

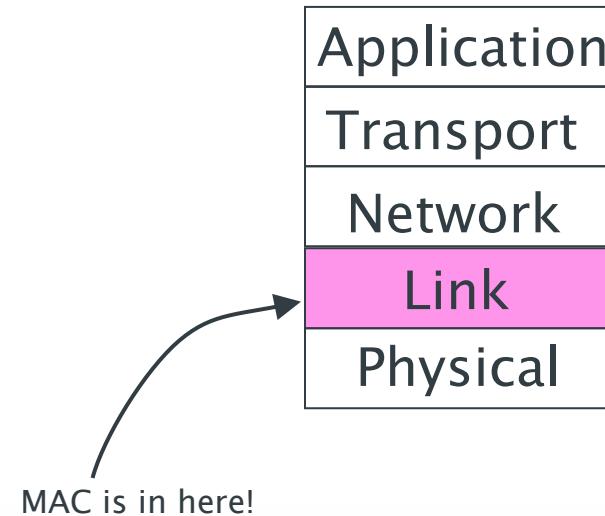
MAC Sublayer

Media Access Control

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ELEC3222/ELEC6255: Networks
See Tanenbaum Chapter 4 (Medium Access Control Sublayer)

Outline

- Introduction
- Channel Allocation Techniques
- MAC Protocols
 - ALOHA
 - Pure
 - Slotted
 - CSMA
 - Persistent
 - Non-persistent
 - p-persistent
 - CSMA-CD
 - Collision-Free
 - Bitmap
 - Token passing
 - Binary countdown
 - Limited Contention
 - Adaptive tree walk
 - Wireless LAN
 - MACA/CSMA-CA: RTS and CTS





Media Access Control

- Here, we consider broadcast links rather than point-to-point links
 - i.e. where multiple nodes are connected directly to the same medium
 - Broadcast channels sometime known as *random access* or *multi-access* channels
 - **Issue:** who gets to speak at any one time?
 - This is the role of the MAC sublayer
 - Technically sits at the ‘bottom’ of the Data Link Layer

Channel Allocation

- Static Channel Allocation (divide up available bandwidth)
 - E.g. FDMA: Frequency Division Multiple Access (e.g an FM radio)
 - E.g. TDMA: Time Division Multiple Access (i.e. a ‘time-slice’)
- Fine if traffic is predictable and constant
- However, if traffic is bursty/variable, it becomes inefficient
 - FDMA wastes unused spectrum
 - TDMA wastes unused time

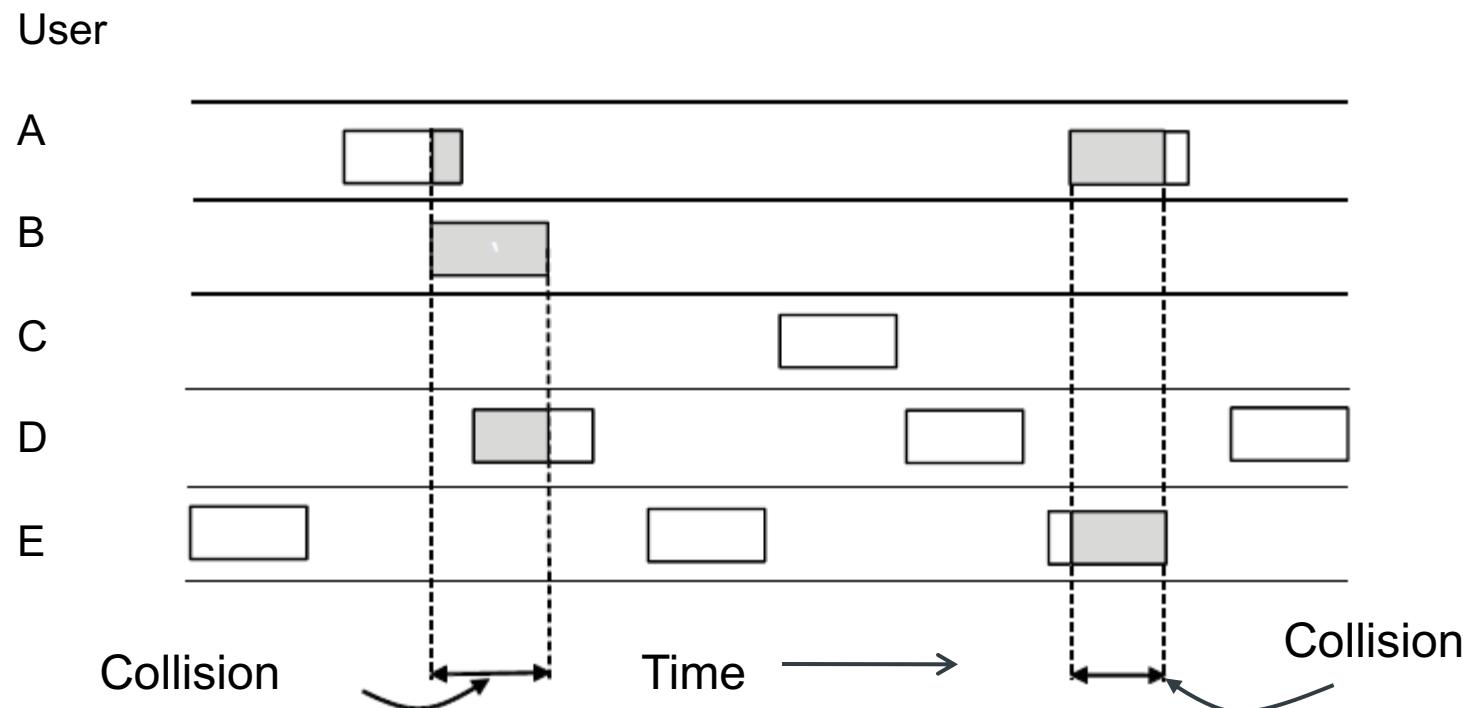
Dynamic Channel Allocation

- Dynamic allocation gives the channel to a user when they need it.
 - Potentially N times as efficient for N users.
- Different schemes may make different assumptions:
 - **Independent traffic:** Network consists of N independent stations/nodes. Often not a good model, but permits analysis
 - **Single channel:** Only one communication channel exists, and it is shared. There is no external way to coordinate senders
 - **Continuous or slotted time?**: Continuous time may be divided down into discrete ‘slotted’ time. This may require time synchronization.
 - **Carrier sense**: Carrier sense allows a station to see if the channel is busy before transmitting.
 - **Observable collisions**: 2 frames transmitted at same time make both unreadable. These collisions can be detected. No other errors occur.

