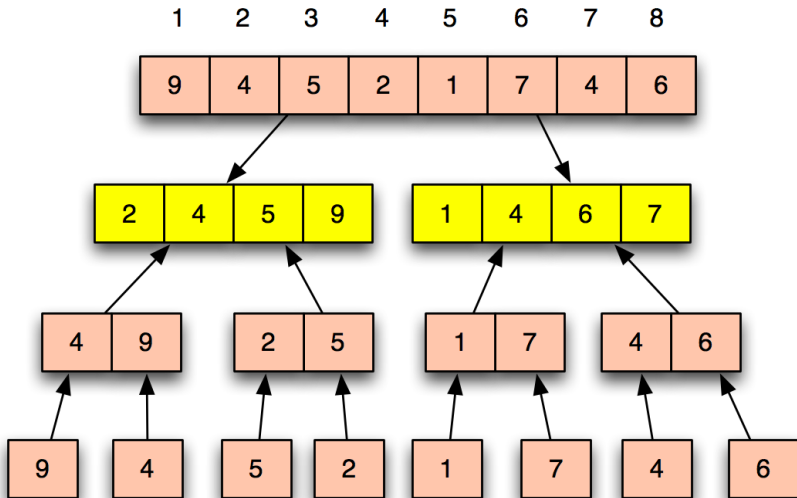
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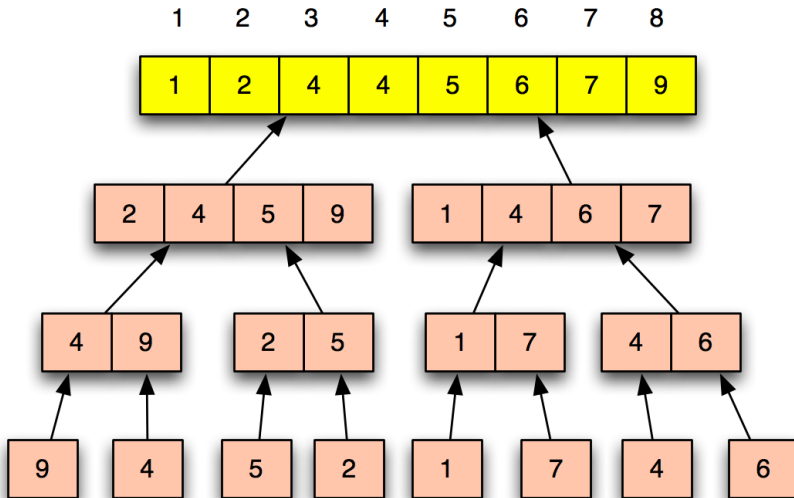
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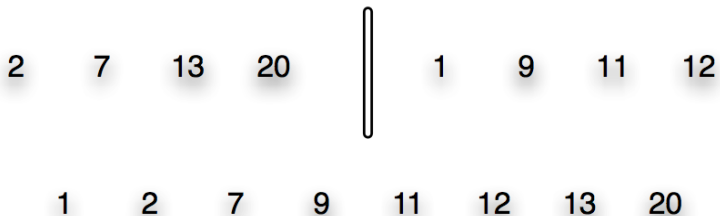
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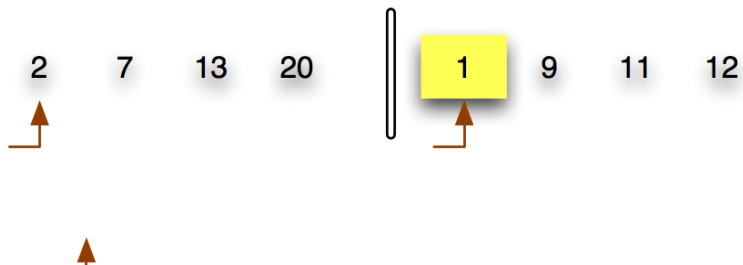
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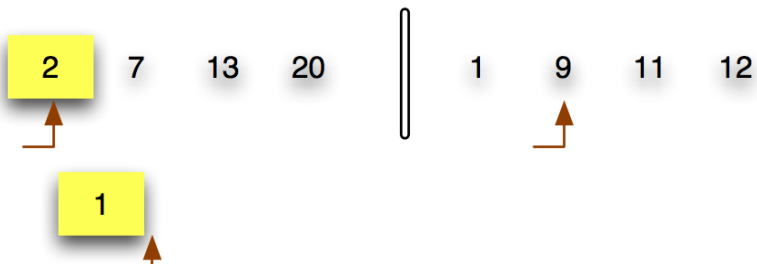
Merging in $\Theta(n)$ time



