

(1)

Linear Dependence and Linear Independence

A set of vectors $S = \{v_1, v_2, \dots, v_r\}$ in a vector space V is linearly independent when the vector equation

$$k_1 \vec{v}_1 + k_2 \vec{v}_2 + \dots + k_r \vec{v}_r = \vec{0} \quad \text{Linearly independent:}$$

has only the trivial solution $k_1 = 0, k_2 = 0, \dots, k_r = 0$.

If there is a non-trivial solution, then S is linearly dependent.

Example ① Determine whether the set of vectors in \mathbb{R}^3 is linearly independent or linearly dependent.

$$S = \{(1, 2, 3), (0, 1, 2), (-2, 0, 1)\}$$

$$k_1 \vec{v}_1 + k_2 \vec{v}_2 + k_3 \vec{v}_3 = \vec{0}$$

Linearly independent houn gai agar tou solution 0 a jai sab ka

$$k_1(1, 2, 3) + k_2(0, 1, 2) + k_3(-2, 0, 1) = (0, 0, 0)$$

$$(k_1 - 2k_3, 2k_1 + k_2, 3k_1 + 2k_2 + k_3) = (0, 0, 0)$$

$$k_1 - 2k_3 = 0$$

$$2k_1 + k_2 = 0$$

$$3k_1 + 2k_2 + k_3 = 0$$

$$\begin{bmatrix} 1 & 0 & -2 & 0 \\ 2 & 1 & 0 & 0 \\ 3 & 2 & 1 & 0 \end{bmatrix}$$

The reduced row echelon matrix is

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad \begin{aligned} k_1 &= 0 \\ k_2 &= 0 \\ k_3 &= 0 \end{aligned}$$

The vectors in S are linearly independent

Example ② Determine the vectors $\vec{v}_1 = (1, -2, 3)$, $\vec{v}_2 = (5, 6, -1)$ and $\vec{v}_3 = (3, 2, 1)$ are linearly independent or linearly dependent in R^3 . (2)

$$k_1 \vec{v}_1 + k_2 \vec{v}_2 + k_3 \vec{v}_3 = \vec{0}$$

$$k_1(1, -2, 3) + k_2(5, 6, -1) + k_3(3, 2, 1) = (0, 0, 0)$$

$$(k_1 + 5k_2 + 3k_3, -2k_1 + 6k_2 + 2k_3, 3k_1 - k_2 + k_3) = (0, 0, 0)$$

$$k_1 + 5k_2 + 3k_3 = 0$$

$$-2k_1 + 6k_2 + 2k_3 = 0$$

$$3k_1 - k_2 + k_3 = 0$$

$$\left[\begin{array}{cccc} 1 & 5 & 3 & 0 \\ -2 & 6 & 2 & 0 \\ 3 & -1 & 1 & 0 \end{array} \right] \Rightarrow \left[\begin{array}{cccc} 1 & 0 & \frac{1}{2} & 0 \\ 0 & 1 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$k_1 + \frac{1}{2}k_3 = 0$$

k_3 = free

$$k_2 + \frac{1}{2}k_3 = 0$$

$$k_1 = -\frac{1}{2}t$$

$$k_2 = -\frac{1}{2}t$$

$$k_3 = t$$

The system has nontrivial solution. The vectors are linearly dependent.

non trivial solution = linearly dependent
trivial solution = linearly independent

Example ③ Determine whether the set of vectors in P_2 is linearly independent or linearly dependent. (3)

