# **CONTROL SYSTEM LAB REPORTS**

# **LAB 05**

## SUBMITTED BY ZARAFSHAN IQBAL

REG NO 17KTELE0556

SEMESTER 8<sup>TH</sup>

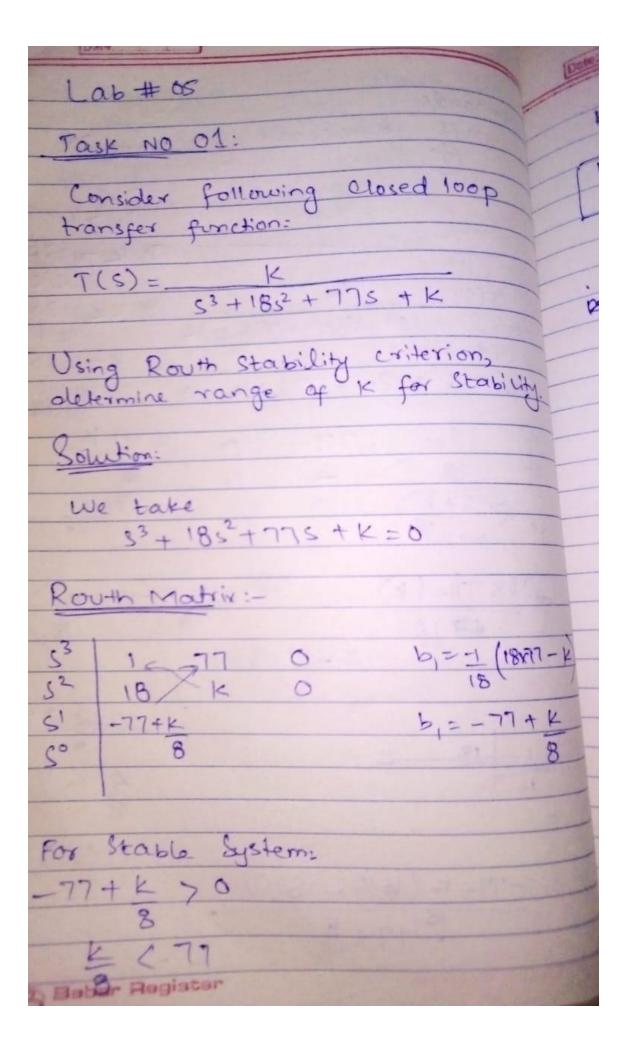
SUBMITTED TO ENGR.M.AMJAD

## **LAB 05**

### **Task 01:**

We have found the range of K on which the system is stable, the range is K<1386 then the system is stable.

The solution of Routh stability criteria,

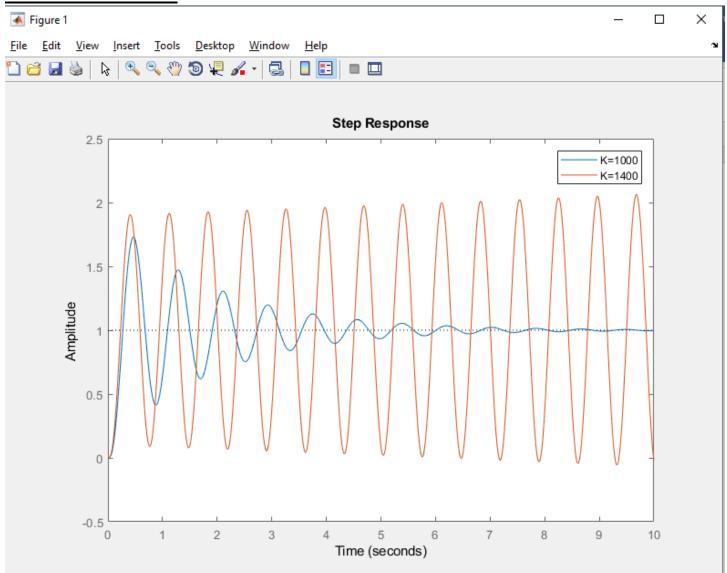


Day\_ K (77X8 K < 1386 For stable system "12" value should be led than 1386. Daham

#### MATLAB code to check whether our obtained range is correct,

```
s=tf('s');
G= 1/(s^3+18*s^2+77*s)
K1=1000;
step(feedback(K1*G,1),10)
hold on
K2= 1400;
step(feedback(K2*G,1),10)
legend('K=1000','K=1400')
```

