



# DATA ANALYSIS AND VISUALIZATION

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# IMAGE PROCESSING

## INTRODUCTION

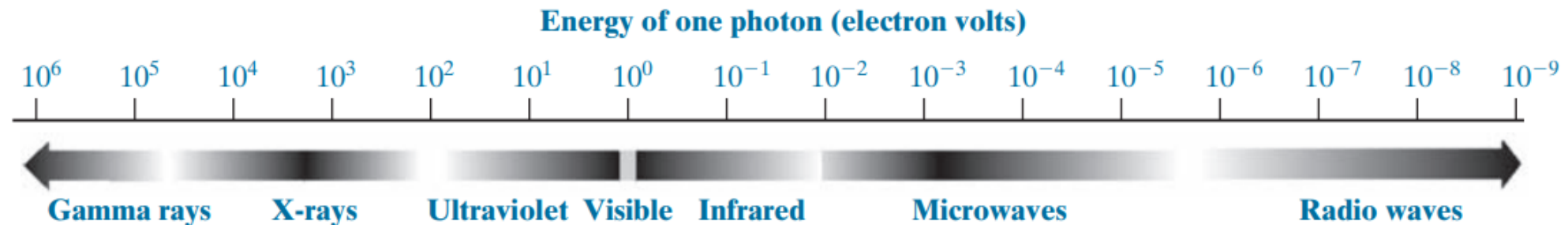


# WHAT IS IMAGE?

- It is defined as a two-dimensional function,  $\mathbf{F(x,y)}$ ,
  - where  $x$  and  $y$  are spatial coordinates.
  - the amplitude of  $\mathbf{F}$  at any pair of coordinates  $(x,y)$  is called the **intensity** of that image at that point.
- When  $x,y$ , and amplitude values of  $\mathbf{F}$  are finite, we call it a **digital image**.

# IMAGE SOURCES

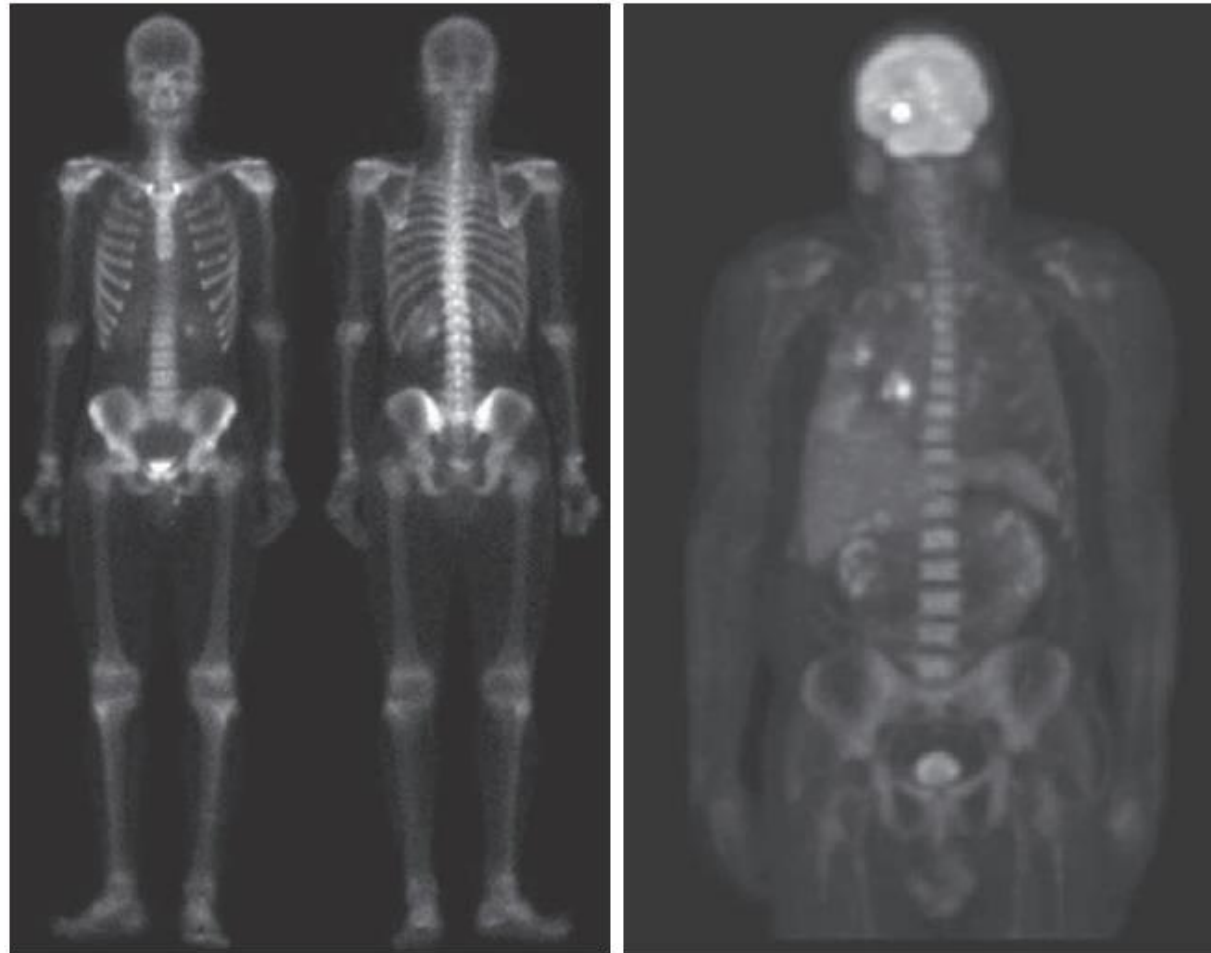
- The principal energy source for images in use today is the electromagnetic energy spectrum



- Synthetic images, used for modeling and visualization, are generated by computer

