

# Equivalent Circuit Model Of Transmission Lines

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**Abstract**—This report aims to verify that transmission lines can be examined by building an equivalent model on Multisim. Lossless and lossy transmission lines are to be analyzed with different conditions. The equivalent circuit can be built using lumped parameters consisting of inductor, capacitor, resistor and Conductance.

## I. INTRODUCTION

Lossless transmission lines are ideal lines with no loss. It only consists of an inductor and a capacitor which are frequency independent. Lossy lines represent real transmission lines which consist of resistance and conductance in addition to inductor and capacitor. Various factors cause losses in a transmission line, some of which are frequency dependent.

## II. LOSSLESS AND LOSSY MODELS

### A. Extraction of Static Line Capacitance

To calculate the capacitance of the coaxial transmission line, the electric field of the structure was calculated initially[1]. The coaxial cable comprises of concentric conductors with a uniform charge density on the inner conductor which is analogous to the electric field of line charge in free space having uniform charge density. Hence, by Gauss's Law, the electric field of the structure having uniform charge density of  $\rho$ , radius  $r$  and relativity permittivity  $\epsilon_r$  is given by (1):

$$E = \frac{\rho}{2\pi\epsilon_0 \epsilon_r r} \quad (1)$$

Next, the voltage between the conductors was obtained by integrating the electric field using the limits as the radius of the conductors as shown below (2).

$$V = - \int_a^b E \cdot dl = \frac{\rho}{2\pi\epsilon_0 \epsilon_r} \ln \frac{b}{a} \quad (2)$$

Where  $b$  and  $a$  are the radiiuses of outer and inner conductors respectively. The capacitance is computed as the ratio of assumed charge to the potential difference. Thus, the capacitance of the structure is gives as (3):

$$C' = \frac{Q}{V} = \frac{2\pi\epsilon_0 \epsilon_r l}{\ln \frac{b}{a}} \quad (3)$$

Thus, the value of capacitance per unit length to be used in equivalent circuit model is given as (4):

$$C = \frac{2\pi\epsilon_0 \epsilon_r}{\ln \frac{b}{a}} \quad (4)$$

By using the values of radiiuses of inner and outer conductors and the relative permittivity as given in the coursework, the value of capacitance per unit length obtained is 66.02 pF.

### B. Extraction of Static Line Inductance

To calculate the inductance of the transmission line of inner and outer radiiuses as  $a$  and  $b$  respectively, it was assumed that a current  $I$  flowing in  $+z$  direction gives rise to a magnetic field inside the coaxial structure. Hence, by Ampere's Law, the magnetic flux is obtained as given below (5):

$$B = \frac{\mu_0 I}{2\pi\rho}, \quad a \leq \rho \leq b \quad (5)$$

Next the magnetic flux,  $\phi$ , is obtained by integrating the magnetic field using the limits as the radiiuses of the conductors as shown below (6):

$$\phi = \int_a^b B \cdot dS = \frac{\mu_0 l}{2\pi} \ln \left( \frac{b}{a} \right) \quad (6)$$

The inductance of the coaxial cable can thus be calculated as the ratio of flux to source current. Hence, the inductance of the structure is given as (7):

$$L' = \frac{\Delta\phi}{I} = \frac{\mu_0 l}{2\pi} \ln \left( \frac{b}{a} \right) \quad (7)$$

Thus, the value of capacitance per unit length to be used in equivalent circuit model is given as (9):

$$L = \frac{\mu_0}{2\pi} \ln \left( \frac{b}{a} \right) \quad (9)$$

By using the values of radiiuses of inner and outer conductors and the relative permeability as given in the coursework, the value of inductance per unit length obtained is 0.371 uH.

### C. Characteristic Impedance

The characteristic impedance of a lossless transmission line is given by (10):

$$Z_0 = \sqrt{\frac{L}{C}} \quad (10)$$

Where  $L$  and  $C$  are the inductance per unit length and capacitance per unit length respectively. By substituting  $L$  and  $C$  from sections A and B, a value of 74.94 ohm is obtained as the characteristic impedance.

### D. Time Delay and Velocity of transmission line

The time delay and velocity of the transmission line is given by (11) and (12) respectively:

$$t_{pd} = \sqrt{LC} \quad (11)$$

$$v_{pd} = \frac{1}{\sqrt{(LC)}} \quad (12)$$

Where  $L$  and  $C$  are the inductance per unit length and capacitance per unit length respectively. By substituting  $L$

and C from I and II , a value of 4.95ns and  $2.021 * 10^8$  m/s obtained as the time delay and velocity of the electromagnetic wave. Since the transmission line is 32m long, the total propagation delay is  $32 * 4.95$  ns = 158.4ns.