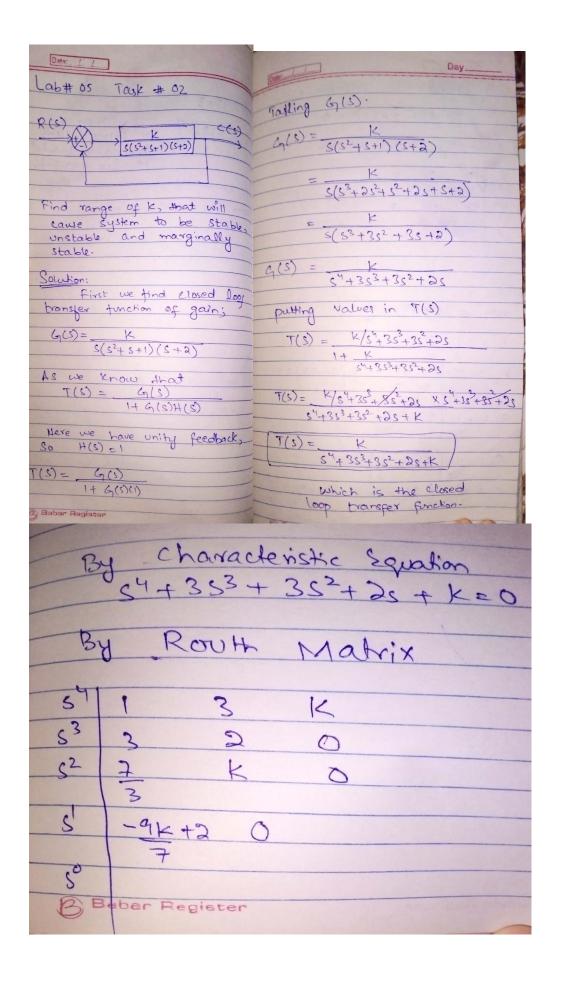
#### **MATLAB RESULT:**

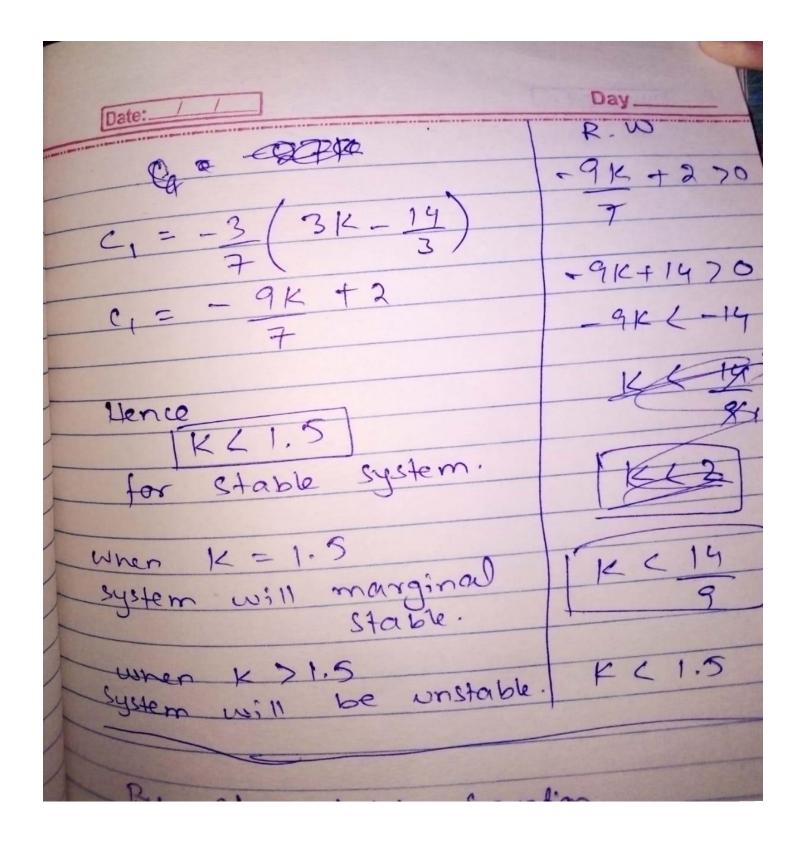


### **TASK 02:**

We have found the range of K on which the system is stable, the range is K<1.5 then the system is stable and if K> 1.5 the system will be unstable and when the K=1.5 the system will be marginally stable

The solution of Routh stability criteria,



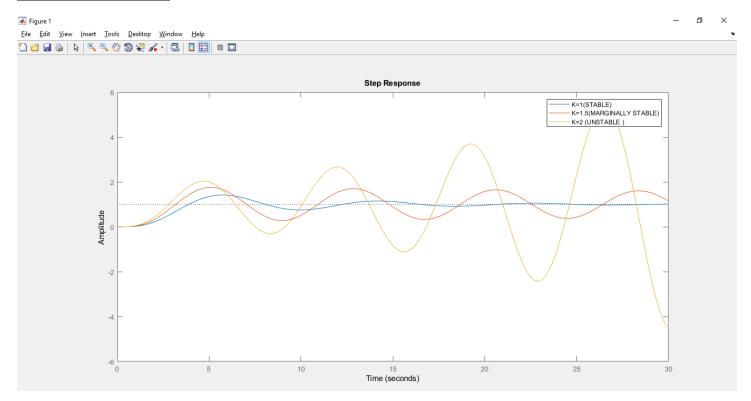


#### MATLAB code to check whether our obtained range is correct,

```
s=tf('s');
G= 1/(s^4+3*s^3+3*s^2+2*s)
K1=0.9;
step(feedback(K1*G,1),50)
```

```
hold on
K2= 5;
step(feedback(K2*G,1),50)
legend('K=2','K=10')
```

#### **MATLAB RESULT:**



### **TASK 03:**