

CSE 221: Algorithms

Introduction to graphs

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BRAC University

References

- 1 Jon Kleinberg and Éva Tardos, *Algorithm Design*. Pearson Education, 2006.
- 2 T. H. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein, *Introduction to Algorithms, Second Edition*. The MIT Press, September 2001.
- 3 M. Goodrich and R. Tamassia, *Algorithm Design*. John-Wiley and Sons. 2002.

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Contents

1 Introduction to Graphs

- Graph basics
- Graph traversal

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- Graph basics
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What is a Graph?

- **Graph** G is a pair (V, E) , where V is a finite set (set of vertices) and E is a finite set of pairs from V (set of edges). We will often denote $n = |V|$, $m = |E|$.
- Graph G can be **directed**, if E consists of ordered pairs, or **undirected**, if E consists of unordered pairs. If $(u, v) \in E$, then vertices u and v are **adjacent**.
- We can assign weight function to the edges: $w_G(e)$ is a weight of edge $e \in E$. The graph which has such function assigned is called **weighted**.
- **Degree** of a vertex v is the number of vertices u for which $(u, v) \in E$ or $(v, u) \in E$ (denote $\deg(v)$). The number of **incoming edges** to a vertex v is called **in-degree** of the vertex (denote $\text{indeg}(v)$). The number of **outgoing edges** from a vertex is called **out-degree** (denote $\text{outdeg}(v)$).

Examples of graphs

Transportation networks How should you design the highway network in a country? What is the quickest way to drive from Badda to Naraynganj?

Communication networks How to send a network packet from Bracu intranet to Yahoo mail server?

Information networks Is the World wide a directed or undirected network?

Social networks Facebook, Myspace, Flickr, . . .

Dependency networks What courses must you take before you can take CSE-423?

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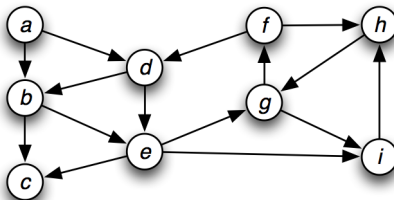
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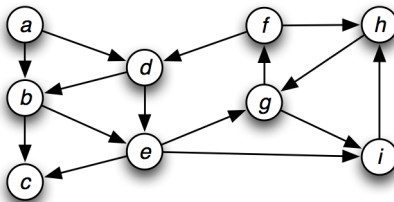


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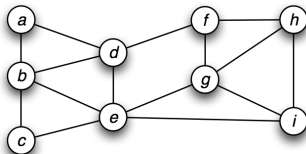
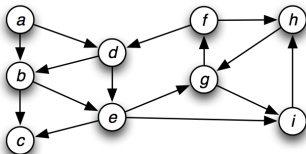
$V = \{a, \dots, i\}, n = 9, m = 15.$

Directed vs. undirected graphs

Definition (Directed vs. undirected graph)

Graph G can be **directed**, if E consists of ordered pairs, or **undirected**, if E consists of unordered pairs. If $(u, v) \in E$, then vertices u and v are **adjacent**.

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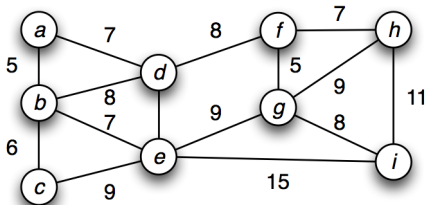


Weighted graphs

Definition (Weighted graph)

We can assign weight function to the edges: $w_G(e)$ is a weight of edge $e \in E$. The graph which has such function assigned is called **weighted**.

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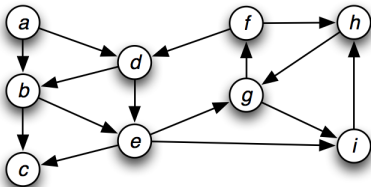


Degree of vertices

Definition (Degree of vertices)

Degree of a vertex v is the number of vertices u for which $(u, v) \in E$ or $(v, u) \in E$ (denote $\deg(v)$). The number of **incoming edges** to a vertex v is called **in-degree** of the vertex (denote $\text{indeg}(v)$). The number of **outgoing edges** from a vertex is called **out-degree** (denote $\text{outdeg}(v)$).

Example (Directed graph)



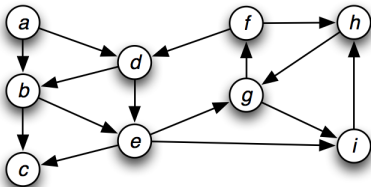
Vertex	in	out
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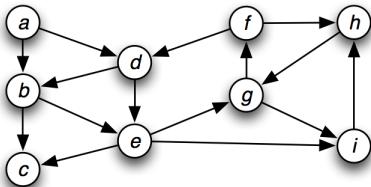
Vertex	in	out
a	0	2

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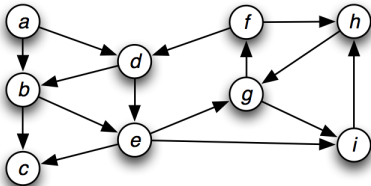
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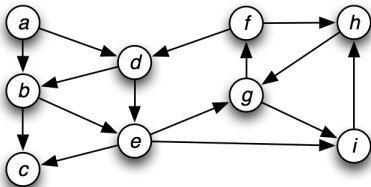
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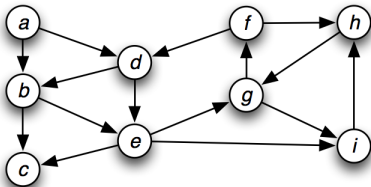
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<i>d</i>	2	2