MAC Protocols

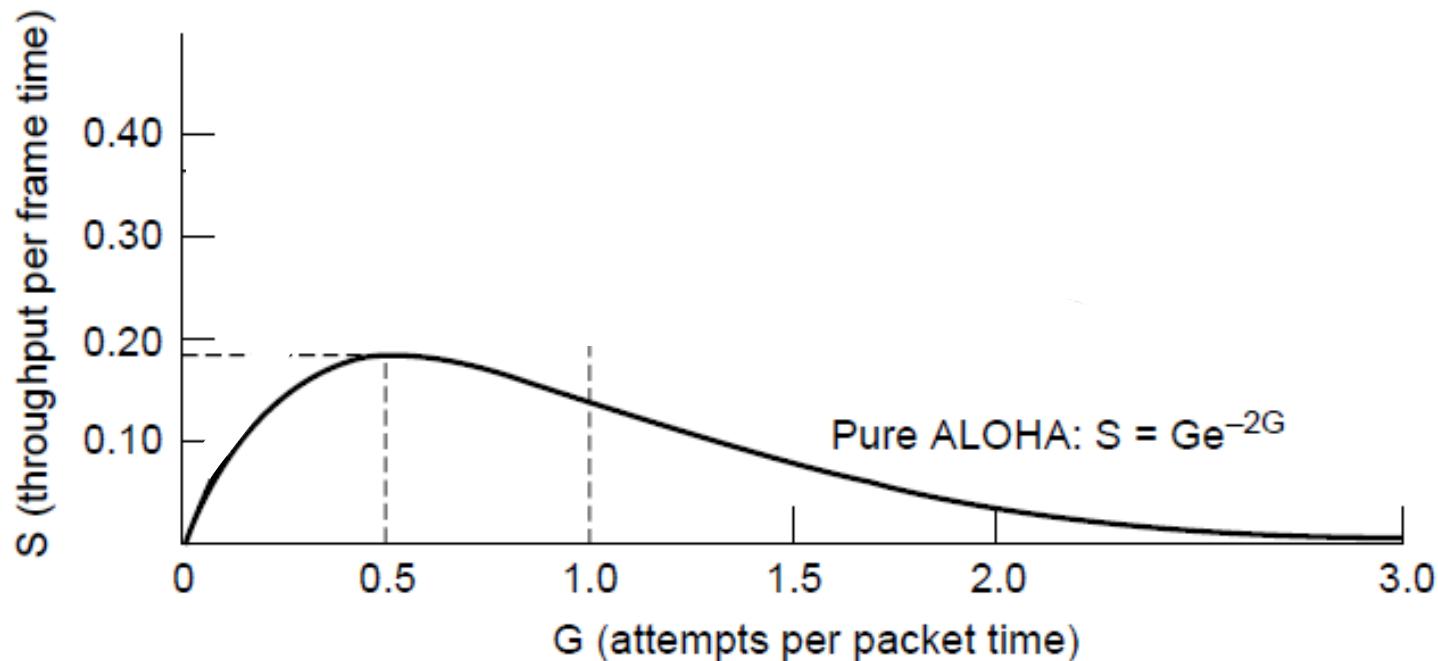
ALOHA

- In pure ALOHA, users transmit frames whenever they have data; users retry after a random time for collisions
 - Efficient and low-delay under low load