# GAMMA RAYS IMAGING

- Bone Scan
- Pet Scan



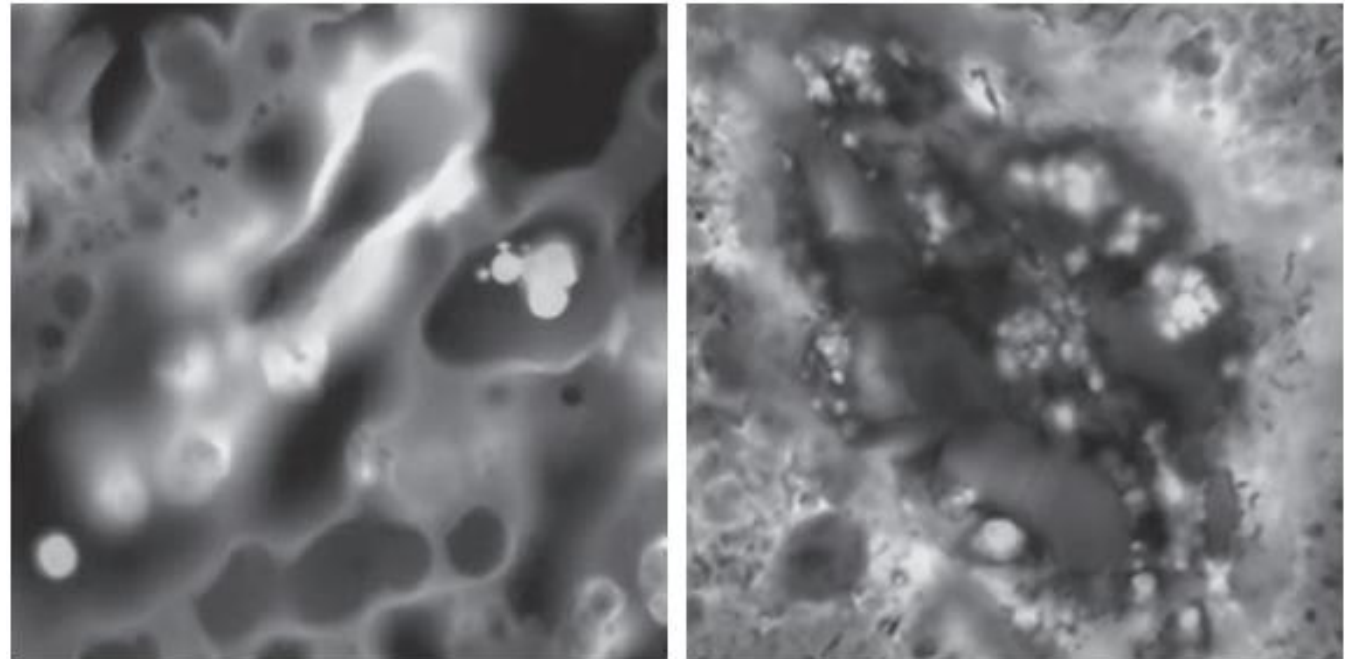
# X-RAY IMAGING

- Chest X Ray
- Head CT Scan



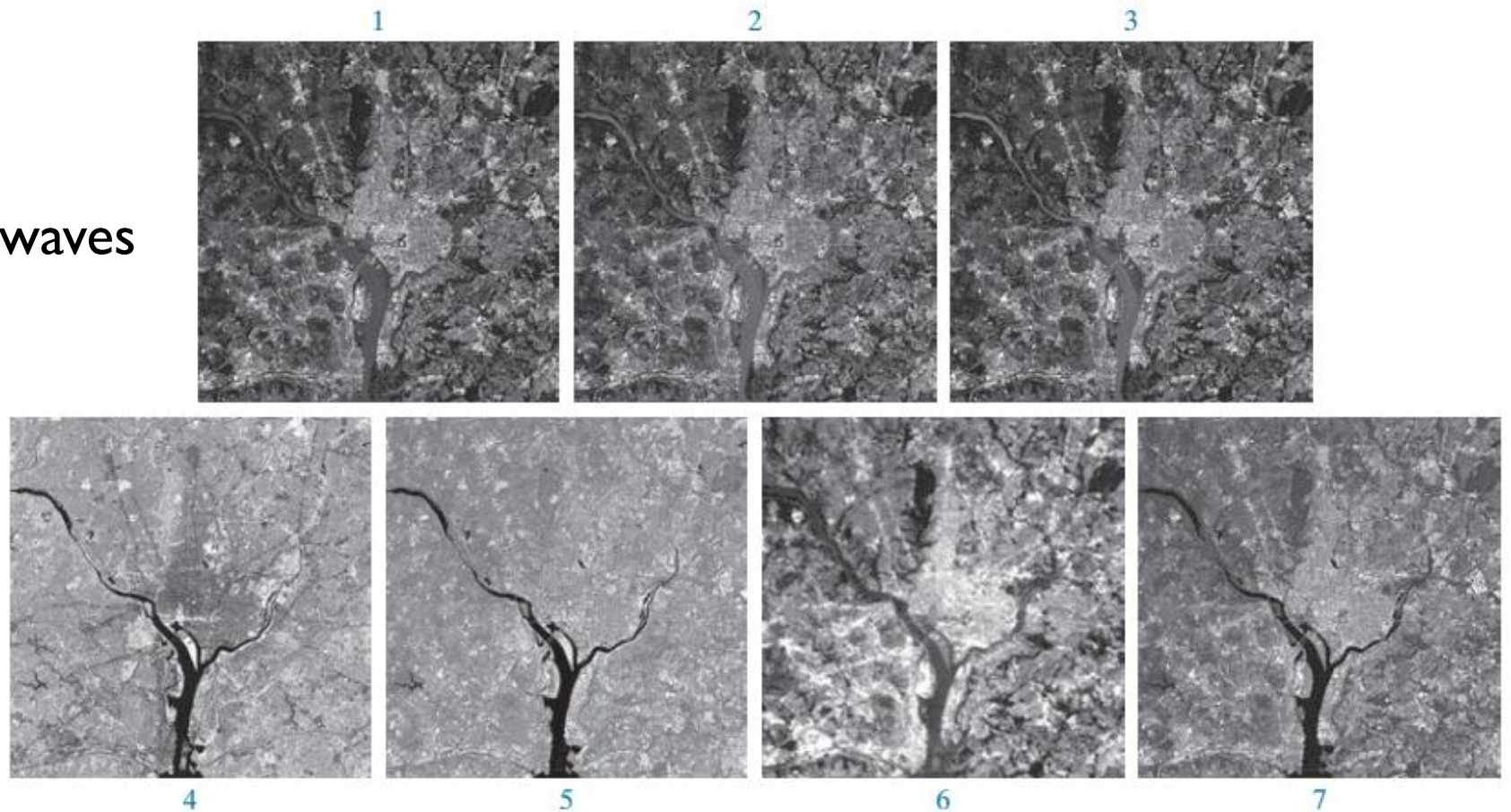
# ULTRAVIOLET IMAGING

- Fluorescence microscopy



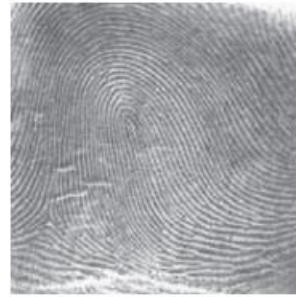
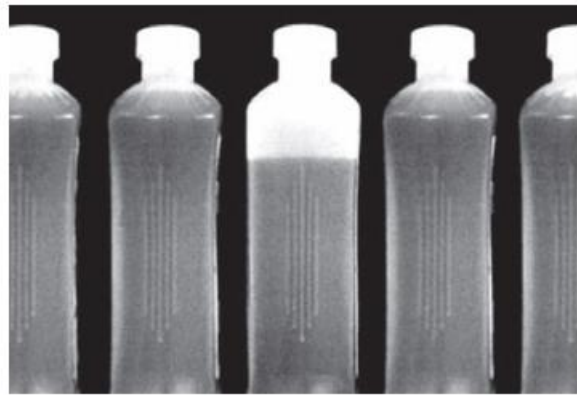
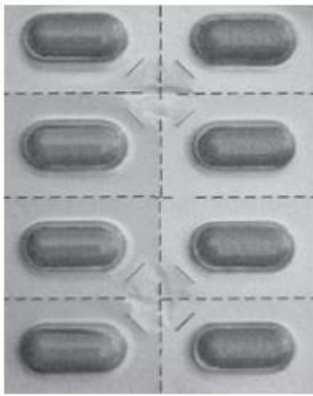
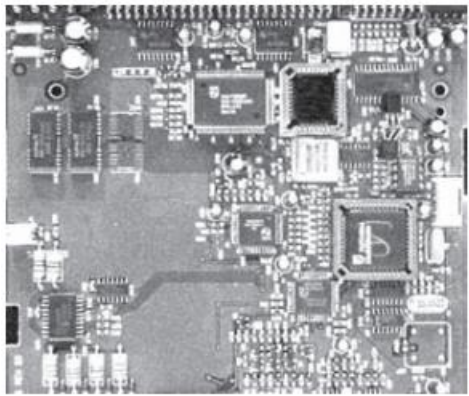
# SATELLITE IMAGES

Captured using different waves





# IMAGES OF VISIBLE SPECTRUM

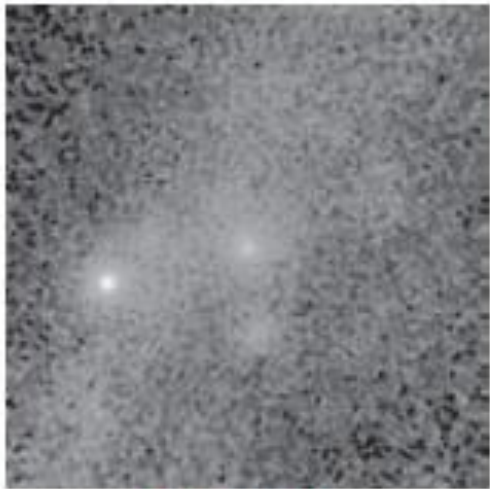


# IMAGING IN THE RADIO BAND

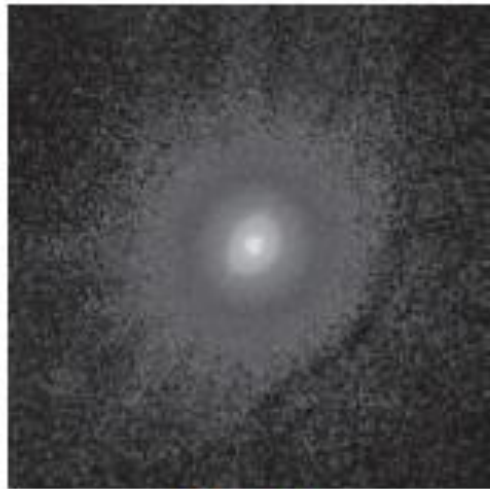
- MRI Scans (Knee, Spine)



