Parallel and Distributed Computing CS3006

Lecture 16

MPI-III

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Sorting in Parallel Era

Sorting: Overview

- One of the most commonly used and well-studied Algorithms.
- Sorting can be comparison-based or non-comparisonbased.
- The fundamental operation of comparison-based sorting is compare-exchange.
- The lower bound on any comparison-based sort of n numbers is $\Theta(n \log n)$.
- Let's explore a comparison-based sorting algorithm.

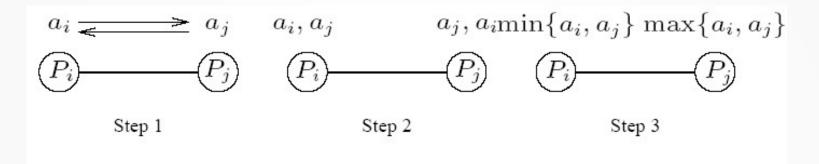
Sorting: Basics

- → What is a parallel sorted sequence?
- → Where are the input and output lists stored?

Answers:

- We assume that the input and output lists are distributed.
- The sorted list is partitioned with the property that each partitioned list is sorted and each element in processor P_i 's list is less than that in P_j 's list if i < j.

Sorting: Parallel Compare Exchange Operation

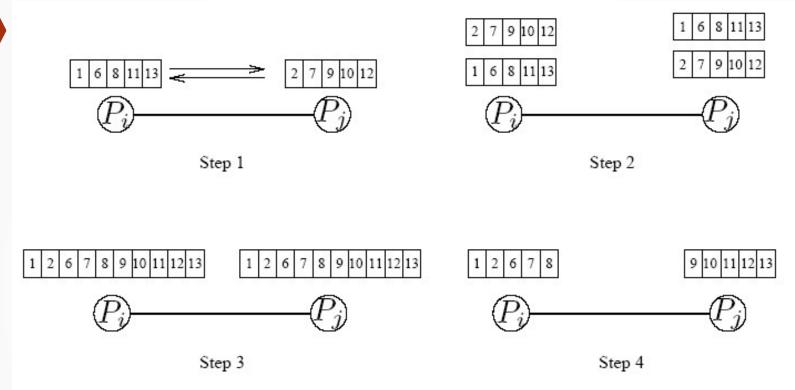


A parallel compare-exchange operation. Processes P_i and P_j send their elements to each other. Process P_i keeps $\min\{a_i,a_j\}$, and P_j keeps $\max\{a_i,a_j\}$.

Sorting: Parallel Compare Exchange Operation [cost estimation]

- If each processor has one element, the compare exchange operation stores the smaller element at the processor with smaller id. This can be done in $t_s + t_w$ time.
- If we have more than one element per processor, we call this operation a compare split. Assume each of two processors have n/p elements.
- After the compare-split operation, the smaller n/p elements are at processor P_i and the larger n/p elements at P_j , where i < j.
- The time for a compare-split operation is $(t_s + t_w n/p)$, assuming that the two partial lists were initially sorted.
 - Note that this time is only accounting communication costs. Computation and memory complexities are separate things.

Sorting: Parallel Compare Exchange



A compare-split operation. Each process sends its block of size n/p to the other process. Each process merges the received block with its own block and retains only the appropriate half of the merged block. In this example, process P_i retains the smaller elements and process P_i retains the larger elements.

Bubble Sort and its Variant

The sequential bubble sort algorithm compares and exchanges adjacent elements in the sequence to be sorted:

```
1. procedure BUBBLE_SORT(n)
2. begin
3. for i := n - 1 downto 1 do
4. for j := 1 to i do
5. compare-exchange(a_j, a_{j+1});
6. end BUBBLE_SORT
```

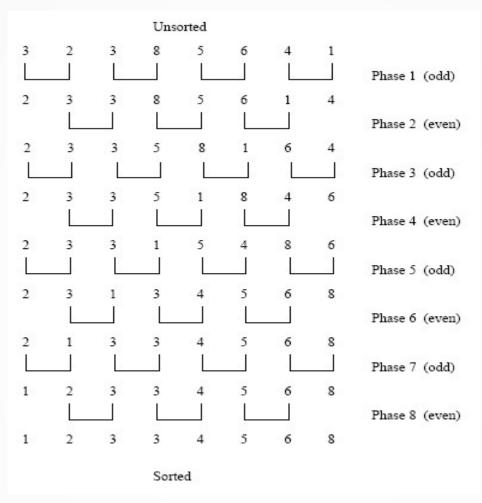
Sequential bubble sort algorithm.

