INTRODUCTION TO SIGNALS AND SYSTEMS

Dr. Arsla Khan

Course Contents

- Introduction
- Basic operations on signals
- Basic system properties
- Time domain analysis of continuous and discrete time systems
- Fourier series analysis of CTS and DTS
- Fourier transform analysis of CTS and DTS
- Laplace Transform
- Z Transform

Text Book:

Signals and Systems

By A.V. Oppenheim and A. S.

Willsky

Second Edition Prentice Hall,

2012

Links for Video Lectures

- Introduction to Signals and Systems:
- https://www.youtube.com/watch?v=s8rsR_TStaA&list=PLBInK6fEyqRhG6s3jYIU 48CqsT5cyiDTO&index=1
- Continuous and Discrete Time Signals
- https://www.youtube.com/watch?v=H4hk6N5vC1Q&list=PLBlnK6fEyqRhG6s3jY IU48CqsT5cyiDTO&index=2
- Time Shifting
- https://www.youtube.com/watch?v=9Cd5nVCFfc0
- https://www.youtube.com/watch?v=3Qzpj6UUxhE&list=PLBlnK6fEyqRhG6s3jYI U48CqsT5cyiDTO&index=273

Signal

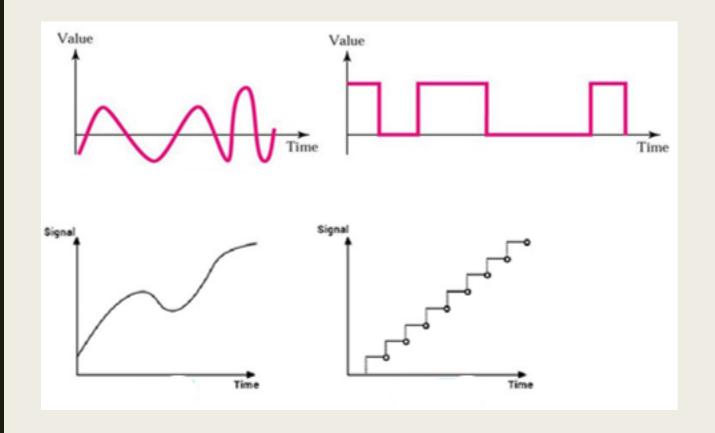
- Signal is defined as:
 - "A quantity used to convey information" e.g. human speech, temperature
 - "a dependent variable or function of one or more independent variables

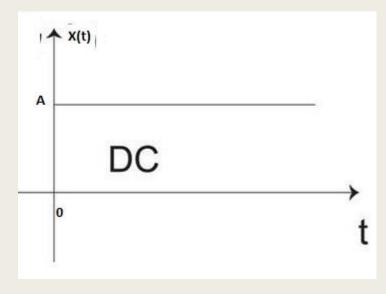
$$f(x_1, x_2, \dots x_n)$$
 \subseteq signal Independent Variables

- Single Variable Signal \rightarrow If signal is dependent on one variable only. f(x), g(t)
- Multi Variable Signal → If signal is depending on more than one variable. $f(x_1, x_2)$

Difference btw signal and a dc value

- anything which is varying is a signal but a constant value is not a signal
- e.g. AC is a signal because current is changing with time. Whereas DC is not a signal because in DC, current is not changing with time.





System

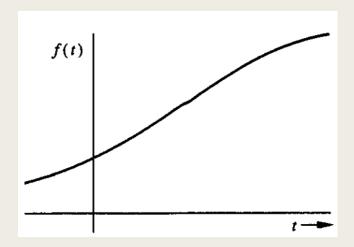
- It is defined as
 - The meaningful interconnection of physical devices and components is called a system
 - An entity that process a set of signals (input signal) and produces another set of signals (output signal).
- System alone can not achieve anything so it must be linked with a signal.

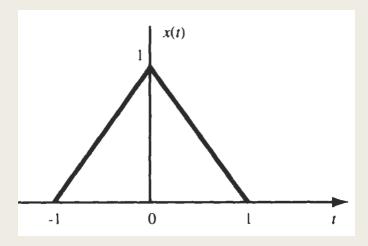


desirable signal

i) Continuous Time Signal (CTS)

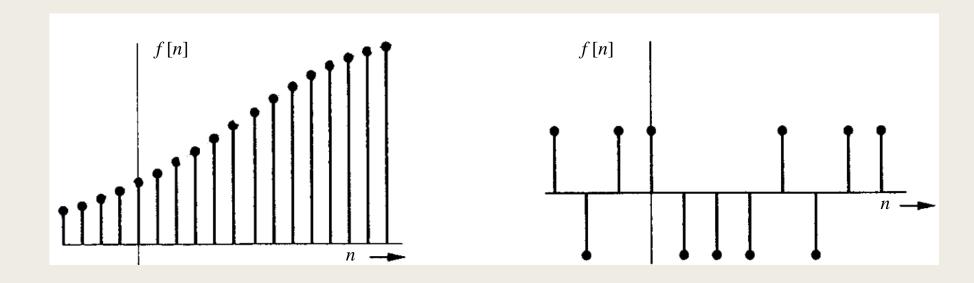
- Signals which are specified for every value of time (t)
- It is written as f(t), x(t), or g(t)





ii) Discrete Time Signals (DTS)

- Signals specified at discrete time intervals
- It is written as f[n], x[n], or g[n] / f(n), x(n), g(n)