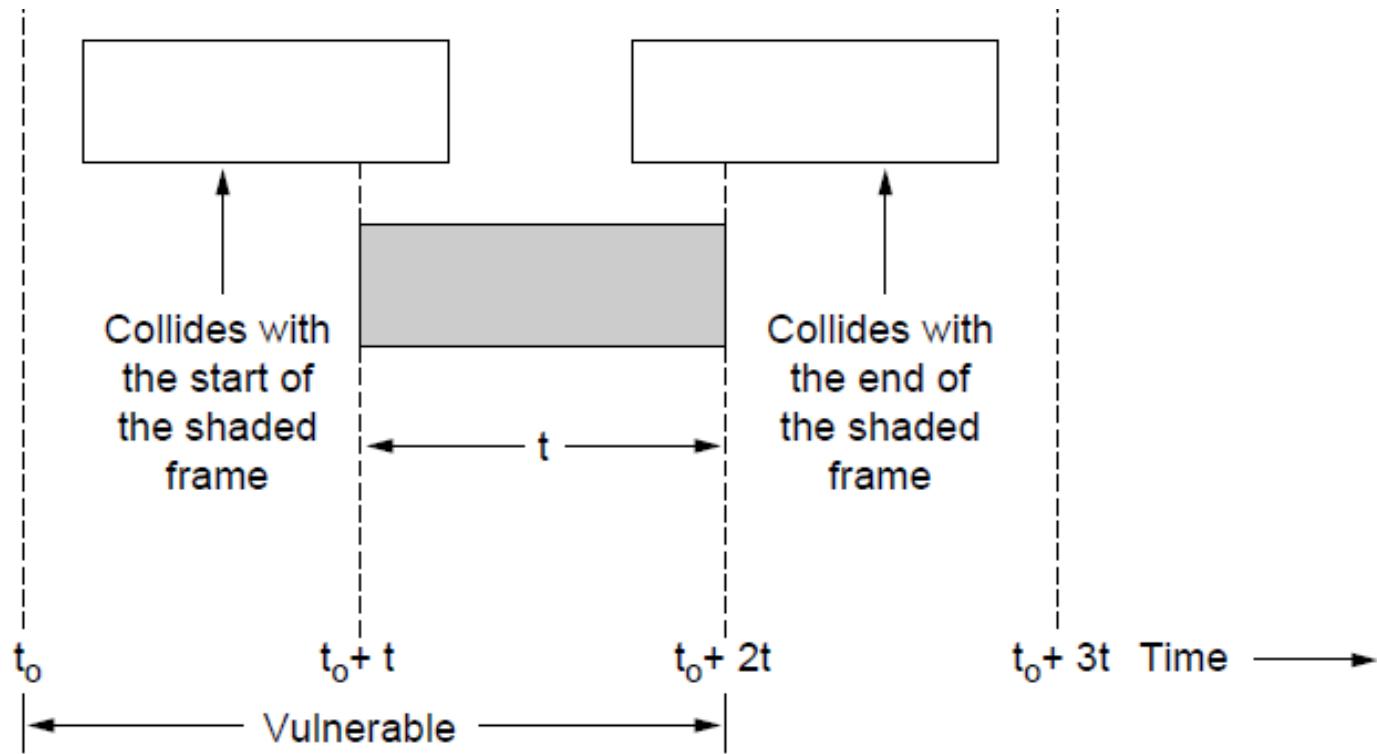
ALOHA

- ALOHA
 - High loads causes collisions
 - Efficiency up to 18% (when maximum throughput occurs)



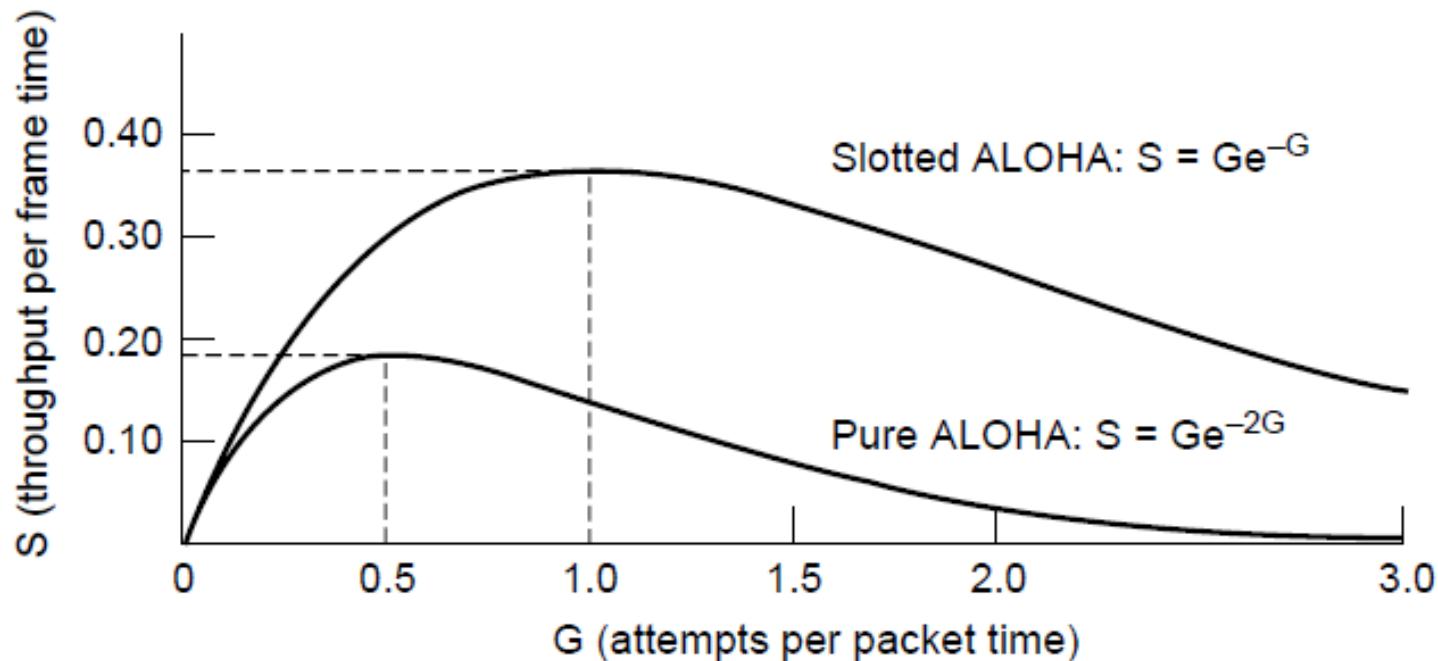
Slotted ALOHA

- Collisions happen when other users transmit during a vulnerable period that is twice the frame time
 - Synchronizing senders to slots can reduce collisions



Slotted ALOHA

- Slotted ALOHA is twice as efficient as pure ALOHA
 - Low load wastes slots, high loads causes collisions
 - Efficiency up to $1/e$ (37%) for random traffic models



CSMA: 1-persistent

CSMA Collision Avoidance improves on ALOHA by sensing the channel

- 1-persistent (greedy)
 - If the channel is idle:
 - the frame is transmitted
 - If the channel is busy:
 - Continues to monitor the channel and instantly sends when it becomes idle
 - *Multiple nodes might have the same idea (and hence collide) – and worsened with increasing propagation delays*
- Better performance than Slotted ALOHA due to carrier sense

CSMA: non-persistent

CSMA Collision Avoidance improves on ALOHA by sensing the channel

- non-persistent
 - If the channel is idle:
 - the frame is transmitted
 - If the channel is busy:
 - Waits for a random back-off time, before trying again
- Better channel utilization but longer delays