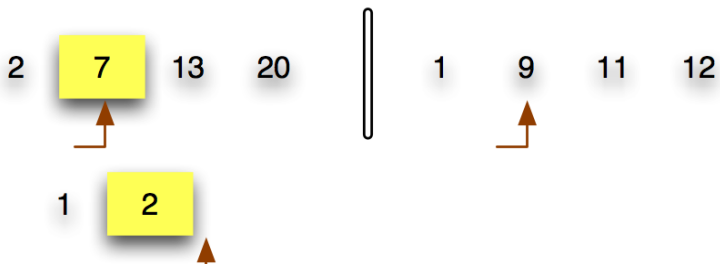
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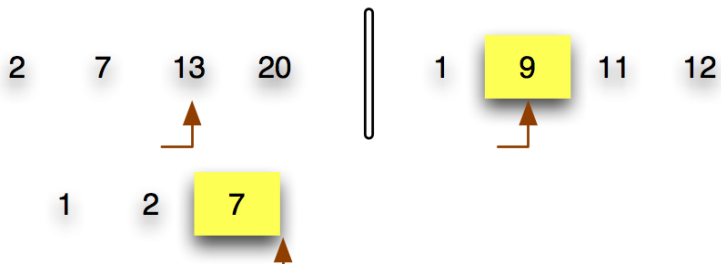
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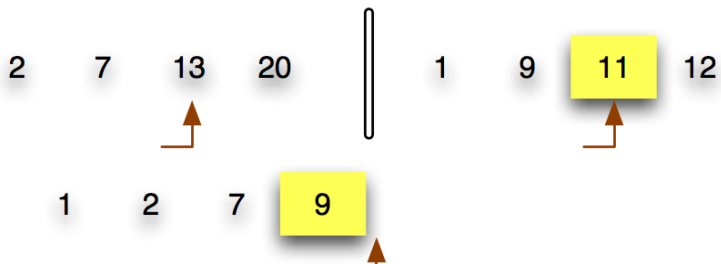
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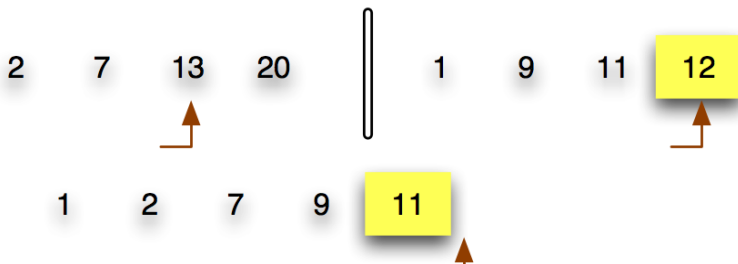
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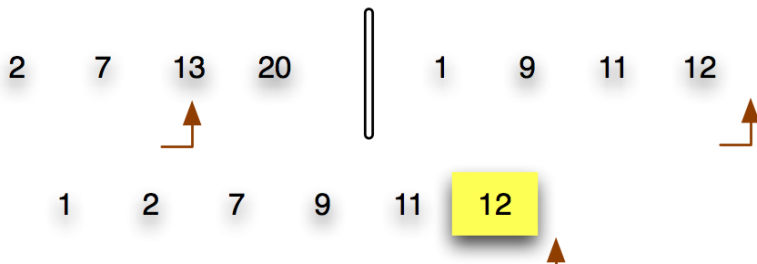
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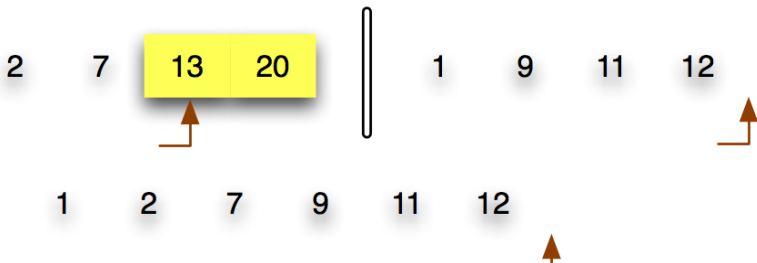
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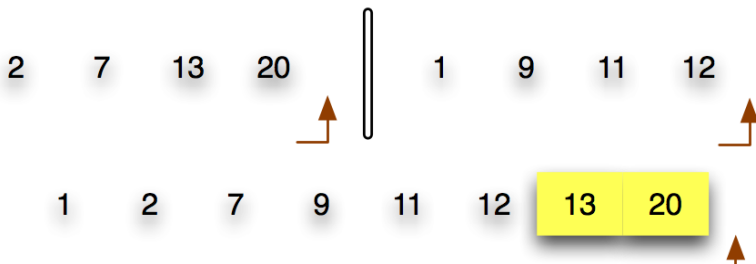
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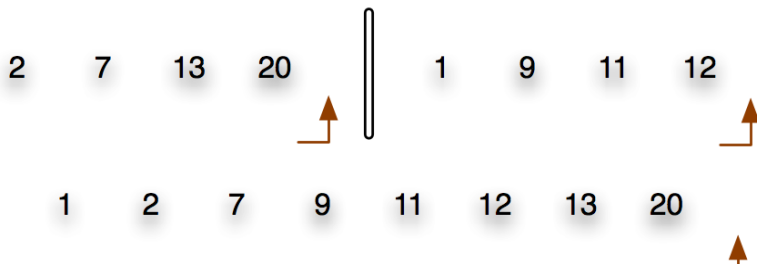
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A $\Theta(n)$ time merge algorithm