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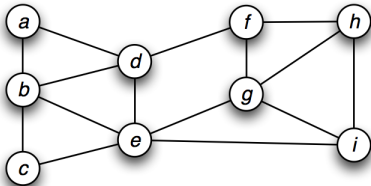
Vertex	in	out
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<i>b</i>	2	2
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<i>e</i>	2	3

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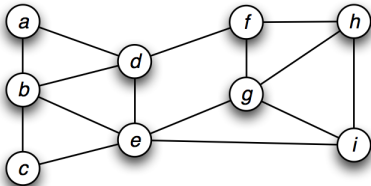
Vertex	deg
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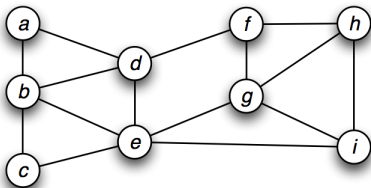
Vertex	\deg
a	2

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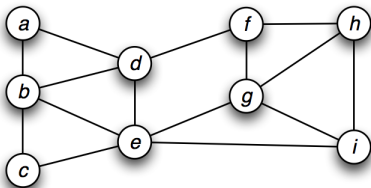
Vertex	\deg
a	2
b	4

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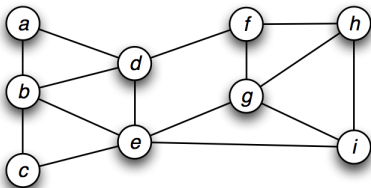
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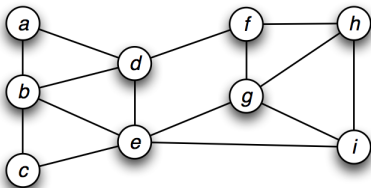
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d	4

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Example (Undirected graph)



Vertex	\deg
<i>a</i>	2
<i>b</i>	4
<i>c</i>	2
<i>d</i>	4
<i>e</i>	5

Relationship of $n = |V|$ and $m = |E|$

Theorem

If G is a graph with m edges, then

$$\sum_{v \in G} \deg(v) = 2m.$$

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If G is a graph with m edges, then

$$\sum_{v \in G} \deg(v) = 2m.$$

Proof.

An edge (u, v) is counted twice in the above summation; once by its endpoint u and once by its endpoint v . Thus, the total contribution of the edges to the degrees of the vertices is twice the number of edges. □

Relationship of $n = |V|$ and $m = |E|$

Theorem

If G is a directed graph (digraph) with m edges, then

$$\sum_{v \in G} \text{indeg}(v) = \sum_{v \in G} \text{outdeg}(v) = m.$$

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Theorem

If G is a directed graph (digraph) with m edges, then

$$\sum_{v \in G} \text{indeg}(v) = \sum_{v \in G} \text{outdeg}(v) = m.$$

Proof.

In a directed graph, an edge (u, v) contributes one unit to the **out-degree** of its origin u and one unit to the **in-degree** of its destination v . Thus, the total contribution of the edges to the out-degrees of the vertices is equal to the number of edges, and similarly for the in-degrees. □

Relationship of $n = |V|$ and $m = |E|$

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If G is a simple **undirected** graph with n vertices and m edges, then $m \leq n(n-1)/2$.

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If G is a simple **undirected** graph with n vertices and m edges, then $m \leq n(n-1)/2$.

Proof.

Since G is a simple undirected graph without self-loops, the maximum degree of a vertex is $n-1$. And, since there are n vertices, and each edge is counted twice (once for each end of an edge (u, v)), the maximum number of edges is $n(n-1)/2$. Thus, $m \leq n(n-1)/2$, or $m = \Theta(n^2)$. □

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If G is a simple **directed** graph with n vertices and m edges, then $m \leq n(n - 1)$.

Proof.

Since G is a simple graph without self-loops, the maximum in-degree of a vertex is $n - 1$. And, since there are n vertices, and no two edges can have the same origin and destination, $m \leq n(n - 1)$, or $m = \Theta(n^2)$. □

Paths and connectivity

Definition (Path)

A **path** in a undirected graph $G = (V, E)$ is sequence P of vertices $v_1, v_2, \dots, v_{k-1}, v_k$ with the property that for $i \in \{1, \dots, k-1\}$, $(v_i, v_{i+1}) \in E$.

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Definition (Simple and cyclic paths)

A path is **simple** if all vertices are distinct. A **cycle** is a path $v_1, v_2, \dots, v_{k-1}, v_k$ in which $k \geq 2$, and the first $k-1$ nodes are all distinct, and $v_1 = v_k$.

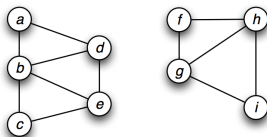
Connected vs. unconnected graphs

Definition (Connected graph)

The undirected graph G is **connected**, if for every pair of vertices u, v there exists a **path** from u to v .

If a graph is not connected, the vertices of the graph can be divided into **connected components**. Two vertices are in the same **connected component** *iff* they are connected by a **path**.