#### E. Equivalent Circuit Model of a lossless Line

The model has to correctly simulate a 32 m long transmission line up to 700MHz. By using the velocity of the electromagnetic wave obtained in section IV, the wavelength corresponding to 700MHz was calculated. Thus, by using (13), a value of 0.289 m was obtained as the wavelength.

$$\lambda = \frac{c}{f} \quad (13)$$

A cable is classified as electrically long cable if the length of the cable is greater than one-tenth of the wavelength. As the length of the cable is 32m and the value of one-tenth of the wavelength is 0.0289m, it can be concluded that the cable is electrically long.

In order to simulate an electrically long cable, we need to divide the electrically long cable into a series of electrically short cables of length  $\Delta x$  such that (14):

$$\Delta x \leq \frac{\lambda}{10} < l, l = 32\text{m} \quad (14)$$

Hence, I have assumed  $\Delta x = 0.0289$  m (one -tenth the value of wavelength).  $\Delta x$  corresponds to one segment of transmission line as shown in fig.1.

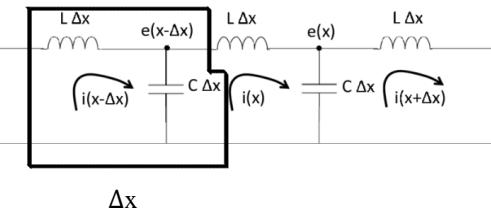


Fig.1. Example of  $\Delta x$  segment of a transmission line.

The value of capacitance and inductance per unit length are 66.02 pF and 0.371 uH as per sections A and B. respectively. I have hence divided the 32 m transmission line into 32 segments of 1 m each. The length of each segment comprising of a capacitor and inductor in 1m line is of  $\Delta x$  m. The number of  $\Delta x$  segments to be used in 1 m are  $34 = \frac{1\text{m}}{0.0289\text{ m}} = 34$ . The value of capacitance of  $\Delta x$  network is 1.942pF and the inductance of  $\Delta x$  network is 10.9nH as per fig .  $\Delta x$  network with the calculated values of parameters is shown in fig.2.

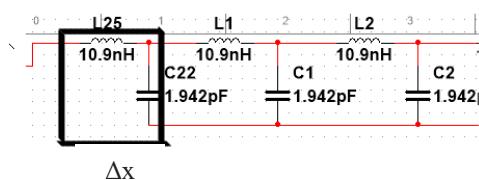


Fig.2.  $\Delta x$  segment of transmission line with scaled values of Inductance and capacitance

The 1m transmission line is shown in fig.3.

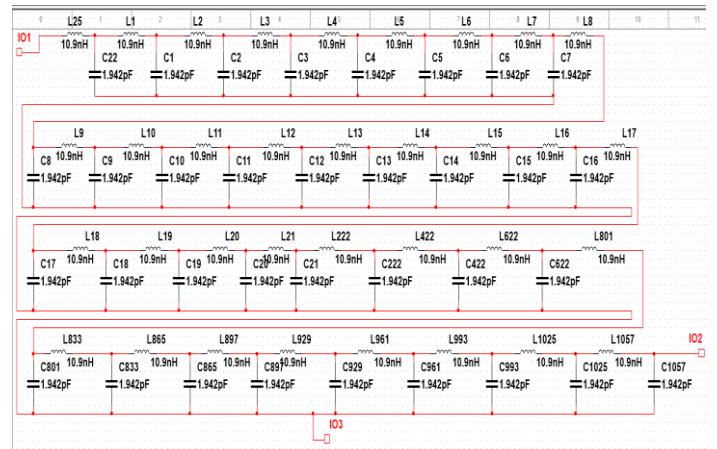


Fig.3. 1m transmission line.

32 blocks of 1m have been cascaded together to constitute for a 32m long coaxial transmission line. A resistor equivalent to characteristic impedance has been attached in series next to the source to account for internal resistance of the source. The equivalent circuit model has been shown in fig.4.