$$\vec{P}_1 = 1+x-2x^2, \quad \vec{P}_2 = 2+5x-x^2, \quad \vec{P}_3 = x+x^2$$

$$k_1 \vec{v}_1 + k_2 \vec{v}_2 + k_3 \vec{v}_3 = \vec{0}$$

$$k_1(1+x-2x^2) + k_2(2+5x-x^2) + k_3(x+x^2) = 0$$

$$(k_1 + 2k_2 + 0k_3) + (k_1 + 5k_2 + k_3)x + (-2k_1 - k_2 + k_3)x^2 = 0$$

$$k_1 + 2k_2 + 0k_3 = 0$$

$$k_1 + 5k_2 + k_3 = 0$$

$$-2k_1 - k_2 + k_3 = 0$$

$$\left[\begin{array}{cccc} 1 & 2 & 0 & 0 \\ 1 & 5 & 1 & 0 \\ -2 & -1 & 1 & 0 \end{array} \right] \Rightarrow \left[\begin{array}{cccc} 1 & 2 & 0 & 0 \\ 0 & 1 & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$k_1 + 2k_2 = 0 \quad k_2 + \frac{1}{3}k_3 = 0 \quad k_3 = t$$

The system has non-trivial solution. The vectors $\vec{P}_1, \vec{P}_2, \vec{P}_3$ are linearly dependent. non trivial = linearly dependent

Theorem A set S with two or more vectors is

- 1) Linearly dependent if and only if at least one of the vectors in S is expressible as a linear combination of the other vectors in S .
- 2) Linearly independent if and only if no vector in S is expressible as a linear combination of the other vectors in S .

Example ④ In example ②, the vectors $\vec{v}_1 = (1, -2, 3)$, $\vec{v}_2 = (5, 6, -1)$, $\vec{v}_3 = (3, 2, 1)$ are linearly dependent.

$$k_1 \vec{v}_1 + k_2 \vec{v}_2 + k_3 \vec{v}_3 = \vec{0}$$

$$k_1 = -\frac{1}{2}t, k_2 = -\frac{1}{2}t, k_3 = t$$

$$\text{For } t = 1, k_1 = -\frac{1}{2}, k_2 = -\frac{1}{2}, k_3 = 1$$

$$-\frac{1}{2} \vec{v}_1 - \frac{1}{2} \vec{v}_2 + \vec{v}_3 = \vec{0}$$

$$\vec{v}_3 = \frac{1}{2} \vec{v}_1 + \frac{1}{2} \vec{v}_2$$

Theorem Two vectors \vec{u} and \vec{v} in a vector space V are linearly dependent if and only if one is a scalar multiple of the other.

Example ⑤ (a) The vectors $\vec{v}_1 = (1, 2, 0)$ and $\vec{v}_2 = (-2, 2, 1)$ are linearly independent because \vec{v}_1 and \vec{v}_2 are not scalar multiples of each other.

(b) The vectors $\vec{v}_1 = (4, -4, -2)$ and $\vec{v}_2 = (-2, 2, 1)$ are linearly dependent because $\vec{v}_1 = -2\vec{v}_2$.

Theorem Let $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_r\}$ be a set of vectors in \mathbb{R}^n . If $r > n$, then S is linearly dependent.

Linear Independence of Functions

Let $\vec{f}_1 = \sin^2 x$, $\vec{f}_2 = \cos^2 x$, $\vec{f}_3 = 5$.

$$\begin{aligned} \text{Then } 5\vec{f}_1 + 5\vec{f}_2 - \vec{f}_3 &= 5\sin^2 x + 5\cos^2 x - 5 \\ &= 5(\sin^2 x + \cos^2 x) - 5 \\ &= 5(1) - 5 = \vec{0} \end{aligned}$$

The vectors $\vec{f}_1, \vec{f}_2, \vec{f}_3$ are linearly dependent.

Wronskian If $\vec{f}_1 = f_1(x), \vec{f}_2 = f_2(x), \dots, \vec{f}_n = f_n(x)$ are functions that are $n-1$ times differentiable on the interval $(-\infty, \infty)$, then the determinant

$$W(x) = \begin{vmatrix} f_1(x) & f_2(x) & \cdots & f_n(x) \\ f'_1(x) & f'_2(x) & \cdots & f'_n(x) \\ \vdots & \vdots & & \vdots \\ f^{(n-1)}_1(x) & f^{(n-1)}_2(x) & \cdots & f^{(n-1)}_n(x) \end{vmatrix}$$

is called the Wronskian of functions $f_1(x), f_2(x), \dots$

Theorem If the functions $\vec{f}_1, \vec{f}_2, \dots, \vec{f}_n$ have $n-1$ derivatives on the interval $(-\infty, \infty)$, the functions linearly independent when the Wronskian of them is not identically zero on $(-\infty, \infty)$.