Example (Connected components)



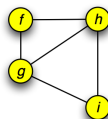
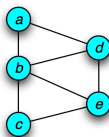
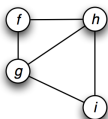
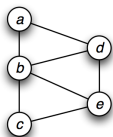
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Trees

Definition (Trees)

A undirected graph is a *tree* if it is *connected* and does not contain a *cycle* (implies that every n -node tree has exactly $n - 1$ edges).

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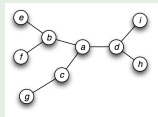
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Example (Trees (or not))



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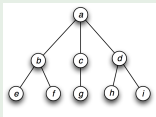
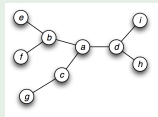
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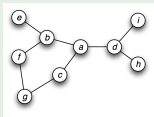
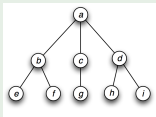
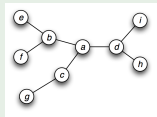
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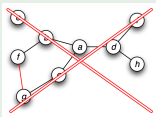
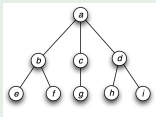
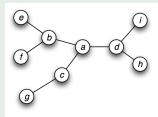
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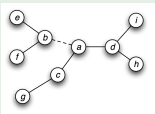
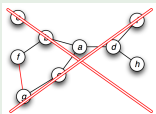
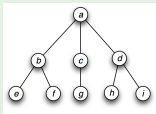
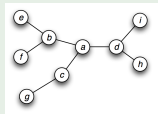
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- ❸ G has $n - 1$ edges.

Example (Trees (or not))



Trees

Definition (Trees)

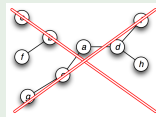
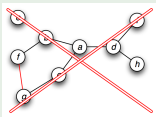
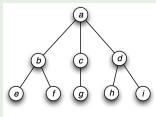
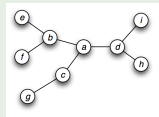
A undirected graph is a *tree* if it is *connected* and does not contain a *cycle* (implies that every n -node tree has exactly $n - 1$ edges).

Theorem

For undirected graph G , any two of the following implies the third.

- ❶ G is connected.
- ❷ G does not contain a cycle.
- ❸ G has $n - 1$ edges.

Example (Trees (or not))



Representation of graphs

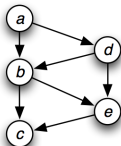
Definition (Adjacency Matrix)

Represents the graph as an $n \times n$ matrix $A = (a_{i,j})$, where

$$a_{i,j} = \begin{cases} 1, & \text{if } (v_i, v_j) \in E, \\ 0, & \text{otherwise.} \end{cases}$$

The matrix is symmetric in case of undirected graph, while it may be asymmetric if the graph is directed.

Example (Directed graph)



	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>
<i>a</i>	0	1	0	1	0
<i>b</i>	0	0	1	0	1
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Representation of graphs

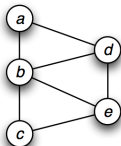
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Example (Undirected graph)



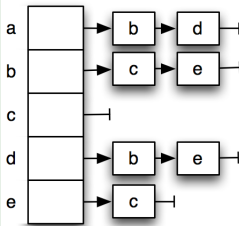
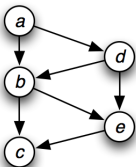
	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>	<i>e</i>
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Representation of graphs

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Represent the graph by listing for each vertex v_i its outgoing vertices in a list $out(v_i)$. (Representation can be linked list, or another appropriate structure.)

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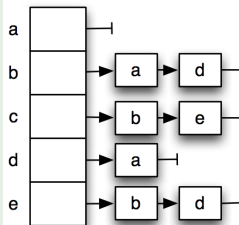
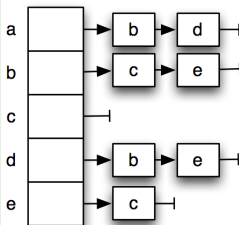
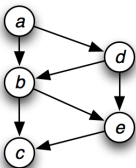
Representation of graphs

Definition (Adjacency List)

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If the graph is directed, it makes sense to build for each vertex v_i also list of its incoming vertices $in(v_i)$.

Example (Directed graph)



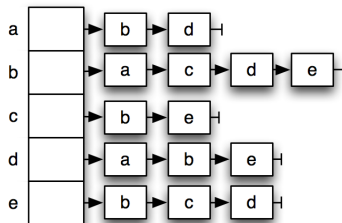
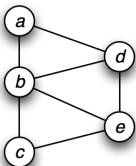
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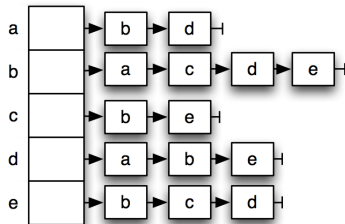
If the graph is undirected, all incident edges are listed for each vertex v_i .

Example (Undirected graph)



Comparison of graph representations

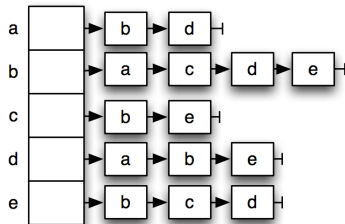
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Operation	Adjacency matrix	Adjacency list
Is $(u, v) \in E$?	$\Theta(1)$	$\Theta(\text{outdeg}(u))$
List edges outgoing from u	$\Theta(n)$	$\Theta(\text{outdeg}(u))$
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Representation note

We will be using adjacency lists to represent graphs, unless stated otherwise.