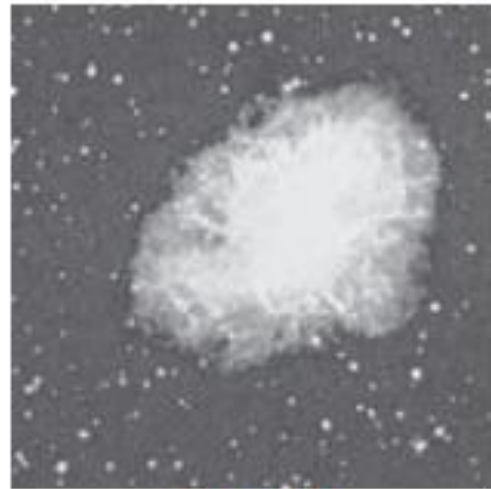
# SPACE IMAGES



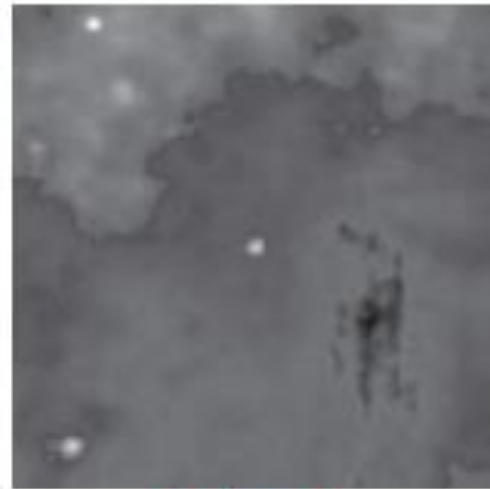
Gamma



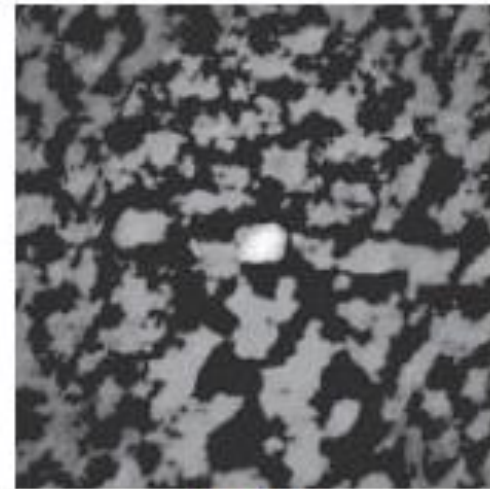
X-ray



Optical



Infrared

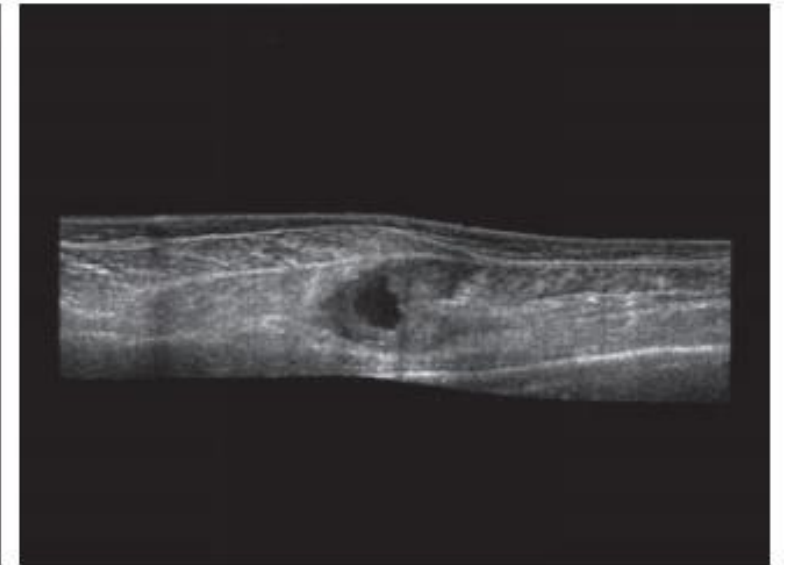
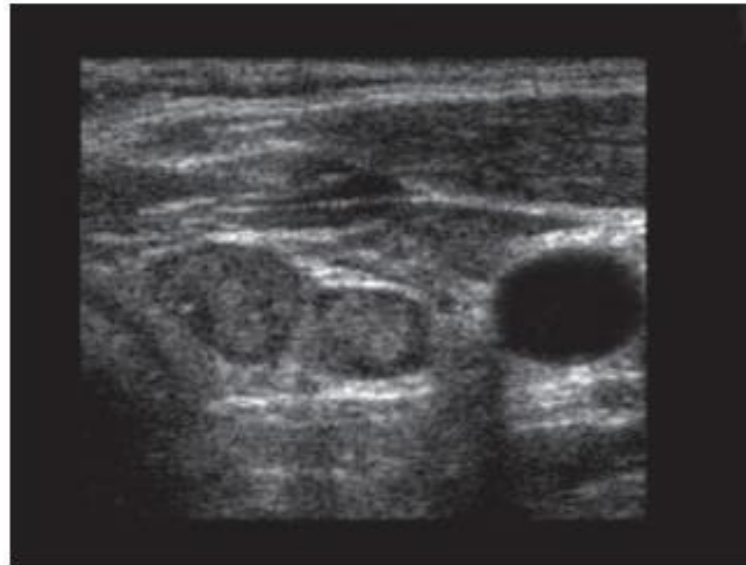


Radio

- Same star is captured using different waves.

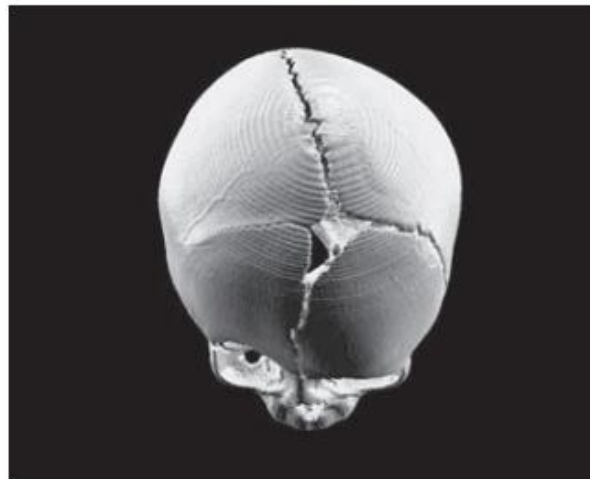
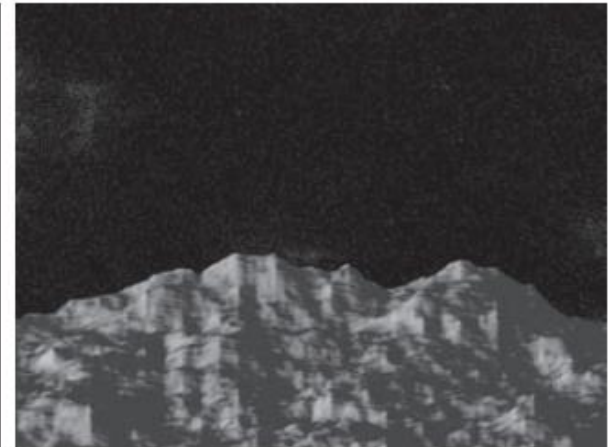
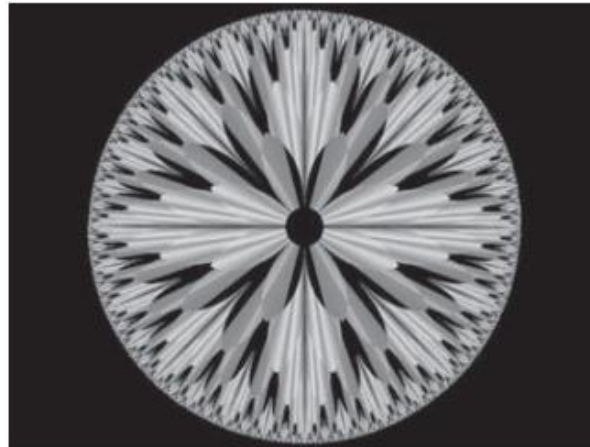
# ULTRASOUND IMAGING

- Thyroid and muscle layer



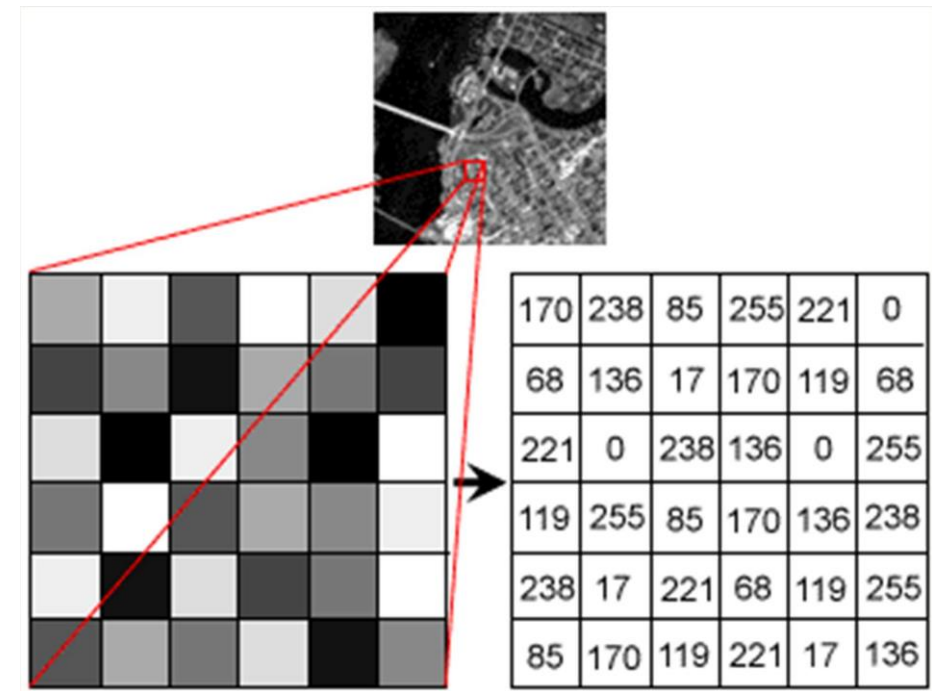
# IMAGE GENERATION BY COMPUTER

- Patterns
- 3D modeling



# PIXEL

- A digital image is composed of a finite number of elements, each of which has a particular location and value.
- These elements are called picture elements, image elements, pels, and pixels



# STEPS OF IMAGE PROCESSING

- Image acquisition
- Image enhancement
- Image restoration
- Color image processing
- Wavelets
- Compression
- Morphing
- Segmentation
- Feature extraction
- Image pattern classification



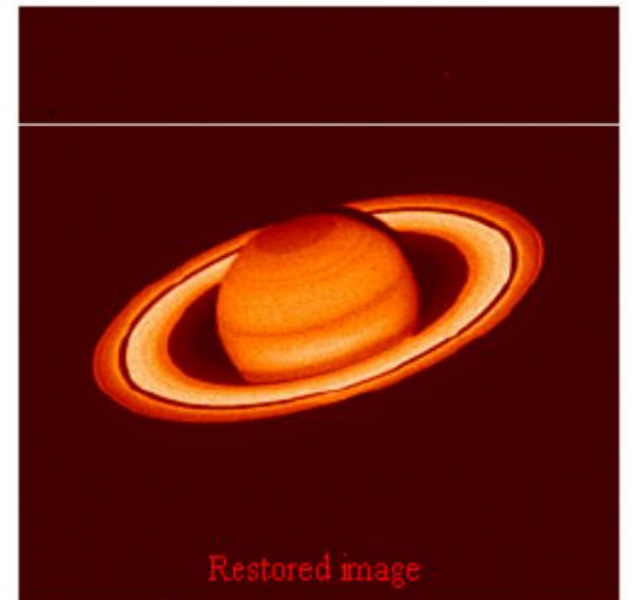
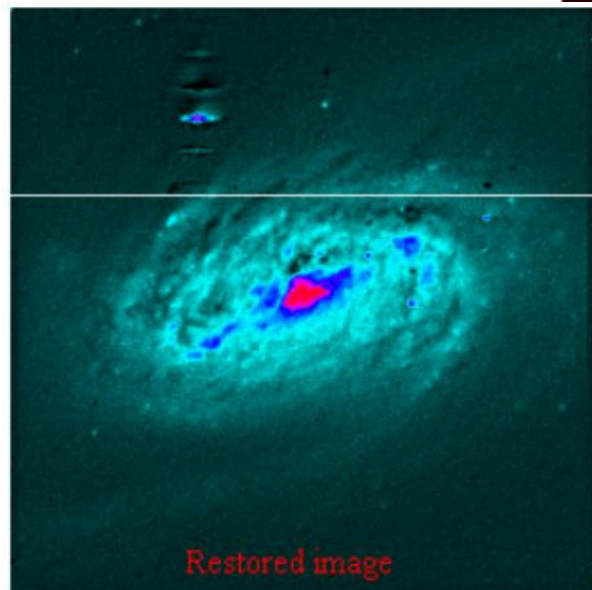
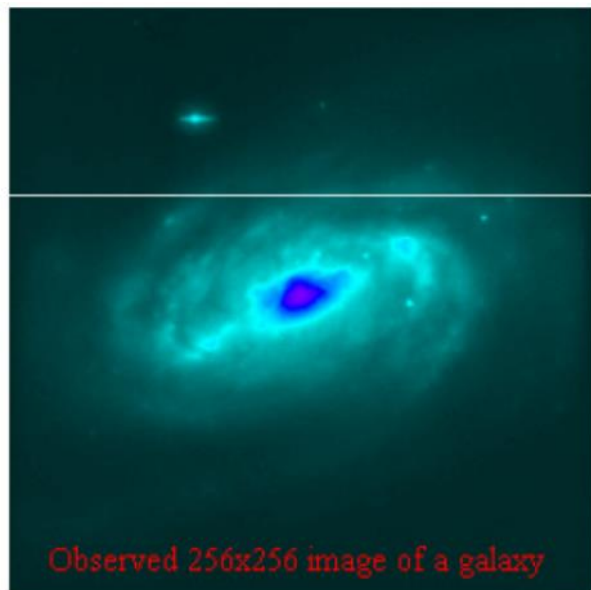
# EXAMPLES