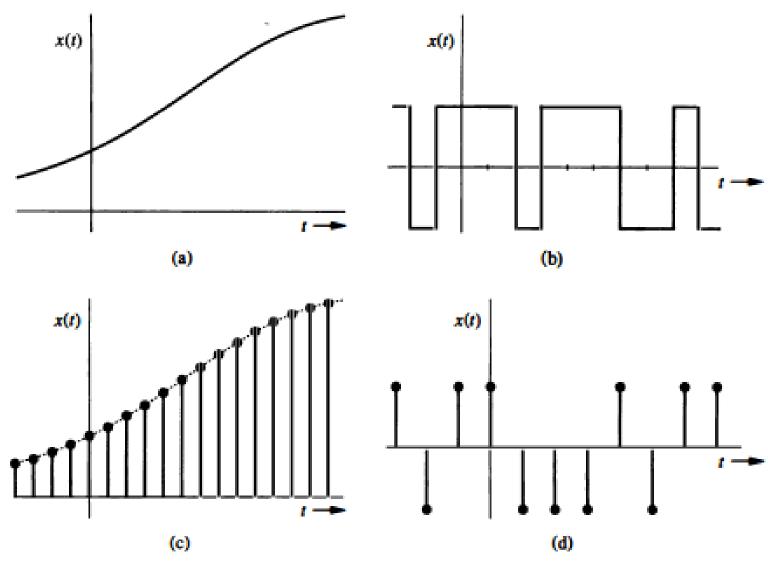


Figure 1.11 Examples of signals: (a) analog, continuous time, (b) digital, continuous time, (c) analog, discrete time, and (d) digital, discrete time.

OPERATIONS ON SIGNALS (INDEPENDENT VARIABLE)

Links for Video Lectures

- 1) Time Shifting
- https://www.youtube.com/watch?v=9Cd5nVCFfc0
- https://www.youtube.com/watch?v=3Qzpj6UUxhE&list=PLBInK6fEyqRhG6s3jYI U48CqsT5cyiDTO&index=273
- 2) Time Scaling
- https://www.youtube.com/watch?v=jnB-U5KBvN4&list=PLBlnK6fEyqRhG6s3jYIU48CqsT5cyiDTO&index=5
- 3) Time Reversal/Flipping/Folding
- https://www.youtube.com/watch?v=BzAbZfT6RxQ&list=PLBlnK6fEyqRhG6s3jYI U48CqsT5cyiDTO&index=9

Operations on Signals

- Operations with respect to x-axis (Time axis) / Transformations on the independent variable
 - Time Shifting
 - Time Reversal/Folding
 - Time Scaling
- Operations with respect to y-axis (Amplitude) / Transformations on the dependent variable
 - Amplitude Multiplication
 - Amplitude Scaling
 - Addition
 - Subtraction



Time Delay

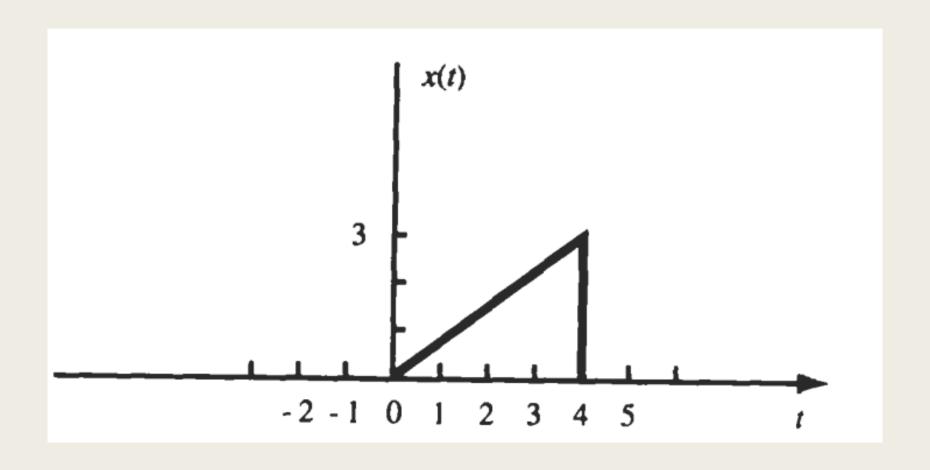
- When the signal is delayed, it is shifted right i.e. x(t - k) or x[n - k] : where k is positive e.g. x(t - 2), x(t - 1.5), x[n - 2], x[n - 3]

■ Time Advance

- When the signal is advanced, it is shifted left i.e. x(t + k) or x[n + k] : where k is positive e.g. x(t + 2), x(t + 1.5), x[n + 2], x[n + 3]



Exp 1.1: For x(t), sketch x(t - 2) and x(t + 2)



$$x(t - 2)$$
:



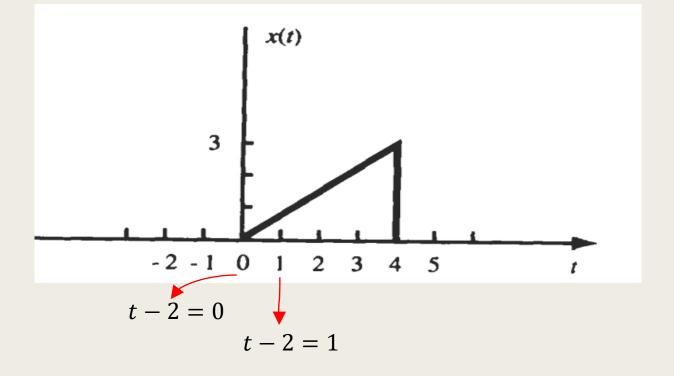
■
$$t-2=0$$
 $\rightarrow t=0+2=2$

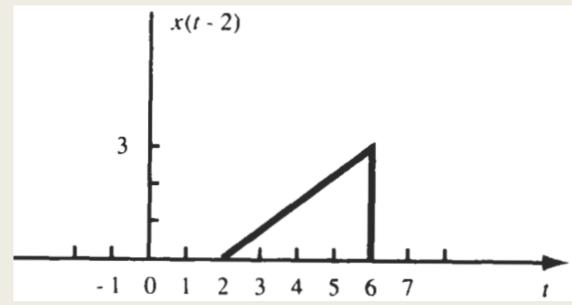
■
$$t-2=1$$
 $\rightarrow t=1+2=3$

■
$$t-2=2$$
 $\rightarrow t=2+2=4$

■
$$t-2=3$$
 $\rightarrow t=3+2=5$

■
$$t-2=4$$
 $\rightarrow t=4+2=6$





Shifted towards right by 2 steps so it is a delayed signal

$$x(t + 2)$$
:



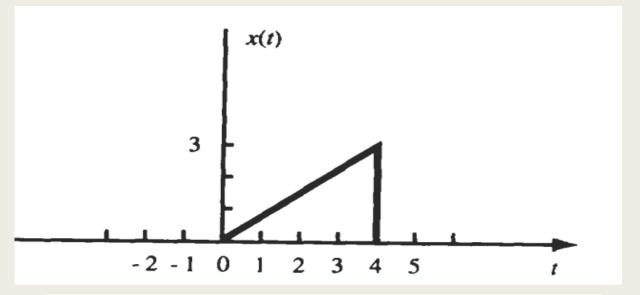
■
$$t + 2 = 0$$
 $\rightarrow t = 0 + 2 = -2$

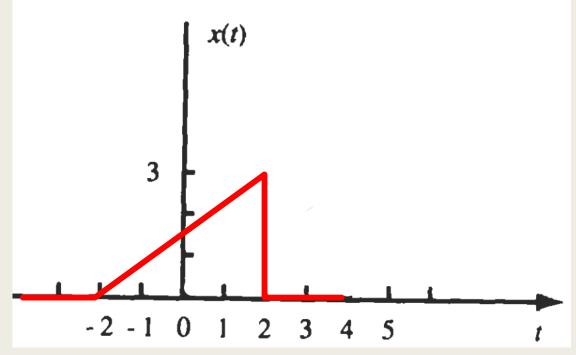
■
$$t + 2 = 1$$
 $\rightarrow t = 1 - 2 = -1$

■
$$t + 2 = 2$$
 $\rightarrow t = 2 - 2 = 0$

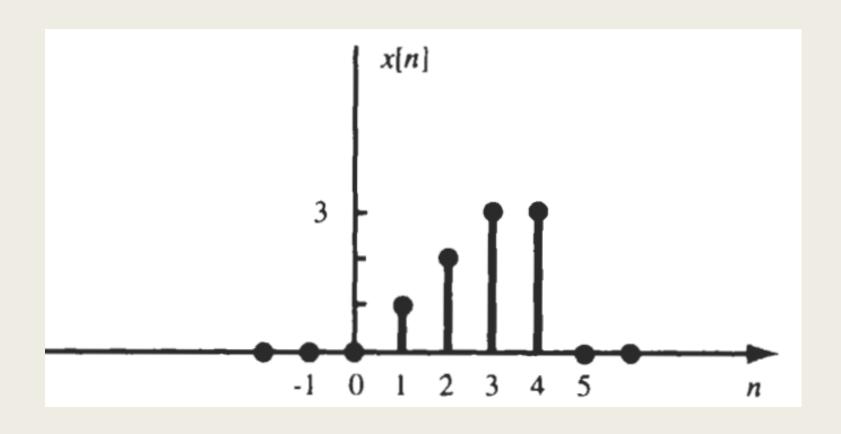
■
$$t + 2 = 3$$
 $\rightarrow t = 3 - 2 = 1$

■
$$t + 2 = 4$$
 $\rightarrow t = 4 - 2 = 2$





Exp 1.2: For x[n], sketch x[n-2]





