Parallel and Distributed Computing CS3006

Lecture 5

Parallel Algorithm Design Life Cycle

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Agenda

- A Quick Review
- Parallel Algorithm Design Life Cycle
- Tasks, Decomposition, and Task-dependency graphs
- Granularity
 - Fine-grained
 - Coarse-grained
- Concurrency
 - Max-degree of concurrency
 - Critical path length
 - Average-degree of concurrency
- Task-interaction Diagrams
 - Processes and mapping

Quick Review to the Previous Lecture

- Static vs Dynamic Interconnections
- Static Network Topologies
 - Linear array
 - Star
 - Mesh
 - Tree
 - Fully-connected
 - Hypercube
- Evaluating Static interconnections
 - Cost
 - Diameter
 - Bisection-width
 - Arc-connectivity

Steps in Parallel Algorithm Design

- 1. Identification: Identifying portions of the work that can be performed concurrently.
 - Work-units are also known as tasks
 - E.g., Initializing two mega-arrays are two tasks and can be performed in parallel
- 2. **Mapping:** The process of mapping concurrent pieces of the work or tasks onto multiple processes running in parallel.
 - Multiple processes can be physically mapped on a single processor.

Steps in Parallel Algorithm Design

- 3. Data Partitioning: Distributing the input, output, and intermediate data associated with the program.
 - One way is to copy whole data at each processing node
 - Memory challenges for huge-size problems
 - Other way is to give fragments of data to each processing node
 - Communication overheads
- 4. **Defining Access Protocol**: Managing accesses to data shared by multiple processors (i.e., managing communication).
- 5. Synchronizing the processors at various stages of the parallel program execution.

Decomposition:

■ The process of dividing a computation into smaller parts, some or all of which may potentially be executed in parallel.

Tasks

- Programmer-defined units of computation into which the main computation is subdivided by means of decomposition
- Tasks can be of arbitrary size, but once defined, they are regarded as indivisible units of computation.
- The tasks into which a problem is decomposed may not all be of the same size
- Simultaneous execution of multiple tasks is the key to reducing the time required to solve the entire problem.

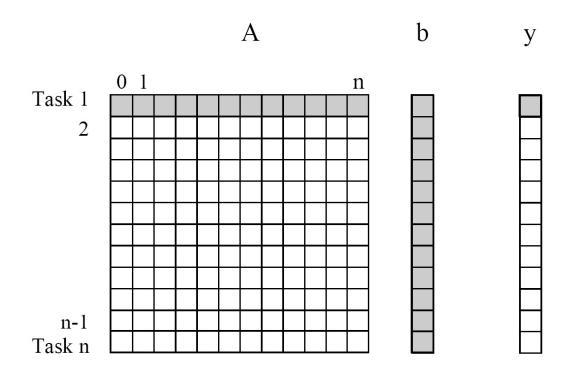


Figure 3.1 Decomposition of dense matrix-vector multiplication into *n* tasks, where *n* is the number of rows in the matrix. The portions of the matrix and the input and output vectors accessed by Task 1 are highlighted.

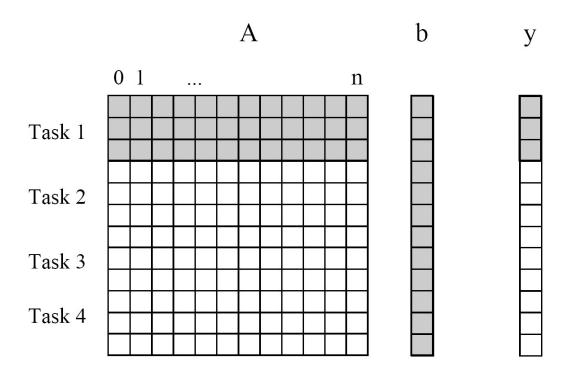


Figure 3.4 Decomposition of dense matrix-vector multiplication into four tasks. The portions of the matrix and the input and output vectors accessed by Task 1 are highlighted.

Granularity

- The number and sizes of tasks into which a problem is decomposed determines the granularity of the decomposition
 - A decomposition into a large number of small tasks is called fine-grained
 - A decomposition into a small number of large tasks is called coarse-grained
- For matrix-vector multiplication Figure 3.1 would usually be considered fine-grained
- Figure 3.4 shows a coarse-grained decomposition as each tasks computes n/4 of the entries of the output vector of length n

Task-Dependency Graph

- The tasks in the previous examples are independent and can be performed in any sequence.
- In most of the problems, there exist some sort of dependencies between the tasks.
- An abstraction used to express such dependencies among tasks and their relative order of execution is known as a task-dependency graph
- It is a directed acyclic graph in which node are tasks and the directed edges indicate the dependencies between them
- The task corresponding to a node can be executed when all tasks connected to this node by incoming edges have completed.