Some very basic questions for a graph

- 1 Starting from a given *source* vertex, can I reach a *target* vertex? *s-t connectivity problem*.

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Contents

1 Introduction to Graphs

- Graph basics
- Graph traversal

Graph traversal techniques

The graph traversal problem

Given a graph $G = (V, E)$, and a *distinguished vertex* s , how do you visit each vertex $v \in V$ exactly once.

Graph traversal techniques

The graph traversal problem

Given a graph $G = (V, E)$, and a *distinguished vertex* s , how do you visit each vertex $v \in V$ exactly once.

Breadth-first search (BFS)

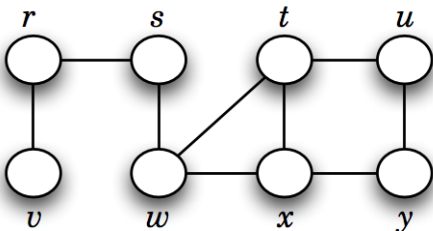
- Start with the source vertex, and *fan out* from there.
- Finds the distance (in terms of edges) of each node from the source.

Depth-first search (DFS)

- Start with the source vertex, *recursively* visit each neighbor, only backtracking when choices are exhausted.
- Remember *pre-order* tree traversal?

Basic idea behind breadth first search (BFS)

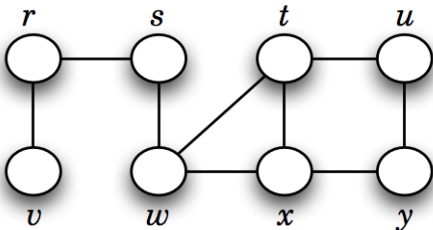
Given a undirected graph $G = (V, E)$, and a distinguished vertex s , systematically visit each vertex $v \in V$ that is reachable from s .



Breadth first search (BFS)

BFS(G, s) $\triangleright G = (V, E)$

```
1   $Q \leftarrow \{s\}$ 
2   $d[v] \leftarrow \infty, \forall v \in V; d[s] \leftarrow 0$ 
3  while  $Q \neq \emptyset$ 
4      do  $u \leftarrow \text{DEQUEUE}(Q)$ 
5          for each  $v \in \text{Adj}[u]$ 
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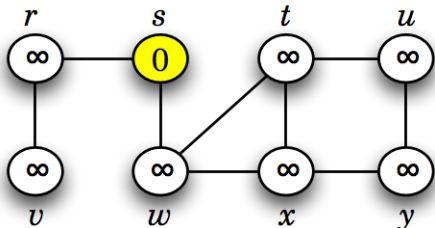


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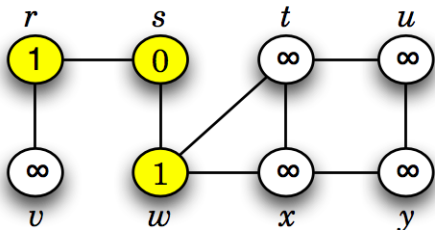
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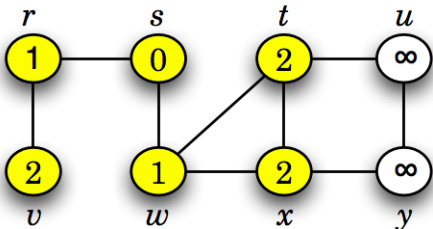
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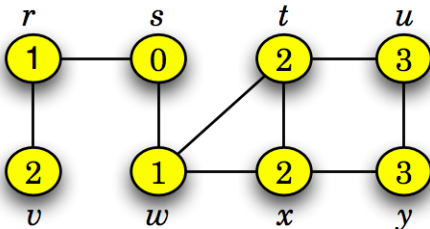


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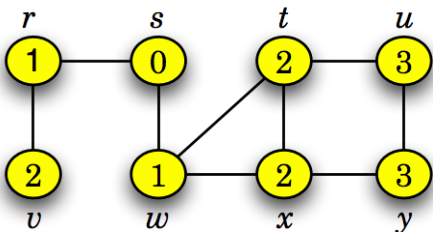
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BFS( $G, s$ )    ▷  $G = (V, E)$ 
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Analysis

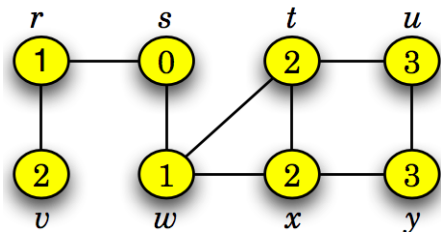
Time = $O(V + E)$.

What does *this* $\text{BFS}(G, s)$ algorithm tell us?



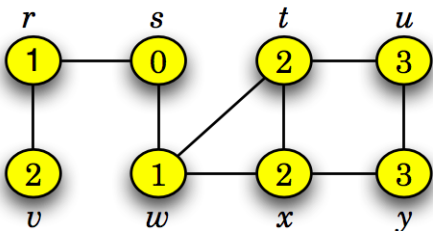
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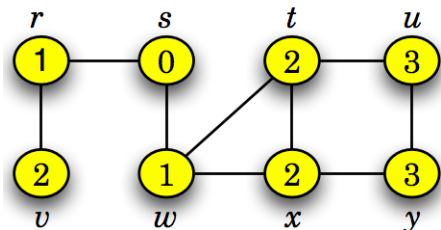
- This graph $G = (V, E)$ is connected since BFS visits all vertices $v \in V$ starting from s .
- The minimum number of *hops* or edges between s and any vertex $t \in V$.

What does *this* $\text{BFS}(G, s)$ algorithm *not* tell us?



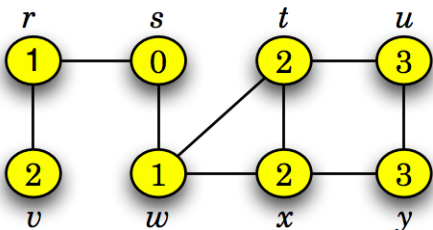
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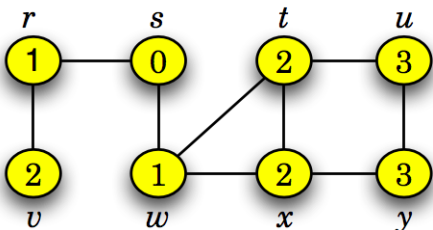
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- Is there a cycle in this graph?
- Given a target vertex $t \in V$, what is the path with smallest number of edges back to s ?
- If this were not a connected graph, how to visit all the vertices?
- Equivalently, how to compute all the connected components of a graph?

Computing connected components

Idea

Since each node is visited no more than once ($d[v] \neq \infty$ after the first visit), simply apply the DFS algorithm over each vertex $v \in V$, creating a new component each time a vertex is found for which $d[v] = \infty$.

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BFS(G) $\triangleright G = (V, E)$