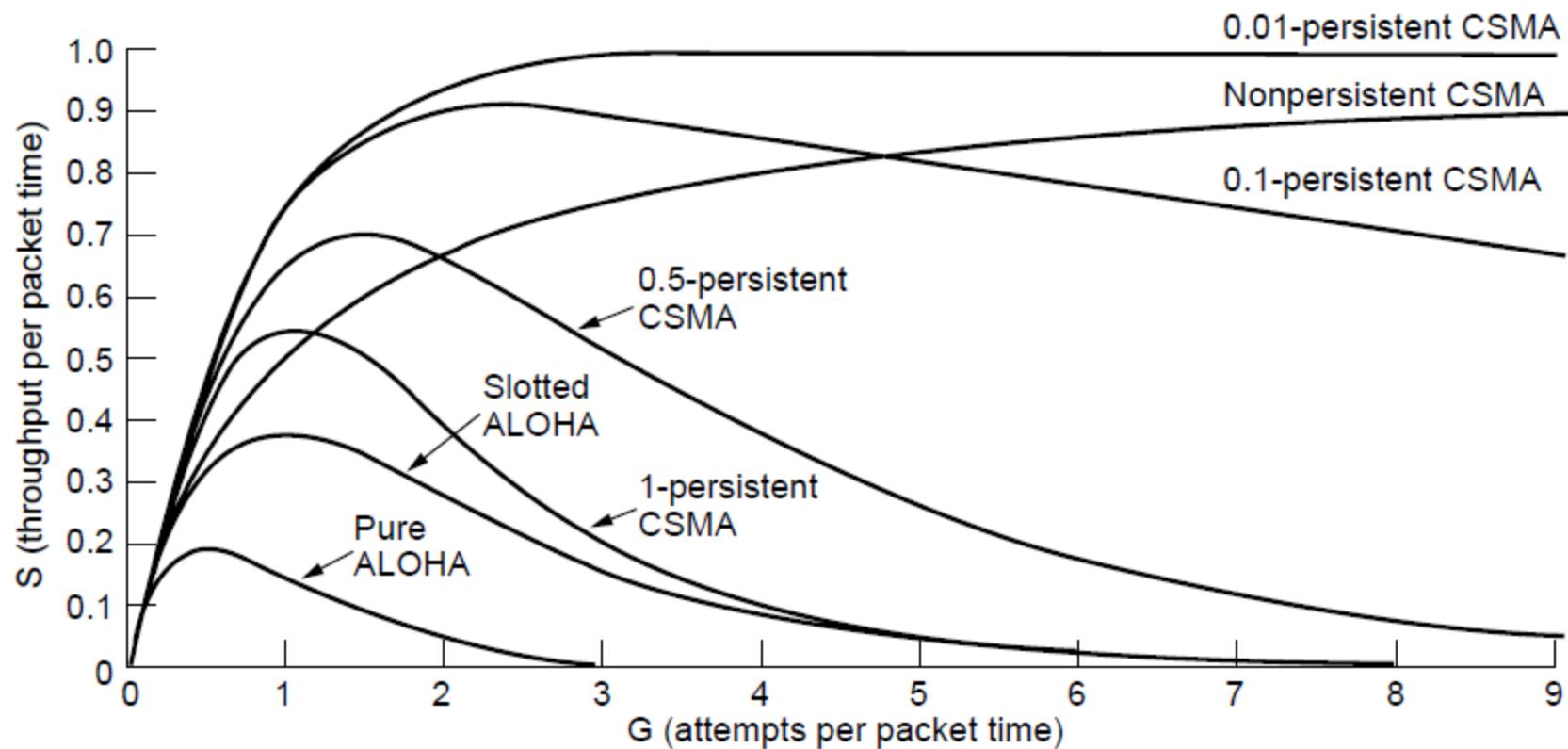
CSMA: p -persistent

CSMA Collision Avoidance improves on ALOHA by sensing the channel

- p -persistent (discrete/slotted time)
 - If the channel is idle:
 - Transmits with a probability p of transmitting
 - Therefore a probability of $1-p$ of not transmitting and waiting until the next slot
 - If, at the next slot, the channel is still idle
 - the process repeats
 - Else
 - it waits for a random back-off time, before starting again
 - If the channel is busy:
 - Waits for the next slot and tries again

CSMA

- CSMA outperforms ALOHA, and being less persistent is better under high load

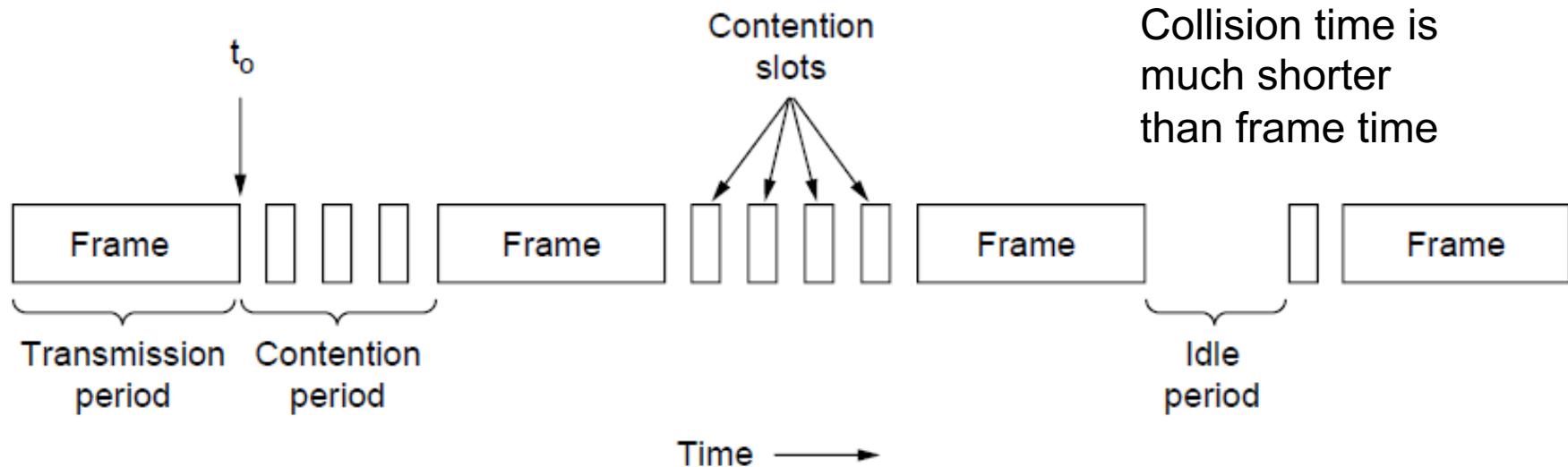


Discussion

- We've talked about throughput...
- What about the minimum/maximum/average latency?
- What's the impact of this on energy consumption?