Select ID, model, year, color from dbtable where model='civic' and year='2001' and (color='White' OR color='Green')

| ID# | Model | Year | Color | Dealer | Price |
|------|---------|------|-------|--------|----------|
| 4523 | Civic | 2002 | Blue | MN | \$18,000 |
| 3476 | Corolla | 1999 | White | IL | \$15,000 |
| 7623 | Camry | 2001 | Green | NY | \$21,000 |
| 9834 | Prius | 2001 | Green | CA | \$18,000 |
| 6734 | Civic | 2001 | White | OR | \$17,000 |
| 5342 | Altima | 2001 | Green | FL | \$19,000 |
| 3845 | Maxima | 2001 | Blue | NY | \$22,000 |
| 8354 | Accord | 2000 | Green | VT | \$18,000 |
| 4395 | Civic | 2001 | Red | CA | \$17,000 |
| 7352 | Civic | 2002 | Red | WA | \$18,000 |

Table 3.1 A database storing information about used vehicles.

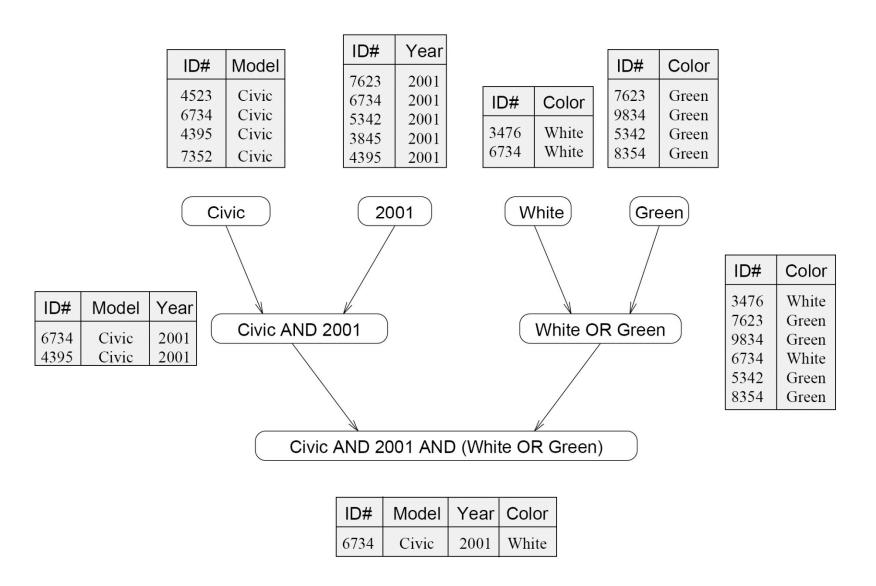


Figure 3.2 The different tables and their dependencies in a query processing operation.

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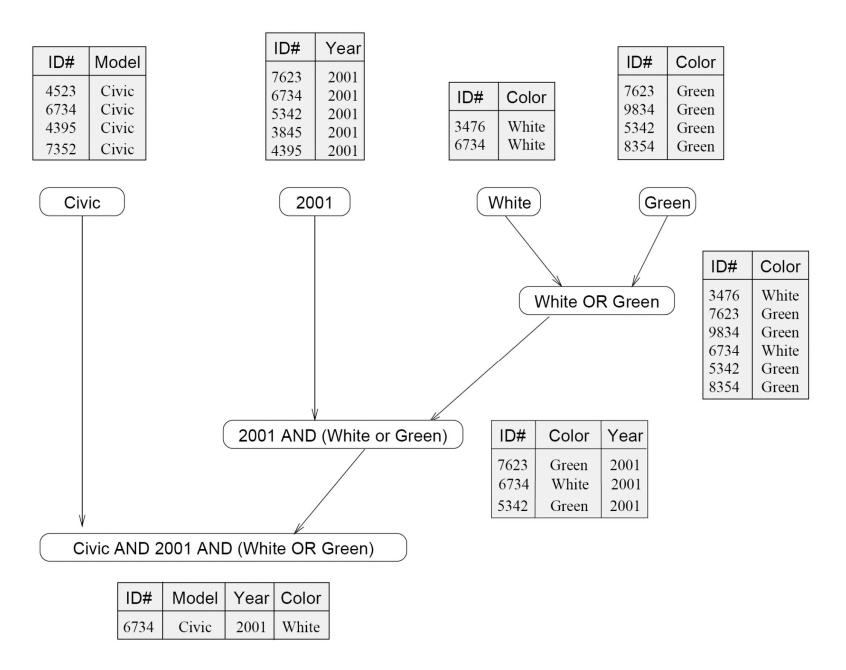
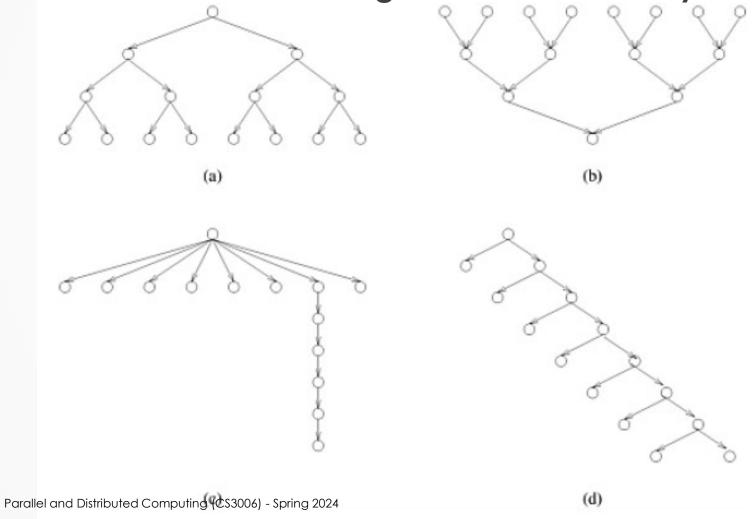