```
1   $d[v] \leftarrow \infty, \forall v \in V$ 
2  for each  $v \in V$ 
3      do if  $d[v] = \infty$ 
4          then BFS( $G, v$ )
```

A better Breadth first search (BFS) algorithm

Information during traversal

- 1 *color*[*v*]: the *color* of each vertex visited

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$BFS(G) \triangleright G = (V, E)$

▷ Initialize the vertex colors and predecessors

```
1 for each vertex  $v \in V$ 
2     do  $color[v] = \text{WHITE}$ 
3      $\pi[v] = \text{NULL}$ 
4 for each vertex  $v \in V$ 
5     do if  $color[v] = \text{WHITE}$ 
6         then  $BFS(G, v)$ 
```

A better Breadth first search (BFS) algorithm

$\text{BFS}(G, s) \triangleright G = (V, E)$

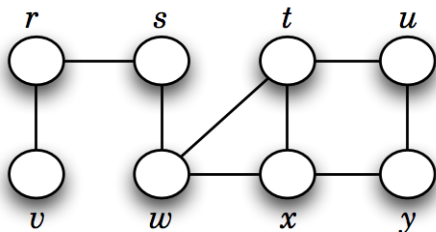
- 1 $color[s] = \text{GRAY}; \pi[s] = \text{NULL}; d[s] = 0$
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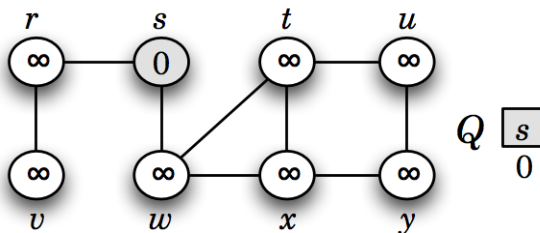
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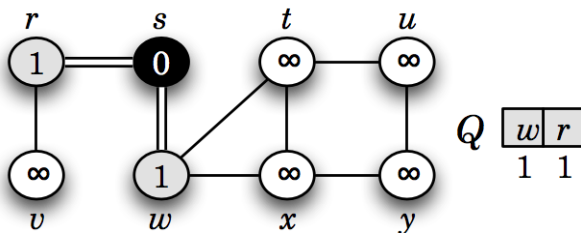
Application of BFS



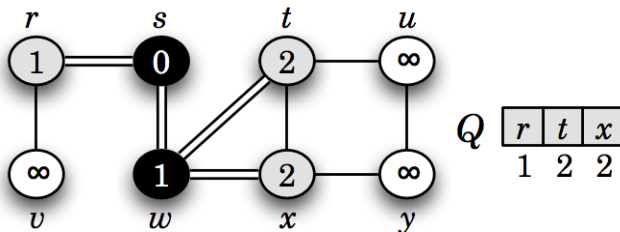
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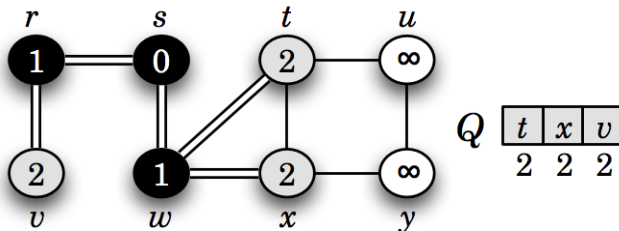
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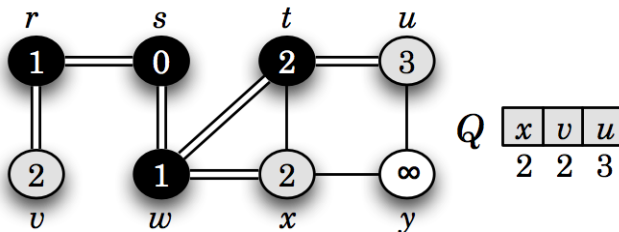
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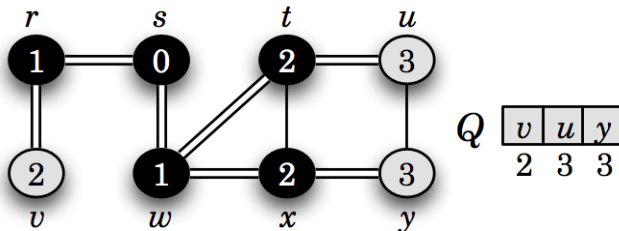
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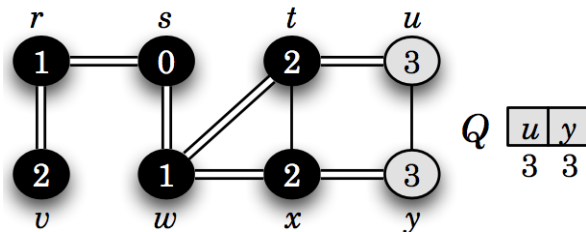
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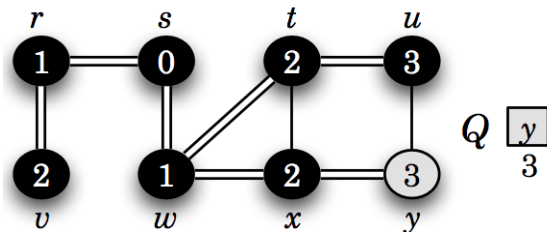