CSMA–CD

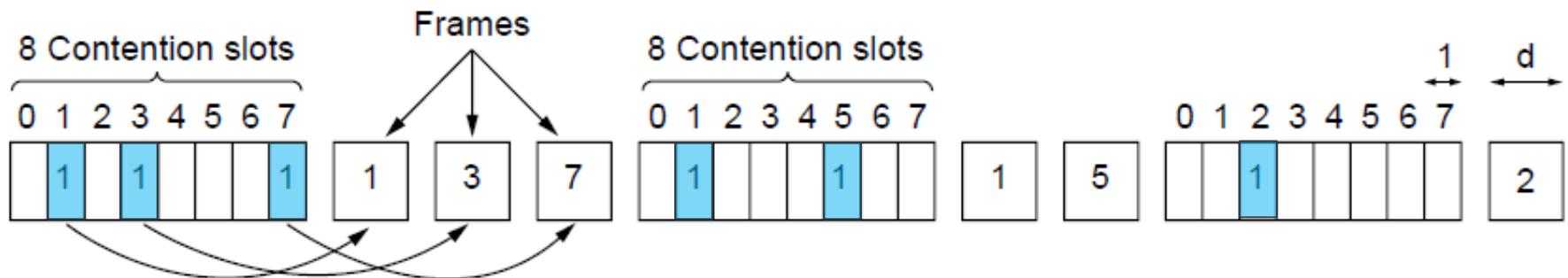
- CSMA/CD = CSMA with Collision Detection
- CSMA/CD improvement is to detect/abort collisions
 - Reduced contention times improve performance



- This avoid collisions (once the channel is captured), but doesn't avoid contention altogether

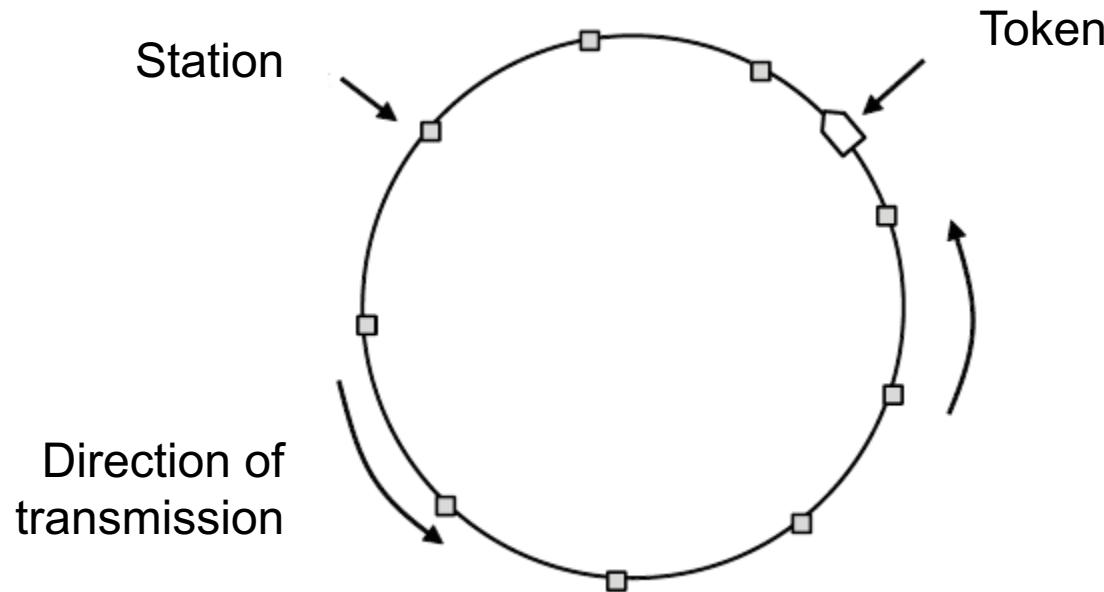
Collision-Free: Bitmap

- Collision-free protocols avoid collisions entirely
 - Senders must know when it is their turn to send
- The basic bit-map protocol:
 - Starts with a contention period consisting of N slots
 - If sender n has a frame to send, it sets the bit in contention slot n
 - After the contention period, senders who set their bit send their frames in turn



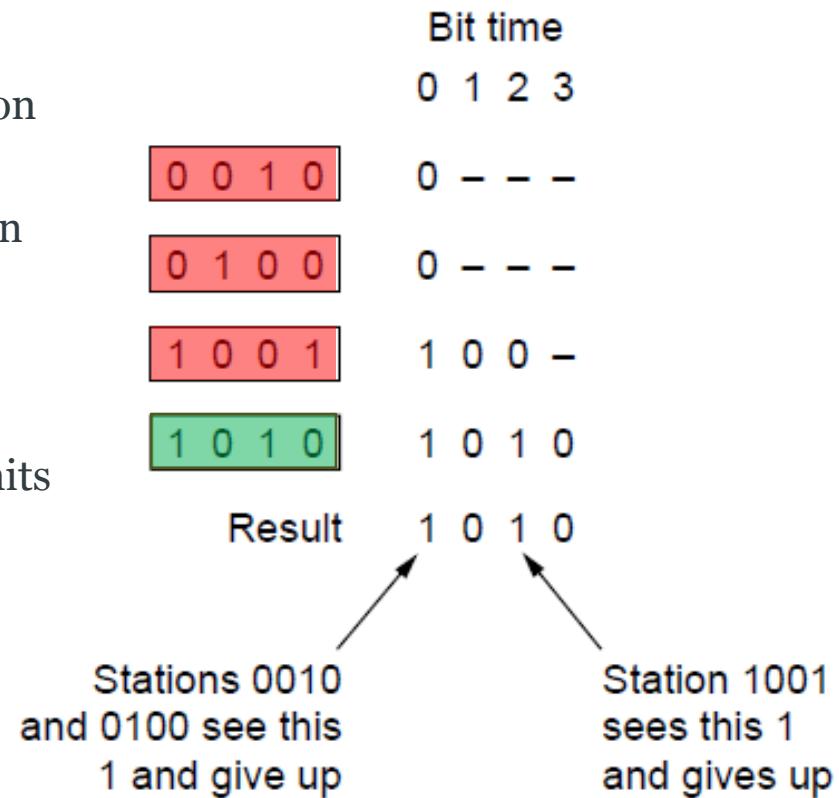
Collision-Free: Token Ring

- Token sent round ring defines the sending order
 - Station with token may send a frame before passing it on to the next station
 - Idea can be used without ring too, e.g., token bus