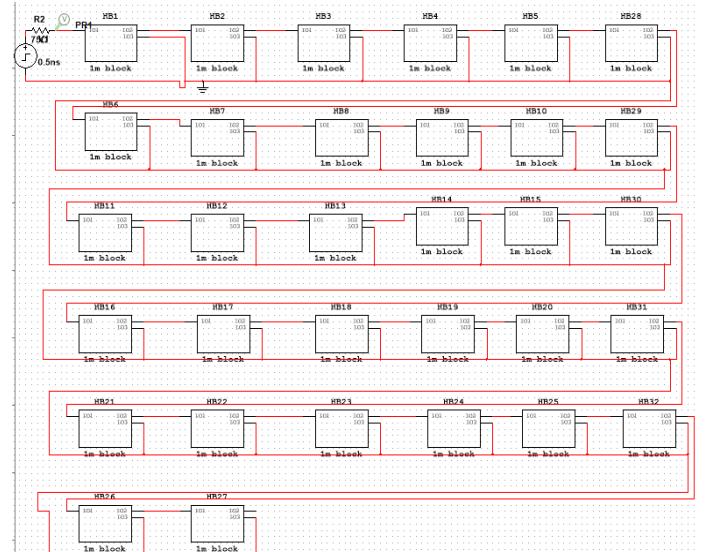


Fig.4. 32m transmission line made of 1m blocks

A similar approach was followed to setup the Multisim TL model. Internal resistance of the source and the characteristic impedance of the transmission line has been specified to construct the equivalent model. Since the transmission line is 32m long, the total propagation delay through the line is  $32 * 4.95$  ns = 158.4ns which has also been considered while constructing the TL model. The equivalent Multisim TL model is shown in fig.5.

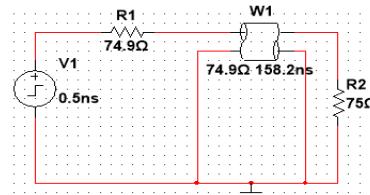


Fig.5. TL model of a lossless line with  $75\Omega$  load

### F. Time Domain Analysis of lossless circuit under Step Voltage Excitation

#### a) 75-ohm load

The initial input voltage,  $V_{in}$ , is 2.5V when  $Z_L = Z_0$ . The output/load voltage,  $V_{out}$  is zero initially due to the propagation delay of the signal through the transmission line. The signal takes 158.4ns to reach from the source to the load. Since the load is matched to  $Z_0$ , the reflection coefficient at the load,  $\Gamma_L$  is almost 0 and therefore the signal is not reflected. Hence,  $V_{out}=V_{in}$  for matched Transmission line. Since no reflection occurs,  $V_{in}$  remains the same. Steady state is achieved at 158.4 ns where  $V_{out}=V_{in}$ , 2.5V. The transient response of matched transmission line is shown in fig.6.

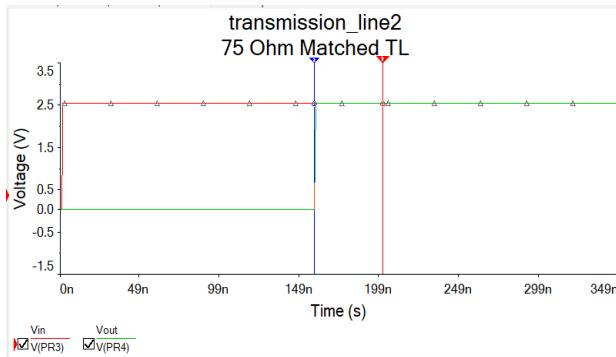


Fig.6. Transient response for Matched Transmission line,  $Z_L = Z_0$ .  $V_{out} = V_{in}$  at 158.4ns.

#### b) Open Circuit Load

At  $t=0$ ,  $Z_{in}=Z_0$ . Therefore, the incident wave,  $V_{in}$  has an amplitude of 2.5V. For  $t < 158.4$  ns,  $V_{out}=0$ . For open circuit load  $Z_L = \infty$ . Thus, from (15),  $\Gamma_L = 1$  at the load which accounts for 0 phase angle difference of reflected wave as compared to the incident wave. Thus, at  $t > 158.4$  ns, the incident wave and reflected wave superimpose each other and  $V_{out} = 2 * V_{in} = 5V$ . At  $t = \frac{2l}{v_p} = 316.68$  ns, the reflected wave reaches back to the source, superimposing the incident wave at the source making  $V_{in} = 5V$ . Current is very small for open circuit. The transient response of open circuit is show in fig.7.

$$\Gamma = \frac{Z_L - Z_0}{Z_L + Z_0} \quad (15)$$

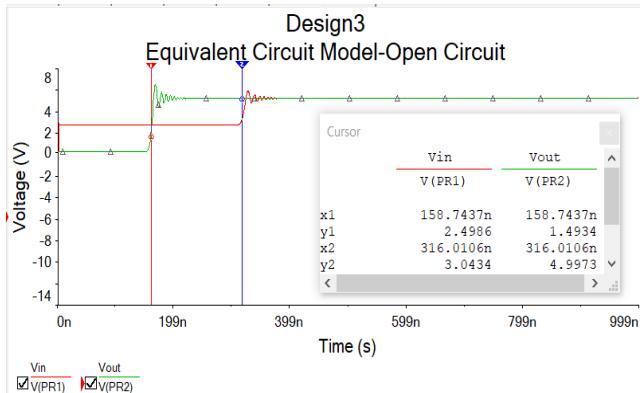


Fig.7. Transient response for Matched Transmission.  $V_{out} = 5V$  at 158.4ns,  $V_{in} = V_{out} = 5V$  at 316.68ns