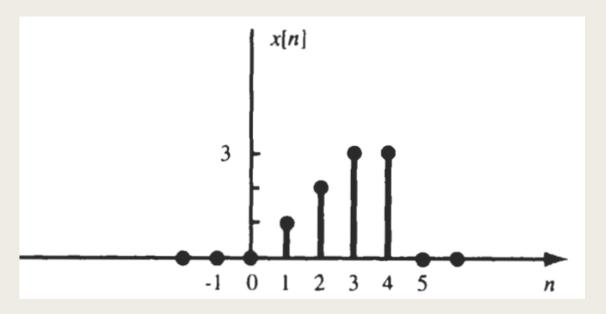
$$n-2=0 \rightarrow n=2-0=2$$

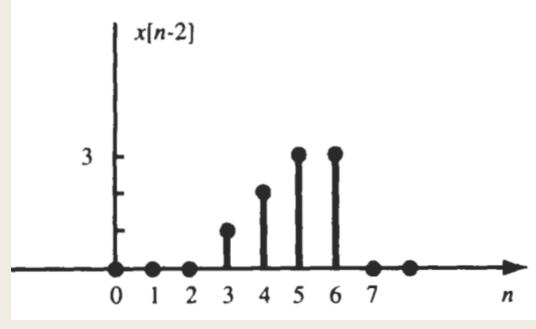
$$n-2=1$$
 $\rightarrow n=1+2=3$

$$n-2=2$$
 $\rightarrow n=2+2=4$

$$n-2=3 \rightarrow n=3+2=5$$

$$n-2=4 \rightarrow n=4+2=6$$





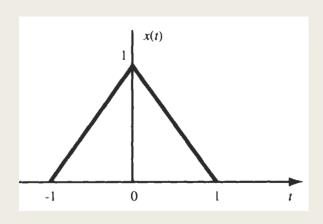
Shifted towards right by 2 steps so it is a delayed signal

PP. 1.1) For signals given, sketch

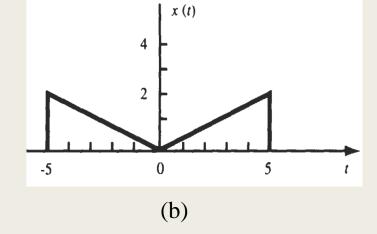
i)
$$x(t - 2.5)$$

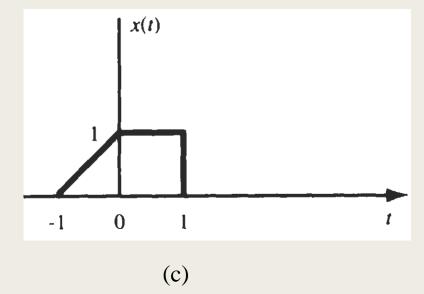
ii) $x(t + 1)$

ii)
$$x(t + 1)$$



(a)

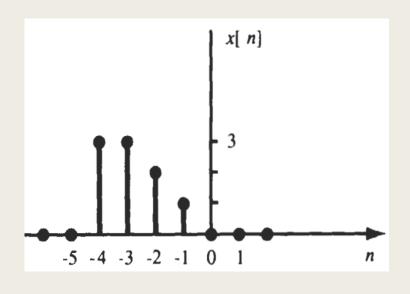




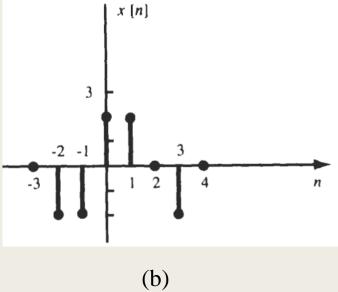
PP. 1.2) For signals given, sketch

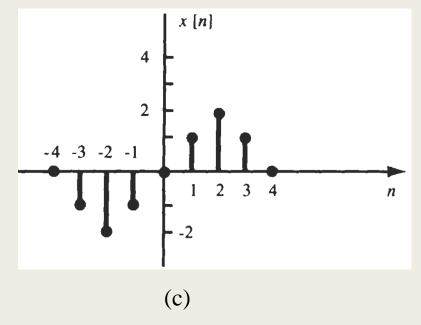
i)
$$x[n-1]$$
 ii) $x[n+3]$

ii)
$$x[n + 3]$$



(a)





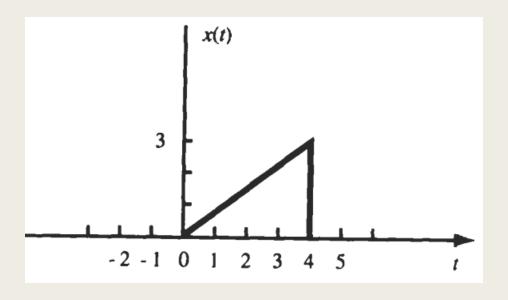
2) Time Reversal/Folding/Flipping

- Reversal of signal about the vertical axis (y-axis) is known as time reversal.
- It converts x(t) into x(-t)
- Therefore, mirror image of the signal x(t) about vertical axis is x(-t)

$$\blacksquare x(t) \rightarrow x(-t)$$

■ Note: Mirror image of the signal x(t) about horizontal axis is -x(t)

Exp 2.1: For x(t), sketch x(-t)