- Image Enhancement

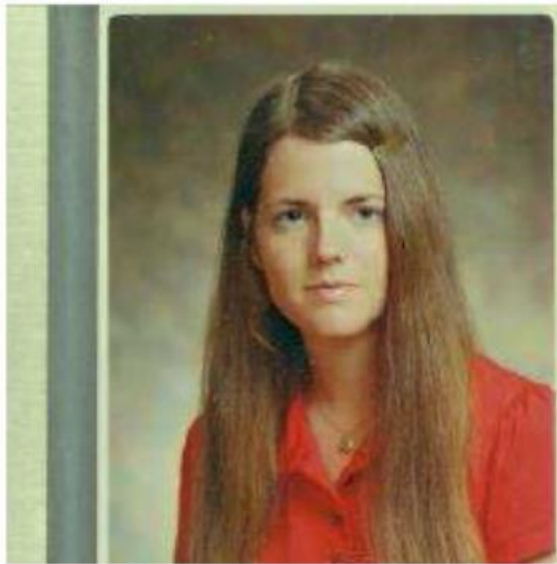




# RESTORATION



# RESTORATION



Original Image

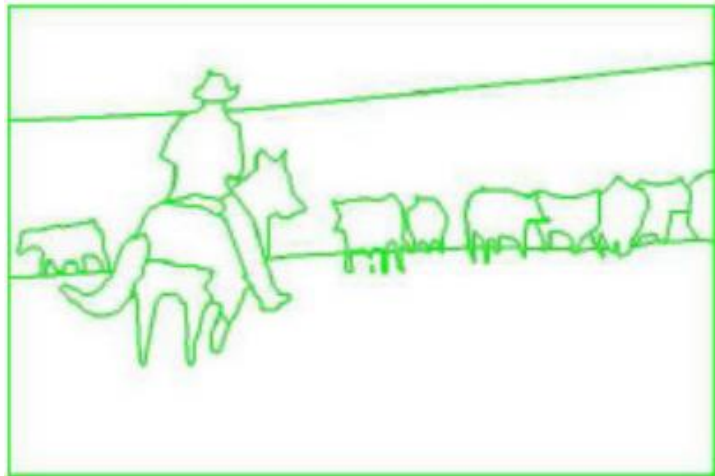


Degraded Image



Restored Image<sup>16</sup>

# SEGMENTATION



# WHY IMAGE PROCESSING

- To facilitate storage and transmission
  - Compression, quality
  - Prepare images for display or printing
- Enhancement and restoration
  - Noise removal, quality, sharpness
- Extract information from images
  - Image understanding
  - Comparison of images to find changes

# RESOLUTION

- Resolution is a common term used with images
- The resolution can be defined in many ways.
  - Pixel resolution,
  - Spatial resolution,
  - Intensity resolution,
  - Spectral resolution.

# SPATIAL RESOLUTION

- Defined as the smallest observable/identifiable detail in an image
- Spatial resolution refers to clarity
- For image clarity comparison, images have to be of the same size
- As spatial resolution reduces, image size also reduces
- Different devices, different measure
  - Dots per inch (DPI) - usually used in monitors.
  - Lines per inch (LPI) - usually used in laser printers.
  - Pixels per inch (PPI) is measure for different devices such as tablets , Mobile phones etc.

# PIXEL RESOLUTION

- Resolution refers to the number of pixels in an image.
- Resolution is sometimes identified by
  - The width and height of the image as well as
  - The total number of pixels in the image
- An image that is 2048 pixels wide and 1536 pixels high (2048 x 1536) contains 3,145,728 pixels (or 3.1 Megapixels).

# RESOLUTION UNITS

- Resolution is the number of pixels in a linear Resolution inch (i.e. pixels per inch or ppi).
- The more pixels per inch (ppi), the higher your image resolution will be.
- Resolution of an image display device or Resolution printing device is described in dots per inch (dpi).



# HOW DOES RESOLUTION PLAY OUT ON COMPUTER SCREEN

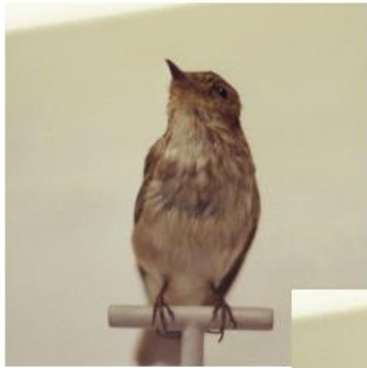
- If your monitor is set to 800 x 600 and
  - You open up an image that is 640 x 480
  - It will only fill up a part of your screen.
- 
- What if you open up an image that is 2048 x 1536?
  - You will find yourself moving the slider bar around to see all the different parts of the image.

## PRINTING SIZE

- You have a 640 x 480 image and
- You want to print it at 200 dpi (dots or pixels per inch).
- What will be the size of the printed image?
- $640 / 200 = 3.2$  and
- $480 / 200 = 2.4$
- So, the size of the printed image is 3.2" x 2.4"

# IMAGES AT DIFFERENT RESOLUTION

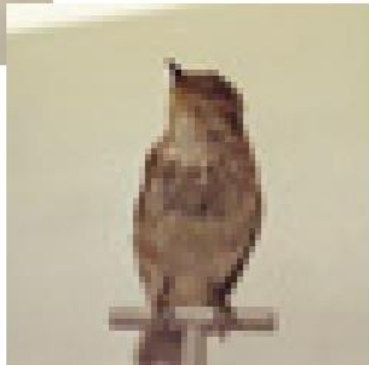
2 inches



300 PPI / 600 x 600 pixel dimension



72 PPI / 144 x 144 pixel dimension



30 PPI / 60 x 60 pixel dimension

# CHARACTER SCANNER AT DIFFERENT RESOLUTIONS

*abcde*

200 dpi

*abcde*

300 dpi

*abcde*

600 dpi

# INTENSITY RESOLUTION

- Intensity/gray-level resolution can be defined as the smallest identifiable change in intensity level.
- image size constant at 452 X 374 pixels
- Decreasing the gray-level resolution of a digital image may result in what is known as false contouring

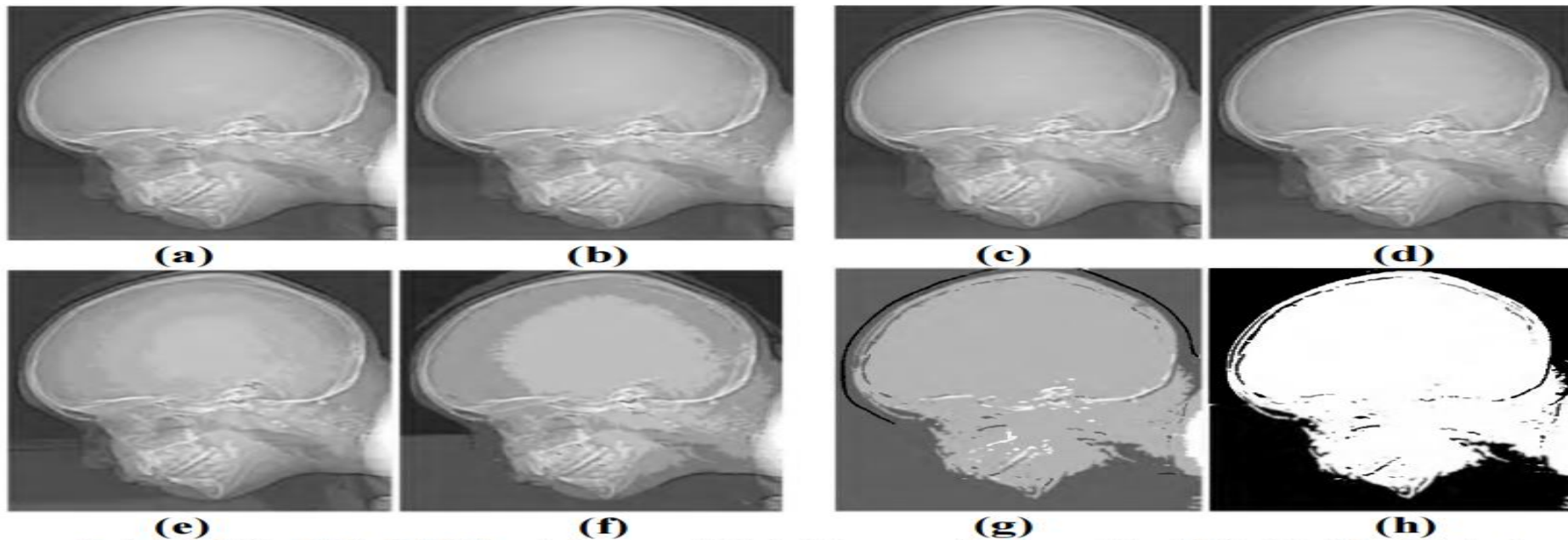


Figure 2.6 (a) 452×374, 256-level image. (b)-(h) Image displayed in 128, 64, 32, 16, 8, 4, and 2 gray levels, while keeping the spatial resolution constant.