#### c) Short Circuit Load

For  $t < 316.68$ ns,  $Z_{in}=Z_0$  and therefore  $V_{in}=2.5V$ .  $Z_L=0$  and  $\Gamma_L = -1$  for short circuit indicating that the reflected

wave has  $\mp 180^\circ$  phase difference as compared to the incident wave. Thus, at  $t > 158.4$ ns, the reflected and incident waves cancel each other out resulting in  $V_{out}$  becoming 0. For  $t > 316.68$ ns, the reflected wave reaches the source and cancels out with the incident wave resulting in  $V_{in}$  becoming 0. Current is maximum for Short circuit. The transient response of short circuit is shown in fig.8.

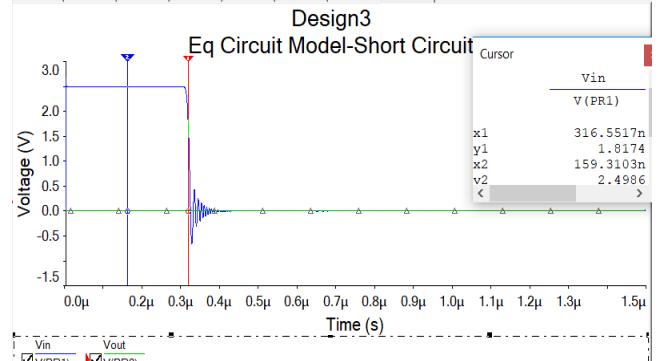


Fig.8. Transient response for Matched Transmission.  $V_{out} = 0V$  at 158.4ns,  $V_{in} = V_{out} = 0V$  at 316.68ns.

#### d) 10Ω load

For  $t < 316.68$  ns,  $Z_{in}=Z_0$  and therefore  $V_{in}=2.5V$ . for  $t < 158.4$  ns,  $V_{out}=0$ . For  $Z_L = 10$  ohm,  $\Gamma_L = -0.765$  at the load as per equation. Thus, at  $t > 158.4$  ns, the reflected wave cancels out with 76.5% of the incident wave, resulting  $V_{out} = 0.588V$ . For  $t > 316.68$ ns, the reflected wave reaches the source and cancels out with 76. 5% of the incident pulse resulting in  $V_{in}$  becoming 0.588V. The current for  $Z_L = 10$  ohm is 58.8mA as per Ohm's Law. The transient response of 10-ohm load resistance is shown in fig.9.

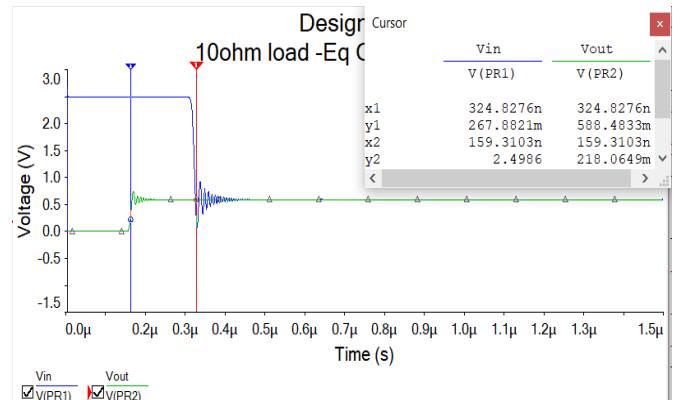


Fig.9. Transient response for Matched Transmission.  $V_{out} = 0.588V$  at 158.4ns,  $V_{in} = V_{out} = 0.588V$  at 316.68ns.

Transient analysis using TL Model for different conditions is shown in figure. As seen from the figure, the output for all the cases is 0 for  $t < 158.4$ ns and  $V_{out}=V_{in}$  after  $t > 316.68$ ns. Furthermore, the steady state in both the models is achieved at the same time. But unlike the equivalent circuit model, The Multisim TL model (fig.10.) is exact and there is no ringing behaviour observed at the step edge. The ringing behaviour in equivalent LC circuit is caused due to Gibbs Phenomenon. The ringing behaviour depends on the rise time and bandwidth of the circuit. Thus, by increasing the number of LC segments and decreasing  $\Delta x$ , the bandwidth of the signal can be increased which in turn increases the accuracy of the LC circuit model.