$$x(-t)=x(t)$$

$$x(-t) = x(t)$$

$$-t = 0 \rightarrow t = 0$$

$$-t = 1 \Rightarrow t = -1$$

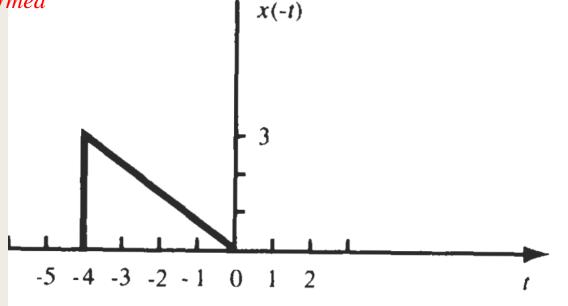
$$-t=2 \Rightarrow t=-2$$

$$-t = 3 \Rightarrow t = -3$$

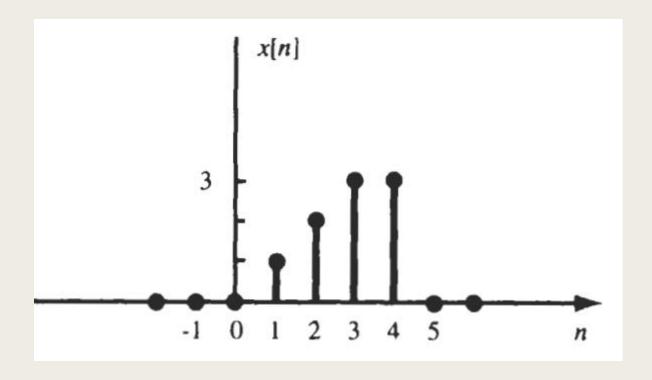
$$-t = 3 \Rightarrow t = -3$$

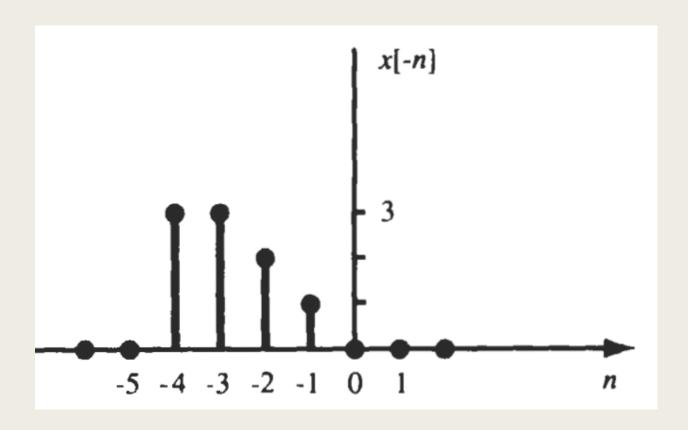
$$-t = 4 \Rightarrow t = -4$$

Points for transformed signal i.e. x(-t)



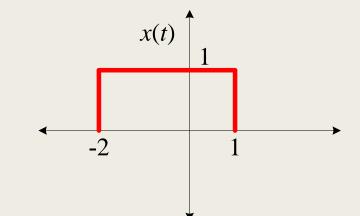
Exp 2.2: For x[n], sketch x[-n]



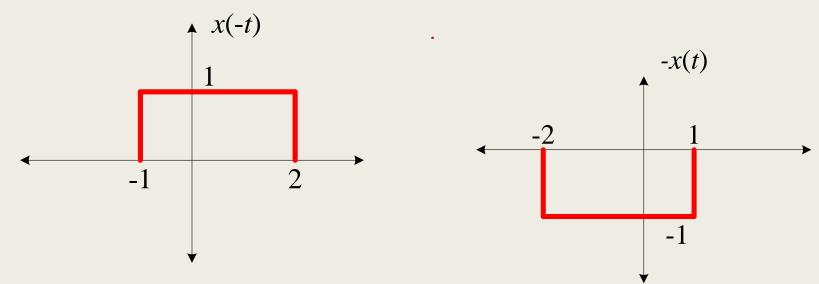


Difference between x(-t) and -x(t)

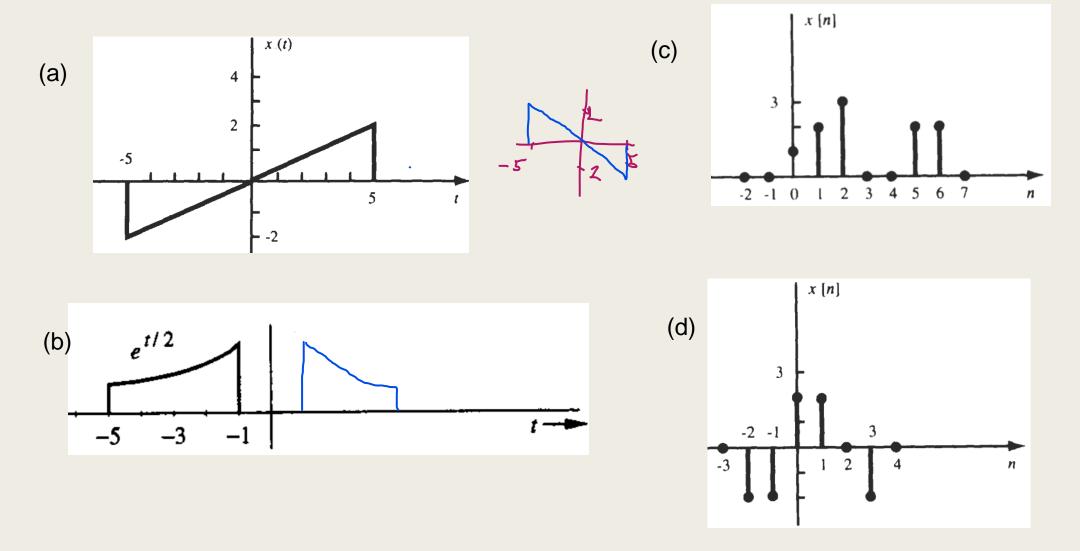
■ $x(t) \rightarrow x(-t)$: Flipping around vertical axis (y-axis)



■ $x(t) \rightarrow -x(t)$: Flipping around horizontal axis (x-axis)



PP. 2.1) For signals given, sketch x(-t) and x[-n]



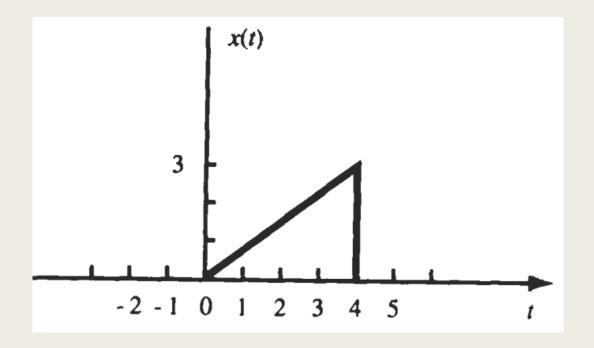
3) Time Scaling

- i) Time Compression: Time axis is compressed
- ii) Time Expansion: Time axis is expanded

$$\blacksquare x(t) \rightarrow x(\alpha t)$$

- If $\alpha > 1$ then scaling results in time compression
- If α < 1 then scaling results in time expansion.