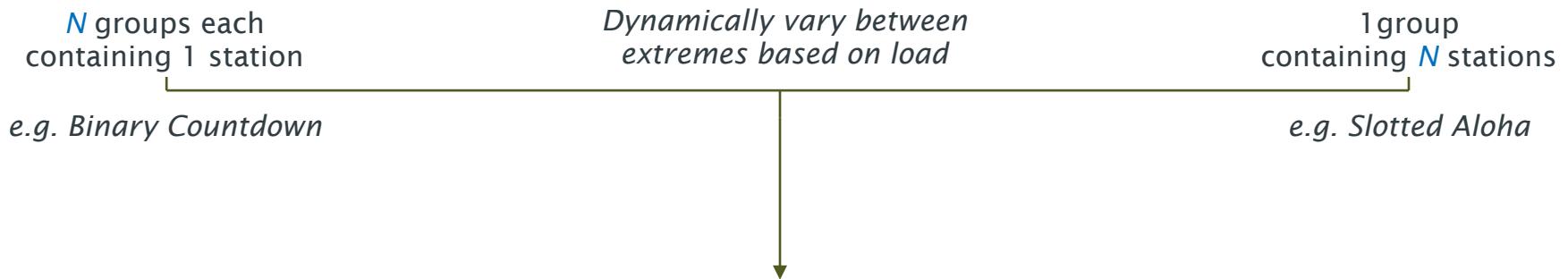
Collision-Free: Countdown

- Both of the above methods have a 1-bit overhead per station
- Binary countdown improves on this
 - Stations send their address in contention slot ($\log N$ bits instead of N bits)
 - Channel ORs bits; stations give up when they send a “0” but see a “1”
 - This gives priority to higher numbered stations
 - Station that sees its full address transmits its frame



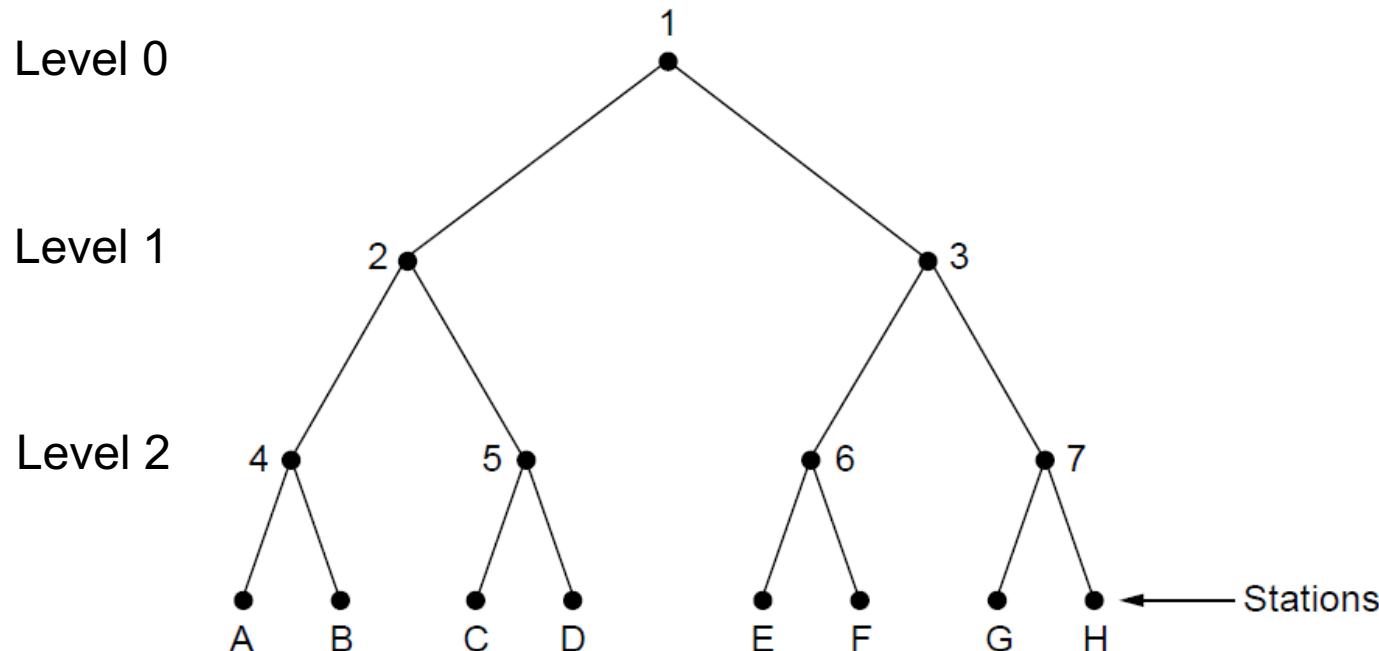
Limited-Contention Protocols

- Contention protocols good for low load
- Contention-free protocols good for high load
- Idea is to divide stations into groups within which only a very small number are likely to want to send
 - Avoids wastage due to idle periods and collisions



Limited Contention: Adaptive Tree Walk

- Tree divides stations into groups (nodes) to poll
 - In a contention slot, if only one station in the entire tree tries to transmit, it will
 - Otherwise, a recursive depth-first search is done underneath the node with collisions