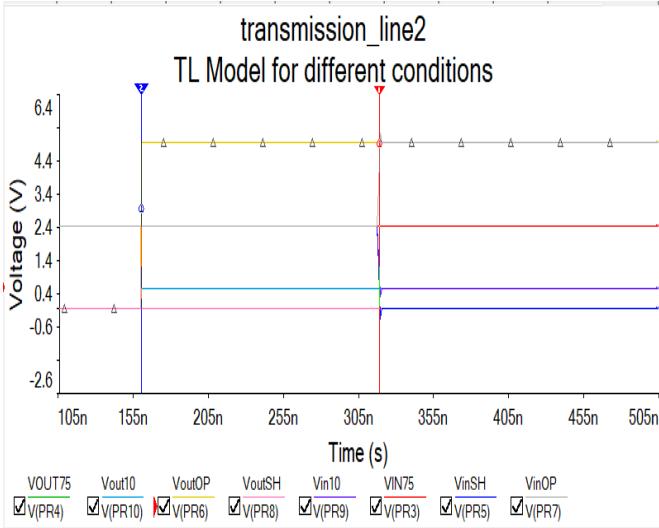


Fig.10. TL Model simulation for different conditions

#### G. AC Analysis of Lossless Lines

Like the Step Voltage input,  $V_{out} = 0$  until the transit time (158.4 ns) but unlike the step voltage input,  $V_{in} \neq V_{out}$  after  $t > (2 * \text{transit time} = 316.68\text{ns})$  except for 75-ohm load.  $V_{out}$  does change after 316.68 ns but there is a phase shift observed as well. The phase shift and the magnitude of  $V_{in}$  can be explained by (16).

$$V(z) = V_0^+ (e^{-\beta l} + \Gamma e^{\beta l}) \quad (16)$$

Where  $\beta = (2\pi/\lambda)$  where  $\lambda$  depends on the frequency of AC source and is calculated as per equation.  $\Gamma$  is the reflection coefficient at the load.  $l = -32\text{m}$  when calculating  $V(z)$  at the source and  $l = -0$  When calculating reflection coefficient at the load. AC inputs have finite frequencies which causes a change in the value of  $\beta$  as per the chosen frequency leading to a change in  $V(z)$ . Thus, a change in  $V(z)$  at the source depends on the frequency used and the reflection coefficient of the load.

#### a) Open Circuit Load

$\Gamma = 1$  for open circuit load. The behaviour of  $V_{out}$  is the same as observed with step voltage. However, there is a change in phase and magnitude of  $V_{in}$  as per equation. As  $\Gamma = 1$ , the phase difference between  $V_{in}$  and  $V_{out}$  will be either  $0^\circ$  or  $180^\circ$ . Simulations have been shown in fig.11 and fig.12.

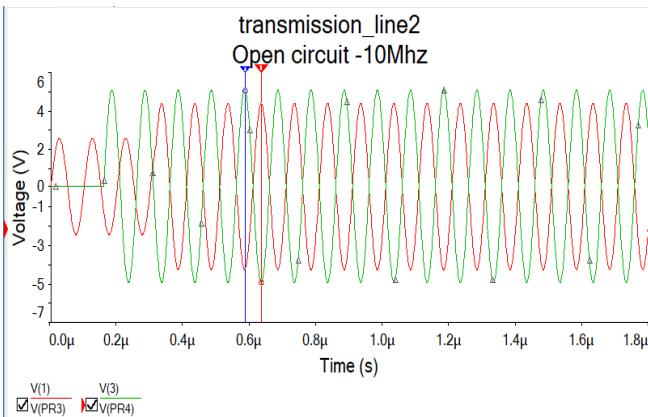


Fig.11. open circuit load at 1MHz with  $V_{out} = 5\text{V}$  after 158.4ns and  $V_{in} = 4.3\text{V}$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is  $180^\circ$ .

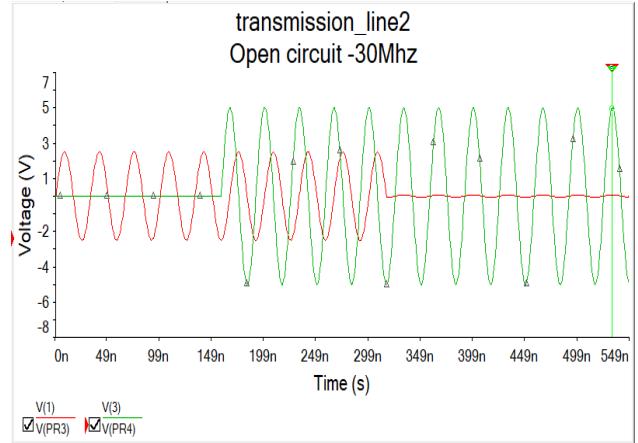


Fig.12. open circuit load at 1MHz with  $V_{out} = 5\text{V}$  after 158.4ns and  $V_{in} = 0.062\text{V}$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is  $0^\circ$ .