Figure 3.3 An alternate data-dependency graph for the query processing operation.

Maximum Degree of Concurrency

- The maximum number of tasks that can be executed simultaneously in a parallel program at any given time is known as its maximum degree of concurrency
- Usually, it is always less than total number of tasks due to dependencies.
- E.g., max-degree of concurrency in the task-graphs of Figures 3.2 and 3.3 is 4.
- Rule of thumb: For task-dependency graphs that are trees, the maximum degree of concurrency is always equal to the number of leaves in the tree

Determine Maximum Degree of Concurrency?



Average Degree of Concurrency

- A relatively better measure for the performance of a parallel program
- The average number of tasks that can run concurrently over the entire duration of execution of the program
- The ratio of the total amount of work to the criticalpath length
 - So, what is the critical path in the graph?

Average Degree of Concurrency

- Critical Path: The longest directed path between any pair of start and finish nodes is known as the critical path.
- Critical Path Length: The sum of the weights of nodes along this path
 - the weight of a node is the size or the amount of work associated with the corresponding task.
- A shorter critical path favors a higher averagedegree of concurrency.
- Both, maximum and average degree of concurrency increases as tasks become smaller(finer)

Average Degree of Concurrency

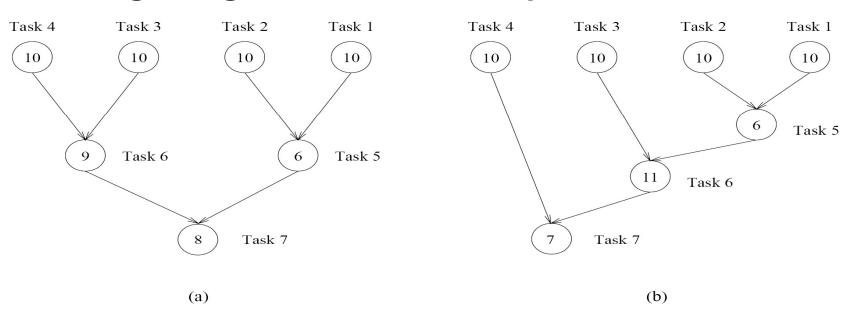


Figure 3.5 Abstractions of the task graphs of Figures 3.2 and 3.3, respectively.

Critical path lengths: 27 and 34

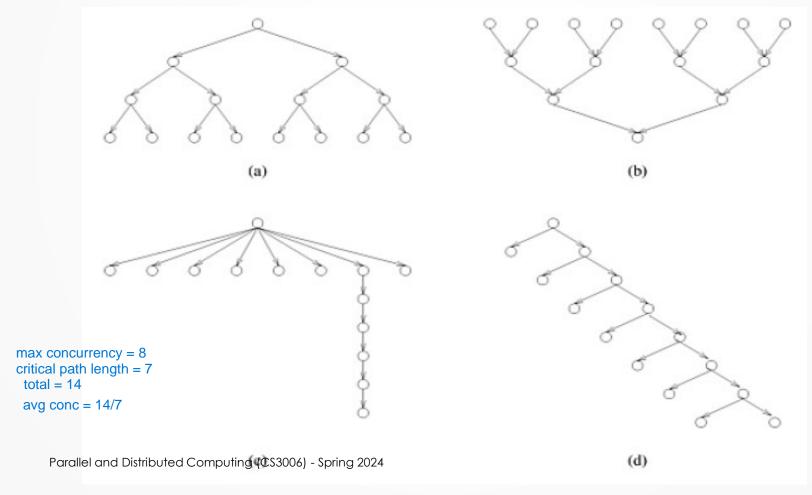
AVG DEG = 63/27 = 2.33

Total amount of work: 63 and 64

Average degree of concurrency: 2.33 and 1.88

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Determine critical path length and averageconcurrency?