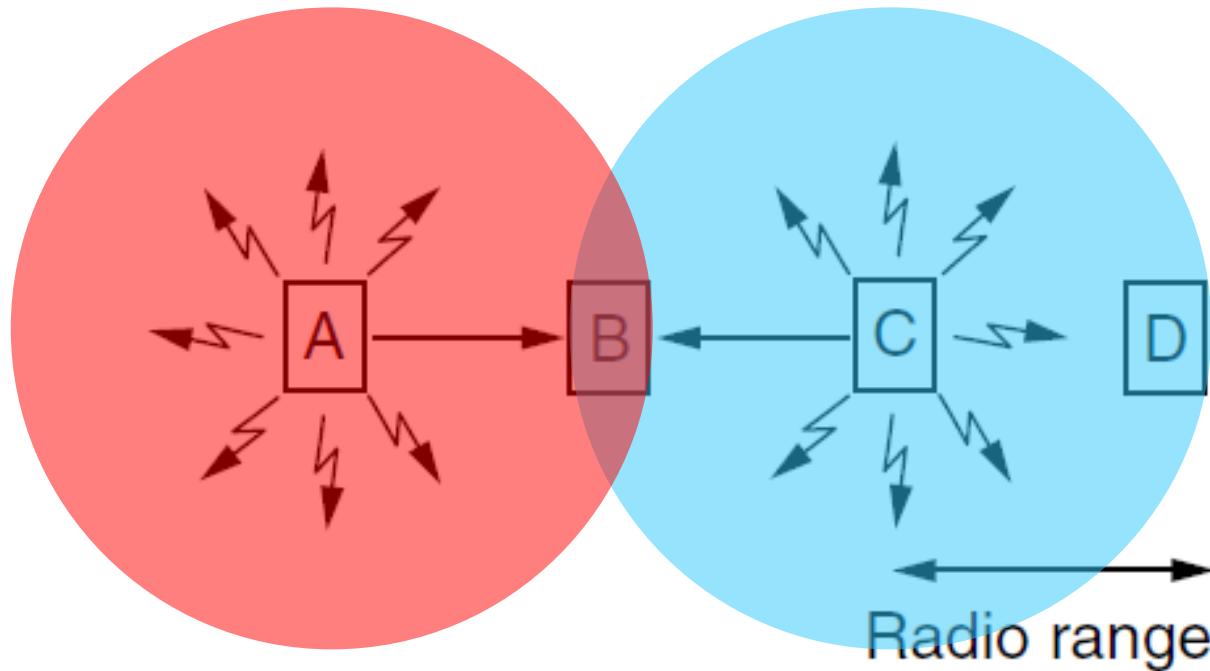
- The search can be started at lower levels if >1 station expected (i.e. high load)

Wireless LANs

- Wireless has complications compared to wired.
- Nodes may have different coverage regions
 - One station/node may not be able to transmit directly to all others
 - Leads to hidden and exposed terminals
- Nodes can't detect collisions, i.e., sense while sending
 - Instead, use acknowledgements
 - Makes collisions expensive and to be avoided

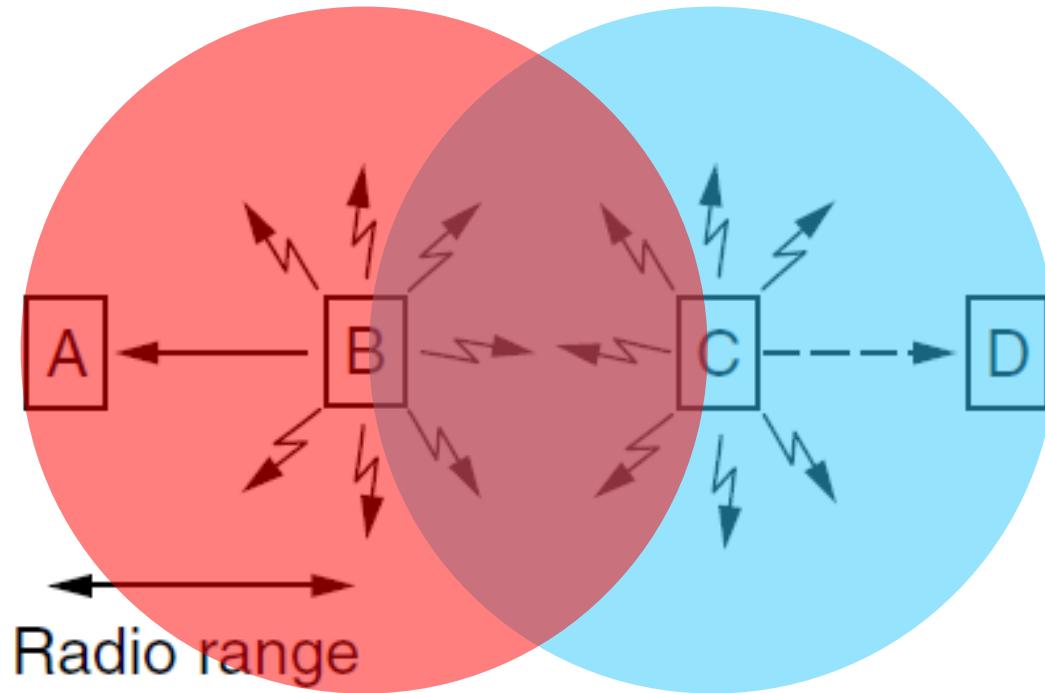
Wireless LANs: Hidden Terminals

- Hidden terminals are senders that cannot sense each other but nonetheless collide at intended receiver
 - Want to prevent; loss of efficiency
 - A and C are hidden terminals when sending to B