#### b) Short Circuit Load

$\Gamma = -1$  for open circuit load. The behaviour of  $V_{out}$  is the same as observed with step voltage. However, there is a change in phase and magnitude of  $V_{in}$  as per equation. As  $\Gamma = -1$ , the phase difference between  $V_{in}$  and  $V_{out}$  will be either  $90^\circ$  or  $270^\circ$ . Simulations have been shown in fig.13 and fig.14.

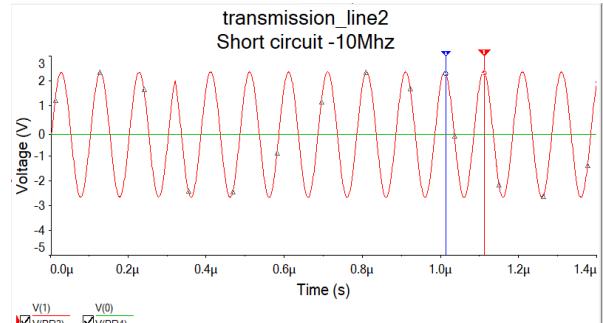


Fig.13. Short circuit load at 10MHz with  $V_{out} = 0\text{V}$  after 158.4ns and  $V_{in} = 2.5\text{V}$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is  $270^\circ$ .



Fig.14. Short circuit load at 30MHz with  $V_{out} = 0\text{V}$  after 158.4ns and  $V_{in} = 4.98\text{V}$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is  $90^\circ$ .

#### c) Matched Load – 75 Ohm

$\Gamma = 0$  for 75-ohm load. The behaviour of  $V_{out}$  is the same as observed with step voltage source. As  $\Gamma = 0$ , the magnitude of  $V_{in} = V_{out}$ . However, the phase difference between  $V_{in}$  and  $V_{out}$  depends on the frequency of the source. Simulations have been shown in fig.15 and fig. 16.

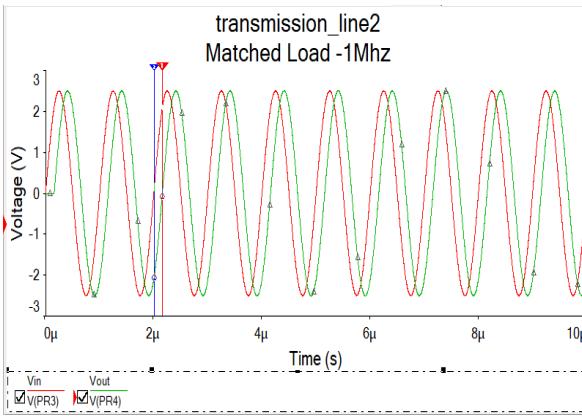


Fig.15. 75-ohm load at 1MHz with  $V_{out} = 2.5V$  after 158.4ns and  $V_{in} = 2.5V$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is 57°.

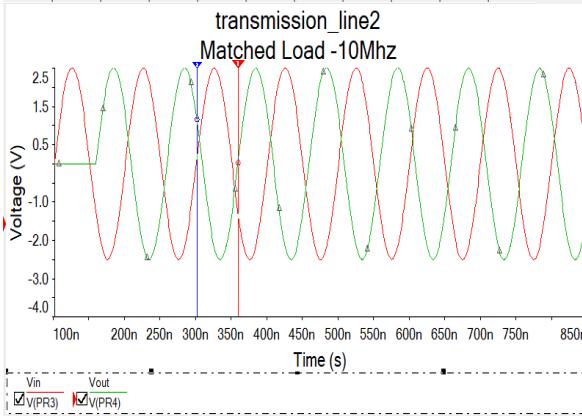


Fig.16. 75-ohm load at 10MHz with  $V_{out} = 2.5V$  after 158.4ns and  $V_{in} = 2.5V$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is 115.56°.

d) 10-ohm load

$\Gamma = -0.764$  for open circuit load. The behaviour of  $V_{out}$  is the same as observed with step voltage. However, there is a change in phase and magnitude of  $V_{in}$  as per equation. The phase difference between  $V_{in}$  and  $V_{out}$  will depend on the source frequency. Simulation at 1MHz is shown in fig.17.

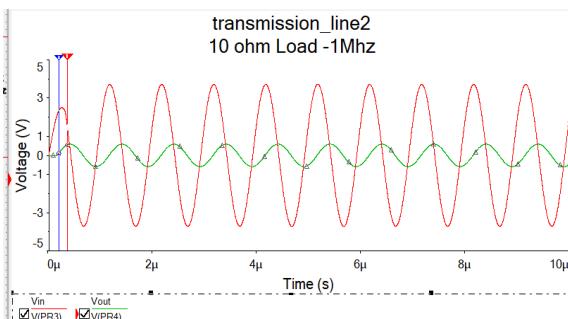


Fig.17. 10-ohm load at 1MHz with  $V_{out} = 3.7V$  after 158.4ns and  $V_{in} = 0.588V$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is 76°.