## BIT DEPTH

- The number of bits used to define a pixel.
- The greater the bit depth, the greater the number of tones that can be represented.
- For example, an image with a bit depth of 1 has pixels with two possible values.
- An image with a bit depth of 8 has  $2^8$ , or 256, possible values.

# TYPES OF IMAGES

- Binary Images
- Gray-scale images
- Color images

# 1 BIT IMAGE/BINARY

- Each pixel consist of only 0/1 information
- Called 1-bit monochrome (since no color) image
- Suitable for simple graphics & text
- How much storage is required for a monochrome image of resolution  $640 \times 480$ ?



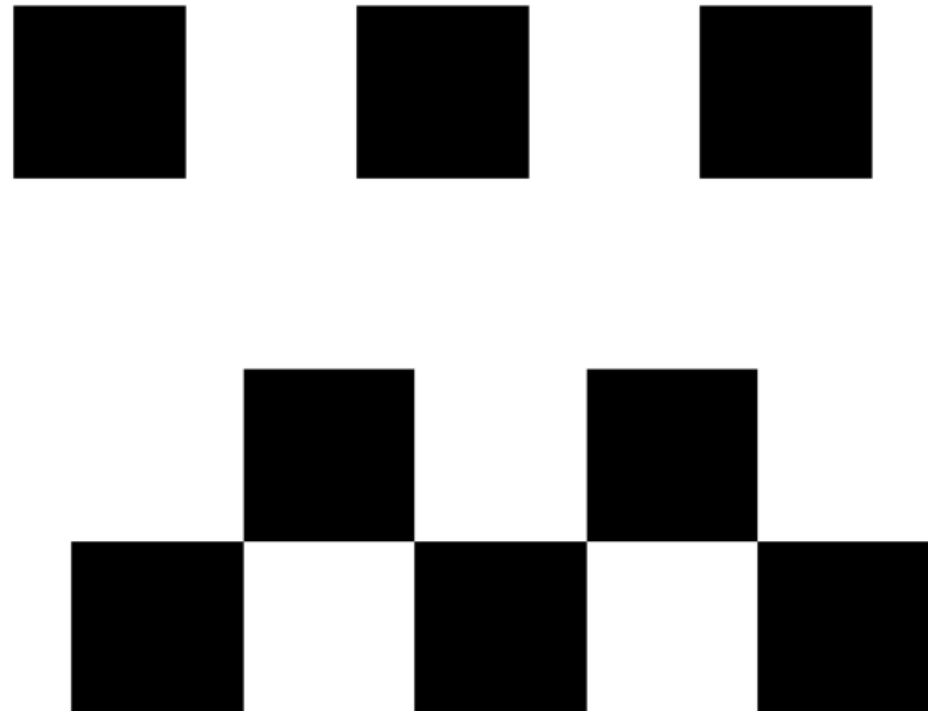


# BINARY IMAGES

■  $x = [0 \ 1 \ 0 \ 1 \ 0]$

■  $x =$

1	0	1	0	1
0	1	0	1	0



## 8 BIT IMAGE (GRAYSCALE)

- Each pixel is represented by a single byte.
- Gray levels between 0 to 255 (black to white).
- How much storage is required for a grayscale image of resolution 640 x 480?



256 gray levels (8bits/pixel)



32 gray levels (5 bits/pixel)



16 gray levels (4 bits/pixel)



8 gray levels (3bits/pixel)



4 gray levels (2bits/pixel)



2 gray levels (1 bit/pixel)

# COLOR IMAGES

- The two most common ways of storing color image contents are
  - 1) RGB representation (24 bit image)
  - 2) Indexed representation (8 bit image)

# COLOR IMAGE

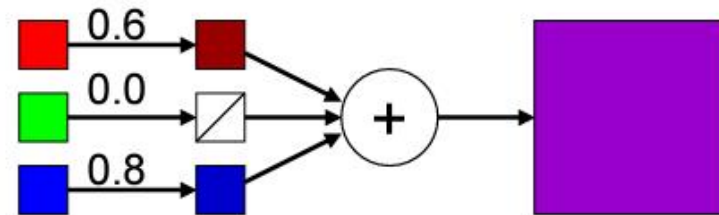
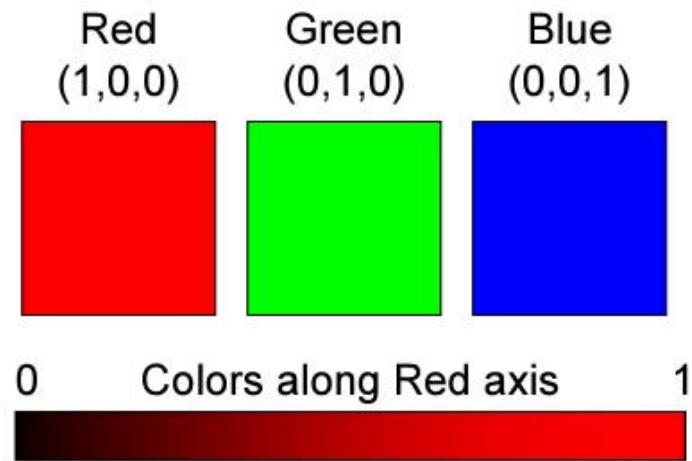
- 24-bit color image
- Each pixel is represented by 3 bytes, RGB
  - Each R, G, B are in the range 0-255
  - $256 \times 256 \times 256$  possible colors



Example of 24-Bit Colors Image

- What is the size (in kB) of a 24-bit, 640 x 480 color image?

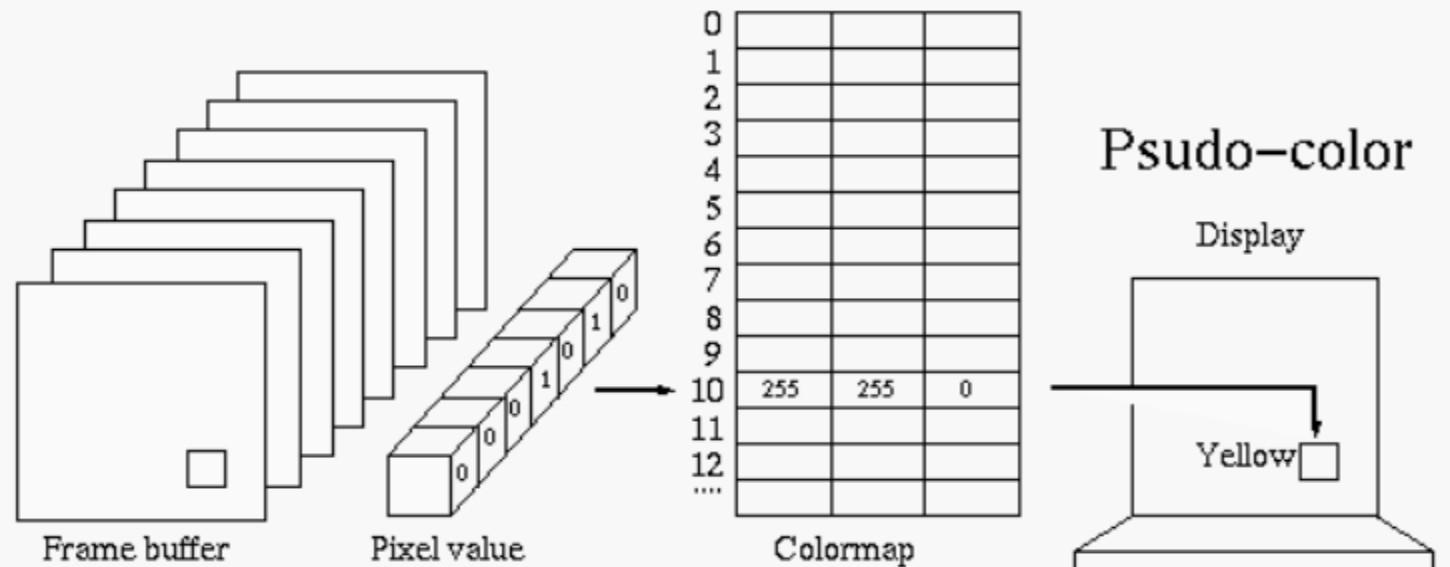
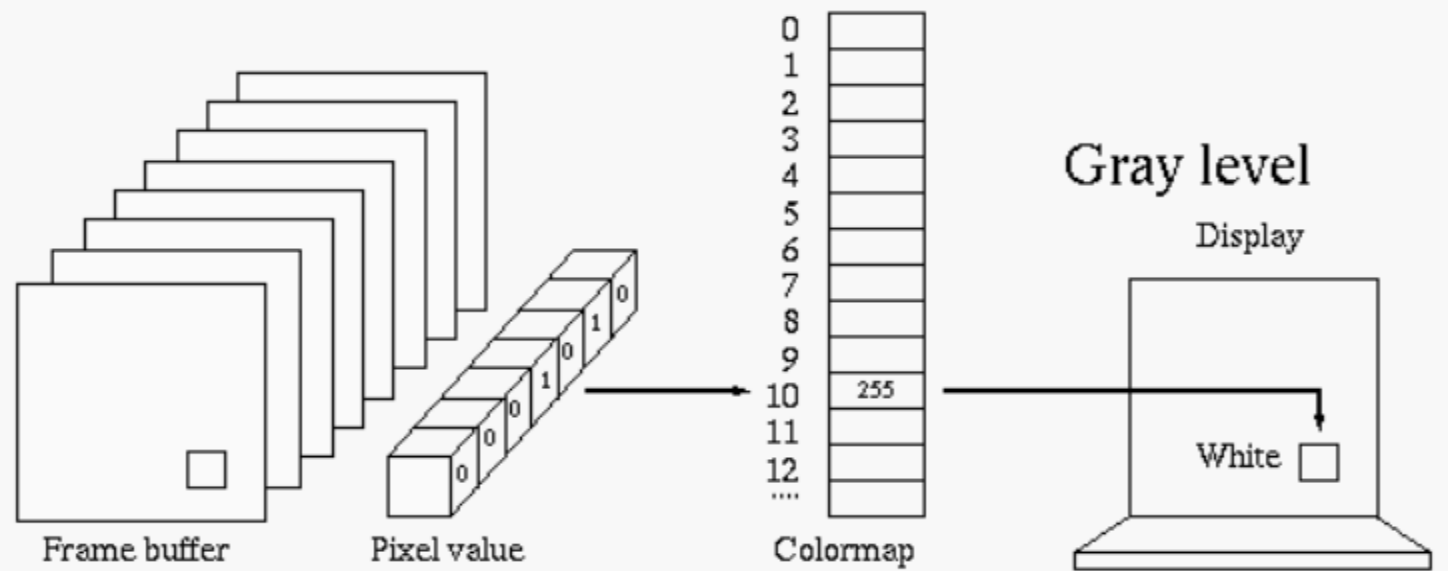
# COLOR IMAGE