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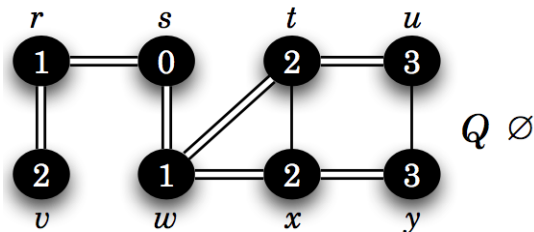
Application of BFS



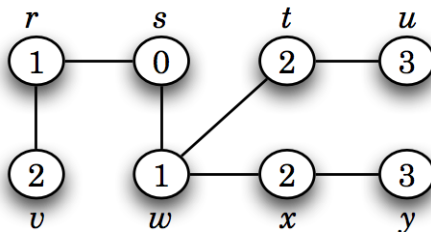
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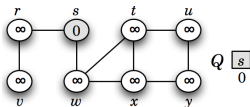
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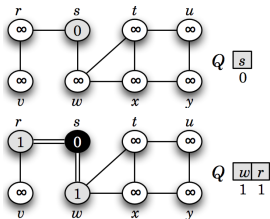
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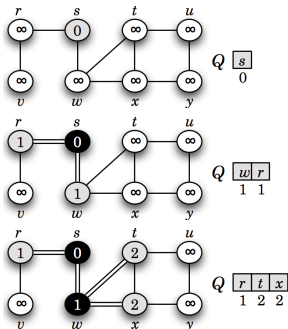
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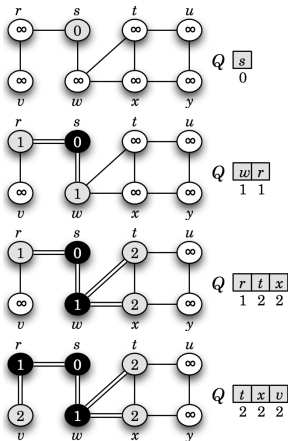
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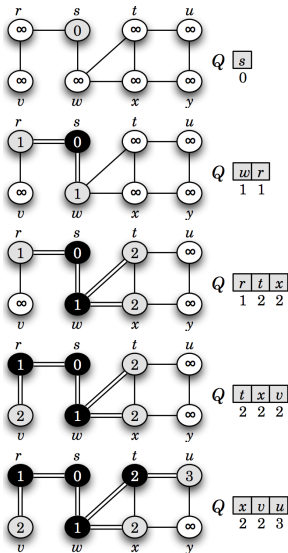
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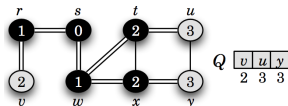
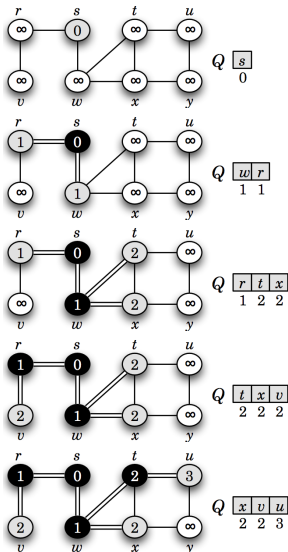
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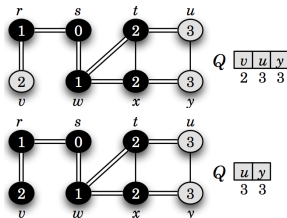
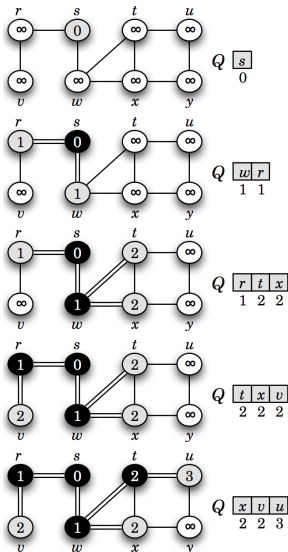
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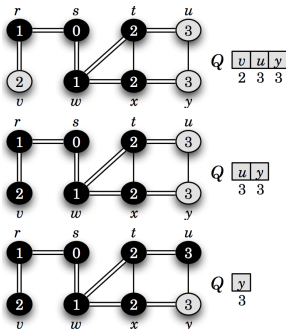
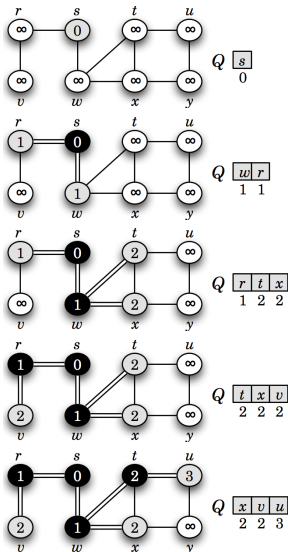
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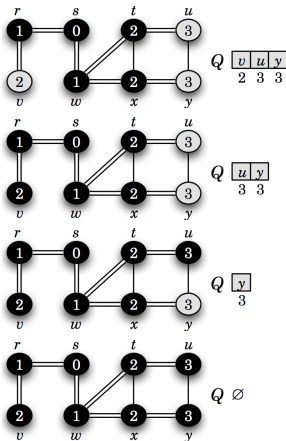
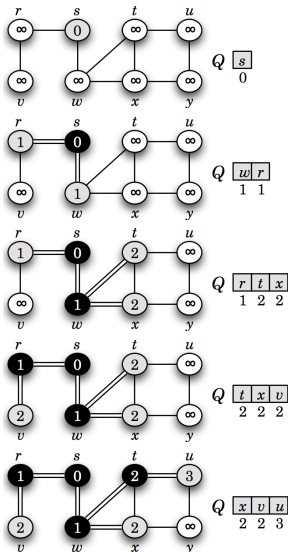
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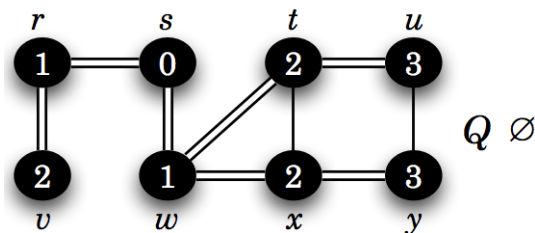
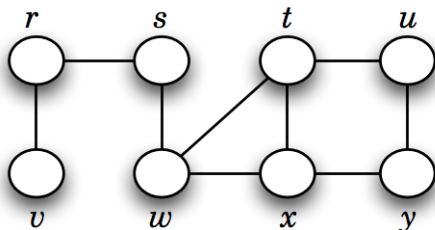
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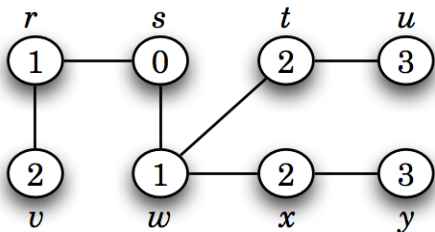
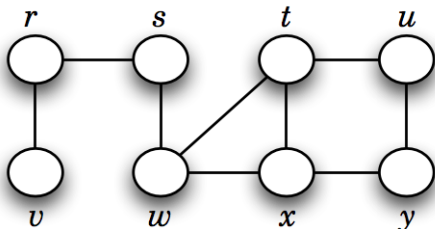
Application of BFS



Breadth first search (BFS) tree



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Depth first search (DFS)