As per fig.12, it can be observed that at 30 MHz open circuit load has  $V_{in}$  as 0.22 mV indicating  $Z_{in} = 0$  at steady state. In contrast with open circuit load, short circuit load has  $V_{in} = 4.9V$  at 30 MHz indicating  $Z_{in} = \infty$  at steady state as per fig.14.

The simulations conducted using TL model and equivalent circuit yielded same results. No ringing behaviour was observed at transient time unlike step voltage source. This is

because there is no drastic sudden change in voltage level of an AC source.

#### H. Equivalent Circuit of Lossy Model

The losses in transmission is characterized by attenuation constant  $\alpha$ , which depends on various factors. The losses due to frequency,  $f$ , is shown in fig 18.

TABLE I. FREQUENCY DEPENDENT LOSSES

$\alpha_C$	Metal loss	$\alpha_C \sqrt{f}$
$\alpha_D$	Dielectric tangent loss	$\alpha_C \alpha f$

Fig.18. Frequency Dependent Losses

As seen in table,  $\alpha_C$  and  $\alpha_G$  cause loss at microwave frequencies. Resistance,  $R$  depends on  $\alpha_C$  and Conductance,  $G$  depends on  $\alpha_D$ . Hence, the values of  $R$  and  $G$  would change with frequency.  $L$  and  $C$  remains the same as previous sections. The values of  $R$  and  $C$  extracted at different frequencies is shown in fig.19. As per section 2, the construction of segment of  $\Delta x$  m changes according to the values of  $R$  and  $L$  obtained at different frequencies which results in the change in the overall circuit model.  $\Delta x$  m segment at 1Mhz is shown in fig.20.

TABLE II. R AND G PARAMETERS OF LOSSY LINE AT VARIOUS FREQUENCIES

$f$ (MHz)	R per unit length ( $\Omega/m$ )	G per unit length (mho/m)	R per segment of $\Delta x$ m ( $\Omega$ )	G per segment of $\Delta x$ m (mho)	Shunt Resistance of $\Delta x$ m ( $1/G_x$ ) ( $\Omega$ )
1	0.20286	830n	5.46m	24.4n	40.96M
10	0.54924	8.3u	16.5m	244.1n	4.096M
30	0.92586	24.9u	27.23m	732.53n	1.365M
Step voltage	0.06774	0.00033p	1.99m	9.94 * $10^{-18}$	10E

$$L = 0.371 \text{ uH/m}, C = 66.02 \text{ pF/m}$$

Fig.19. Resistance and Conductance of lossy line at different frequencies

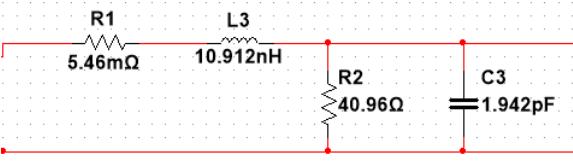


Fig.20  $\Delta x$  m segment at 1MHz

#### I. AC ANALYSIS OF LOSSY MODEL

The simulation graphs of lossy line are shown in figure. On comparison with  $75 \Omega$  load of lossless lines with AC source, it is observed that unlike lossless lines, the Magnitude of  $V_{in} \neq V_{out}$ , indicating that there is some loss in the line. This is because attenuation constant,  $\alpha$ , increases with frequency which causes signal attenuation and increases the difference between  $V_{in}$  and  $V_{out}$ . The attenuation is not significantly big indicating a low loss line. However, the phase difference between  $V_{in}$  and  $V_{out}$  is the same as lossless lines. The simulations at various frequencies are shown in fig.21, fig.22 and fig.23. The attenuation Constant for a low loss lines is given by (17):

$$\alpha = 0.5 \left( \frac{R}{Z_0} + GZ_0 \right) \quad (17)$$

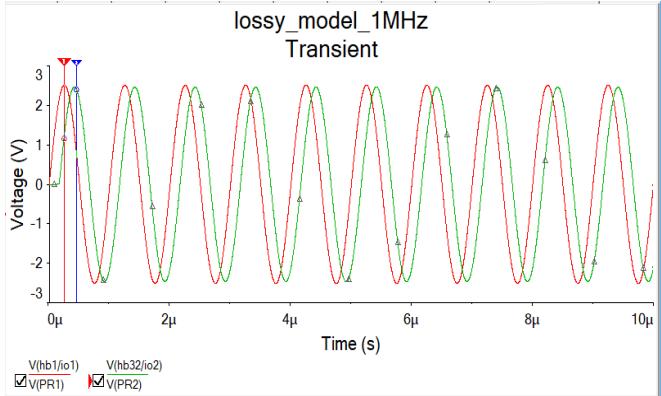


Fig.21. 75-ohm load at 1MHz with  $V_{out} = 2.4V$  after 158.4ns and  $V_{in}= 2.5V$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is  $57^\circ$ .  $\alpha = 0.00138$