## 8 BIT COLOR IMAGE

- 8- bit color image
  - Carefully chosen 256 colors represent the image
  - stores only the index of the color, the file header will contain the mapping information.
  - The mapping is performed using the color lookup table (LUT).
- What is the size (in kB) of a 8-bit, 640 x 480 color image?

# COLOR LOOK UP TABLE





# RGB TO GREY-SCALE IMAGE CONVERSION

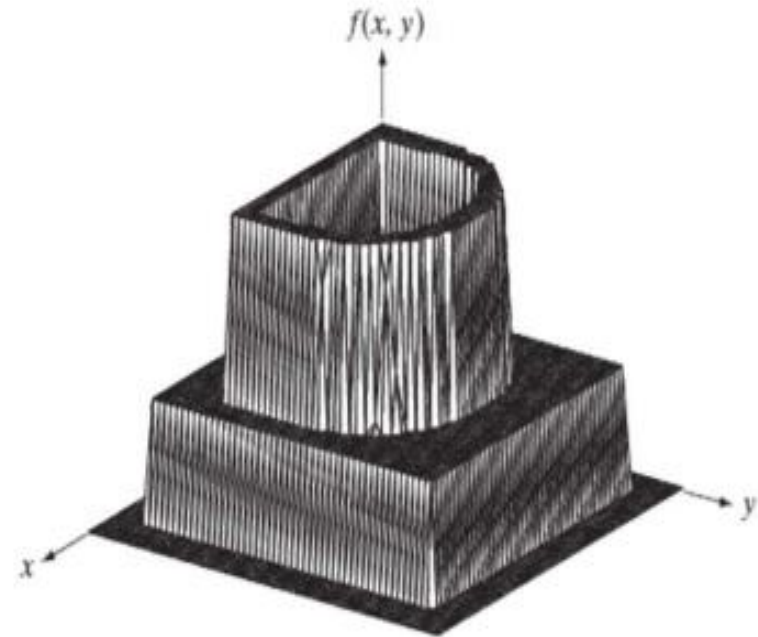
- Can convert from an RGB colour space to a grey-scale image
- Grey-scale conversion is the initial step in many image analysis algorithms
  - simplifies (i.e. reduces) the amount of information in the image.
- Grey-scale image contains less information than a colour image, the majority of important, feature related information is maintained, such as edges, regions, blobs, junctions and so on.
- An RGB colour image can converted to grey scale

$$I_{\text{grey-scale}}(n, m) = \alpha I_{\text{colour}}(n, m, r) + \beta I_{\text{colour}}(n, m, g) + \gamma I_{\text{colour}}(n, m, b)$$

- Conversion is a noninvertible transformation

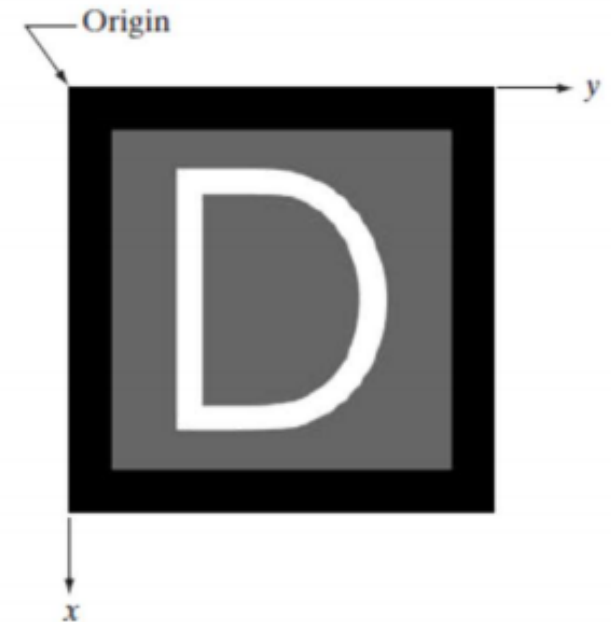
# REPRESENTING DIGITAL IMAGES

- Basic ways to represent  $f(x, y)$ :
- Image plotted as a surface
  - First method is a plot of the function  $f(x, y)$ , with two axes determining spatial location and the third axis being the values of  $f$  (intensities) as a function of the



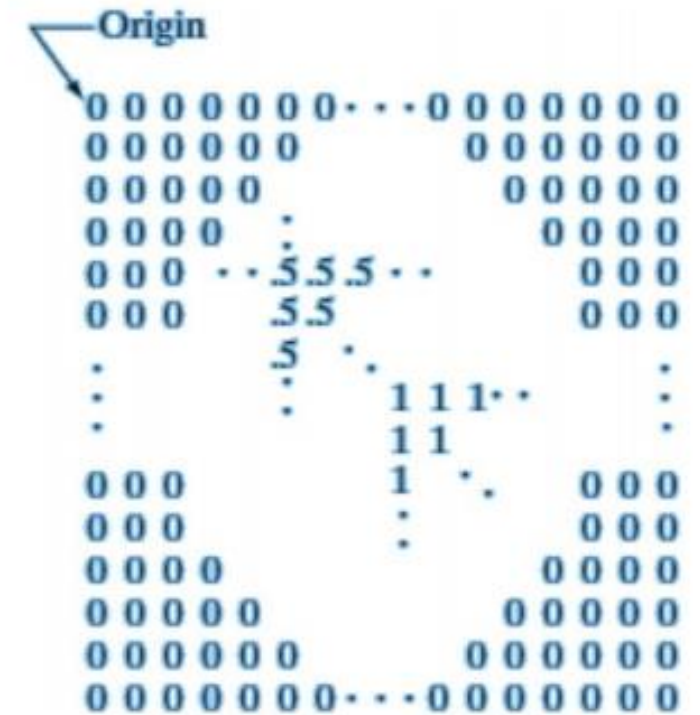
# REPRESENTING DIGITAL IMAGES

- Image as a visual intensity
- In this figure, there are only three equally spaced intensity values.
- If the intensity is normalized to the interval  $[0, 1]$ , then each point in the image has the value 0, 0.5, or 1.
- • A monitor or printer simply converts these three values to black, gray, or white, respectively



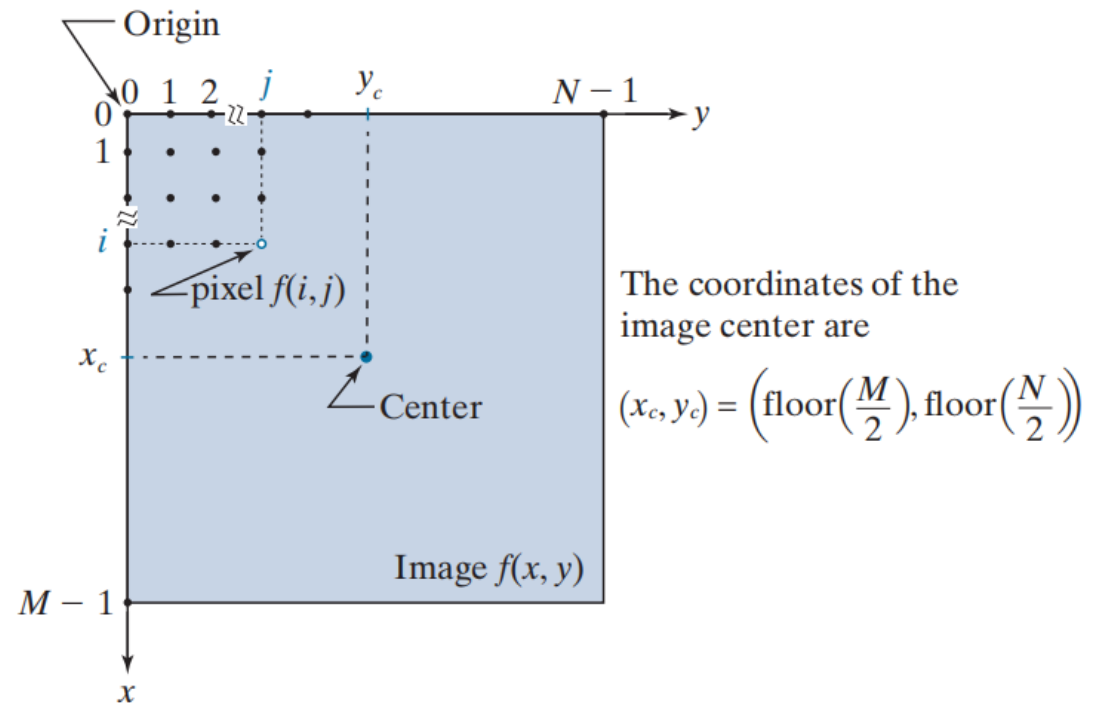
# REPRESENTING DIGITAL IMAGES

- Image shown as a 2-D numerical array
- In this example,  $f$  is of size 600 X 600 elements, or 360,000 numbers
- Image displays allow us to view results at a glance and Numerical arrays are used for processing and algorithm development