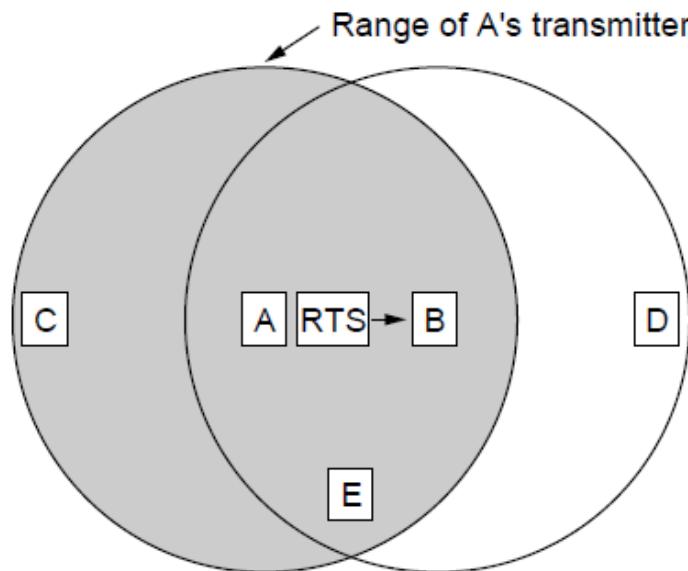
Wireless LANs: Exposed Terminals

- Exposed terminals are senders who can sense each other, but can still transmit safely (to different receivers)
 - Desirably concurrency; improves performance
 - $B \rightarrow A$ and $C \rightarrow D$ are exposed terminals

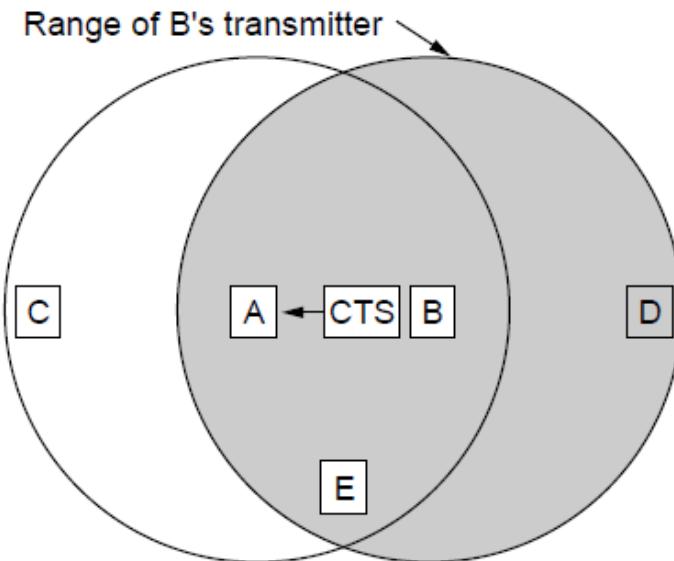


Wireless LANs: MACA

- MACA (Multiple Access with Collision Avoidance) grants access for **A** to send to **B**
 - **A** sends *RTS* (Request To Send) to **B** – *RTS contains frame length it wants to send*
 - **B** replies with *CTS* (Clear To Send) – *CTS contains the same frame length*



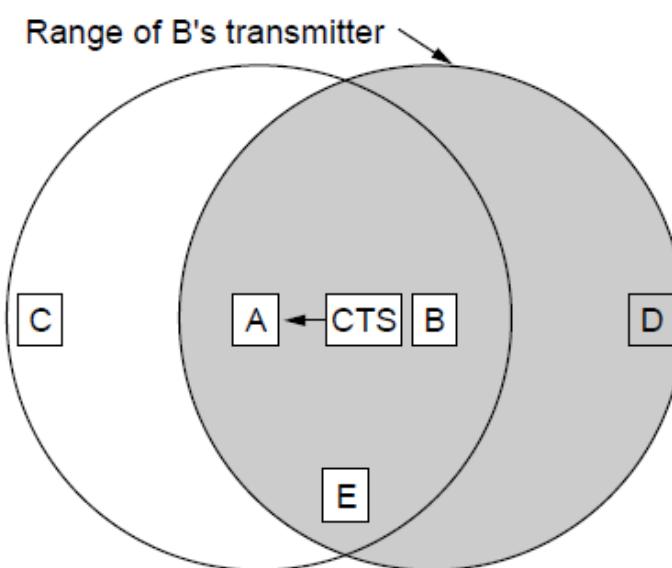
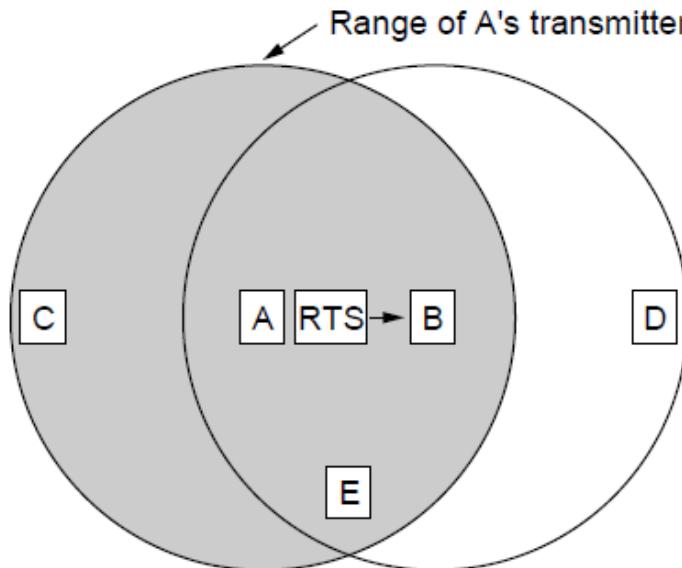
A sends RTS to B; C and E
hear and defer for CTS



B replies with CTS; D and
E hear and defer for data

Wireless LANs: MACA

- Exposed Terminals
 - C is within the range of A, but not B (hence is an *exposed terminal*)
 - It keeps quiet long enough for a CTS to be returned, which it does not hear
 - Therefore, it is free to transmit (this is fine, as won't interfere with B's reception)
- Hidden Terminals
 - D is within the range of B, but not A (hence it is a *hidden terminal*)
 - When it hears the CTS, it knows a nearby station is about to receive, and so stays quiet



ELEC3222 2018/19 Exam Question

(a) State the role of the MAC sublayer

(b) A LAN contains 10 stations arranged in a ring topology, with a fixed frame size of 1024 bytes, and a data-rate of 1 Mbps. Calculate the worst-case (longest) time that a station might have to wait before it can begin transmitting its frame when:

- (i) using the basic bit-map MAC protocol;
- (ii) using the token ring MAC protocol.



Questions?