First pass Exchange No Exchange Exchange Exchange Exchange Exchange Exchange Exchange 93 in place after first pass

Bubble Sort and its Variant

- The complexity of bubble sort is $\Theta(n^2)$.
- Bubble sort is difficult to parallelize since the algorithm has no concurrency.
- A simple variant, though, uncovers the concurrency.

Bubble Sort [Odd-Even Transposition]



Sorting n = 8 elements, using the odd-even transposition sort algorithm. During each phase, at most 8 elements are compared. [This according to sequential algorithm]
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Bubble Sort [Odd-Even Transposition]

```
procedure ODD-EVEN(n)
2.
         begin
3.
              for i := 1 to n do
              begin
5.
                   if i is odd then
6.
                        for j := 0 to n/2 - 1 do
7.
                            compare-exchange(a_{2j+1}, a_{2j+2});
                   if i is even then
                        for j := 1 to n/2 - 1 do
10.
                            compare-exchange(a_{2i}, a_{2i+1});
11.
              end for
12.
         end ODD-EVEN
```

Sequential odd-even sort algorithm.

Odd-Even Sort (Seq. Complexity)

- After n phases of odd-even exchanges, the sequence is sorted.
- Each phase of the algorithm (either odd or even) requires $\Theta(n)$ comparisons.
- Serial complexity is $\Theta(n^2)$.

	Step 0	P ₀	P ₁	P_2	P_3	P ₄	P_5	P_6	P ₇
		4 -	- 2	7 -	→ 8	5 -	- 1	3 -	→ 6
Time	1	2	4 🕶	→ 7	8 🕶	→ 1	5 -	3	6
	2	2 -	 4	7 -	→ 1	8 -	→ 3	5	→ 6
	3	2	4 -	→ 1	7 -	- 3	8 -	→ 5	6
	4	2 -	- 1	4 -	- 3	7 -	- 5	8 -	- 6
	5	1	2 -	- 3	4 -	- 5	7 -	- 6	8
	6	1 -	→ 2	3 🕶	→ 4	5 -	→ 6	7 🕶	→ 8
	. 7	1	2 -	→ 3	4 -	- 5	6 🕶	→ 7	8

(for P=n)

Parallel time complexity: $T_{par} = O(n)$

Algorithm Through Observations:

1. There are total **P** phases/steps. Where P is number of processes

2. For even phases

- i. If 'myrank' is even → Communication partner is ('myrank'+1)
- ii. If 'myrank' is odd → Communication partner is ('myrank' 1)

3. For odd phases:

- i. If 'myrank' is even → Communication partner is ('myrank' 1)
- ii. If 'myrank' is odd → Communication partner is ('myrank'+1)
- 4. Communication partners remain constant
- 5. If 'myrank' is less-than the partner, then keep lower values in compare-split-operation

Complexity when *n*==P

- Consider the one item per processor case.
- There are P iterations, in each iteration, each processor does one compare-exchange.
- The parallel run time of this formulation is $\Theta(n)$.
- Parallel run time means computation performed by each of the processors in parallel.

Complexity when n > P

- Consider a block of n/p elements per processor.
- The first step is a local sort.
- In each subsequent step, the compare exchange operation is replaced by the compare split operation.
- The parallel run time of the formulation is:

$$T_P = \Theta\left(\frac{n}{p}\log\frac{n}{p}\right) + \Theta(n) + \Theta(n).$$

comm. steps for a single process

- 1. #include <stdlib.h>
- 2. #include <mpi.h> /* Include MPI's header file */
- 3. main(int argc, char *argv[])
- 4. {
- 5. int n; /* The total number of elements to be sorted */
- 6. int npes; /* The total number of processes */
- 7. int myrank; /* The rank of the calling process */
- int nlocal; /* The local number of elements, and the array that stores them */
- 9. int *elmnts; /* The array that stores the local elements */
- 10. int *relmnts; /* The array that stores the received elements */
- 11. int oddrank; /* The rank of the partner during odd-phase communication */
- 12. int evenrank; /* The rank of the partner during even-phase communication */
- 13. int *wspace; /* Working space during the compare-split operation */

```
/* Initialize MPI and get system information */
18
      MPI Init (&argc, &argv);
19
20
      MPI Comm size (MPI COMM WORLD, &npes);
21
      MPI Comm rank (MPI COMM WORLD, &myrank);
22
23
      n = atoi(argv[1]);
24
      nlocal = n/npes; /* Compute the number of elements to be stored locally. */
25
     /* Allocate memory for the various arrays */
26
27
     elmnts = (int *)malloc(nlocal*sizeof(int));
28
     relmnts = (int *)malloc(nlocal*sizeof(int));
29
      wspace = (int *) malloc(nlocal*sizeof(int));
30
     /* Fill-in the elmnts array with random elements */
31
32
     srandom(myrank);
      for (i=0; i<nlocal; i++)
33
34
        elmnts[i] = random();
35
     /* Sort the local elements using the built-in quicksort routine */
36
      gsort(elmnts, nlocal, sizeof(int), IncOrder);
37
```

Determining communication partner during Even and odd steps of the algorithm.

■ If my partner is out of bounds, then set it to NULL process.

```
if (myrank \%2 == 0) {
41
42
        oddrank = myrank-1;
        evenrank = myrank+1;
44
45
    else {
46
     oddrank = myrank+1;
        evenrank = myrank-1;
47
48
49
     /* Set the ranks of the processors at the end of the linear */
51
    if (oddrank == -1 || oddrank == npes)
        oddrank = MPI PROC NULL;
     if (evenrank == -1 || evenrank == npes)
53
        evenrank = MPI PROC NULL;
54
```

P Steps for actual algorithm

```
56
      /* Get into the main loop of the odd-even sorting algorithm */
      for (i=0; i<npes-1; i++) {
57
        if (i%2 == 1) /* Odd phase */
58
59
           MPI Sendrecv(elmnts, nlocal, MPI INT, oddrank, 1, relmnts,
               nlocal, MPI INT, oddrank, 1, MPI COMM WORLD, &status);
60
        else /* Even phase */
61
           MPI Sendrecv(elmnts, nlocal, MPI INT, evenrank, 1, relmnts,
62
               nlocal, MPI INT, evenrank, 1, MPI COMM WORLD, &status);
63
64
         CompareSplit (nlocal, elmnts, relmnts, wspace,
65
66
                    myrank < status.MPI SOURCE);
67
     1
68
69
      free (elmnts); free (relmnts); free (wspace);
      MPI Finalize();
70
71 }
```

Compare-Split function

```
CompareSplit(int nlocal, int *elmnts, int *relmnts, int *wspace,
74
75
                  int keepsmall)
76
77
      int i, j, k;
78
      for (i=0; i<nlocal; i++)
79
        wspace[i] = elmnts[i]; /* Copy the elmnts array into the wspace array */
80
81
82
      if (keepsmall) { /* Keep the nlocal smaller elements */
        for (i=j=k=0; k\leq nlocal; k++) {
83
           if (j == nlocal || (i < nlocal && wspace[i] < relmnts[j]))
84
             elmnts[k] = wspace[i++];
85
86
          else
87
             elmnts[k] = relmnts[i++];
88
89
      else { /* Keep the nlocal larger elements */
90
        for (i=k=nlocal-1, j=nlocal-1; k>=0; k--) {
91
          if (j == 0 \mid | (i >= 0 \&\& wspace[i] >= relmnts[j]))
92
93
             elmnts[k] = wspace[i--];
94
          else
95
             elmnts[k] = relmnts[j--];
96
        1
97
98
```

IncOrder function

```
/* The IncOrder function that is called by qsort is defined as follows */
int IncOrder(const void *e1, const void *e2)
{
  return (*((int *)e1) - *((int *)e2));
}
```

Questions



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References

1. Kumar, V., Grama, A., Gupta, A., & Karypis, G. (2017). *Introduction to parallel computing*. Redwood City, CA: Benjamin/Cummings.