# REPRESENTING DIGITAL IMAGES

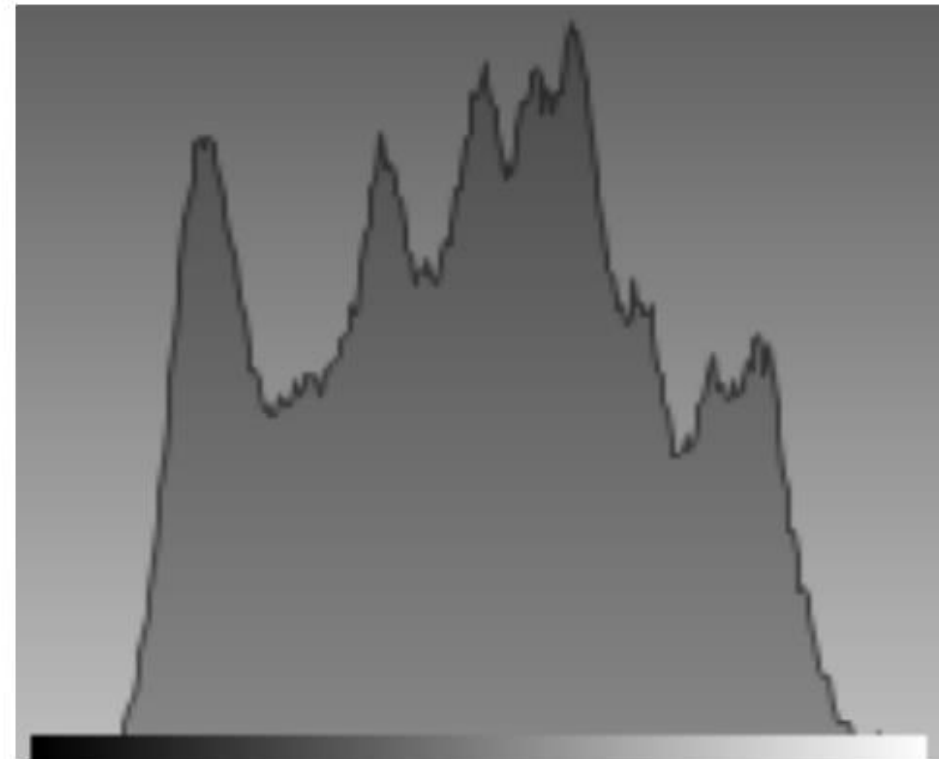
- Coordinate convention to represent digital image



# IMAGE HISTOGRAM

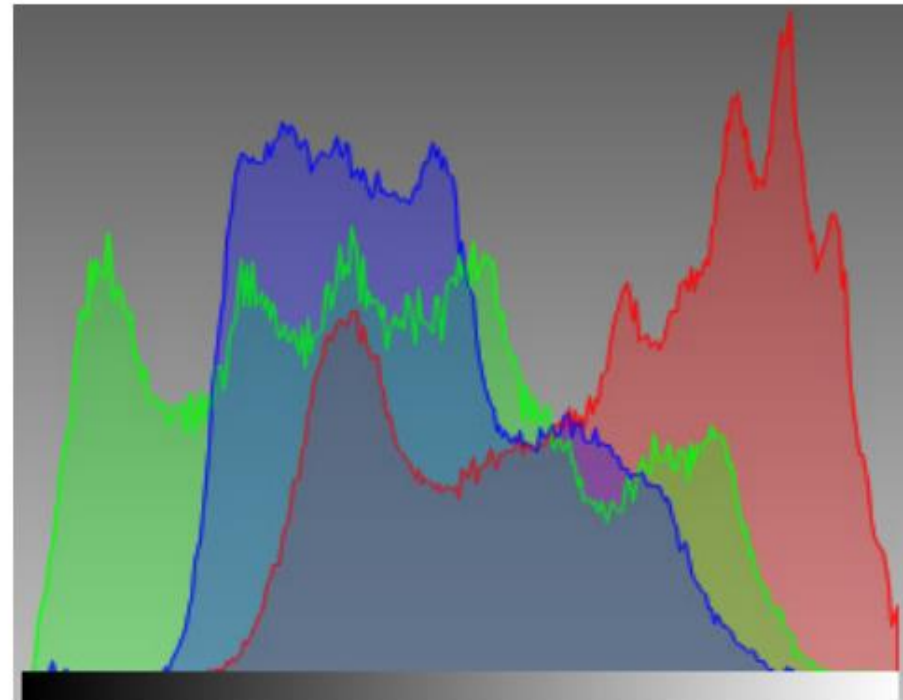
- Histogram which acts as a graphical representation of the tonal distribution in a digital image.
- It plots the number of pixels for each tonal value.
- It can be used to judge the entire tonal distribution of an image at a glance.

# IMAGE HISTOGRAM



Histogram of Lena's grayscale image

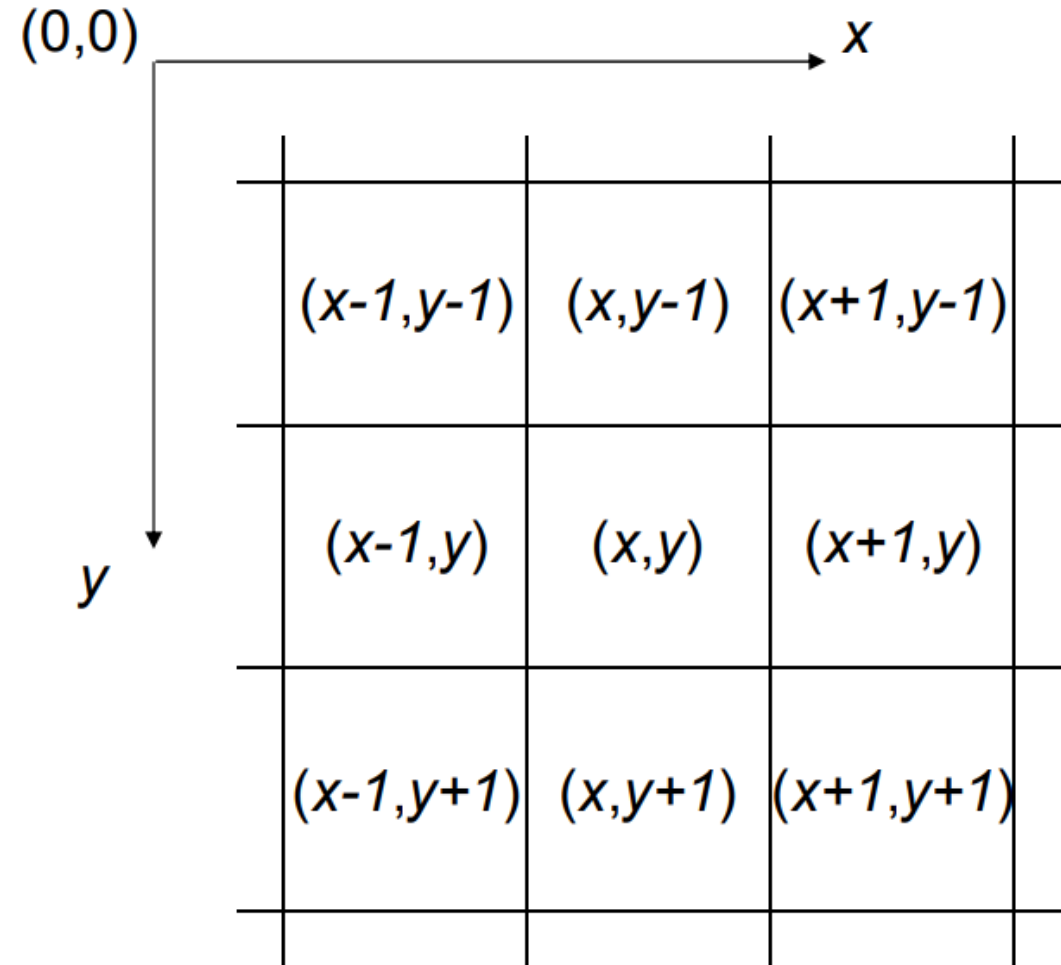
# IMAGE HISTOGRAM



Histogram of Lena's colored image



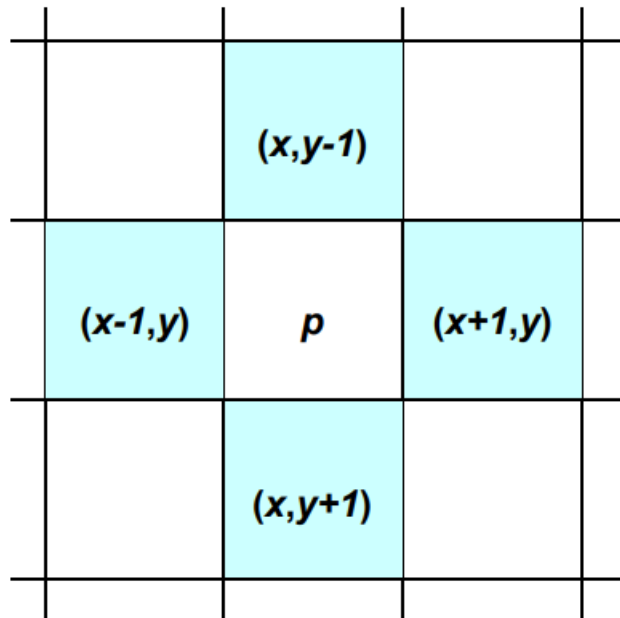
# RELATIONSHIP BETWEEN PIXELS



Conventional indexing method

## NEIGHBORS OF A PIXEL

- Neighborhood relation is used to tell adjacent pixels. It is useful for analyzing regions.