Exp 3.1: For the signal given, sketch x(2t) and x(t/2)



x(2t):

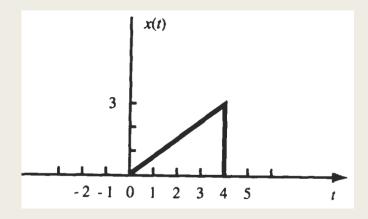
$$2t = 0 \rightarrow t=0$$

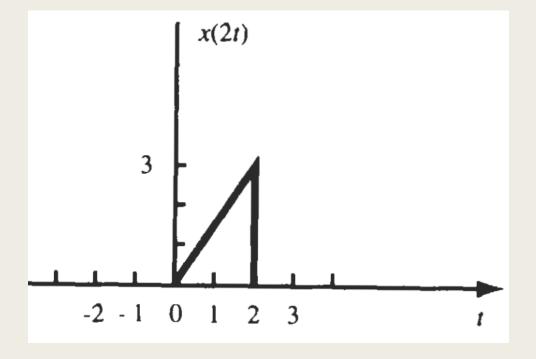
$$= 2t = 1 \rightarrow t = 1/2 = 0.5$$

$$= 2t = 2 \rightarrow t = 2/2 = 1$$

■
$$2t = 3 \rightarrow t = 3/2 = 1.5$$

$$= 2t = 4 \rightarrow t = 4/2 = 2$$





Signal is compressed by 2 times

x(t/2):

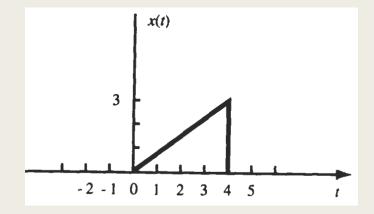
■
$$t/2 = 0 \rightarrow t=0$$

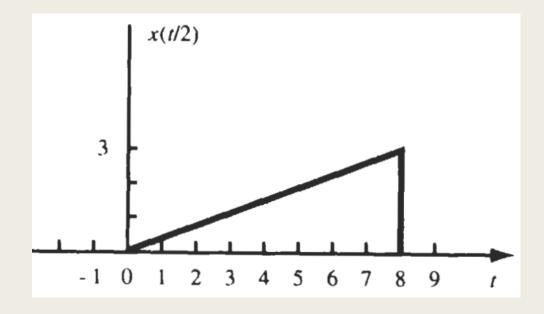
■
$$t/2 = 1 \rightarrow t=2x1=2$$

■
$$t/2 = 2 \rightarrow t = 2x2 = 4$$

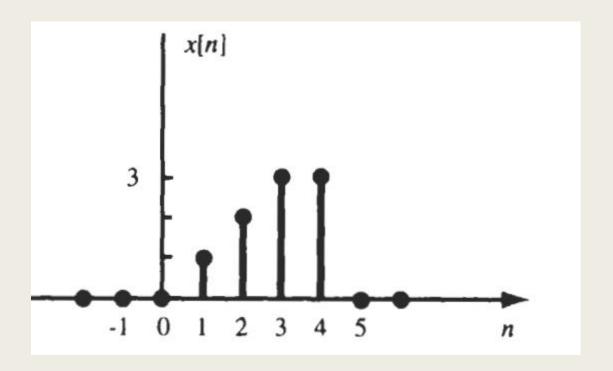
■
$$t/2 = 3 \rightarrow t = 2x3 = 6$$

■
$$t/2 = 4 \rightarrow t = 2x4 = 8$$





Exp 3.2: For the signal given, sketch x[2n] and x[n/2]