MERGE(A, B)

INPUT: Two sorted arrays A and B

OUTPUT: Returns C as the merged array

▷ $n_1 = \text{length}[A]$, $n_2 = \text{length}[B]$, $n = n_1 + n_2$

- 1 Create $C[1..n]$
- 2 Initialize two indices to point to A and B
- 3 **while** A and B are not empty
- 4 **do** Select the smaller of two and add to end of C
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- 6 **if** A or B is not empty
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MERGE-SORT(A) $\triangleright A[1 \dots n]$

1 **if** $n = 1$

2 **then return**

3 **else** \triangleright recursively sort the two subarrays

4 $A_1 = \text{MERGE-SORT}(A[1 \dots \lceil n/2 \rceil])$

5 $A_2 = \text{MERGE-SORT}(A[\lceil n/2 \rceil + 1 \dots n])$

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Few notes on the algorithm

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- ➋ The merging algorithm presented here is an out-of-place algorithm, which will increase space complexity.

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$$T(n) = T(n/2) + \Theta(1) \Rightarrow T(n) = \Theta(\lg n).$$

Conclusion

- Divide and Conquer is just one of several algorithm design strategies.
- Used by many of the commonly used algorithms
 - Binary search
 - Merge sort
 - Fast Fourier Transform (FFT)
 - Finding closest pair of points
 - Matrix multiplication (Strassen's algorithm)
 - Matrix inversion
 - Quicksort and (k^{th}) selection
 - ...
- Can be easily analyzed using recurrences
- Often leads to efficient algorithms