Linear Independence of Functions

(5)

Let $\vec{f}_1 = \sin^2 x$, $\vec{f}_2 = \cos^2 x$, $\vec{f}_3 = 5$.

Then $5\vec{f}_1 + 5\vec{f}_2 - \vec{f}_3 = 5\sin^2 x + 5\cos^2 x - 5$.

$$= 5(\sin^2 x + \cos^2 x) - 5$$

$$= 5(1) - 5 = 0$$

The vectors $\vec{f}_1, \vec{f}_2, \vec{f}_3$ are linearly dependent.

Wronskian If $\vec{f}_1 = f_1(x), \vec{f}_2 = f_2(x), \dots, \vec{f}_n = f_n(x)$ are n functions that are $n-1$ times differentiable on the interval $(-\infty, \infty)$, then the determinant

$$W(x) = \begin{vmatrix} f_1(x) & f_2(x) & \cdots & f_n(x) \\ f'_1(x) & f'_2(x) & \cdots & f'_n(x) \\ \vdots & \vdots & & \vdots \\ f^{(n-1)}(x) & f^{(n-1)}(x) & \cdots & f^{(n-1)}(x) \end{vmatrix}$$



is called the Wronskian of functions $f_1(x), f_2(x), \dots, f_n(x)$.

Theorem If the functions $\vec{f}_1, \vec{f}_2, \dots, \vec{f}_n$ have $n-1$ continuous derivatives on the interval $(-\infty, \infty)$, the functions are linearly independent when the Wronskian of those functions is not identically zero on $(-\infty, \infty)$.

Example ⑥ Use the Wronskian to show that $\vec{f}_1 = x$ and $\vec{f}_2 = \sin x$ are linearly independent.

$$W(x) = \begin{vmatrix} x & \sin x \\ 1 & \cos x \end{vmatrix} = x \cos x - \sin x$$

2 function dia yai hin tou ham n - 1 tak derivative find karin gai

$W(x) = x \cos x - \sin x$ is not identically zero on the interval $(-\infty, \infty)$. The functions are linearly independent.

Example ⑦ Use the Wronskian to show that the functions $\vec{f}_1 = 1$, $\vec{f}_2 = e^x$, $\vec{f}_3 = e^{2x}$ are linearly independent.

$$W(x) = \begin{vmatrix} 1 & e^x & e^{2x} \\ 0 & e^x & 2e^{2x} \\ 0 & e^x & 4e^{2x} \end{vmatrix} = 1 \begin{vmatrix} e^x & 2e^{2x} \\ e^x & 4e^{2x} \end{vmatrix} = 2e^{3x}$$

The Wronskian $W(x) = 2e^{3x}$ is not identically zero. Therefore the functions $\vec{f}_1, \vec{f}_2, \vec{f}_3$ on $(-\infty, \infty)$ are linearly independent.

Example ⑧ $\vec{f}_1 = x^2 \quad \vec{f}_2 = x + 3 \quad \vec{f}_3 = 4x^2 + 2x + 6$

$$W(x) = \begin{vmatrix} x^2 & x+3 & 4x^2+2x+6 \\ 2x & 1 & 8x+2 \\ 2 & 0 & 8 \end{vmatrix}$$

$$\begin{aligned} &= x^2(8 - 0) - (x+3)(16x + 16x - 4) + (4x^2 + 2x + 6)(0 - 2) \\ &= 8x^2 + 4(x+3) - 2(4x^2 + 2x + 6) \\ &= \cancel{8x^2} + 4x + 12 - \cancel{8x^2} - \cancel{4x} - \cancel{12} \end{aligned}$$

wronskian mai ulta hisab kitab hi

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The functions are linearly dependent.

EX 4.3
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