$x[2n] \rightarrow Down-sampling$

■
$$2n = -2 \rightarrow n=-1$$

$$=$$
 2n = -1 \rightarrow n=-1/5=-0.5

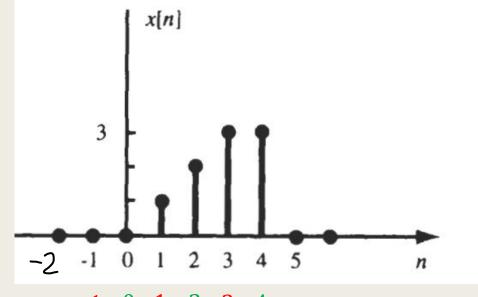
■
$$2n = 0 \rightarrow n=0$$

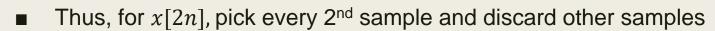
$$=$$
 2n = 1 \rightarrow n=1/2=0.5

■
$$2n = 2 \rightarrow n = 2/2 = 1$$

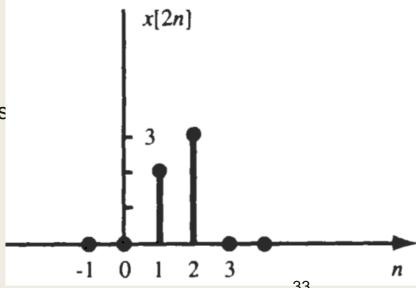
■
$$2n = 3 \rightarrow n = 3/2 = 1.5$$

$$=$$
 2n = 4 \rightarrow n=4/2 = 2





Similarly for x[3n], pick every 3^{rd} sample and discard other samples



$x[n/2] \rightarrow Up$ -sampling

■
$$n/2 = -2 \rightarrow n=-4$$

$$n/2 = -1 \rightarrow n = -1 \times 2 = -2$$

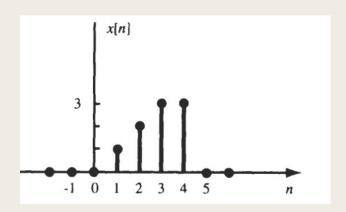
■
$$n/2 = 0 \rightarrow n=0$$

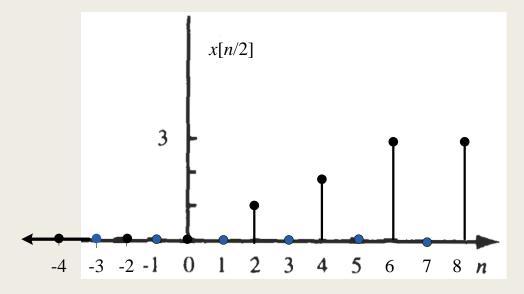
$$n/2 = 1 \rightarrow n=1 \times 2= 2$$

$$n/2 = 2 \rightarrow n=2 \times 2=4$$

$$n/2 = 3 \rightarrow n=3 \times 2=6$$

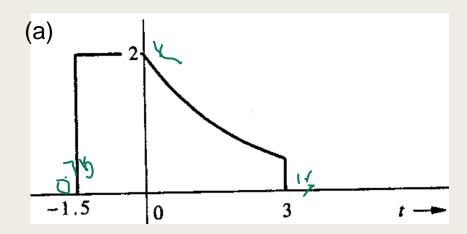
$$n/2 = 4 \rightarrow n=4 \times 2 = 8$$

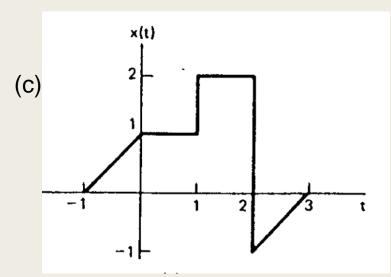


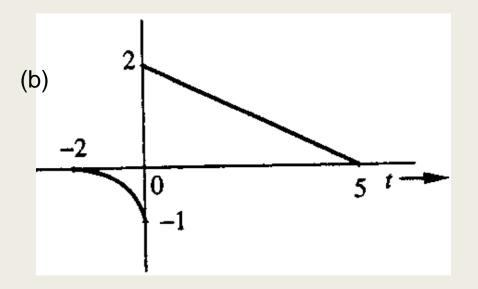


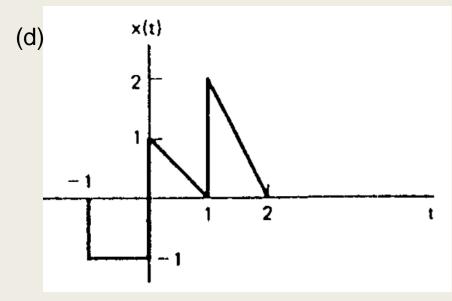
- Thus, $x[n/2] \rightarrow$ place samples at every 2nd place whereas zeros will be placed in between the samples
- Thus, x[n/3] → place samples at every 3rd place whereas zeros will be placed in between the samples

PP. 3.1) For signals given, sketch (i) x(2t) (ii) x(t/3) (iii) x(1.5t)

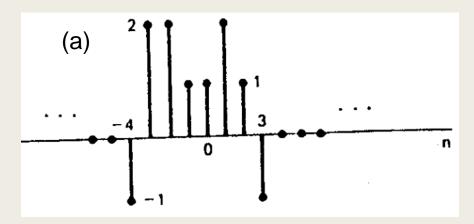


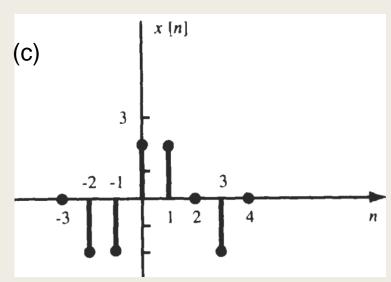


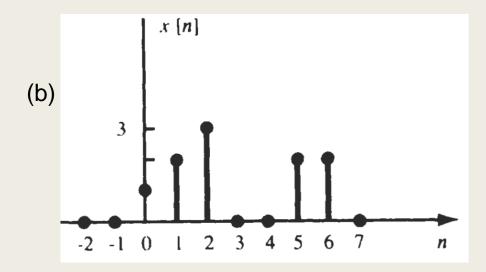


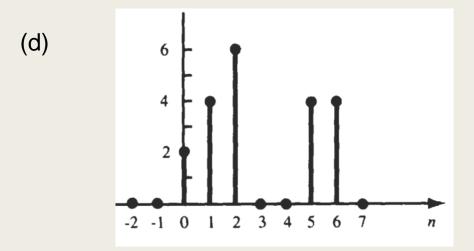


PP. 3.2) For signals given, sketch (i) x[2n] (ii) x[3n] (iii) x[n/3]