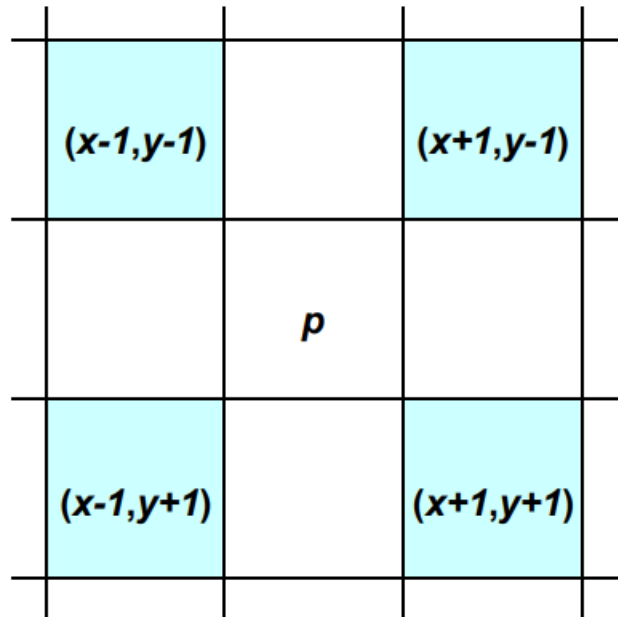


**4-neighbors of  $p$ :**

$$N_4(p) = \left\{ \begin{array}{l} (x-1, y) \\ (x+1, y) \\ (x, y-1) \\ (x, y+1) \end{array} \right\}$$

- 4-neighborhood relation considers only vertical and horizontal neighbors.

## NEIGHBORS OF A PIXEL



**Diagonal neighbors of  $p$ :**

$$N_D(p) = \left\{ \begin{array}{l} (x-1, y-1) \\ (x+1, y-1) \\ (x-1, y+1) \\ (x+1, y+1) \end{array} \right\}$$

Diagonal-neighborhood relation considers only diagonal neighbor pixels.

## NEIGHBORS OF A PIXEL

$(x-1, y-1)$	$(x, y-1)$	$(x+1, y-1)$
$(x-1, y)$	$p$	$(x+1, y)$
$(x-1, y+1)$	$(x, y+1)$	$(x+1, y+1)$

**8-neighbors of  $p$ :**

$$N_8(p) = \left\{ \begin{array}{l} (x-1, y-1) \\ (x, y-1) \\ (x+1, y-1) \\ (x-1, y) \\ (x+1, y) \\ (x-1, y+1) \\ (x, y+1) \\ (x+1, y+1) \end{array} \right\}$$

8-neighborhood relation considers all neighbor pixels.

# SPATIAL OPERATIONS

- Spatial operations are performed directly on the pixels of an image.
  - Single pixel operations
  - Neighborhood operations
  - Geometric spatial transformations

## SINGLE-PIXEL OPERATIONS

- Alter the intensity of an image's pixels individually using a transformation function.

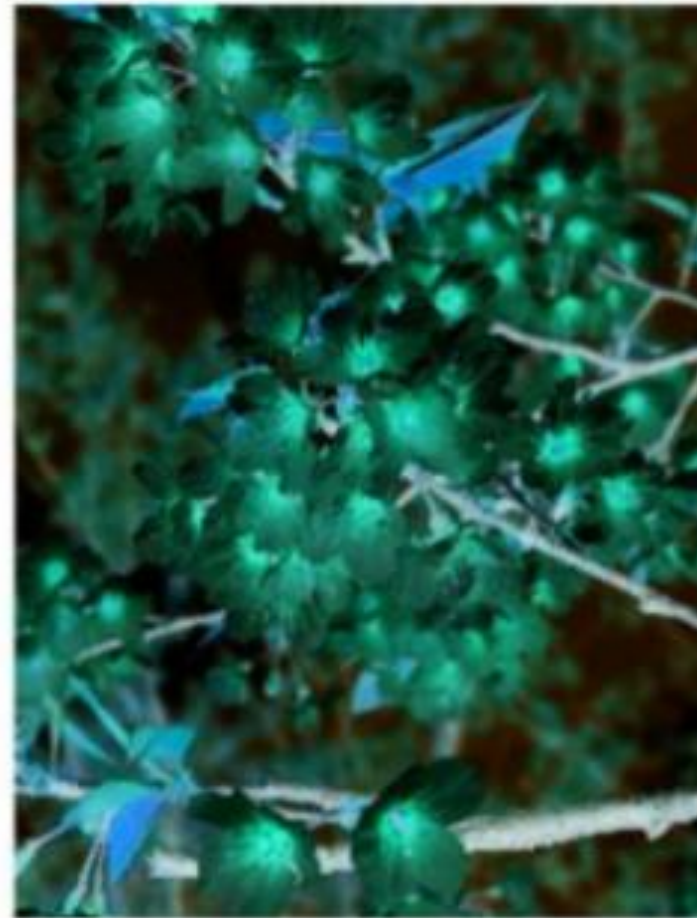
$$s = T(z)$$

# EXAMPLE

**Original image**



**Negative Image**



# NEIGHBORHOOD OPERATIONS

- Neighborhood processing generates a corresponding pixel at the same coordinates in an output image, such that the value of that pixel is determined by a specified operation on the neighborhood of pixels in the input image.

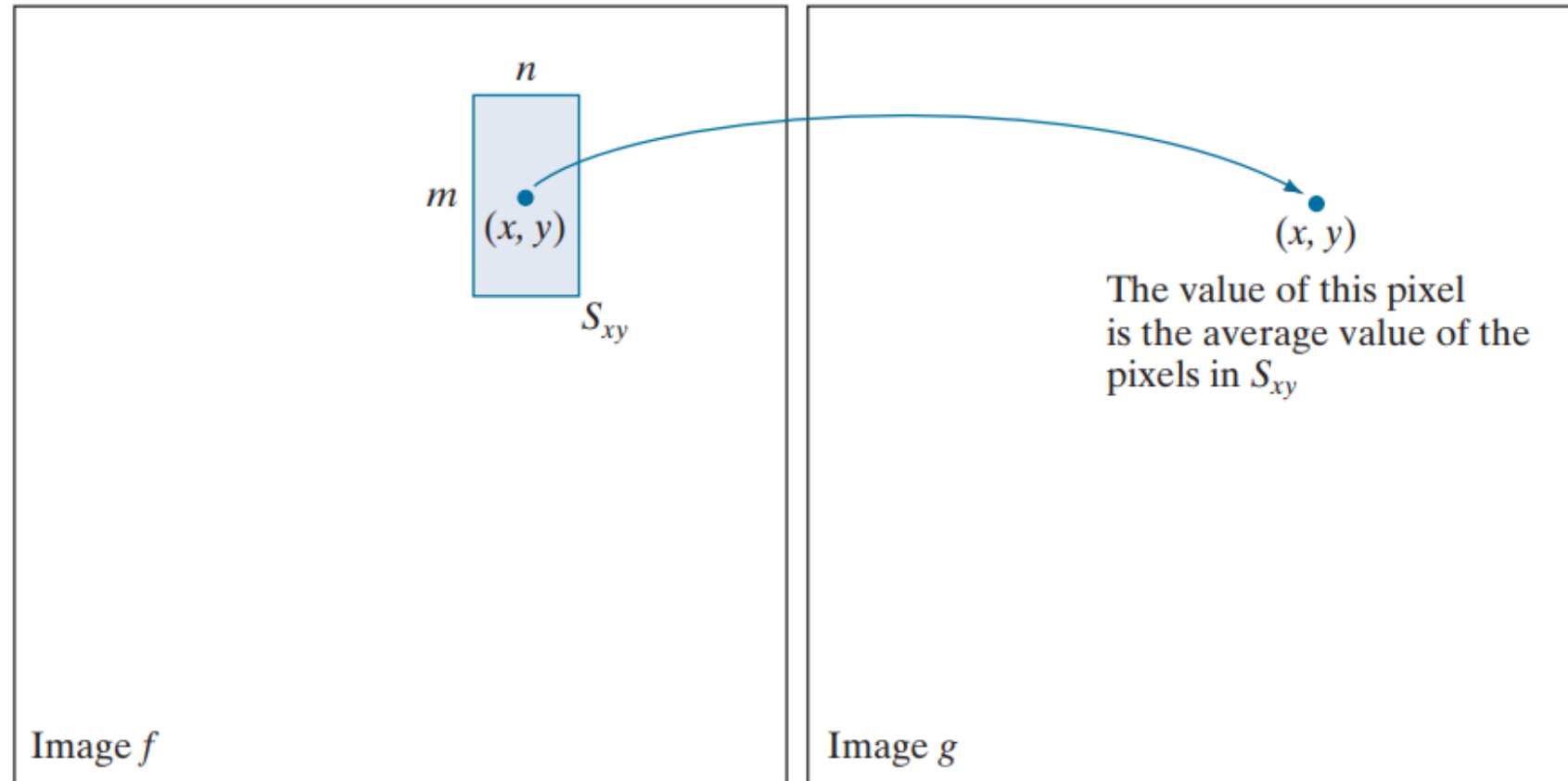


# EXAMPLE

## ■ Averaging Operation

$$g(x, y) = \frac{1}{mn} \sum_{(r, c) \in S_{xy}} f(r, c)$$

$S_{xy}$  Represents the set of neighborhood, m and n represents rectangular size of neighborhood.



# EXAMPLE

- Blurring of an image.

