

# University of Jordan School of Engineering Department of Mechatronics Engineering Microprocessor and Microcontroller Laboratory 0908432



Exp. 9: Serial Communication

# **Objectives**

- 1- To become familiar with the use of serial communications through the USART.
- 2- To demonstrate methods of remote control using serial communications.
- 3- To use the debugging facility of the MPLAB IDE to fix program bugs.

### **Pre-lab Preparation:**

- 1- Review the sections in the book regarding the USART.
- 2- Read the PIC16F877A data sheet especially chapter 10.
- 3- Review the instruction set of the PIC 16F877A.
- 4- Read the assembly programs **carefully** and try to understand the operation and the settings used.

### **Procedure:**

we are going to use the USART of the PIC to receive a character from the PC and return (send) next character to PC again. The communication is done using the RS232 protocol by utilizing the TTL to RS232 converter IC MAX202 on the board. You will need to use a communications program on the PC to monitor the data sent by the PIC.

## Exercise: -

- -Modify the code to receive a number and show the next one on 7-Segments and sent it to the PC again.
- -Modify the code to classify the characters into 9 groups (1-9) as following and show the number of group on 7-Segments

Group	1	2	3	4	5	6	7	8	9
Character	A, B, C	D, E, F	G, H, I	J, K, L	M, N, O	P, Q, R	S, T, U	V, W, X	Y, Z

This program to receive a character from the PC and return (send) next character to PC again. include "p16f877A.inc" **CONFIG** \_CP\_OFF & \_WDT\_OFF & \_BODEN\_OFF & \_PWRTE\_OFF & \_XT\_OSC : User-defined variables cblock0x20 WTemp ; Must be reserved in all banks StatusTemp Counter endc cblock 0x0A0 ; bank 1 assignnments WTemp1 ; bank 1 WTemp endc cblock0x120 ; bank 2 assignnments ; bank 2 WTemp WTemp2 endc cblock 0x1A0 ; bank 3 assignnments ; bank 3 WTemp WTemp3 endc ; Macro Assignments push macro movwf WTemp ;WTemp must be reserved in all banks STATUS,W ;store in W without affecting status bits swapf banksel StatusTemp ;select StatusTemp bank movwf StatusTemp ;save STATUS endm pop macro StatusTemp ;point to StatusTemp bank banksel StatusTemp,W ;unswap STATUS nybbles into W swapf movwf **STATUS** restore STATUS (which points to where W was stored) WTemp,F ;unswap W nybbles swapf restore W without affecting STATUS WTemp,W swapf endm

```
; Start of executable code
         0x00
                  ; Reset vector
    org
    nop
        Main
    goto
; Interrupt vector
    org
         0x04
                  ; interrupt vector
    goto IntService
; Main program
Main
                  ; Initialize everything
    call
         Initial
MainLoop
    nop
    nop
    goto
         MainLoop ; Do it again
; Initial Routine
Initial
    movlw
              D'25'
                       ; This sets the baud rate to 9600
              SPBRG
    banksel
                            ; assuming BRGH=1 and Fosc=4.000 MHz
              SPBRG
    movwf
    banksel
              RCSTA
    bsf
              RCSTA, SPEN
                            ; Enable the serial port
              RCSTA,RX9; Disable9-bit Receive
    bcf
                            : Enable continuous receive
    bsf
              RCSTA,CREN
    banksel
              TXSTA
    bcf
              TXSTA,SYNC
                            ; Set up the port for asynchronous operation
    bsf
              TXSTA,TXEN
                            ; Transmit enabled
    bsf
              TXSTA,BRGH
                            ; High baud rate
              TXSTA,TX9; Disable9-bit send
    bcf
    banksel
              PIE1
                       ; Enable the Timer2 interrupt
         PIE1, RCIE
    bsf
         TRISC,RC6
    bcf
                       ; Set RC6 to output Send Pin
```

```
bsf
          TRISC,RC7
                          ; Set RC7 to input Receive Pin
                               ; Enable global and peripheral interrupts
     banksel
               INTCON
     bsf
          INTCON, GIE
     bsf
          INTCON, PEIE
     banksel
               Counter
     clrf Counter
     return
; Interrupt Service Routine
; This routine is called whenever we get an interrupt.
IntService
     push
     btfsc PIR1, RCIF; Check for a Timer2 interrupt
     call
          RECEIVE
                    ; Check for another interrupt
     btfsc ...
     call
     btfsc ...
                    ; Check for another interrupt
     call
     pop
     retfie
RECEIVE
     movf RCREG,w
     movf RCREG,w
     movwf
               Counter
     incf Counter,w
     banksel
               TXREG
                               ; Send a next character out the serial port
     movwf
               TXREG
     banksel
               TXSTA
     btfss TXSTA,TRMT
L1
     goto L1
     return
     end
```