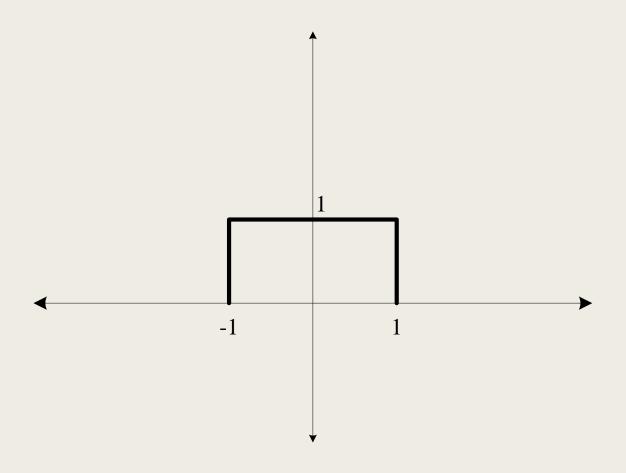
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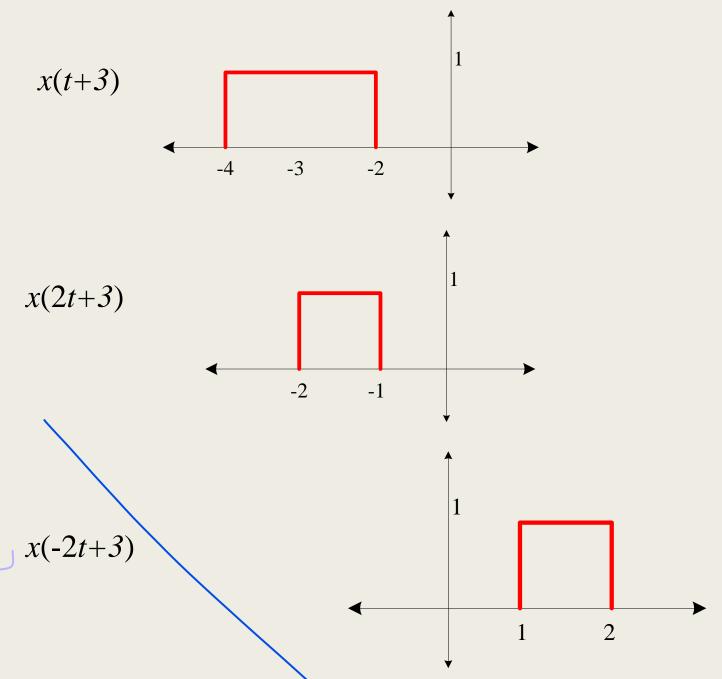
4. Precedence Rule for Combined Operations

- **e.g. Method 1:** x(t) is the given signal
- i) Time shifting operation x(t-k), x(t+k)
- ii) Time scaling operation $x(\alpha t k)$, $x(\alpha t + k)$
- iii) Time flipping $x(-\alpha t k)$, $x(-\alpha t + k)$
- **e.g. Method 2:** x(t) is the given signal
- \blacksquare i) Time scaling operation $x(\alpha t)$
- ii) Time shifting operation $x(\alpha(t-k/\alpha), x(\alpha(t+k/\alpha))$
- iii) Time flipping $x(-\alpha(t-k/\alpha), x(-\alpha(t+k/\alpha))$

There is no precedence rule. You can apply operations in any order

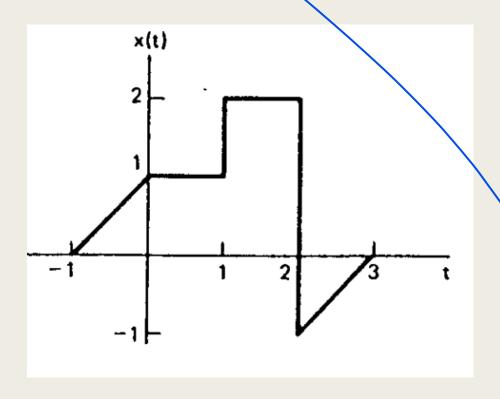
Exp 4.1: For the signal given, sketch x(-2t + 3)



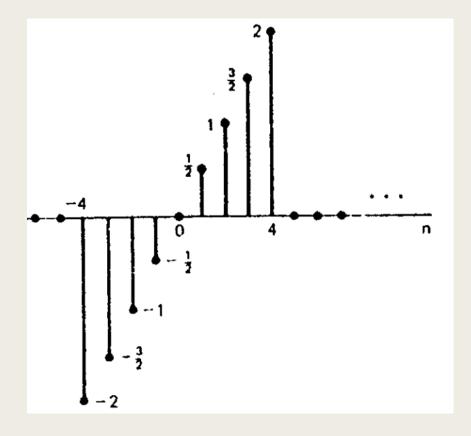


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PP. 4.1) For signals given, sketch (i) x(t/2-2) (ii) x(1-2t) (iii) x(2-t/3)



PP. 4.2) For signals given, sketch (i)
$$x[4-n]$$
 (ii) $x[2n+1]$ (iii) $x[-\frac{n}{3}+2]$



Thank You !!!