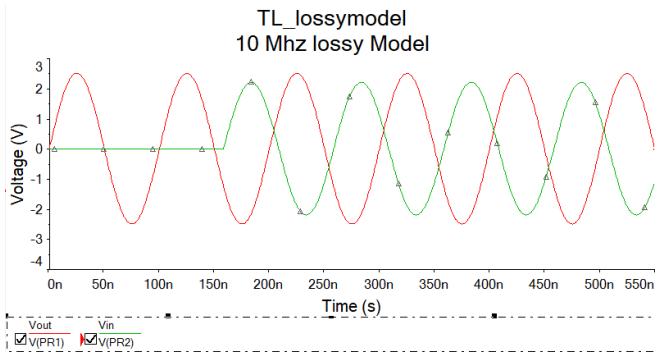


Fig.22. 75-ohm load at 10MHz with  $V_{out} = 2.2V$  after 158.4ns and  $V_{in}= 2.5V$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is  $115.56^\circ$ .  $\alpha = 0.00397$ .

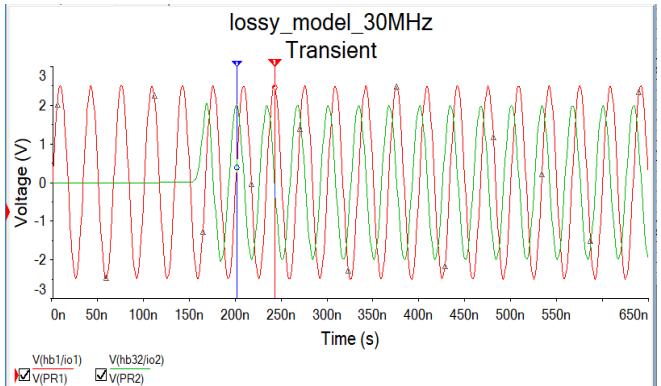


Fig.23. 75-ohm load at 30MHz with  $V_{out} = 1.984V$  after 158.4ns and  $V_{in}= 2.5V$  after 316.68ns. Phase difference between  $V_{in}$  and  $V_{out}$  is  $270^\circ$ .  $\alpha = 0.00712$ .

### J. Step Voltage Analysis

With step voltage source, it was observed that the magnitude of  $V_{in}$  and  $V_{out}$  was not equal like the lossless

model although the transit time is the same. This is also due to the attenuation constant  $\alpha$ . Moreover, since  $(R/L) \neq (G/C)$ , there is distortion at transit time due to different frequency components reaching the end of the line at different frequencies. The simulation is shown in fig.24.

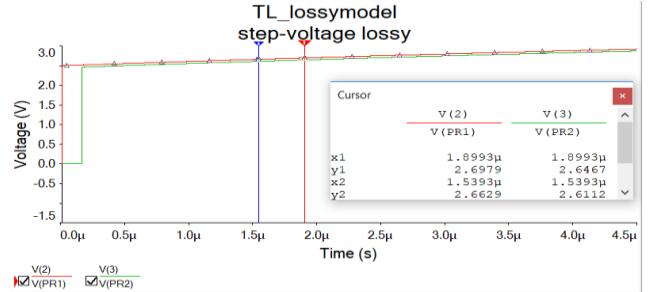


Fig.24 Lossy line with Step Voltage Source

### III. CONCLUSION

As per section 1, the phase velocity is reduced by 32.6% which indicates that the speed of the photons will be lesser than the speed of light due to permittivity of the line. For lossless lines, it is concluded that  $V_{load}$  depends on the load used as it changes the reflection coefficient  $\Gamma$ , the magnitude of  $V_{out}$  is maximum for open load and minimum for short circuit load. For matched load,  $V_{out}=V_{in}$  as  $\Gamma= 0$ . For step voltage source, there was a ringing behaviour observed at transit time for equivalent circuit which can be reduced by increasing the number  $\Delta x$  segments.  $V_{in}$  changed after 316.68ns for AC source but not with step voltage source which indicates that  $\beta$  varies with frequency. The phase difference observed between input and output voltages also depends on  $\Gamma$  and  $\beta$ . Different factors cause losses in transmission line which depend on frequency used. R and G are frequency dependent whereas L and C are not. Losses in transmission line cause signal attenuation causing a difference in  $V_{in}$  and  $V_{out}$  for matched load.

### REFERENCES

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