- Starts from an initial vertex.
- Recursively visits each adjacent vertex.
- Strategy to search **deeper** into the graph, unlike BFS which fans out.

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- 4 $f[v]$: the **finish time** – when processing of v and all its descendants have finished.

DFS algorithm

$\text{DFS}(G) \triangleright G = (V, E)$

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1  for each vertex  $u \in V[G]$ 
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$\text{DFS-VISIT}(G, u) \triangleright G = (V, E), u \in V$

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1   $\text{color}[u] \leftarrow \text{GRAY}$ 
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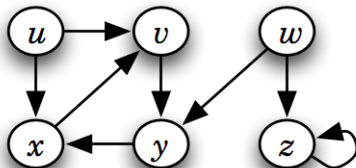
Application of DFS

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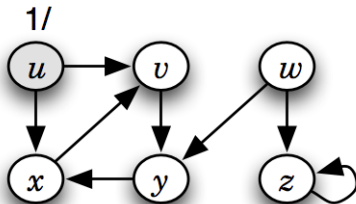
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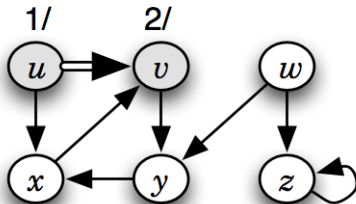
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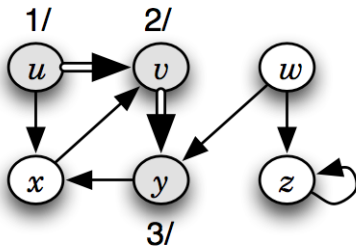
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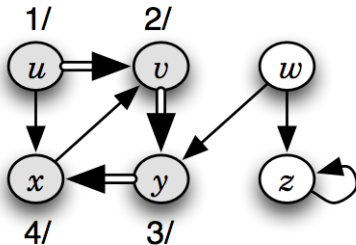
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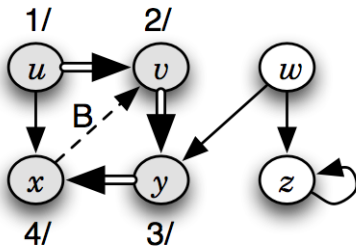
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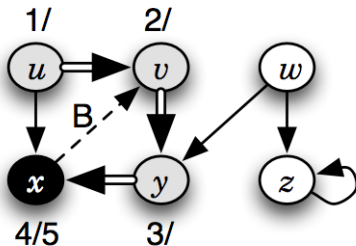
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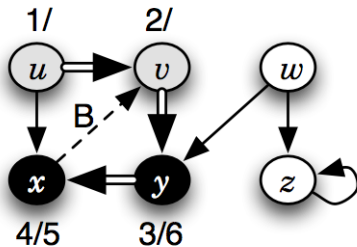
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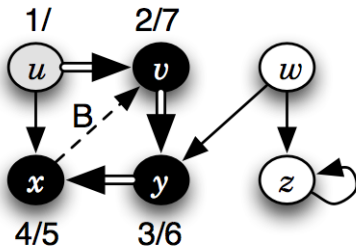