Task Interact Graph

- Depicts pattern of interaction between the tasks
- Dependency graphs only show that how output of first task becomes input to the next level task.
- But how the tasks interact with each other to access distributed data is only depicted by task interaction graphs
- The nodes in a task-interaction graph represent tasks
- The edges connect tasks that interact with each other

Task Interact Graph

- The edges in a task interaction graph are usually undirected
 - but directed edges can be used to indicate the direction of flow of data, if it is unidirectional.
- The edge-set of a task-interaction graph is usually a superset of the edge-set of the task-dependency graph
- In database query processing example, the taskinteraction graph is the same as the taskdependency graph.

Task Interact Graph (Sparse-matrix multiplication)

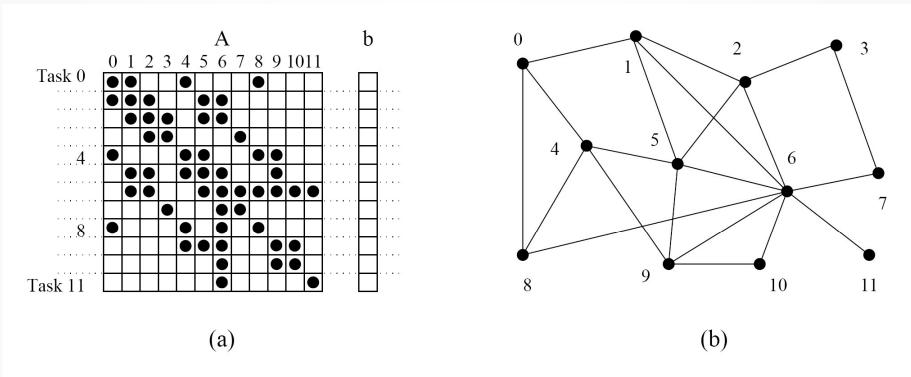


Figure 3.6 A decomposition for sparse matrix-vector multiplication and the corresponding task-interaction graph. In the decomposition Task i computes $\sum_{0 \le j \le 11, A[i,j] \ne 0} A[i,j].b[j]$.

Processes and Mapping

- Logical processing or computing agent that performs tasks is called process.
- The mechanism by which tasks are assigned to processes for execution is called *mapping*.
- Multiple tasks can be mapped on a single process
- Independent task should be mapped onto different processes
- Map tasks with high mutual-interactions onto a single process

Processes and Mapping

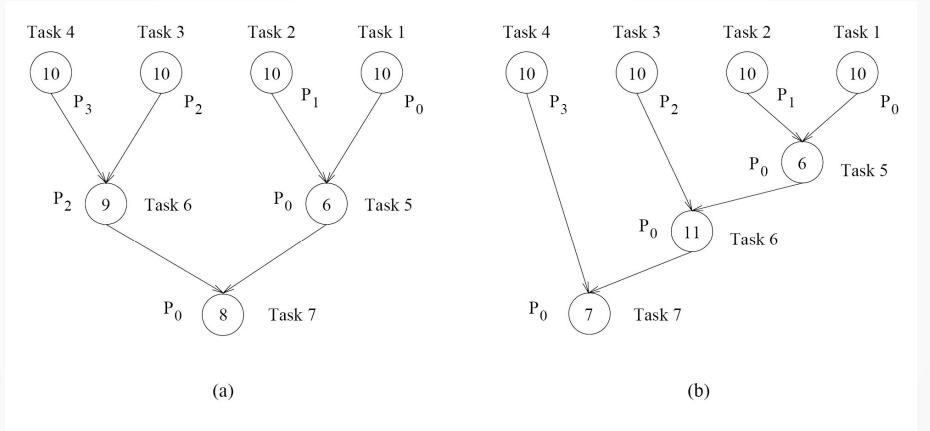


Figure 3.7 Mappings of the task graphs of Figure 3.5 onto four processes.

Processes and Processors

- Processes are logical computing agents that perform tasks
- Processors are the hardware units that physically perform computations
- Depending on the problem, multiple processes can be mapped on a single processor
- But, in most of the cases, there is one-to-one correspondence between processors and processes
- So, we assume that there are as many processes as the number of physical CPUs on the parallel computer

Questions



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References

- 1. Kumar, V., Grama, A., Gupta, A., & Karypis, G. (1994). *Introduction to parallel computing* (Vol. 110). Redwood City, CA: Benjamin/Cummings.
- 2. Quinn, M. J. Parallel Programming in C with MPI and OpenMP,(2003).