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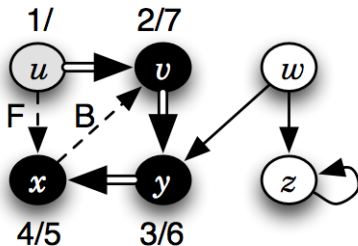
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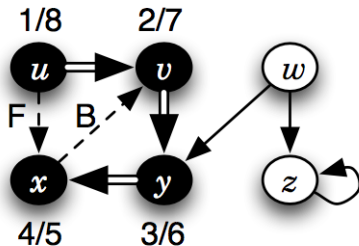
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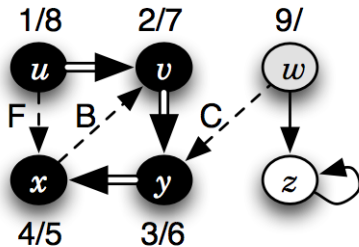
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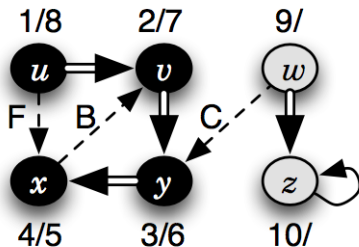
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$\text{DFS-VISIT}(G, u)$

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6          then  $\pi[v] \leftarrow u$ 
7               $\text{DFS-VISIT}(v)$ 
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9   $f[u] \leftarrow \text{time} + 1$ 
  
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Application of DFS

$\text{DFS}(G) \triangleright G = (V, E)$

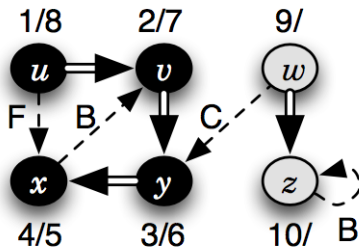
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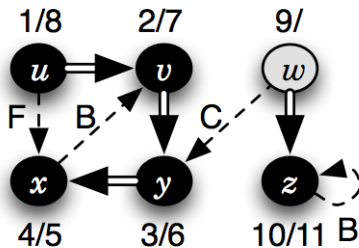
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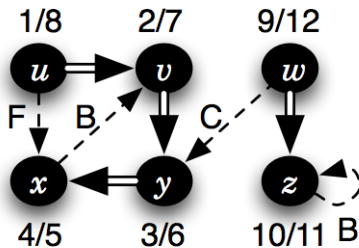
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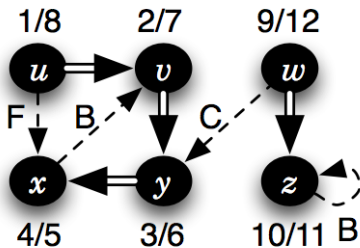
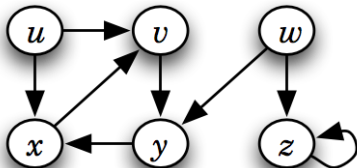
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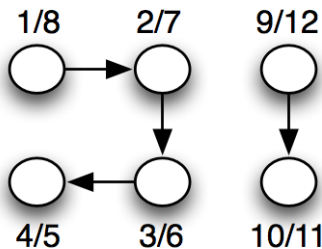
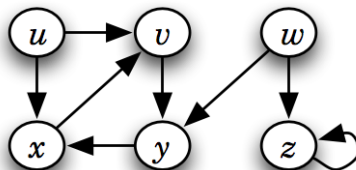
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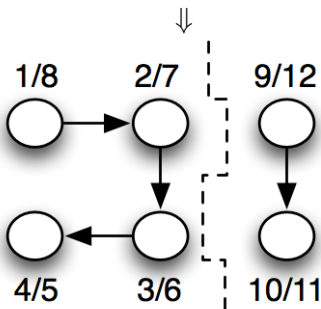
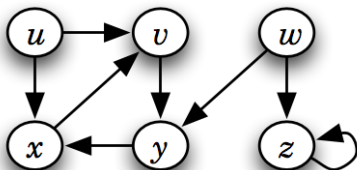
Breadth first search (DFS) tree (or, forest)



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